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II



W HANDLU
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we Lwowie.

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II 1

Desy ty z abranie

z 14
z 14

(z 13)

procurator z 13

termodynamiki

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^{These}
Kunst ^{Ullrich} Chemie N. d. d. 5 p. 5-28
D. M. Zurep 202 E. 6

Georg ^{Robert} Doltum Wied. Am. 57 p. 783

W. 5 v. 24 Maxwell Physic. Papers 1

Helmholtz { Wied. Am. 7 p. 337 (1879)
= Ges. Math. I p. 855
Dorn Wied. A. 9 p. 513 (1880)
10 p. 46 } Stimmungstöne
etc.

Hardy Journ. ph. Chem 4 p. 335 (1900)
Z. ph. Chem. 33 p. 385

How small is x :

$$x! = x^x e^{-x} \sqrt{2\pi x}$$

Jżeli gaz ma ciśnienie p i temp θ ; jkij pseudopod. zbioru z normalnej
gęstości $\bar{p} = \frac{p}{R\theta}$ to n w jednym mm^3 ?

N.p. pseudopod. gęstości $\propto \bar{p}$?

$\propto \bar{p}$ będzie jeżeli w owym mm^3 będą $\propto \bar{N}$ cząstek

Prawdopodob. żeby prawa drobina znajdowała się w owym $\omega = W = \frac{U}{V}$

^{niezależnie}
czyli $\frac{1}{V} = \alpha \frac{\omega}{V}$ n się znajdowały $= \left(\frac{\omega}{V}\right)^n = \left(\alpha \frac{U}{V}\right)^n$

Jżeli
Nie chodzi jednak o indywidualności tych drobin, więc jakakolwiek kombinacja możliwa

to należy owe wyrażenie pomnożyć przez ilość możliwych ~~przebiegów~~ kombinacji

czyli $\propto n \frac{U}{V}$ z n elementami $= \frac{n!}{(\alpha n \frac{U}{V})!}$

Wtedy w całości:
$$\left(\frac{\omega}{V}\right)^{\alpha n \frac{U}{V}} \cdot \frac{n \cdot (n-1) \cdot (n-2) \cdots (n - \alpha n \frac{U}{V} + 1)}{1 \cdot 2 \cdot 3 \cdots \alpha n \frac{U}{V}} \cdot \frac{(n - \alpha n \frac{U}{V})!}{(n - \alpha n \frac{U}{V} - 1)!}$$

$$\binom{n}{\alpha n \frac{U}{V}} = \frac{n!}{(\alpha n \frac{U}{V})! (n - \alpha n \frac{U}{V})!} = \frac{\Gamma(n)}{\Gamma(\alpha n \frac{U}{V}) \cdot \Gamma(n - \alpha n \frac{U}{V})}$$

$$\frac{\alpha n \frac{U}{V} \cdots 3 \cdot 2 \cdot 1}{(n - \alpha n \frac{U}{V} + 1) \cdots (n - \alpha n \frac{U}{V} + 1 + \alpha n \frac{U}{V} - 1)} = \frac{\Gamma(n - \alpha n \frac{U}{V})}{(\alpha n \frac{U}{V})!}$$

$$W = \frac{\left(\frac{\omega}{V}\right)^{\alpha n \frac{U}{V}} (\alpha n \frac{U}{V})^n}{(\alpha n \frac{U}{V})^{\alpha n \frac{U}{V}} \Gamma(n - \alpha n \frac{U}{V})} = \frac{(\alpha n \frac{U}{V})^n}{(\alpha n)^{\alpha n \frac{U}{V}} \Gamma(n - \alpha n \frac{U}{V})}$$

$$W \propto \frac{U}{v} \frac{n}{\left(\frac{\alpha n U}{v}\right)^{\alpha + \frac{1}{v}} e^{-\alpha n \frac{U}{v}} \sqrt{\ln \alpha n \frac{U}{v}}} = \left(\frac{U}{\alpha}\right)^{\alpha n \frac{U}{v}} \frac{1}{\sqrt{2\pi \alpha n \frac{U}{v}}}$$

vize omangge lihty esitusek --

$$W = \left(\frac{U}{\alpha}\right)^v \frac{1}{\sqrt{2\pi v}}$$

$$\frac{\partial W}{\partial v} = \left(\frac{U}{\alpha}\right)^v \left[\frac{1}{\sqrt{2\pi v}} \log \frac{U}{\alpha} - \frac{\frac{1}{2}}{\sqrt{2\pi v^3}} \right] \left(\frac{U}{\alpha}\right)^v \frac{1}{\sqrt{2\pi v}} = 0$$

$$\log \frac{U}{\alpha} = \frac{1}{4\pi v} = 1 - \log \alpha$$

$$\log \alpha = 1 - \frac{1}{4\pi v}$$

~~for~~

$$\int_0^\infty W dx = \frac{U^v}{\sqrt{2\pi v}} \int \frac{dx}{\alpha^v} = \left[-\frac{U^v}{\sqrt{2\pi v}} \frac{1}{\alpha^{v-1}} \right]_0^\infty$$

$$\log \frac{U}{\alpha} = \frac{1}{4\pi v} + 1 = 1 - \log \alpha$$

just rise to ~~the~~ $\log \alpha = -\frac{1}{4\pi v}$

$$\alpha = U e^{-\frac{1}{4\pi v}} \neq 1$$

hijpaandp. $\alpha = 1$

Równie prawdy, jeżeli będzie $n!$ Permutacji $= \bar{W}_1$

z tych będzie $\binom{n}{\alpha n \frac{w}{v}}$ takich par, których dane elementy znajdują się w tej samej

a to prawdy $\bar{W}_1 \frac{n!}{\binom{n}{\alpha n \frac{w}{v}}}$ równa się zatem $\left(\frac{w}{v}\right)^v$

z czego otrzymamy się prawdy. \bar{W}_1 dla jedności z pierwszych możliwych Permutacji:

$$\bar{W}_1 = \left(\frac{w}{v}\right)^v \frac{\binom{n}{\alpha n \frac{w}{v}}}{n!} = \left(\frac{w}{v}\right)^v \frac{1}{(\alpha n \frac{w}{v})! (n - \alpha n \frac{w}{v})!}$$

$$1 = \int_0^1 W d\alpha = \int_0^1 \left(\frac{w}{v}\right)^{\alpha m} \frac{1}{\sqrt{2\pi \alpha m}} d\alpha \quad \begin{matrix} \alpha m = v \\ \alpha = \frac{v}{m} \end{matrix}$$

$$= \frac{1}{m} \int_0^m \left(\frac{w}{v}\right)^v \frac{1}{\sqrt{2\pi v}} dv$$

12
3 4 5

$\left(\frac{w}{v}\right)^v$ prawdy po zmianie pierwszych v elementów

składamy $v+1$; prawdy że ona nie będzie porażką: $\frac{v-w}{v}$

teraz nam nie chodzi o identyfikację, ale o to, jak będzie

czy prawdy ich, jeżeli będzie v było większe niż zero: $\left(\frac{w}{v}\right)^v \frac{v-w}{v} (v+1)$

składamy $v+2$; prawdy że będzie zero o mnie więcej: $\left(\frac{w}{v}\right)^v \left(\frac{v-w}{v}\right)^2 (v+1)$

możemy się zamknąć z v będzie zero więcej

12	13	14
3 4	2 4	1 4
14	13	23
3 2	2 3	1 3
34	24	12

$$\left(\frac{w}{v}\right)^v \left(\frac{v-w}{v}\right)^2 (v+1)$$

(700-)

$$N \text{ w } 1 \text{ cm}^3 = 21 \cdot 10^{18}$$

przewodzący jest w jakim mm³, $21 \cdot 10^{15}$

$$W_0 = e^{21 \cdot 10^{15}}$$

Przewodzący jest w jakiej $\frac{nW}{v} = W_0$

zależy

że n zależy od v: $W_0 = 1$

w x-dw: $dW =$

Zobacz Pascal & Motin p. 518:

$$u = n \quad p = \frac{\omega}{v} \quad q = \frac{v-\omega}{v}$$

$$n = v$$

$$W = \frac{n!}{v! (n-v)!} \left(\frac{\omega}{v}\right)^v \left(\frac{v-\omega}{v}\right)^{n-v}$$

$$x! = \frac{x^x}{e^x} \sqrt{2\pi x}$$

$$= \frac{\left(\frac{n}{e}\right)^n \sqrt{2\pi n}}{\left(\frac{v}{e}\right)^v \sqrt{2\pi v} \left(\frac{n-v}{e}\right)^{n-v} \sqrt{2\pi(n-v)}} \left(\frac{\omega}{v}\right)^v \left(1 - \frac{\omega}{v}\right)^{n-v}$$

$$= \frac{n^n}{v^v (n-v)^{n-v}} \sqrt{\frac{n}{2\pi v(n-v)}} \left(\frac{\omega}{v}\right)^v \left(1 - \frac{\omega}{v}\right)^{n-v}$$

$$= \frac{n^{n-v} \cdot n^v}{(n-v)^{n-v} v^v} \cdot \frac{1}{\left(1 - \frac{v}{n}\right)^{n-v} \left(\frac{v}{n}\right)^v} \sqrt{\frac{1}{2\pi v \left(1 - \frac{v}{n}\right)}}$$

$$\lim \left(1 - \frac{v}{n}\right)^n = \left(1 - \frac{v}{n}\right)^{\frac{n}{v} \cdot v} = e^{-v}$$

$$= \left(\frac{n}{e v}\right)^v \frac{1}{\sqrt{v \cdot 2\pi}}$$

$$W = \frac{1}{v^2} \left(\frac{m}{e v} \right)^v \left(\frac{\omega}{v} \right)^v \cdot [] \cdot \left(1 - \frac{\omega}{v} \right)^{n-v} = \frac{\left(1 - \frac{\omega}{v} \right)^n}{\left(1 - \frac{\omega}{v} \right)^v} = \frac{\left(1 - \frac{\omega}{v} \right)^{\frac{v}{\omega} \cdot \frac{\omega}{v}}}{\left(1 - \frac{\omega}{v} \right)^v} = e^{-\frac{(n-v)\omega}{v}}$$

$$= \left(\frac{1}{e\alpha} \right)^v \frac{1}{v \cdot 2\pi} \cdot e^{-\frac{v}{\alpha}}$$

$$\neq e^{-\frac{v}{\alpha}} \quad \frac{n\omega}{v} = \frac{v}{\alpha}$$

~~$$\frac{v}{v^2} \left(\frac{m}{e v} \right)^{n-v} = \frac{v}{v^2} \left(\frac{m}{e v} \right)^{n-v} \cdot \frac{1}{v} \left(\frac{\omega}{v} \right)^{n-v} = \frac{1}{v^2} \left(\frac{m}{e v} \right)^{n-v} \left(\frac{\omega}{v} \right)^{n-v}$$~~

~~$$= \left(\frac{\omega}{v} \right)^n = \frac{(n-v) \left(\frac{\omega}{v} \right)^{n-v}}{1} \cdot \frac{1}{v}$$~~

~~$$W_0 = e^{21 \cdot 10^{15}} \cdot \frac{1}{\sqrt{2\pi \cdot 21 \cdot 10^{15}}} \cdot e^{-\frac{21 \cdot 10^{15}}{2.7}}$$~~

$$W = \frac{1}{(e\alpha)^v e^{\frac{v}{\alpha}} \sqrt{2\pi v}} = \frac{1}{\sqrt{2\pi v} \cdot \alpha^v \cdot e^{\frac{v}{\alpha} + \frac{v}{2\alpha}}}$$

$$N_p \cdot \alpha = 1$$

$$W_0 = \frac{1}{\sqrt{2\pi v} e^{2v}}$$

$$\frac{W}{W_0} = \frac{e^{2v}}{\alpha^v \cdot e^{\frac{v}{\alpha} + \frac{v}{2\alpha}}} = \frac{e^{v - \frac{v}{\alpha}}}{\alpha^v} = \left(\frac{e}{\alpha} \right)^v \left(\frac{1}{e} \right)^{\frac{v}{\alpha}} \quad \parallel \quad \frac{W_{\alpha=e}}{W_{\alpha=1}} = \left(\frac{1}{e} \right)^{\frac{v}{e}}$$

N_p. kotni o dĺžini bokov 1μ: r₀ = 21 · 10⁶

$$10^5 \text{ cm: } r_0 = 21 \cdot 10^3$$

$$10^{-6} \text{ cm: } r_0 = 21$$

$$\frac{1}{100} \mu$$

$$\frac{W_{\alpha=\frac{e}{2}}}{W_0} = 2^v \left(\frac{1}{e} \right)^{\frac{2v}{e}}$$

prez cisinnosť $\frac{762}{21} = 36 \text{ mm}$
jedna drôhina na každý kotník

$$\lg \frac{W_{\alpha=\frac{e}{2}}}{W_0} = v \lg 2 - \frac{2v}{e} \lg e = v \left[\lg 2 - \frac{2}{e} \right]$$

$$\begin{array}{r} 0.30103 \cdot 2306 \\ - 0.43429 \\ \hline 0.86674 - 1 \end{array} \quad \begin{array}{r} 0.7357 \\ 0.3010 \\ \hline - 0.4347 \end{array}$$

$$\alpha = 1 + \delta$$

$$W = \frac{1}{[e(1+\delta)]^v e^{\frac{v}{1+\delta}} \sqrt{2\pi v}}$$

$$(1+\delta)^v = (1+\delta)^{\frac{1}{\delta} \cdot v\delta} = e^{v\delta}$$

$$= \frac{1}{e^{v+v\delta + \frac{v}{1+\delta}} \sqrt{2\pi v}} = \frac{1}{e^{2v} \sqrt{2\pi v}}$$

$$v' = \frac{1}{e} \sqrt{2\pi v}$$

$$\frac{\mu!}{n!} \frac{1}{(1+\delta)^v} = \frac{\mu!}{n!} \frac{1}{e^{2v} \sqrt{2\pi v}}$$

$$= \frac{\mu!}{n! (\mu-n)! \mu^n \sqrt{2\pi n \frac{\mu-n}{\mu}}} = \frac{\mu!}{n! \mu^n (\mu-n)! \sqrt{2\pi n \frac{\mu-n}{\mu}}}$$

$$n < \mu$$

$$= \frac{\left(\frac{\mu}{n}\right)^n \left(\frac{\mu}{\mu-n}\right)^{\mu-n} \sqrt{2\pi n \frac{\mu-n}{\mu}}}{\left(\frac{\mu}{n}\right)^n}$$

$$= \mu! \left(\frac{\mu}{n}\right)^n \left(\frac{\mu}{\mu-n}\right)^{\mu-n} \sqrt{2\pi n \frac{\mu-n}{\mu}}$$

$$= \mu! \left(\frac{\mu}{n}\right)^n \left(\frac{1}{\mu + \frac{n}{\mu}}\right)^{\mu-n}$$

$$\mu - n = h$$

$$\mu - n = \mu - \mu p + h$$

$$= \mu(1-p) + h$$

$$= \mu q + h$$

$$\frac{1}{2} \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \psi = - \frac{1}{2} \psi$$

$$\frac{1}{2} \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \psi = - \frac{1}{2} \psi$$

$$\left[\frac{1}{2} \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) + \frac{1}{2} \right] \psi = 0$$

$$\frac{1}{2} \Delta \psi = \frac{1}{2} \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \psi + \frac{1}{2} \psi = - \frac{1}{2} \psi$$

$$\frac{1}{2} \Delta \psi = - \frac{1}{2} \psi$$

$$\Delta \psi = - \psi$$

$$= \mu \left[2 \frac{\Delta \tilde{\psi}}{4} + \tilde{\psi} - \psi \right]$$

Drei Kultur spezialisierte & wenig mischbar: bei einer Mischung



Jede einzelne kulturelle Stimmung?

$$= \left[\frac{1}{2} \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) + \frac{1}{2} \right] \psi = 0$$

$$u = A \frac{\partial \psi}{\partial r} + B \left[x \frac{\partial \psi}{\partial x} - y \frac{\partial \psi}{\partial y} \right] - A C \quad \left| \begin{array}{l} = -\frac{B}{r} (y - \omega x) + \frac{A}{r} \omega x \\ = \frac{B}{r} \omega x - \frac{A}{r} \omega x \end{array} \right.$$

$$v = A \frac{\partial \psi}{\partial r} - B \omega x \quad \left| \begin{array}{l} = \frac{B}{r} \omega x - \frac{A}{r} \omega x \end{array} \right.$$

$$\frac{1}{r} \frac{\partial \psi}{\partial r} = \frac{1}{r} \frac{\partial \psi}{\partial r} - \frac{1}{r} \frac{\partial \psi}{\partial r}$$

$$\frac{1}{r} \frac{\partial \psi}{\partial r} = \frac{1}{r} \frac{\partial \psi}{\partial r} - \frac{1}{r} \frac{\partial \psi}{\partial r}$$

$$u = \frac{B}{r} \left(\frac{1}{r} \frac{\partial \psi}{\partial r} - \frac{1}{r} \frac{\partial \psi}{\partial r} \right) + \frac{A}{r} \left(\frac{1}{r} \frac{\partial \psi}{\partial r} - \frac{1}{r} \frac{\partial \psi}{\partial r} \right) - \frac{A}{r} \omega x$$

$$v = \frac{B}{r} \left(\frac{1}{r} \frac{\partial \psi}{\partial r} - \frac{1}{r} \frac{\partial \psi}{\partial r} \right) - \frac{A}{r} \omega x$$

$$B \frac{1}{r} \frac{\partial \psi}{\partial r} = \frac{B}{r} \left(\frac{1}{r} \frac{\partial \psi}{\partial r} - \frac{1}{r} \frac{\partial \psi}{\partial r} \right) - \frac{A}{r} \omega x$$

$$\frac{\partial \psi}{\partial r} = -4\pi\epsilon_0$$

$$u = \frac{1}{r} \left[x \frac{\partial \psi}{\partial x} - y \frac{\partial \psi}{\partial y} \right] - \frac{A}{r} \omega x$$

$$\epsilon = \frac{\partial \psi}{\partial r}$$

$$u = -\frac{\mu}{4\pi\epsilon} (r^2 - R^2)$$

$$2\pi R \frac{\mu R}{2\pi\epsilon} \int \epsilon d\phi = \frac{\mu R^2}{\epsilon} \frac{\partial \psi}{\partial r}$$

$$\frac{\partial u}{\partial r} = -\frac{\mu R}{2\pi\epsilon}$$

$$= \frac{\mu R^2}{\epsilon} \frac{\partial \psi}{\partial r} = \frac{E R^2}{\epsilon}$$

$$\text{Max } E = \frac{\mu R^2}{\epsilon}$$



$$u = -\frac{1}{r} \quad v = \frac{1}{r} \frac{r}{X}$$

$$u = c \left[1 - \frac{3}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3} - \frac{3}{4} \frac{a}{r^3} \left(1 - \frac{a^2}{r^2} x^2 \right) \right]$$

$$v = -c \frac{3}{4} \frac{a}{r^3} \left(1 - \frac{a^2}{r^2} \right) x \omega$$

$$u = c \left[1 - \frac{3}{4} \frac{a}{r} (1 + \cos^2 \theta) - \frac{1}{4} \frac{a^3}{r^3} (1 - 3 \cos^2 \theta) \right]$$

$$v = -\frac{3}{4} \frac{ac}{r} \left(1 - \frac{a^2}{r^2} \right) \sin \theta \omega$$

$$u = u_{r=a} + \frac{\partial u}{\partial r} \rho$$

$$\frac{\partial u}{\partial r} = c \left[\frac{3}{4} \frac{a}{r^2} (1 + \cos^2 \theta) + \frac{3a^3}{4r^4} (1 - 3 \cos^2 \theta) \right]$$

$$= \frac{3}{4} \frac{c}{a} [1 + \cos^2 \theta + 1 - 3 \cos^2 \theta] = \frac{3}{2} \frac{c}{a} \sin^2 \theta$$

$k=2$

$$\frac{\partial v}{\partial r} = -\frac{3}{4} ac \sin \theta \omega \left[\left(1 - \frac{a^2}{r^2} \right) \frac{1}{r^2} + \frac{2a^2}{r^4} \right] = \frac{3}{4} \frac{c}{a} \left[1 - \frac{3a^2}{r^2} \right]$$

$$= -\frac{1}{r^2} + \frac{3a^2}{r^4} = -\frac{3}{2} \frac{c}{a} \sin \theta \omega$$

$$u = \frac{3}{2} \frac{c}{a} \sin^2 \theta \cdot \rho$$

$$v = -\frac{3}{2} \frac{c}{a} \sin \theta \omega \cdot \rho$$

$$vel_{\theta} = \sqrt{u^2 + v^2} = \frac{3}{2} \frac{c}{a} \sin \theta \cdot \rho$$

$$vel_{\perp} = -(u \sin \theta + v \omega) = -\frac{3}{2} \frac{c}{a} \sin \theta \rho (\sin^2 \theta + \omega \theta)$$

$$= \frac{3}{2} \frac{c}{a} \sin \theta \cdot \rho$$

size of the part is the same as the whole, so the velocity is the same

całkowity
 potencjał elektryczny, równy do sumy potencjałów (w punkcie p.p. θ):
 (zobacz rysunek)

$$\varphi = \int u \varepsilon dp = -\frac{1}{4\pi} \int u \frac{\partial \varphi}{\partial p} dp$$

podstawiamy wyrażenie na u
 i otrzymujemy do θ

$$= -\frac{1}{4\pi} \cdot \frac{3}{2} \cdot \frac{c}{a} \cdot \frac{1}{a} \int \frac{\partial \varphi}{\partial p} p dp$$

$$= -\frac{3}{8\pi} \cdot \frac{c}{a} \cdot \frac{1}{a} \int_0^\infty \frac{\partial \varphi}{\partial p} p dp = \varphi_i - \varphi_e$$

$$= \frac{3}{2} \cdot \frac{c}{a} \cdot \frac{1}{4\pi} \cdot \frac{1}{a} (\varphi_e - \varphi_i)$$

Wzrost potencjału elektrycznego
 $\mathcal{I} = \lambda \frac{\partial \varphi}{\partial \theta}$

$$U = \int \frac{1}{2} \cdot \frac{3}{2} \cdot \frac{c}{a} \cdot \frac{1}{a} \cdot \frac{\varphi_e - \varphi_i}{4\pi} a \cdot r \cdot d\theta$$

Potencjał w punkcie θ : $\frac{3}{2} \cdot \frac{c}{4\pi a} \cdot \frac{\varphi_e - \varphi_i}{2} \cos \theta$

Jaki system pól powstanie wskutek potencjału $U = A \cos \theta$?



$$u_1 = \frac{M_1}{r_1}$$

$$U = u_1 + u_2 = M_1 \left(\frac{1}{r_1} - \frac{1}{r_2} \right) = \frac{M_1}{r_2} \cos \theta$$

czyli $\frac{M_1^2}{a^2} = \frac{3}{2} \cdot \frac{c}{4\pi a} (\varphi_e - \varphi_i)$

to będzie pole $U = \frac{3}{2} \cdot \frac{c}{4\pi a} (\varphi_e - \varphi_i) \frac{a^2}{r^2} \cos \theta$

czyli $\sum i (U_{10} - U_{20}) =$

$$\int_0^{2\pi} \int_0^\pi \sin \theta d\theta d\phi$$

$$3ac \cdot \frac{2\pi}{a} \cdot \frac{2\pi}{a}$$

$$d\vec{r} = \frac{3}{2} \frac{c}{a} \frac{r_e - r_i}{r^2} \omega \theta d\theta$$

$$W = \int_0^{\frac{\pi}{2}} 2\pi a \sin\theta \frac{3}{2} \frac{c}{a} \frac{r_e - r_i}{4\pi} \omega \cdot 2 \frac{3}{2} \frac{c}{4\pi} \frac{r_e - r_i}{\lambda} \omega \theta d\theta$$

$$= 4\pi \frac{3}{2} \frac{c}{a} \frac{1}{\lambda} (r_e - r_i)^2 \int_0^{\frac{\pi}{2}} \omega \theta \sin\theta d\theta$$

$$= \frac{\omega^3 \theta}{3}$$

$$= \frac{3c^2}{16\pi^2} \frac{r_e - r_i}{\lambda}$$

rotacijski moment u odnosu na osi $\frac{J}{a} = \frac{3c}{\lambda} \left(\frac{r_e - r_i}{4\pi} \right)^2$

što je to moment inercije u odnosu na osi:

odnosno: $6\pi uac$

$$\frac{1 - \frac{6x^2}{r^2} + \frac{9x^4}{r^4} + \frac{9x^2\omega^2}{r^4}}{\frac{9x^2}{r^2} + 1 + \frac{3x^2}{r^2}} \quad \left| v = \frac{Ca^2}{r^3} \sqrt{1 - \frac{3x^2}{r^2}} \right.$$

$$Ca^2 \omega \theta = U = \frac{Ca^2 x}{r^3}$$

$$\frac{dx}{d\omega} = - \frac{\frac{\partial U}{\partial \omega}}{\frac{\partial U}{\partial x}} = - \frac{\frac{\partial U}{\partial \omega}}{\frac{\partial U}{\partial x}}$$

$$U = \frac{Ca^2 x}{(x^2 + \omega^2)^{3/2}}$$

$$\frac{\partial U}{\partial x} = - \frac{Ca^2}{r^3} \left[1 - \frac{3x^2}{r^2} \right]$$

$$- \frac{3x\omega}{r^2} \frac{\partial x}{\partial \omega} + \left[1 - \frac{3x^2}{r^2} \right] \frac{\partial x}{\partial x} = 0$$

$$v = - \frac{\partial U}{\partial \omega} = \frac{3Ca^2 x \omega}{r^5}$$

$$\frac{\partial x}{\partial \omega} = - \frac{3x}{r^2} \frac{\partial x}{\partial \omega} + \frac{\partial x}{\partial x} = 0$$

$$\frac{\partial x}{\partial \omega} = - \frac{3x}{r^2} \frac{\partial x}{\partial \omega} + \frac{\partial x}{\partial x} = 0$$

$$\frac{\partial x}{\partial \omega} = - \frac{3x}{r^2} \frac{\partial x}{\partial \omega} + \frac{\partial x}{\partial x} = 0$$

$$\left(\frac{\partial U}{\partial \omega} \right) = - \frac{3Ca^2 x \omega}{r^5}$$

$$\left(1 - \frac{3x^2}{r^2} \right) d\omega + \frac{3x\omega}{r^2} dx = 0$$

$$(\omega^2 - 2x^2) d\omega + 3\omega x dx = 0$$

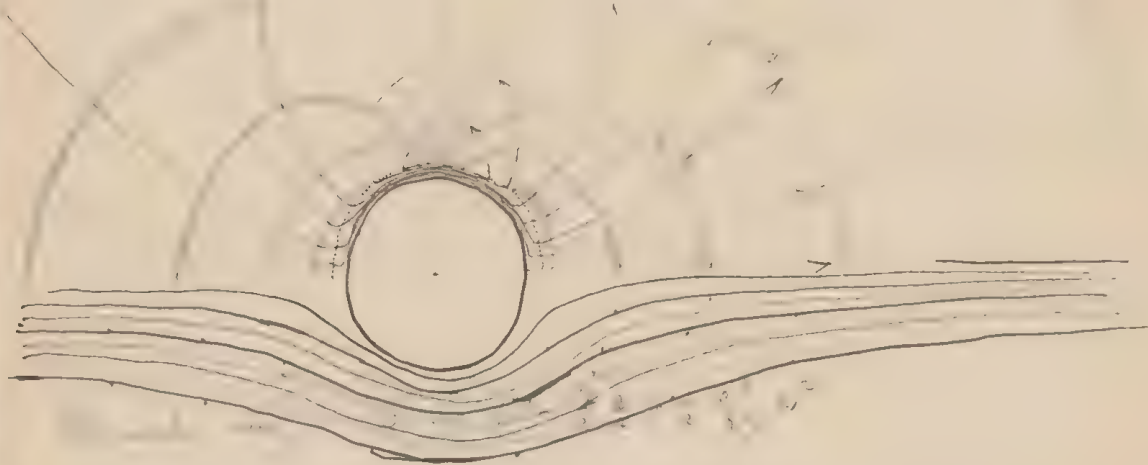
$$\frac{\partial x}{\partial \omega} = - \frac{\frac{\partial U}{\partial \omega}}{\frac{\partial U}{\partial x}}$$

$$d\left(\frac{\omega^2}{2^3}\right) = \left(\frac{2\omega}{2^3} - \frac{3\omega^3}{2^5}\right) d\omega - \frac{3\omega^2 x}{2^5} dx$$

$$= \frac{\omega}{2^5} \left[(2x^2 + 2\omega^2 - 3\omega^2) d\omega - 3\omega x dx \right]$$

$$= \frac{\omega}{2^5} \left[4\omega(2x^2 - \omega^2) d\omega - 3\omega x dx \right]$$

These lines represent: $\frac{\omega^2}{2^3} = \text{const}$



$$1 - \frac{3}{2} \frac{a}{r} \quad \frac{v}{u} = \frac{-\frac{3}{4} \frac{ca}{r^3} (1 - \frac{a^2}{r^2}) x \omega}{-\frac{3}{4} \frac{ca}{r^3} (1 - \frac{a^2}{r^2}) x^2 + c (1 - \frac{1}{2} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3})}$$

$$= \frac{\omega}{x - \frac{4}{3ax} \frac{1 - \frac{3}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3}}{1 - \frac{a^2}{r^2}}} = \frac{\omega}{x - \frac{4r^3 - 3ar^2 - a^3}{3ax(1 - \frac{a^2}{r^2})}}$$

$$\frac{m}{\omega^2} = 1 - \frac{3}{2} \frac{a}{r} + \frac{1}{2} \frac{a^3}{r^3}$$

$$|x=0 \quad r=a$$

$$r = 1a$$

$$r = \frac{3}{2}a$$

$$r = 2a$$

$$r = 3a$$

$$r = 4a$$

$$\frac{m}{\omega^2} = 1 - \frac{3}{2} \frac{a}{r} + \frac{1}{2} \frac{a^3}{r^3}$$

$$\frac{m}{\omega^2} = 0$$

$$\frac{m}{\omega^2} = 1 - 1 + \frac{1}{2} \frac{8}{27} = \frac{4}{27}$$

$$= 1 - \frac{3}{2} \frac{1}{2} + \frac{1}{2} \frac{1}{8} = \frac{16-12+1}{16} = \frac{5}{16}$$

$$= 1 - \frac{3}{2} \frac{1}{3} + \frac{1}{2} \frac{1}{27} = \frac{19}{27}$$

$$= 1 - \frac{3}{2} \frac{1}{4} + \frac{1}{2} \frac{1}{64} = \frac{81}{128}$$

$m=1$	$m=\frac{1}{4}$	$m=\frac{1}{9}$
$\sqrt{\frac{5}{16}} = 0.39$	1.5	0.87
1.8	0.9	0.6
1.4	0.7	0.47
1.25	0.63	0.42

$$m=1$$

Przy przepływie prądu w maki

$$U = \frac{\pi \cdot P \cdot R^2}{8 \pi \cdot L}$$

$$\bar{c} = \frac{P \cdot 6 \cdot (y_i - y_o)}{4 \pi k^2}$$

$$J = \frac{E \cdot \pi \cdot R^2}{6 \cdot L}$$

$$P_{max} = E \cdot J = \frac{P^2 R^2 \cdot 6 \cdot (y_i - y_o)^2}{4 k^2 L \cdot 4 \pi k^2} = U \cdot \frac{11 (y_i - y_o)^2 \cdot 6 P}{2 R^2 \pi^2 k^2}$$

~~$$\frac{1.3 \cdot 10^9 \cdot 4 \cdot 10^8}{5 \cdot 10^7} = \Delta p \cdot 11$$~~

jeżeli ciśnienie dodatkowe, spowodowane przepływem:

$$\Delta p = \frac{11 (y_i - y_o)^2 \cdot 6 P}{2 R^2 \pi^2 k^2}$$

$$\Delta p \cdot (y_i - y_o) = 4 V = 4$$

~~$$\frac{10^3 \cdot 10^9}{5 \cdot 10^7} = \frac{10^6}{10^7} = 10^{-1}$$

 $\frac{1 \text{ est.}}{t^2} \cdot t = \frac{1}{t}$
 $\frac{1 \text{ est.}}{t^3} \cdot t = \frac{1}{t^2}$~~

Conventions:

$$I \text{ to } p_{\text{max}} = c \cdot \pi \cdot R^2 \cdot q = \frac{1}{t} \cdot \frac{1}{t^2} \cdot \frac{t^3}{t} = \frac{1}{t^2} \cdot \frac{t^3}{t} = \frac{1}{t}$$

slowly increases to steady
up pressure, not!

$$H_f = \frac{10^4 \cdot 10^9}{9 \cdot 10^{20}} = \frac{1}{1 \cdot 10^7} \text{ (est.)}$$

$$4 \cdot 6 \cdot 10^{-8} \cdot 10^{16} = 1.17$$

$$4 \cdot 6 \cdot 10^{-8} \cdot 10^{16} = 1.17$$

400

$$\frac{1.3 \cdot 1.7 \cdot 1}{3 \cdot 1 \cdot 3 \cdot 24} = 4 \cdot 10^{-2}$$

$$I_{\text{eff}} = 10^{10} \cdot \frac{10^{-10}}{1.14} = 4 \cdot 10^8 = \frac{4 \cdot 10^8 \cdot 10^{-14}}{9} = \frac{4}{9} \cdot 10^{-3} \text{ (ESS)}$$

$$k = 0.018$$

$$\frac{4 \pi \cdot 0.018 \cdot 2.2}{\frac{4}{9} \cdot 10^{-7} \cdot 10^6 \cdot 1.3} =$$

$$\frac{1}{2} \cdot 10^9 = 2.5$$

$$\epsilon = \frac{1.4}{1.5} = 4 \cdot 10^8 \text{ (ESS)}$$

$$\mu_0 \cdot \frac{1}{2} \cdot 10^{-4} \cdot \frac{1}{\text{cm}} = \frac{10^{-15}}{9} \cdot 10^{16}$$

$$\frac{9 \pi \cdot 2.2 \cdot 0.018}{1.3 \cdot 1.4} = 0.2$$

$$\frac{9 \pi \cdot 2.2 \cdot 0.18}{1.3 \cdot 1.4} = \frac{9 \pi \cdot 1.4}{1.3 \cdot 1.4} = 4.9$$

$$\frac{1}{0.1496} = 6.68$$

$$4 \pi \cdot 1.4 = \frac{2 \cdot 2}{1.3} = 6$$

$$4 \pi \cdot \frac{1.78}{1.82} \cdot 2.113 = \frac{3.14 \cdot 2.11}{1.1 \cdot 1.3} = \frac{3.14 \cdot 2.1}{1.5} = 4$$

$$\frac{\Delta p}{p} = \frac{(1 - \epsilon) \cdot 6}{2 R^2 \pi^2 \cdot 3}$$

$$r_1 - r_2 = 4 \bar{V} = \frac{4}{300} \text{ (ESS)}$$

$$\delta = \frac{4}{9} \cdot 10^{-7} = 4.6 \cdot 10^{-8}$$

$$\eta = 0.010$$

$$R = 0.2294 \text{ mm}$$

$$= \left(\frac{4}{300} \right)^2 \cdot \frac{4}{300 \cdot 0.2294 \cdot 3.14} \cdot \frac{4 \cdot 10^{-8}}{2 \cdot 0.01}$$

$$= \left(\frac{4}{3.14 \cdot 3 \cdot 10^{23}} \right)^2 \cdot 2.3 \cdot 10^{-4} = \frac{4}{2.2} \cdot \frac{2.3 \cdot 10^{-4}}{1.27 \cdot 2.3 \cdot 10^{-4}} = 0.8 \cdot 10^{-3}$$

Kilohi

$$\frac{\text{Opin. de transp.}}{\text{Opin. tarra}} = \frac{\frac{3a}{\lambda} \left(\frac{\varphi_2 - \varphi_1}{2\pi} \right)^2}{6\pi \mu a c} = \frac{\frac{1}{\lambda} \left(\frac{\varphi_2 - \varphi_1}{2\pi} \right)^2}{2\pi \mu a \eta}$$

Nº. $\varphi_2 - \varphi_1 = 4V = \frac{4}{300} \text{ C.S.S}$

$$\frac{1}{\lambda} = 6 = 7.6 \cdot 10^{-8}$$

$$\eta = 0.010$$

$$\frac{4.6 \cdot 10^{-8} \cdot \left(\frac{4}{300 \cdot 4.344} \right)^2}{2.314 \cdot 0.01 \cdot a} = \frac{2.9 \cdot 10^{-6} \cdot \frac{1}{1000}}{3.14 \cdot a}$$

Wk = Opin. d. = $\eta \cdot \text{Tarra}$ j. i. l. $a = 10^{-12} \text{ cm} !$

↳

Nº. Opin. d. = Opin. tarra j. i. l.:

$$\frac{\frac{1}{4.300.511}}{0.01} \cdot \frac{4.6 \cdot 10^{-8}}{a^2} = 1 = \left(\frac{1}{0.942} \right)^2 \cdot \frac{4.6 \cdot 10^{-12}}{a^2}$$

$$a^2 = \frac{4.6}{0.88} \cdot 10^{-12} = 5.1 \cdot 10^{-12}$$

$$a \neq 2.1 \cdot 10^{-6} \text{ cm} = 2.10^{-2} \mu = 0.02 \mu$$

Робота елемента $U = \frac{M \cos \theta}{r^2}$ створює

векторний момент $T_2 = 2\lambda \frac{M \sin \theta}{a^3}$ на одиничний $T_2 = 2\lambda \frac{M \sin \theta}{a^3}$

векторний момент від $\theta=0$ до θ :

$$\int 2\lambda r \sin \theta d\theta = \frac{2\lambda M \sin \theta}{a^3} = \frac{4\lambda M}{a} \int_0^\theta \sin \theta d\theta$$

$$= \frac{4\lambda M}{a} \left[-\cos \theta \right]_0^\theta = \frac{4\lambda M}{a} (1 - \cos \theta) = \frac{4\lambda M}{a} \cdot \frac{2 \sin^2 \frac{\theta}{2}}{2} = \frac{4\lambda M}{a} \sin^2 \frac{\theta}{2}$$

то векторний момент буде дорівнювати 0

векторний момент, що діє на одиничний вектор: $\frac{2\lambda M \sin \theta}{a} = \frac{\lambda M \sin \theta}{a^2}$

векторний момент $\frac{3}{2} \frac{c}{a} \sin \theta \frac{r_0 - r_1}{4\pi}$

то векторний момент $M = \frac{3}{2} \frac{c}{a} \frac{r_0 - r_1}{4\pi} \sin \theta$ вектор: $\vec{M} = \frac{3}{2} \frac{c}{a} \frac{r_0 - r_1}{4\pi} \frac{\sin \theta}{r^2}$

Робота елемента:

$$W = 2 \int_0^{\frac{\pi}{2}} 2\lambda r \cos \theta d\theta \cdot U_{a0} \lambda \frac{dU_{a0}}{dr}$$

$$= 4\lambda r \frac{3}{2} \frac{c}{a} \frac{r_0 - r_1}{4\pi} \cdot \lambda \frac{3c}{a^2} \frac{r_0 - r_1}{4\pi} \int_0^{\frac{\pi}{2}} \cos \theta \sin \theta d\theta$$

$$= \frac{1}{3}$$

$$= \frac{9c^2 (r_0 - r_1)^2}{8\pi a \lambda} \cdot \frac{1}{3} = \frac{3c^2 (r_0 - r_1)^2}{8\pi a \lambda}$$

$$\frac{W}{c} = \Delta F = \frac{3c (r_0 - r_1)^2}{8\pi a \lambda}$$

Векторний момент $\frac{3 (r_0 - r_1)^2}{8\pi a \lambda}$

векторний момент $= \frac{(r_0 - r_1)^2}{16\pi a^2 \lambda} = \left(\frac{r_0 - r_1}{4\pi} \right)^2 \frac{1}{a^2}$

Jaki bezpośredni wpływ ładunku elektrycznego?

jużi wiemy, że pot. dana to ładunek prop. a^2

zatem siła $\sim \frac{a^2 \cdot a^2}{r^2}$ najniższym k malarce $= 2a$

$\therefore f \sim a^2$ zatem przy zmniejszeniu rozmiarów układu a i zmniejszeniu a ,
wpływu. Zatem teoria o rażąco błędna nie może.

Umieszczając 'dopasłość' zatem 2 takie ładunki przeciwne



$\Phi_i = -\Phi_e$ zatem wpływ na zewnętrzny $= 0$

Najpełniej elektryczność:

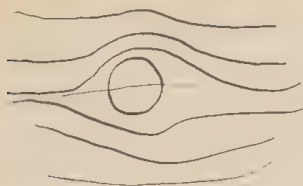
gdzie Φ_i i Φ_e będą takie same, wtedy skutek był $= 0$.

Wtedy jednak Φ_e ma większą wartość niż Φ_i i dlatego kierunek Φ_i i drugi

$$\left. \begin{aligned} \left(\nabla u \frac{\partial u}{\partial x} \right) &= \frac{\partial}{\partial x} \left(u \nabla u \right) - u \nabla^2 u \\ \frac{\partial}{\partial x} \left(\frac{1}{4\pi} u \nabla u - \gamma \right) &= u \nabla^2 u - \gamma \nabla^2 u \\ \frac{\partial}{\partial y} \left(\frac{1}{4\pi} u \nabla u - \gamma \right) &= u \nabla^2 u - \gamma \nabla^2 u \end{aligned} \right\} \begin{aligned} \frac{\partial u}{\partial y} &= -\frac{3}{2} c \frac{a^3 x y}{r^5} \\ \frac{\partial u}{\partial z} &= -\frac{3}{2} c \frac{a^3 x z}{r^5} \\ \frac{\partial u}{\partial x} &= -\frac{3}{2} c \frac{a^3 x^2}{r^5} \end{aligned}$$

$$r=a \quad \frac{\partial u}{\partial x} = \frac{3}{2} c \left[1 - \frac{x^2}{a^2} \right]$$

Jaki rozkład przy działaniu zwojownicy nity X



$$\nabla^2 u = 0$$

$$\frac{\partial u}{\partial n} \Big|_{r=a} = 0$$

$$r^2 = r^2 + r_\theta^2$$

$$\frac{\partial u}{\partial r} = \frac{\partial u}{\partial r} + \frac{\partial u}{\partial \theta} \frac{1}{r}$$

$$\frac{\partial u}{\partial r} = \frac{1}{2} \frac{\partial u}{\partial r}$$

$$u = c x \left[1 + \frac{a^3}{2r^3} \right] = c r \cos \theta \left[1 + \frac{a^3}{2r^3} \right]$$

$$\frac{\partial u}{\partial x} = c \left[1 + \frac{a^3}{2r^3} \right] - \frac{3cx^2 a^3}{2r^5} \Big|_{r=a} = c$$

Wzrost

$$\frac{\partial u}{\partial r} = c \cos \theta \left[1 + \frac{a^3}{2r^3} \right] - c r \cos \theta \frac{3a^3}{2r^4} = c \cos \theta \left[1 + \frac{a^3}{2r^3} - \frac{3a^3}{2r^3} \right] = 0$$

Na powierzchni kuli:

$$\frac{\partial u}{\partial \theta} = \frac{-1}{a} c r \sin \theta \left[1 + \frac{a^3}{2r^3} \right] = -\frac{3c}{2} \sin \theta$$

$$\frac{\partial u}{\partial \theta} = c \cos \theta \left[\frac{3a^3}{2r^4} \right] \Big|_{r=a} = \frac{3c \cos \theta}{a}$$

Ogólne rozwiązanie:

Rozkład:

$$X = \frac{\partial u}{\partial x} = -k \left(\frac{\partial u}{\partial x} + \frac{\partial u}{\partial r} + \frac{\partial u}{\partial \theta} \right)$$

$$X = \frac{\partial u}{\partial x} \in \mathcal{G}$$

\mathcal{G} = przestrzeń wektorowa

(zawierająca wszystkie wektory)

ogólnie:

$$\bar{X} = \varepsilon \frac{\partial u}{\partial x} =$$

$$\frac{1}{4\pi} \nabla^2 u \cdot \frac{\partial u}{\partial x} - \frac{\partial u}{\partial x} = -k \nabla^2 u$$

$$\frac{1}{4\pi} \nabla^2 u \cdot \frac{\partial u}{\partial y} - \frac{\partial u}{\partial y} = -k \nabla^2 u$$

$$\frac{1}{4\pi} \nabla^2 u \cdot \frac{\partial u}{\partial z} - \frac{\partial u}{\partial z} = -k \nabla^2 u$$

$$\frac{\partial}{\partial x}$$

$$\frac{\partial}{\partial y}$$

$$\frac{\partial}{\partial z}$$

$$\nabla^2$$

$$\nabla^2$$

$$\nabla^2$$

$$\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} + \frac{\partial u}{\partial z} = 0$$

$\nabla^2 u = 0$ wynika z ogólnych warunków granicznych na powierzchni

Wir wandeln perinschreibung:

$$\frac{\partial^2 u}{\partial r^2} = \frac{\partial}{\partial r} \left\{ c \cos \theta \left[1 - \frac{a^3}{r^3} \right] \right\}$$

$$= c \cos \theta \frac{3a^3}{r^4} \Big|_{r=a} = \frac{3c \cos \theta}{a}$$

$$\frac{\partial^3 u}{\partial r^3} = -c \cos \theta \frac{12a^3}{r^5} \Big|_{r=a} = -\frac{12c \cos \theta}{a^2}$$

Setzen $U = U_a + \left(\frac{\partial U}{\partial r} \right)_a \rho + \frac{\rho^2}{1.2} \left(\frac{\partial^2 U}{\partial r^2} \right)_a + \dots$

$$= \frac{\rho^2}{1.2} \frac{3c \cos \theta}{a} + \frac{\rho^3}{1.2.3} \frac{12c \cos \theta}{a^2} + \dots$$

$$U = \frac{3c \cos \theta}{2a} \rho^2 - \frac{2c \cos \theta}{a^2} \rho^3 + \dots$$

Bed. v. Krümmungsänderungen (pro cm durch räumliche):

$$\lambda \frac{\partial U}{\partial (r\theta)} \Big|_{r=a \cos \theta} = \frac{\lambda}{r} \frac{\partial U}{\partial \theta} = -\lambda c \sin \theta \left[1 + \frac{a^3}{2r^3} \right]$$

$$= -\lambda c \sin \theta \left[1 + \dots \right]$$

$$= -\frac{3}{2} \lambda c \sin \theta \left[1 + \frac{a^3}{a^3} \right]$$

Wzręć zadanie zadania:

Zadanie potęgi U :

$$\Delta U = 0 \quad \text{a na powierzchni kuli} \quad \text{dane wartości dla } \frac{\partial U}{\partial r}$$

Conwersja przed 2 kuli przysięga do cięży 2 dany zły

$$\frac{d}{d\theta} = \frac{1}{a} \frac{d}{d\theta} = \frac{3}{2} \frac{c}{a^2} \frac{(r_2 - r_1)}{4\pi} \cos \theta$$

Przed pociąg uderzenia: $\frac{d}{d\theta} = \frac{3c}{4\pi} (r_2 - r_1) \sin \theta$

nieco $\frac{d}{d\theta} = \frac{3c}{2} (r_2 - r_1) \sin \theta \cos \theta d\theta$

podobno pociąg: $2a^2 \sin \theta d\theta$

zatem zotami uderzenia i krawędzi uderzenia po cm^2 :

$$\frac{3c}{4\pi} \frac{r_2 - r_1}{a^2} \cos \theta = \lambda \left(\frac{\partial U}{\partial r} \right)_{r=a, \theta}$$

Wzręć zadanie zadania U dane na kuli U pociąg uderzenia

$$\left(\frac{\partial U}{\partial r} \right)_{r=a} = m \cos \theta \quad \text{a u uderzenia } r=a$$

$$U=0$$

toż U jest uderzenia: (pociąg uderzenia): $U = \frac{M \cos \theta}{22}$

$$\lambda \left(\frac{\partial U}{\partial r} \right)_{r=a} = - \frac{2\lambda M \cos \theta}{a^3} = \frac{3c}{4\pi} \frac{r_2 - r_1}{a^2} \cos \theta$$

$$M = - \frac{3c a}{8\lambda} \frac{r_2 - r_1}{a^2}$$

zatem: $U = - \frac{3c a}{2\lambda} \frac{r_2 - r_1}{4\pi} \frac{\cos \theta}{a^2}$

$$u = u_0 + u_1$$

$$-\frac{\partial p}{\partial x} = -k \nabla^2 u_0$$

$$-\frac{\partial p}{\partial y} = -k \nabla^2 u_0$$

$$\frac{1}{4\pi} \nabla^2 u \frac{\partial u}{\partial x} = -k \nabla^2 u_1$$

$$\frac{1}{4\pi} \nabla^2 u \frac{\partial u}{\partial y} = -k \nabla^2 u_2$$

$$\frac{1}{4\pi} \nabla^2 u \frac{\partial u}{\partial z} = -k \nabla^2 u_3$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$\frac{\partial u_0}{\partial x} + \frac{\partial v_0}{\partial y} = 0$$

$$\frac{\partial u_1}{\partial x} + \frac{\partial v_1}{\partial y} = 0$$

~~$$u = \frac{1}{4\pi} \nabla^2 u \frac{\partial u}{\partial x} + \frac{1}{4\pi} \nabla^2 u \frac{\partial u}{\partial y} + \frac{1}{4\pi} \nabla^2 u \frac{\partial u}{\partial z}$$~~

Opisujemy rozwiązanie:

~~$$\frac{1}{4\pi} \nabla^2 u \frac{\partial u}{\partial x} = -k \nabla^2 u_1 + \frac{\partial p}{\partial x}$$~~

~~$$\frac{1}{4\pi} \nabla^2 u \frac{\partial u}{\partial y} = -k \nabla^2 u_2 + \frac{\partial p}{\partial y}$$~~

~~$$\frac{1}{4\pi} \nabla^2 u \frac{\partial u}{\partial z} = -k \nabla^2 u_3 + \frac{\partial p}{\partial z}$$~~

Przyjmujemy teraz dla u : superpozycję

rozkładu przy działaniu zewnętrznego pola X

i rozkładu p.t. własnego podłoża:

$$u = A \times \left[1 + \frac{a^3}{2r^3} \right] + u_0$$

pyłkowy składnik: rozkład przy działaniu zewnętrznego pola X

składnik u_0

$$\frac{\partial p}{\partial x} = 0 \quad \frac{\partial p}{\partial y} = 0 \quad \int \nabla^2 u \cdot dxdydz = \int \left[\frac{\partial u}{\partial x} \frac{\partial p}{\partial x} + \frac{\partial u}{\partial y} \frac{\partial p}{\partial y} + \frac{\partial u}{\partial z} \frac{\partial p}{\partial z} \right] dxdydz$$

nie można uwzględnić pyłków wewnątrz co bardzo mało i nie rozważamy tego
to rozkład przy działaniu zewnętrznego pola X i rozkład p.t. własnego podłoża

$$\frac{1}{4\pi} \nabla^2 u \frac{\partial u}{\partial x} = -k \nabla^2 u_1 + \frac{\partial p}{\partial x}$$

składnik u_0 (1) $\frac{\partial u}{\partial x}$ mało

A zatem to $\int p d\Omega$ będzie

$$= -\frac{3}{2} A \sin \theta \left[1 + \frac{a^3}{r^3} \right]$$

$$= \frac{\partial u}{\partial \rho^2} = \rho \frac{\partial u}{\partial \rho} - \frac{1}{\rho} = \rho - \frac{1}{\rho}$$

$\frac{\partial p}{\partial s}$ takie przybliżenie stałe i dyktuje

$$\text{zatem } \int p d\Omega \frac{\partial p}{\partial s} = \frac{\partial p}{\partial s} \frac{p^2}{2} \neq 0$$

$$\frac{3}{2} A \sin \theta \frac{p_2 - p_1}{4\pi} = k (u_1 - u_0) + \rho \frac{du}{d\rho}$$

można to stać $= -u_0 k$
zatem $\lim_{\rho \rightarrow 0} \rho \frac{\partial u}{\partial \rho} = 0$ [co każdy rozumie] - posteriori
i skąd

zatem

To drugi raz do varstvenih pogojev, do s tem in pretekli

$$z=0 \quad \text{not } \nabla^2 u_1$$

$$k \nabla^2 u = \frac{\partial f}{\partial x} \quad \text{etc.}$$

Zadanie będzie style ~~z~~ endów wch ciesz z tymi kto na poziomie

Kali petrus wammuk: $v_s / \frac{r}{h} = \frac{2}{L} A \sin \theta \frac{\varphi_1 - \varphi_2}{4\pi}$

$$x_j: u = -\frac{3}{2} \frac{A}{k} \frac{\varphi_i - \varphi_0}{m} \left(1 - \frac{x^2}{a^2}\right)$$

$$\sin \theta \cos \theta \cos \varphi = \frac{y \cdot x}{a^2}$$

2. 0 m 2.4

$$v = \frac{xy}{a^2}$$

$$V = \frac{xz}{y^2}$$

Integrando ora ogni: $u = \frac{M}{2\mu k^3} (x^2 + z^2) + \frac{N}{x^5} (x^2 - 3xy) + C \frac{13C}{2} (1 - \frac{x^2}{e})$

$$v = \frac{M}{2\mu v^3} x_4 - \frac{3N}{25} x_7 \quad -\frac{3}{2} c \frac{x_4}{a}$$

$$W = \frac{M}{2r^3} x_2^2 - \frac{3N}{25} x_2$$

for $r=a$: $\frac{M}{2\mu a^3} (a^2 + x^2) + \frac{N}{a^5} (a^2 - 3x^2) + C = -\frac{3}{2} \frac{A}{x} \dots \left(1 - \frac{x^2}{a^2}\right)$

$$\frac{M}{2na} - \frac{3N}{a^3} = \frac{3}{2} \frac{A}{a} \dots$$

$$\frac{M}{2\mu a} + \frac{N}{a^3} = -\frac{3}{2} \frac{A}{R}$$

$$\frac{4N}{a^3} + c = -3A \dots$$

$$\frac{4M}{2na} + 3c = -2 \frac{3}{2} A -$$

$$u_x + v_y + w_z = \frac{M}{2\mu r^2} \underbrace{[x(r^2 + r^2) + xy^2 + xz^2]}_{2r^2x} + \frac{N}{r^5} \underbrace{(r^4 - 3x^3 - 3xy^2 - 3xz^2)}_{-2r^2x} + cx$$

$$= \frac{M}{\mu} \frac{x}{r} - \frac{2N}{r^3} \frac{x}{r^2} + cx$$

$$\mu = \mu_0 + \frac{M}{2} \frac{x^2}{r^3}$$

$$u = \frac{M}{2\mu} \left(\frac{1}{r} + \frac{x^2}{r^3} \right) + \frac{N}{r^3} \left(\frac{1}{r^3} - \frac{3x^2}{r^5} \right) + c$$

$$r \frac{d}{dr} = -\frac{M}{2\mu} \left(\frac{1}{r^2} + \frac{3x^2}{r^3} \right) - N \left(\frac{3}{r^3} - \frac{15x^2}{r^5} \right) + \mu$$

$$+ \left(\frac{M}{2\mu} \frac{1}{r^3} - \frac{3N}{r^5} \right) r \frac{d(x^2)}{dr}$$

$$\underbrace{= x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} + z \frac{\partial}{\partial z}}_{= 2x^2} = 2x^2$$

$$= \frac{M}{2\mu} \left[-\frac{1}{r} - \frac{3x^2}{r^3} + \frac{2x^2}{r^3} \right] + 3N \left[-\frac{1}{r^3} + \frac{5x^2}{r^5} - \frac{2x^2}{r^5} \right]$$

$$r \frac{du}{dr} = -\frac{M}{2\mu} \left[\frac{1}{r} + \frac{x^2}{r^3} \right] - 3N \left[\frac{1}{r^3} - \frac{3x^2}{r^5} \right]$$

$$-u = -\frac{M}{2\mu} [\dots] - N [\dots] - c$$

$$\left. \begin{aligned} \mu \left[\dots \right] &= -\frac{M}{2\mu} \left[\frac{1}{r} + \frac{x^2}{r^3} \right] - 4N \left[\frac{1}{r^3} - \frac{3x^2}{r^5} \right] - c\mu \\ \mu \frac{\partial}{\partial x} (u_x + v_y + w_z) &= \frac{M}{2\mu} \left[\frac{1}{r} - \frac{x^2}{r^3} \right] - 2N \left[\frac{1}{r^3} - \frac{3x^2}{r^5} \right] + c\mu \end{aligned} \right\}$$

$$-p_x = -p_0x - M \frac{x^2}{r^3}$$

$$r p_{rx} = -p_0x - 3M \frac{x^2}{r^3} - 6N \left[\frac{1}{r^3} - \frac{3x^2}{r^5} \right]$$

$$p_{rx} = -p_0 \frac{x}{a} - \frac{6N_\mu}{a^2} - 3 \frac{x^2}{a^2} \left[M - \frac{6N_\mu}{a^2} \right]$$

$$= -p_0 \frac{x}{a} + \frac{3\mu}{2a} \left[3 \frac{A}{\mu} \frac{y_0 - y_i}{4n} + c \right] - \frac{3x^2}{a^2} \left[-\frac{3}{2} \frac{A}{\mu} \frac{y_0 - y_i}{4n} + \frac{3}{2} \frac{3A}{\mu} \frac{y_0 - y_i}{4n} \right]$$

$$p_{rx} = -p_0 \frac{x}{a} + \frac{3}{2} \left[3 \frac{A}{a} \frac{y_0 - y_i}{4n} + c \mu \right] - \frac{3x^2}{a^2} 2A \frac{y_0 - y_i}{4n}$$

$$P = \iint p_{rx} dA = 2\pi$$

$$= -p_0 \cos \theta + \frac{3}{2a} \left[3A \frac{y_0 - y_i}{4n} + c\mu \right] - 6 \cos^2 \theta \frac{A}{a} \frac{y_0 - y_i}{4n}$$

$$P_x = 2\pi a^2 \int_0^\pi \sin \theta d\theta \cdot p_{rx}$$

$$= 2\pi a^2 \left\{ \frac{3}{2a} \left[3A \frac{y_0 - y_i}{4n} + c\mu \right] - 6 \frac{A}{a} \frac{y_0 - y_i}{4n} \frac{2}{3} \right\}$$

$$P_x = 2\pi a^2 \left[5A \frac{y_0 - y_i}{4n} + 3c\mu \right]$$

jeżeli to ma być = 0 to wynika: $c = - \frac{5A}{3\mu} \frac{y_0 - y_i}{4n}$

zatem 1). pytkoni niedługo od a

2). prop. A

3). odrz. prop. μ zatem zależy prop. od temp.

$$c = b A$$

$$i = A \lambda$$

$$J = A \lambda q$$

$$= b \frac{E}{l}$$

$$Q = i q t = \frac{E}{e} \lambda q t$$

$$d = ct = b \frac{E}{e} t = b \frac{Q}{\lambda q} = \frac{b}{\lambda q} \cdot Q$$

výše dráha zohrávaná prúdom vzhľadom na silu elektr. [uni at E, uni at d]
[ale at q]

$$c = b \frac{J}{\lambda q} = \frac{b}{\lambda q} \cdot J$$

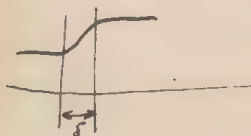
tož samo

prírodn. Winkler, 1903
Günther, P. Nr. 113 (1869)

Elektr. Doppelschicht

$$\int_0^{\delta} \nabla^2 V dx = V_2 - V_1 = \int_0^{\delta} 4\pi \epsilon dx$$

$$\int_0^{\delta} \epsilon dx = 6\delta$$



Možno nájsť vyjadrenie $6 = \frac{1}{4\pi} \frac{V_2 - V_1}{\delta}$

na dvoch zhranoch oddelených prúdom δ

~~Je to teda vyjadrenie prúdu vzhľadom na silu elektr. a na dráhu~~



$$W = \frac{1}{2} \oint \varphi dx = \frac{1}{2} \oint \left(\frac{\partial V}{\partial x} \right)^2$$

pro cm² porušenia:

$$W = \frac{1}{2} \frac{1}{4\pi} \frac{(V_2 - V_1)^2}{\delta}$$

Je to tiež sila, ktorou môže pôsobiť.

a dla vody

= 80 c.s.s.

dla vody / náhle tvorí mrazu

$$V_2 - V_1 = N_1 \cdot \frac{4}{300} = \frac{4}{300}$$

$$\delta = \frac{1}{8\pi} \frac{1}{80} \left(\frac{4}{300} \right)^2$$

$$= \frac{1}{31} \left(\frac{1}{600} \right)^2 = \frac{1}{31 \cdot 36} 10^{-6} = 10^{-7} \text{ cm}$$

To ni mniej by żądało identyfikacji

do n.p. dodanie $\frac{1}{10}$ do Noll zmniejsza φ o $0.1 V$ do $2.7 V$ podwyższa
a wtedy wzrasta. Doświadczenia!

W każdym razie należy przyjąć, że φ jest takie samo, jeżeli nie, to należy zmniejszyć, to jest więcej, jeżeli nie, to

Przy kondens. lub strumieniu emulacji porównania zmniejsza się granicę
tegoż wyznaczenia.
zatem energia elektryczna.

ilosci S6 z jednej i z drugiej strony się wypracowuje

(niezależność od z) przed przekształceniem
do miz

To staramy się zwrócić do każdej powierzchni:

Wtedy dla x, y w powierzchni z normalną

$$\frac{1}{4\pi} \nabla^2 u \cdot \frac{\partial u}{\partial x} = -\mu \nabla^2 u + \frac{\partial f}{\partial x}$$

$$\frac{1}{4\pi} \nabla^2 u \cdot \frac{\partial u}{\partial y} = -\mu \nabla^2 u + \frac{\partial f}{\partial y}$$

$$\nabla^2 u = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2}$$

to samo

$$\frac{\partial u}{\partial x} \text{ i } \frac{\partial u}{\partial y} \text{ może zmienne w dyfuzji}$$

$$\text{zatem } \int_0^{\delta} \nabla^2 u \cdot \frac{\partial u}{\partial x} \cdot z dz = \left| \frac{\partial u}{\partial x} \right| \int_0^{\delta} \nabla^2 u \cdot z dz$$

! jednakże w ostatniej!

~~###~~

$$\frac{1}{4\pi} \nabla^2 u \cdot \frac{\partial u}{\partial z} = -\mu \nabla^2 u + \frac{\partial f}{\partial z}$$

Pierwszą równość do por. bo $u_0 = 0$ $v_0 = 0$ $w_0 = 0$

$$u = z \left(\frac{\partial u}{\partial x} \right)_0 + \frac{z^2}{2} \left(\frac{\partial^2 u}{\partial x^2} \right)_0$$

$$v = z \left(\frac{\partial v}{\partial z} \right)_0 + \frac{z^2}{2} \left(\frac{\partial^2 v}{\partial z^2} \right)_0$$

$$w = z \left(\frac{\partial w}{\partial z} \right)_0 + \frac{z^2}{2} \left(\frac{\partial^2 w}{\partial z^2} \right)_0$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

$$z \left(\frac{\partial^2 u}{\partial x^2} \right)_0 + \frac{z^2}{2} \left(\frac{\partial^3 u}{\partial x^2 \partial x} \right)_0 + z \left(\frac{\partial^2 v}{\partial z^2} \right)_0 + \frac{z^2}{2} \left(\frac{\partial^3 v}{\partial y \partial z^2} \right)_0 + \frac{\partial u}{\partial z} + z \left(\frac{\partial^2 u}{\partial z^2} \right)_0 = 0$$

z tego wynika, że z dostateczną dokładnością $\left(\frac{\partial v}{\partial z} \right)_0 = 0$

Próbujemy to:

$$\frac{\partial}{\partial x} \left(\frac{\partial u}{\partial z} \right)_0 + \frac{\partial}{\partial y} \left(\frac{\partial v}{\partial z} \right)_0 + \left(\frac{\partial^2 w}{\partial z^2} \right)_0 = 0$$

$$\frac{\partial}{\partial x} \left(\frac{\partial^2 u}{\partial z^2} \right)_0 + \frac{\partial}{\partial y} \left(\frac{\partial^2 v}{\partial z^2} \right)_0 + \left(\frac{\partial^3 w}{\partial z^3} \right)_0 = 0$$

$$\nabla^2 u = 2 \left[\frac{\partial^2}{\partial x^2} \left(\frac{\partial u}{\partial z} \right) + \frac{\partial^2}{\partial y^2} \left(\frac{\partial u}{\partial z} \right) \right] + \frac{z^2}{2} \left[\frac{\partial^2}{\partial x^2} \left(\frac{\partial^2 u}{\partial z^2} \right) + \frac{\partial^2}{\partial y^2} \left(\frac{\partial^2 u}{\partial z^2} \right) \right] + \left(\frac{\partial^2 u}{\partial z^2} \right)$$

więc dla dostatecznej metody 2:

$$\nabla^2 u = \left(\frac{\partial^2 u}{\partial z^2} \right)$$

W ten
miedobedroci!

$$\frac{1}{4\pi} \frac{\partial u}{\partial x} \int_0^{\delta} \frac{\partial u}{\partial z^2} z dz = -\mu \int_0^{\delta} \left(\frac{\partial^2 u}{\partial z^2} \right) z dz + \frac{\partial u}{\partial x} \int_0^{\delta} z dz$$

$\frac{\partial u}{\partial z} z = \int \frac{\partial u}{\partial z} dz$

Sobowaztem gdzie $\frac{\partial u}{\partial z} = 0$

$$\frac{1}{4\pi} \frac{\partial u}{\partial x} (u_i - u_a) = \mu \frac{(u_i - u_a)}{z} = \mu u_a$$

dla dost. metody 2:

$$\int z \frac{\partial^2 u}{\partial z^2} dz = z \frac{\partial u}{\partial z} - u$$

$$\frac{1}{4\pi} \frac{\partial u}{\partial y} (u_i - u_a) = \mu \frac{(u_i - u_a)}{z} = \mu u_a + \left(\frac{\partial^2 u}{\partial z^2} \right)$$

$$\int \nabla^2 u z dz = \frac{z^2}{2} \left(\frac{\partial^2 u}{\partial z^2} \right) + \frac{z^3}{3} \left[\left(\frac{\partial^2}{\partial x^2} \right) + \left(\frac{\partial^2}{\partial y^2} \right) \left(\frac{\partial u}{\partial z} \right) \right] + \frac{z^4}{2 \cdot 4} \left[\left(\frac{\partial^2}{\partial x^2} \right) + \left(\frac{\partial^2}{\partial y^2} \right) \left(\frac{\partial^2 u}{\partial z^2} \right) \right]$$

Rozłóżmy zadanie w

$$u = u_0 + u_1$$

$$\left\{ \begin{array}{l} -\frac{\partial k}{\partial x} = \mu \nabla^2 u_0 \\ -\frac{\partial k}{\partial y} = \mu \nabla^2 v_0 \\ -\frac{\partial k}{\partial z} = \mu \nabla^2 w_0 \end{array} \right\} \left\{ \begin{array}{l} \frac{\partial u_0}{\partial x} + \frac{\partial v_0}{\partial y} + \frac{\partial w_0}{\partial z} = 0 \\ \frac{\partial u_1}{\partial x} + \frac{\partial v_1}{\partial y} + \frac{\partial w_1}{\partial z} = 0 \end{array} \right.$$

~~Stwierdzenie~~ $u_1 = v_1 = w_1 = 0$ na powierzchni kuli $|x| = a$

$$\frac{\partial k}{\partial x} (\text{dla } x=0) = A \quad \frac{\partial k}{\partial y} = \frac{\partial k}{\partial z} = 0$$

$$u = A \times \left[1 + \frac{a^3}{2r^3} \right] \quad \text{tylko } f(r+az)$$

~~Stwierdzenie~~

Wiemy tylko tyle że $\int \rho \, dp = \varphi_a - \varphi_i$

$$\int \frac{\partial v}{\partial r} \rho \, dp = \frac{\partial v}{\partial \rho} \cdot \rho \Big|_0^{\delta} - \underbrace{\int_0^{\delta} \frac{\partial v}{\partial \rho} \, dp}_{v_a/\delta} = \frac{\partial v}{\partial \rho} \Big|_{\delta} \cdot \delta - v_a/\delta$$

$$\frac{\varphi_i - \varphi_a}{4\pi} \cdot \frac{4\pi}{\delta} = \mu \nabla^2 u_1$$

Przeanalizujmy elektryczność

$$\nabla^2 u_1 = 0 \quad \nabla^2 v_1 = 0 \quad \nabla^2 w_1 = 0$$

$$\nabla^2 v = 0$$

$$\frac{\partial u_1}{\partial x} + \frac{\partial v_1}{\partial y} + \frac{\partial w_1}{\partial z} = 0$$

$$\text{div } v = 0$$

$$v = \text{curl } A$$

$$\text{curl curl } v = \nabla \text{div } v - \nabla^2 v = 0$$

$$\text{curl } v = \nabla A = \nabla \text{div } v - \nabla^2 v$$

$$\text{differential } v = \nabla^2 A = 0$$

dla nieskończoności i tak $\varphi_a = 0 \Rightarrow \nabla A = 0$

Erster Beweis:

$$\frac{\partial u}{\partial x} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = X - \frac{1}{\rho} \frac{\partial p}{\partial x} - \frac{\mu}{\rho} \nabla^2 u$$

Wird von dem Komprimierten
Hypothesen. dass u, v, w
ist

$$u, v, w, p,$$

$$u \frac{\partial u}{\partial x} + \dots - u, \frac{\partial u}{\partial x} \dots = (1)$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = u, \frac{\partial u}{\partial x} + v, \frac{\partial u}{\partial y} + w, \frac{\partial u}{\partial z}$$

$$u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} = u, \frac{\partial v}{\partial x} + v, \frac{\partial v}{\partial y} + w, \frac{\partial v}{\partial z}$$

$$u \frac{\partial w}{\partial x} + \dots =$$

$$\frac{\partial(u-u)}{\partial x} + \dots = 0$$

$$\frac{\partial u}{\partial x} = - \frac{\partial v}{\partial y} - \frac{\partial w}{\partial z}$$

$$u \left(v \frac{\partial u}{\partial y} - u \frac{\partial v}{\partial y} \right) + \left(w \frac{\partial u}{\partial z} - u \frac{\partial w}{\partial z} \right) = \dots$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = \frac{\partial}{\partial x} \left(\frac{u^2}{2} \right) + \frac{\partial(uv)}{\partial y} + \frac{\partial(uw)}{\partial z} - \underbrace{u \frac{\partial v}{\partial y} - u \frac{\partial w}{\partial z}}_{= u \frac{\partial u}{\partial x} = \frac{1}{2} \frac{\partial u^2}{\partial x}}$$

$$= \frac{\partial}{\partial x} (u^2) + \frac{\partial}{\partial y} (uv) + \frac{\partial}{\partial z} (uw)$$

Rozmianio 2 zmiennymi, inextensible terms

Podstawiamy; n.p. nach kotory $u = -\omega \frac{x}{2}$ $v = \omega \frac{y}{2}$

$$= -y \varphi \quad = x \varphi$$

$$\frac{\partial u}{\partial x} = \frac{y}{2} \frac{d\varphi}{dr}$$

$$\frac{\partial u}{\partial y} = \varphi + \frac{y}{2} \frac{d\varphi}{dr}$$

$$\frac{\partial^2 u}{\partial x^2} = y \left(\frac{1}{2} \frac{d^2 \varphi}{dr^2} - \frac{x^2}{r^3} \frac{d\varphi}{dr} + \frac{x^2}{r^2} \frac{d^2 \varphi}{dr^2} \right)$$

$$\frac{\partial^2 u}{\partial y^2} = x \left(\frac{1}{2} \frac{d^2 \varphi}{dr^2} - \frac{y^2}{r^3} \frac{d\varphi}{dr} + \frac{y^2}{r^2} \frac{d^2 \varphi}{dr^2} \right)$$

$$\frac{\partial^2 u}{\partial y^2} = 3 \frac{d^2 \varphi}{dr^2} \frac{y}{2} - \frac{y^3}{r^3} \frac{d\varphi}{dr} + \frac{y^3}{r^2} \frac{d^2 \varphi}{dr^2}$$

$$\Delta^2 u = 3 \frac{y}{2} \frac{d^2 \varphi}{dr^2} + y \frac{d^2 \varphi}{dr^2}$$

$$\mu = f(r) \quad \frac{\partial \mu}{\partial r} = \frac{x}{r} \frac{d\mu}{dr}$$

$$\frac{\partial \mu}{\partial x} = \mu \nabla^2 u$$

$$\frac{x}{r} \frac{d\mu}{dr} = -y \left[\frac{3}{2} \frac{d^2 \varphi}{dr^2} + \frac{d^2 \varphi}{dr^2} \right] x$$

$$\frac{y}{r} \frac{d\mu}{dr} = x \left[\frac{3}{2} \frac{d^2 \varphi}{dr^2} + \frac{d^2 \varphi}{dr^2} \right] y$$

$$2 \frac{d\mu}{dr} = 0$$

$$\mu = \text{const}$$

$$r^3 \frac{d\varphi}{dr} = \text{const}$$

$$\varphi = \frac{1}{r^2} + \dots$$

$$\frac{d\varphi}{dr} = -\frac{2}{r^3} + \dots$$

Integracja podana mieliby

Strung itoj dva konca drzani su krom o vinyu stene:

$$\frac{\partial^2 \xi}{\partial x^2} = -\omega^2 \frac{\partial^2 \xi}{\partial t^2}$$

$$\xi = \sum \left[A_k \sin \frac{kx}{l} \sin \left(\frac{k\omega t}{l} + \delta_k \right) + B_k \cos \frac{kx}{l} \sin \left(\frac{k\omega t}{l} + \delta_k \right) \right]$$

$$x=0 \quad \xi = \sum_{k=1}^{\infty} B_k \sin \frac{k\omega t + \delta_k}{l} = M \sin \omega t$$

$$x=l \quad \xi = \sum B_k \cos \frac{k\omega t + \delta_k}{l} = N \sin \omega t$$

Posledica

$$B_1 \sin \left(\frac{\omega t}{l} + \delta_1 \right) + B_2 \sin \left(\frac{2\omega t}{l} + \delta_2 \right) + B_3 \sin \left(\frac{3\omega t}{l} + \delta_3 \right) + \dots = M \sin \omega t$$

Posledica

$$-B_1 \sin \left(\frac{\omega t}{l} + \delta_1 \right) + B_2 \sin \left(\frac{2\omega t}{l} + \delta_2 \right) - B_3 \sin \left(\frac{3\omega t}{l} + \delta_3 \right) + \dots = N \sin \omega t$$

$$B_2 \sin \left(\frac{2\omega t}{l} + \delta_2 \right) + B_4 \sin \left(\frac{4\omega t}{l} + \delta_4 \right) + \dots = \frac{1}{2} [M \sin \omega t + N \sin \omega t]$$

$$B_1 \sin \left(\frac{\omega t}{l} + \delta_1 \right) + B_3 \sin \left(\frac{3\omega t}{l} + \delta_3 \right) + \dots = \frac{1}{2} [M \sin \omega t - N \sin \omega t]$$

$$B_k = \frac{2}{l} \int_0^l [M \sin \omega t + N \sin \omega t] \sin \frac{kx}{l} dx \quad \int_0^{\frac{2\pi}{\omega}} \sin \omega t \cdot \sin \omega t dt$$

$$\begin{aligned} \int_0^{\frac{2\pi}{\omega}} \sin \omega t \sin \omega t dt &= \int_0^{\frac{2\pi}{\omega}} [\cos(\omega t - \omega t) - \cos(\omega t + \omega t)] dt \\ &= \frac{\sin(\omega t - \omega t)}{\omega - \omega} \Big|_0^{\frac{2\pi}{\omega}} - \frac{\sin(\omega t + \omega t)}{\omega + \omega} \Big|_0^{\frac{2\pi}{\omega}} \end{aligned}$$

$$B_1 \cos \delta_1 \sin \frac{\pi x t}{l} + B_3 \cos \delta_3 \sin \frac{3\pi x t}{l} + \dots$$

$$\left. \vphantom{\int_0^{2l/a}} \right\} = \frac{1}{2} [M \sin t - N \cos t] = F_2$$

$$+ B_1 \sin \delta_1 \cos \frac{\pi x t}{l} + B_3 \sin \delta_3 \cos \frac{3\pi x t}{l} + \dots$$

$$-2 \int_0^{2l/a} \sin \frac{m\pi x t}{l} \sin \frac{n\pi x t}{l} dt = \int_0^{2l/a} \left[\cos \frac{(m+n)\pi x t}{l} - \cos \frac{(m-n)\pi x t}{l} \right] dt =$$

$$= \frac{\sin \frac{(m+n)\pi x t}{l}}{\frac{(m+n)\pi}{l}} \bigg|_0^{2l/a} - \frac{\sin \frac{(m-n)\pi x t}{l}}{\frac{(m-n)\pi}{l}} \bigg|_0^{2l/a} = 0$$

$$2 \int_0^{2l/a} \sin^2 \frac{m\pi x t}{l} dt = \int_0^{2l/a} \left[1 - \cos \frac{2m\pi x t}{l} \right] dt = \frac{2l}{a}$$

$$2 \int_0^{2l/a} \cos \frac{m\pi x t}{l} \sin \frac{n\pi x t}{l} dt = \int_0^{2l/a} \left[\sin \frac{(m+n)\pi x t}{l} - \sin \frac{(m-n)\pi x t}{l} \right] dt =$$

$$= \frac{\cos \frac{(m+n)\pi x t}{l}}{\frac{(m+n)\pi}{l}} \bigg|_0^{2l/a} - \frac{\cos \frac{(m-n)\pi x t}{l}}{\frac{(m-n)\pi}{l}} \bigg|_0^{2l/a} = 0$$

$$B_k \cos \delta_k = \frac{a}{l} \int_0^{2l/a} F_2 \sin \frac{k\pi x t}{l} dt \quad \parallel \quad B_k \sin \delta_k = \frac{a}{l} \int_0^{2l/a} F_2 \cos \frac{k\pi x t}{l} dt$$

$$-2 \int_0^{2l/a} \sin \alpha t \sin \frac{k\pi x t}{l} dt = \frac{\sin \left(\alpha + \frac{k\pi x}{l} \right) t}{\alpha + \frac{k\pi x}{l}} \bigg|_0^{2l/a} - \frac{\sin \left(\alpha - \frac{k\pi x}{l} \right) t}{\alpha - \frac{k\pi x}{l}} \bigg|_0^{2l/a}$$

$$= \frac{\sin \frac{2\alpha l}{a}}{\alpha + \frac{k\pi x}{l}} - \frac{\sin \frac{2\alpha l}{a}}{\alpha - \frac{k\pi x}{l}} = \sin \frac{2\alpha l}{a} \cdot \frac{-2 \frac{k\pi x}{l}}{\alpha^2 - \left(\frac{k\pi x}{l} \right)^2}$$

Jaka będzie praca wykonana w punkcie 0?

$$X = E \frac{\partial \xi}{\partial x}$$

$$\int \frac{\partial \xi}{\partial x} d\xi = \int \left(\frac{\partial \xi}{\partial x} \right) \left(\frac{\partial \xi}{\partial t} \right) dt$$

$$\left(\frac{\partial \xi}{\partial t} \right) = \sum A_k \frac{k a}{l} \sin\left(\frac{k n a t}{l} + \delta_k\right)$$

$$\left(\frac{\partial \xi}{\partial t} \right)_{x=0} = \sum \cancel{A_k \sin\left(\frac{k n a t}{l} + \delta_k\right)}$$

$$= \sum \left[A_k \sin \frac{k n x}{l} + B_k \cos \frac{k n x}{l} \right] \frac{k n a}{l} \cos \delta_k$$

$$= \sum B_k \frac{k n a}{l} \cos\left(\frac{k n a t}{l} + \delta_k\right)$$

$$\frac{\partial p}{\partial x} = \mu \nabla^2 u$$

$$\frac{\partial p}{\partial y} = \mu \nabla^2 v$$

$$\frac{\partial p}{\partial z} = \mu \nabla^2 w$$

$$\frac{\partial p}{\partial x} = \mu \nabla^2 u$$

$$\vdots$$

$$\vdots$$

$$\frac{\partial (p-p_1)}{\partial x} = \mu \nabla^2 (u-u_1)$$

$$\frac{\partial (p-p_1)}{\partial y} = \mu \nabla^2 (v-v_1)$$

$$\frac{\partial (p-p_1)}{\partial z} = \mu \nabla^2 (w-u_1)$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

$$\nabla p = 0$$

$$\nabla (p-p_1) = 0$$

$$\nabla p = \mu \nabla^2 \vec{v} = -\mu \text{curl}^2 \vec{v}$$

$$\text{div} \vec{v} = 0$$

$$\vec{v} = \nabla A + \text{curl} \vec{U}$$

$$\text{curl}^2 = \nabla \text{div} - \nabla^2$$

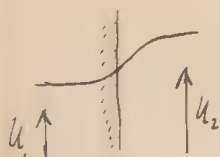
~~$$\text{curl} \nabla p = 0 = \mu \text{curl} \nabla^2 \vec{v} = \mu \nabla \text{curl}^2 \vec{v} = \mu \nabla \text{curl}^2 \vec{v} = 0$$~~

~~$$\nabla \cdot \frac{\nabla^2 \vec{v}}{r} = \nabla \cdot \left(\frac{\text{div} \vec{v}}{r} + \text{curl} \left(\frac{\text{curl} \vec{v}}{r} \right) \right)$$~~

$$\vec{v} = \nabla A + \text{curl} \int \frac{\text{curl} \vec{v}}{r} dv$$

$$\nabla p = \text{curl}^3 \vec{U}$$

Ne wartować elektryczności.



Cr'innu merlon

$$p_{xx} = - \int \epsilon \frac{\partial u}{\partial x} dx$$

$$= \frac{1}{4\pi} \int \frac{\partial^2 u}{\partial x^2} \frac{\partial u}{\partial x} dx =$$

$$= \frac{1}{8\pi} \left(\frac{\partial u}{\partial x} \right)^2 \Big|_0^\infty = - \frac{1}{8\pi} \left(\frac{\partial u}{\partial x} \right)^2$$

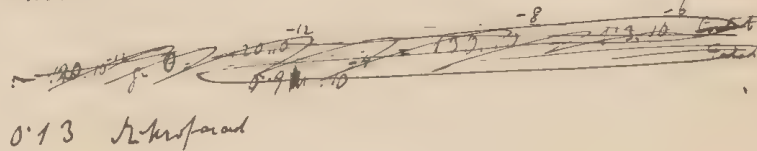
Zastępnym przy wariancie porob.

$$\frac{\partial u}{\partial x} = \frac{u_2 - u_1}{s} = -4\pi b$$

$$p_{xx} = 2\pi b^2$$

Trzy polaryzacji wiatry kółkramu.

przejmował po 1mm²



$$\text{po } 1\text{cm}^2 : 13 \text{ mikrofarad} = 13 \cdot 10^{-6} \frac{\text{Coulomb}}{\text{Volt}}$$

$$\frac{1\text{ Volt}}{1\text{ cm}^2} \quad b = 13 \cdot 10^{-6} \text{ Coul.} = 13 \cdot 10^{-6} \cdot 3 \cdot 10^9 \text{ (coul)} = 39 \cdot 10^3 = 4 \cdot 10^2$$

$$p_{xx} = 2\pi (4 \cdot 10^2)^2 = 2 \cdot 32 \cdot 16 \cdot 10^4 = 10^6 \text{ dy} \\ = 1 \text{ mikrofarad.}$$

Die volle ~~spit~~ spitzen; was ist die Form der X
 ist gegeben?

$$\mu \frac{du}{dr} = \text{const}$$

$$\frac{du}{dr} = \frac{C}{r}$$

$$u - u_1 = C \log \frac{r}{r_1}$$

$$u_2 = 0$$

$$\frac{u - u_1}{u_1 - u_2} = \frac{\log \frac{r}{r_1}}{\log \frac{r_2}{r_1}}$$

$$\mu \frac{\partial u}{\partial x} =$$

$$\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x}$$

Ne notwendig partiell + V paribus bzgl:

$$X_1 = Y_1 = Z_1 = 0$$

$$\text{zaten: } \mu - 2\mu \left(\frac{\partial v}{\partial y} \right) = 0$$

$$v \text{ must be } 0 \text{ at } r = r_1 \text{ so } \frac{\partial v}{\partial r} = 0, \mu = 0$$

$$\left(\frac{\partial u}{\partial y} \right) + \left(\frac{\partial v}{\partial x} \right) = 0$$

$$\left(\frac{\partial u}{\partial y} \right) = 0$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

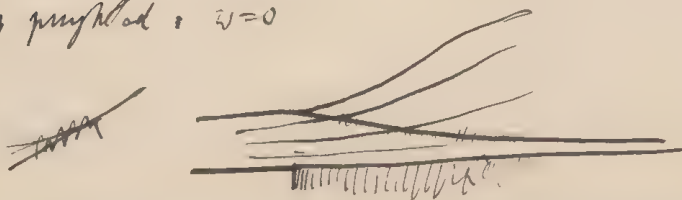
$$u_1 - u_2 =$$

$$\left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) = 0$$

$$\left(\frac{\partial u}{\partial y} \right) = 0$$

$$u = \text{const}$$

Incompressible fluid: $w = 0$



Przykład 10 - teoria: wyznaczmy tyłko energię kinetyczną i potencjał

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = -\frac{\partial \phi}{\partial x} - \gamma \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$$

$$u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} = -\frac{\partial \phi}{\partial y} - \gamma \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) \quad \left. \begin{array}{l} \text{zauważmy, że tyłko } \phi = \phi(x, y) \\ \text{nie ma!} \end{array} \right\}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

wzrostek na powierzchni: $\phi = 0$ w $y = 0$ ogólnie ogólnie $\phi = 0$

$$\frac{\partial u}{\partial x} = 0$$

Upiszmy przybliżenie: $u = a$

v w ogólnie ma być zero v zauważmy

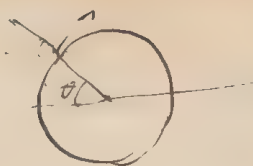
$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = v \frac{\partial u}{\partial y} - u \frac{\partial v}{\partial y} = u^2 \frac{\partial}{\partial y} \left(\frac{v}{u} \right)$$

$$u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} = u \frac{\partial v}{\partial x} - v \frac{\partial u}{\partial x} = u^2 \frac{\partial}{\partial x} \left(\frac{v}{u} \right) = -u^2 \frac{\partial}{\partial x} \left(\frac{u}{v} \right)$$

$$\Delta^2 \phi =$$

Recht links sowie 2. logarithmieren

$$u = c \cdot \frac{M}{2\pi} \left(\frac{1}{2} + \frac{3x^2}{2} \right) - N \left(\frac{3}{2} - \frac{15x^2}{2} \right)$$



$$p_{\theta z} = \lambda \cdot v_{\theta}$$

$$p_{rx} = \lambda \cdot \underbrace{u \cos \theta + v \sin \theta}_{\text{cos } \theta} = \underbrace{u \cos \theta}_{\text{cos } \theta} + \underbrace{v \sin \theta}_{\text{sin } \theta}$$

$$p_{\theta z} = p_{rx} \sin \theta = p_{rx} \cos \theta + p_{ry}$$

Ich so: wieviel ist potentiell vermindert elektr.?

$$\psi = -\frac{c}{2} \left(1 - \frac{3}{2} \frac{a}{2} + \frac{1}{2} \frac{a^3}{2} \right) \omega^2$$

oder: $\psi = 0$

$$r = a + \delta \quad \omega = \Omega + \delta$$

$$\psi = -\frac{c\Omega^2}{2} \left[1 - \frac{3}{2} \left(1 - \frac{\delta}{a} \right) + \frac{1}{2} \left(1 - \frac{3\delta}{a} \right) \right] (1 + 2\frac{\delta}{a})$$

= 0

$$= -\frac{c\Omega^2}{2} \left[1 - \frac{3}{2} \left(1 + \frac{\delta}{a} \right)^{-1} + \frac{1}{2} \left(1 + \frac{\delta}{a} \right)^{-3} \right] (1 + \frac{\delta}{a})^2$$

$$= -\frac{c\Omega^2}{2} \left[\left(1 + \frac{\delta}{a} \right)^2 - \frac{3}{2} \left(1 + \frac{\delta}{a} \right) + \frac{1}{2} \left(1 + \frac{\delta}{a} \right)^{-1} \right]$$

$$= -\frac{c\Omega^2}{2} \left[1 + 2\frac{\delta}{a} + \frac{\delta^2}{a^2} - \frac{3}{2} - \frac{3}{2} \frac{\delta}{a} + \frac{1}{2} \left(1 - \frac{\delta}{a} - \frac{\delta^2}{a^2} \right) \right]$$

$$\psi = -\frac{c\Omega^2}{2} \frac{\delta^2}{2a^2} = -\frac{c\delta^2}{4}$$

W. willkür. orthogon. $r \rightarrow \infty$: $\psi = -\frac{c}{2} \omega^2 = -\frac{c\delta^2}{4}$

rotiert: $\omega = \frac{\delta}{\sqrt{2}}$

potencjał porażczego prądu nat.
 Dotychczasowe obliczenia polegały na założeniu że równanie $\nabla^2 u = -\gamma \rho \varepsilon$
 ma nie tylko w samej warstwie, a także i w jej otoczeniu z jej obydwo stron
 otęgnięciem $\varepsilon = 0$

Jeżeli jednak prąd płynie w ε obszarze, to musimy to być rozstrzygnąć równaniem:

$$-\frac{\partial \varepsilon}{\partial t} = \frac{\partial i_x}{\partial x} + \frac{\partial i_y}{\partial y} + \frac{\partial i_z}{\partial z} = -\lambda \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right)$$

↓

$$= 4\pi \lambda \varepsilon$$

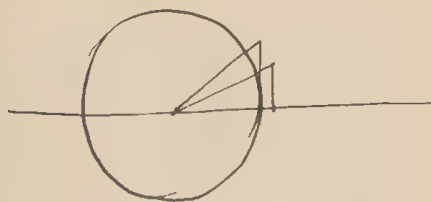
$$\frac{\partial \varepsilon}{\partial t} + u \frac{\partial \varepsilon}{\partial x} + v \frac{\partial \varepsilon}{\partial y} + w \frac{\partial \varepsilon}{\partial z}$$

Jeżeli się przyjmiemy x w kierunku linii prądu s:

$$-u \frac{\partial \varepsilon}{\partial s} = 4\pi \lambda \varepsilon$$

$$\frac{1}{\varepsilon} \frac{\partial \varepsilon}{\partial s} = -\frac{4\pi \lambda}{u}$$

$$\lg \varepsilon = -4\pi \lambda \int \frac{ds}{u}$$



$$u = r$$

$$-c \frac{\partial^2 \varepsilon}{\partial s^2} = -\frac{c(\partial_0 \varepsilon \sin \theta)^2}{4}$$

$$\partial_0 = \frac{\partial_0}{\sin \theta}$$

opracujemy wartość ∂ w punkcie $\theta_1 = \theta$

$$\partial_0 = \partial_1 \sin \theta_1 = \rho \sin \theta$$

zatem w każdej warstwie

$$\varepsilon = \text{const}$$

$$\int_0^{\theta} \frac{a d\theta}{\frac{3}{2} \frac{c}{a} \sin \theta_1 \partial_1} = \frac{2}{3} \frac{a^2}{c \partial_1} \frac{\theta_1 - \theta}{\sin \theta_1}$$

$$\varepsilon = \varepsilon_0 \quad -4\pi\lambda \frac{2}{3} \frac{a^2}{c\delta} \frac{\theta_1 - \theta}{\sin\theta_1}$$

$$-4\pi\lambda \frac{2}{3} \frac{a^2}{c\delta} \frac{\theta_1 - \theta}{\sin\theta_1} = \lg \frac{\varepsilon}{\varepsilon_0}$$

$$\text{Nip. } \frac{\varepsilon}{\varepsilon_0} = \frac{1}{2}$$

$$\theta_1 = \frac{\pi}{2}$$

$$a = 10^{-5}$$

$$\delta = 10^{-6}$$

$$\lambda = \frac{1}{3} \cdot 10^8$$

Wstawiamy do a

$$\frac{2}{3} \cdot 4\pi \cdot \frac{1}{5} \cdot 10^8 \cdot \frac{10^{-5}}{10^{-6} \cdot c} \left(\frac{\pi}{2} - \theta \right) = \approx 0.3 \cdot 2.3$$

zrobić w stole

$$\lg \frac{\varepsilon}{\varepsilon_0} = -4\pi\lambda \frac{a}{u}$$

u jest to minimum energii

$$\text{Nip. } a = 10^{-6}$$

$$0.3 \cdot 2.3 = -4\pi\lambda \frac{1}{5} \cdot 10^8 \cdot \frac{10^{-6}}{u}$$

$$u = \text{cca } 200 \frac{\text{cm}}{\text{ns}}!$$

zatem to są już w rzeczywistości
małe wartości!

Najbardziej istotną kwestią (wg mnie) to drobne ilości energii, które muszą być wyrażone

ale i tym samym izolowane wartości energii deformacyjnej i energii elektrycznej

Jaki ruch cieczy koło białej powierzchni pływającej przez wodę?



Zależy się to będzie podobnie jak
ruch kuli w cieczy i dedukuj!

do toru na powierzchni można zanurzyć

Czy nie można by stworzyć kulki z białki n.p. koloidalnej, napęcznieć H_2
oily równy ciśnień jak powietrze i pociąć do wody, porównując z powietrzem?

z tego będzie się ruchem pływającym

Podobnie dla cieczy
leżącej od wody!

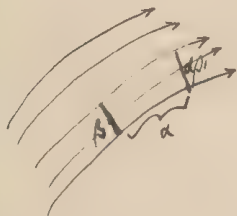
Białki H_2 będą porównywalne pływające (z powodu innego toru) niż O_2 .

Analogia do „Spherical Vortex” Lamb. p. 265

Nauzumi i który przed ciecżą z H_2 toru

W bliskości powierzchni prędkości mogą być odstępn; kierunek: dystans krzywej

$$v = \left(\frac{\partial v}{\partial n} \right)_0 N$$



to będzie zatem taki kierunek linii prądu elektrycznego.

$$\text{przy } \frac{i}{\partial \beta} = \int \left(\frac{\partial v}{\partial n} \right)_0 N \, dN = \left(\frac{\partial v}{\partial n} \right)_0 \frac{(\varphi_0 - \varphi_1)}{4\pi}$$

Najbardziej wyraźnie będzie $(\text{div}) i = \lambda \frac{\partial u}{\partial n}$

$$\lambda \frac{\partial u}{\partial n} = \frac{\partial i_x}{\partial x} + \frac{\partial i_y}{\partial y}$$

$$i \, d\beta - i' \, d\beta' = i \, d\beta - d\beta' + (i - i') \, d\beta$$

$$= \left[i \frac{\partial \beta}{\partial x} + \beta \frac{\partial i}{\partial x} \right] dx = \lambda \frac{\partial u}{\partial n} \, d\beta \, d\beta'$$

~~$$\int \frac{\partial u}{\partial x} dy dz$$~~

Prody se konstanty jsou rovny nule pro všechny
fukce, tedy tohle by se rovnalo

~~$$\frac{\partial u}{\partial x} = \left(\frac{\partial u}{\partial x_0} \right) \frac{\varphi_2 - \varphi_1}{\varphi_2} = \delta' \frac{\partial u}{\partial x}$$~~

~~$$\frac{\partial u}{\partial x} = \mu \frac{\partial u}{\partial x}$$~~

~~$$\int dxdy$$~~
~~$$= \int \int \int$$~~

$$\iint \left(\frac{\partial u}{\partial N_0} \right) dF = \iiint \nabla^2 u \, dxdydz = \frac{1}{\mu} \iiint \frac{\partial^2 u}{\partial x^2} \, dxdydz = \frac{1}{\mu} \int \int f \, dydz$$

$$= \frac{1}{\mu} \int \int f \cos \alpha \, dF$$

$$\int \left[\cos \alpha \cdot \left(\frac{\partial u}{\partial N} \right) + \cos \alpha_1 \left(\frac{\partial u}{\partial N} \right) + \cos \alpha_2 \left(\frac{\partial u}{\partial N} \right) \right] dF = \frac{1}{\mu} \int \int f \, dF$$

že $u = \cos \alpha$; $f = \cos \alpha$ se identifikuje

$\Delta u = 0$ $\Delta f = 0$ upřesnění identifikace pomocí rovnice to odpovídá
 $\cos \alpha = \frac{\partial u}{\partial n} \sim \frac{\partial f}{\partial n}$

$$\frac{\partial u}{\partial n} = \frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} = \frac{\varphi_2 - \varphi_1}{\varphi_2} \left[\frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x_0} \right) + \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial x_0} \right) \right]$$

$$\frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x_0} \right) + \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial x_0} \right) = - \left(\frac{\partial^2 u}{\partial x^2} \right)_0 = \nabla_0^2 u = \frac{1}{\mu} \frac{\partial f}{\partial n}$$

Wise bytely vopole:

$$u_1 - u_2 = \frac{\varphi_2 - \varphi_1}{\varphi_2} \frac{1}{\mu} (f_1 - f_2) \quad (?)$$

Jaki procent ^{elektrycznej} pracy przy zgrzewaniu stali? ^{Stalowy stwin?}

$$W_e = \frac{P^2 (\varphi_1 - \varphi_2)^2}{(4\pi\mu)^2} \frac{\phi}{L}$$

$$W_f = \frac{\pi P^2 R^2}{8\pi L}$$

$$\frac{W_e}{W_f} = \frac{(\varphi_1 - \varphi_2)^2 \phi}{2\pi\mu\varphi} = \frac{\left(\frac{4}{300}\right)^2 \cdot 4 \cdot 6 \cdot 10^{-8}}{2 \cdot 3 \cdot 14 \cdot 0.010 \cdot 10^{-4}} = \frac{4 \cdot 10^{-9}}{10^{-6}}$$

powiększyć maszynę: podstawić $\phi = \frac{1}{2}$

zmniejszyć φ

Nie, większe drożdżenie i dobry izolator

Jaki mł. Browne powodowany przez zmniejszenie prędkości, jako mł. przy
pracy rozprężona?

$$N_f. \quad 2r = 0.001 \text{ mm} = 10^{-4} \text{ cm}$$

$$v = 0.003 \frac{\text{mm}}{\text{sec}} = 3 \cdot 10^{-4}$$

$$\sigma_{pr} = 6\pi a \mu v \quad \mu = 0.018$$

$$\text{praca po sec: } 6\pi a \mu v^2 = \frac{6^3 \cdot 3 \cdot 14 \cdot 10^{-4} \cdot 0.018 \cdot 9 \cdot 10^{-8}}{2}$$

$$= 10^{-12} \cdot \frac{0.17 \cdot 9}{1.5} = 1.5 \cdot 10^{-12} \text{ erg}$$

$$\text{objętość takiej kulki: } \frac{4\pi}{3} \cdot \frac{1}{8} 10^{-12} = \frac{1}{2} 10^{-12} \text{ cm}^3$$

$$\text{Zatem praca po } 1 \text{ cm}^3 \text{ młota wgi: } 3 \frac{\text{erg}}{\text{sec}}$$

$$\text{Pro dzień: } 60 \cdot 60 \cdot 24 = 86400 \text{ s} \quad 260.000 \text{ erg} = \frac{260.000}{42 \cdot 10^6} \text{ cal} = \frac{1}{160} \text{ cal}$$

Energia Atkrostoni' ogy keli: $\alpha \cdot 0 = 4\pi r^2 \alpha$

$$= 3.14 \cdot 80 \cdot 10^{-8} \text{ (gy)}$$

$$= 25 \cdot 10^{-7}$$

Zatem Energia Atkrostoni' ogy keli: $\frac{25 \cdot 10^7}{1.5 \cdot 10^{12}} = 10 \cdot 10^5 \text{ sec.}$
 $= 2 \text{ dni}$

~~16.10~~
~~16.10~~

Prak keli u ci'ay, ay ni mo'ina mo'ly dui "inertia terms"

Ila terms:

$$u = \frac{M}{2} \left(\frac{x^1}{2} + \frac{x^2}{2^3} \right) + \frac{N}{2^3} \left(1 - \frac{3x^2}{2^2} \right) + c$$

$$v = \frac{M}{2} \frac{x^4}{2^3} - \frac{3N}{2^3} x^4$$

$$w = \frac{M}{2} \frac{x^8}{2^3} - \frac{3N}{2^5} x^2$$

Prak terms:

$$u = \frac{N}{2^3} \left(1 - \frac{3x^2}{2^2} \right) + c$$

$$v = - \frac{3N}{2^5} x^4$$

$$w = \frac{3N}{2^5} x^4$$

$$0 = \frac{\partial F}{\partial x} - \mu \nabla^2 u$$

$$0 = \frac{\partial F}{\partial y} - \mu \nabla^2 v$$

$$0 = \frac{\partial F}{\partial z} - \mu \nabla^2 w$$

$$(u_1 + u_2) \frac{\partial (u_1 + u_2)}{\partial x} + \dots = - \frac{\partial F}{\partial x} + \mu (\nabla^2 u_1 + \nabla^2 u_2)$$

$$u_1 \frac{\partial u_1}{\partial x} + u_2 \frac{\partial u_1}{\partial x} + u_1 \frac{\partial u_2}{\partial x} + u_2 \frac{\partial u_2}{\partial x} = - \frac{\partial F}{\partial x} + \frac{\partial F}{\partial x} + \mu (\nabla^2 u_1 + \nabla^2 u_2)$$

$$= u_1 \frac{\partial (u_1 + u_2)}{\partial x} + u_2 \frac{\partial (u_1 + u_2)}{\partial x}$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = - \frac{\partial F}{\partial x}$$

$$u = \frac{M}{2} \left(\frac{1}{2} + \frac{x^2}{25} \right) + \frac{N}{25} \left(1 - \frac{3x^2}{25} \right) + c$$

La forma: $u = c + \frac{M}{2} \frac{\partial}{\partial x} \left(\frac{x}{25} \right) + \frac{N}{6} \frac{\partial}{\partial x} \left(\frac{x}{25} \right)$

$$\frac{\partial u}{\partial x} = M \left[-\frac{x}{2^3} + \frac{2x}{2^3} - \frac{3x^3}{25} \right] + N \left[-\frac{3x}{25} - \frac{6x}{25} + \frac{15x^3}{2^7} \right]$$

$$= M \left[\frac{x}{2^3} - \frac{3x^3}{25} \right] + N \left[-\frac{9x}{25} + \frac{15x^3}{2^7} \right]$$

$$\frac{\partial u}{\partial y} = M \left[-\frac{y}{2^3} - \frac{3x^2 y}{25} \right] + N \left[-\frac{3y}{25} + \frac{15x^2 y}{2^7} \right]$$

$$\frac{\partial u}{\partial z} = M \left[-\frac{2}{2^3} - \frac{3x^2 z}{25} \right] + N \left[-\frac{3z}{25} + \frac{15x^2 z}{2^7} \right]$$

$$\begin{array}{c} \frac{1}{2} + \frac{x^2}{2^3} \\ \frac{x y}{2^3} \\ \frac{x z}{2^3} \end{array} \left| \begin{array}{c} \frac{N}{25} \left(1 - \frac{3x^2}{25} \right) + c \\ - \frac{3N x y}{25} \\ - \frac{3N x z}{25} \end{array} \right.$$

$$M \left\{ \cancel{\frac{12}{2^6}} - \cancel{\frac{3x^3}{2^6}} + \cancel{\frac{15x^3}{2^6}} - \cancel{\frac{3x^5}{2^8}} - \cancel{\frac{x^5}{2^6}} - \cancel{\frac{3x^3 y^2}{2^8}} - \cancel{\frac{3x^3 z^2}{2^8}} \right\} +$$

$$+ N \left\{ -\frac{12}{2^6} + \frac{15x^3}{2^8} - \frac{3x^3}{2^8} + \frac{15x^3}{2^{10}} - \frac{3x^4 y^2}{2^8} + \frac{15x^3 y^2}{2^{10}} - \frac{3x^2 z^2}{2^8} + \frac{15x^3 z^2}{2^{10}} \right\}$$

$$= \cancel{M \left\{ -\frac{3x^3}{2^6} - \frac{3x^5}{2^8} \right\}} + N \left\{ -\frac{12x}{2} - \frac{9x^5}{2} + \frac{15x^5}{2^{10}} \right\} - \frac{12x}{2^6} + \frac{27x^3}{2^8}$$

$$v = \frac{x y}{2^3} \left[M - \frac{3N}{2^2} \right]$$

$$\frac{\partial v}{\partial x} = \left[\frac{y}{2^3} - \frac{3x^2 y}{2^5} \right] \left[M - \frac{3N}{2^2} \right] + \frac{6N x^2 y}{2^7}$$

$$\frac{\partial v}{\partial x} = M \left[\frac{y}{2^3} - \frac{3x^2 y}{2^5} \right] + \frac{3N}{2^2} \left[-\frac{y}{2^5} + \frac{5x^2 y}{2^7} \right]$$

$$\frac{\partial v}{\partial y} = M \left[\frac{x}{2^3} - \frac{3x^2 y^2}{2^5} \right] + 3N \left[-\frac{x}{2^5} + \frac{5x y^2}{2^7} \right]$$

$$\frac{\partial v}{\partial z} = \frac{M - 3x y z}{2^5} + 3N \frac{5x y z}{2^7}$$

$$\begin{array}{c} \frac{1}{2} + \frac{x^2}{2^3} \\ \frac{x y}{2^3} \\ \frac{x z}{2^3} \end{array} \left| \begin{array}{c} \frac{N}{25} \left(1 - \frac{3x^2}{25} \right) + c \\ - \frac{3x y}{2^2} \\ - \frac{3x z}{2^2} \end{array} \right.$$

$$M \left\{ \frac{y}{2^4} - \frac{3x^2y}{2^6} + \frac{x^4}{2^6} - \frac{3x^2y}{2^8} + \frac{x^4}{2^6} - \frac{3x^2y}{2^8} - \frac{3x^2y}{2^8} \right\} \\ + 3N \left\{ -\frac{y}{2^6} + \frac{5x^2y}{2^8} - \frac{x^4}{2^8} + \frac{5x^4}{2^{10}} - \frac{x^4}{2^8} + \frac{5x^4}{2^{10}} + \frac{5x^4}{2^{10}} \right\} =$$

$$\Pi = M \left\{ \frac{y}{2^4} - \frac{4x^2y}{2^6} \right\} + 3N \left\{ \frac{y}{2^6} + \frac{8x^2y}{2^8} \right\}$$

$$I = M \left\{ -\frac{4x^3}{2^6} \right\} + N \left\{ -\frac{12x}{2^6} + \frac{24x^3}{2^8} \right\}$$

For $\frac{\partial I}{\partial y} = \frac{\partial \Pi}{\partial x} = 0$

$$-4M \left\{ \frac{6x^3y}{2^8} \right\} + 12N \left\{ \frac{6xy}{2^8} - \frac{16x^3y}{2^{10}} \right\} \parallel M \left\{ -\frac{4xy}{2^6} - \frac{8xy}{2^6} + \frac{24x^3y}{2^8} \right\} + \\ + 3N \left\{ -\frac{6xy}{2^8} + \frac{16xy}{2^8} - \frac{64x^3y}{2^{10}} \right\}$$

72-30

$$M \left\{ \frac{12x^3y}{2^8} \right\} + N \left\{ \frac{42x^3y}{2^8} \right\} =$$

$$u_2 \frac{\partial u_1}{\partial x} + u_2 \frac{\partial u_1}{\partial y} + u_2 \frac{\partial u_1}{\partial z} = M C \left(\frac{x}{2^3} - \frac{3x^3}{2^5} \right) + \frac{MN}{2^3} \left\{ \frac{x}{2^3} - \frac{3x^3}{2^5} - \frac{3x^3}{2^5} + \frac{9x^5}{2^7} \right.$$

$$\left. + \frac{3x^4y^2}{2^8} + \frac{9x^3y^2}{2^8} + \frac{3x^2y^2}{2^8} + \frac{9x^3y^2}{2^8} \right\} \quad \frac{7x}{2^3}$$

$$= MC \left(\frac{x}{2^3} - \frac{3x^3}{2^5} \right) + 4N \frac{4x}{2^6}$$

$$u_z \frac{\partial v_1}{\partial x} + v_z \frac{\partial v_1}{\partial y} + w_z \frac{\partial v_1}{\partial z} = M_c \left(\frac{y}{z^3} - \frac{3x^2 y}{z^5} \right) + \frac{MN}{z^3} \left\{ \frac{y}{z^3} - \frac{3x^2 y}{z^5} - \frac{3x^4 y}{z^5} + \frac{9x^2 y^3}{z^7} - \frac{3x^4 y^3}{z^5} + \frac{9x^2 y^5}{z^7} + 9 \frac{x^2 y z^2}{z^7} \right\}$$

$$= M_c \left(\frac{y}{z^3} - \frac{3x^2 y}{z^5} \right) + \frac{MN}{z^6} \frac{y}{z^6}$$

$$\frac{\partial}{\partial y} \left\{ M_c \left(\frac{x}{z^3} - \frac{3x^3}{z^5} \right) + MN \frac{xy}{z^6} \right\} - \frac{\partial}{\partial x} \left\{ M_c \left(\frac{y}{z^3} - \frac{3x^2 y}{z^5} \right) + MN \frac{y}{z^6} \right\} =$$

$$M_c \left\{ -\frac{3xy}{z^5} + \frac{15x^3 y}{z^7} + \frac{3xy}{z^5} - \frac{15x^3 y}{z^7} - \frac{6xy}{z^5} \right\} + MN \left\{ -\frac{24xy}{z^8} + \frac{6xy}{z^8} \right\}$$

$$= M_c \left(-\frac{6xy}{z^5} \right) + MN \left(\frac{18xy}{z^8} \right)$$

$$M^2 \frac{12xy}{z^6} + MN \frac{60xy}{z^8} \star = \cancel{48} \geq 0 \quad \text{zatem nie ma tu}$$

warunku

$$0 = \frac{\partial f_1}{\partial x} - \mu \tilde{V}(u_1 + u_2)$$

$$0 = \frac{\partial f_1}{\partial y} - \mu \tilde{V}(u_1 + u_2)$$

$$0 = \frac{\partial f_1}{\partial z} - \mu \tilde{V}(u_1 + u_2)$$

$$u_2 \frac{\partial u_1}{\partial x} + v_2 \frac{\partial u_1}{\partial y} + w_2 \frac{\partial u_1}{\partial z} = -\frac{\partial f_2}{\partial x}$$

$$u_2 \frac{\partial v_1}{\partial x} + v_2 \frac{\partial v_1}{\partial y} + w_2 \frac{\partial v_1}{\partial z} = -\frac{\partial f_2}{\partial y}$$

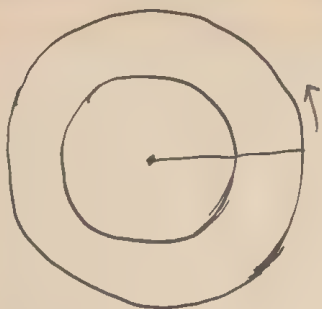
$$\text{Total energy} = (u_1 + u_2) \frac{\partial (u_1 + u_2)}{\partial x} + \dots = -\frac{\partial f_1}{\partial x} + \mu \tilde{V}(u_1 + u_2)$$

$$u_1 \frac{\partial u_1}{\partial x} + u_2 \frac{\partial u_1}{\partial x} + u_1 \frac{\partial u_2}{\partial x} + u_2 \frac{\partial u_2}{\partial x} = -\frac{\partial f_1}{\partial x} + \mu \tilde{V}(u_1 + u_2)$$

$$= -\frac{\partial (f_1 - f_1)}{\partial x}$$

$$u_1 \frac{\partial u_1}{\partial x} + u_2 \frac{\partial u_1}{\partial x}$$

$$= \frac{\partial (f_1 + u_2 - f_1)}{\partial x}$$



Ruch wzdłuż okręgu

$$\frac{L}{2} = W = \text{pęd kinetyczny} = \varphi(r)$$

$$u = -\frac{L}{2} = -\varphi y$$

$$v = \frac{L}{2} = \varphi x$$

$$\frac{\partial u}{\partial x} = -\varphi' \frac{xy}{r}$$

$$\frac{\partial v}{\partial y} = \varphi' \frac{xy}{r}$$

$$\frac{\partial^2 u}{\partial x^2} = -\varphi'' \frac{x^2 y}{r^2} - \frac{\varphi' y}{r} + \varphi' \frac{x^2 y}{r^3}$$

$$\frac{\partial^2 v}{\partial y^2} = \varphi'' \frac{xy^2}{r^2} + \frac{\varphi' x}{r} - \varphi' \frac{xy^2}{r^3}$$

$$\frac{\partial u}{\partial y} = -\varphi - \varphi' \frac{y^2}{r}$$

$$\frac{\partial v}{\partial x} = \varphi + \varphi' \frac{x^2}{r}$$

$$\frac{\partial^2 u}{\partial y^2} = -3\varphi' \frac{y}{r} - \varphi'' \frac{y^3}{r^2} + \varphi' \frac{y^3}{r^3}$$

$$\frac{\partial^2 v}{\partial x^2} = 3\varphi' \frac{x}{r} + \varphi'' \frac{x^3}{r^2} - \varphi' \frac{x^3}{r^3}$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = -\varphi'' y - 3\varphi' \frac{y}{r}$$

$$\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} = \varphi'' x + 3\varphi' \frac{x}{r}$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = \varphi \varphi' \frac{xy^2}{r} - \varphi^2 x - \varphi \varphi' \frac{xy^2}{r} = -\varphi^2 x$$

$$u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} = -\varphi^2 y - \varphi \varphi' \frac{x^2 y}{r} + \varphi \varphi' \frac{x^2 y}{r} = -\varphi^2 y$$

1. Deszcz: $\frac{\partial L}{\partial x \partial y} = 2\varphi \varphi' \frac{xy}{r} = 4\varphi \varphi' \frac{xy}{r}$ nie dgi iednego zmiennika

$$\left. \begin{aligned} -\varphi^2 x &= -\frac{\partial \mathcal{L}}{\partial x} \\ -\varphi^2 y &= -\frac{\partial \mathcal{L}}{\partial y} \end{aligned} \right\} \frac{x}{2} \quad \frac{y}{2} \quad \frac{dp}{dr} = \varphi^2 \frac{x^2 + y^2}{r} = r \cdot \varphi^2$$

$$p = \int \varphi^2 \cdot r \, dr$$

φ niezmienne, dowolne
mimo że dane mogą być $\varphi(r)$ powierchni

II Rozwinięcie:

$$\frac{1}{\mu} \frac{\partial f}{\partial x} = -\varphi'' y - 3\varphi' \frac{y}{2} \quad \left\| \quad \frac{x}{2}\right.$$

$$\frac{1}{\mu} \frac{\partial f}{\partial y} = \varphi'' x + 3\varphi' \frac{x}{2} \quad \left\| \quad \frac{y}{2}\right.$$

$$\frac{1}{\mu} \frac{d\mu}{dr} = 0$$

$$\mu = \text{const}$$

$$\varphi'' + 3\frac{\varphi'}{r} = 0$$

$$\frac{d}{dr}(r^3 \varphi') = r^3 \varphi'' + 3r^2 \varphi' = r^3 (\varphi'' + 3\frac{\varphi'}{r}) = 0$$

$$\begin{aligned} \frac{1}{\mu} \frac{\partial f}{\partial x \partial y} &= -\varphi'' - 3\frac{\varphi'}{r} - \varphi'' \frac{xy}{r} - 3\varphi' \frac{xy}{r^2} + 3\varphi' \frac{xy}{r^3} \\ &= \varphi'' + 3\frac{\varphi'}{r} + \varphi'' \frac{xy}{r} + 3\varphi' \frac{xy}{r^2} - 3\varphi' \frac{xy}{r^3} = 0 \end{aligned}$$

$$\frac{3}{r^4} - \frac{3xy}{r^5} - \frac{3}{r^4} - 9\frac{xy}{r^6} + \frac{12xy}{r^6} = 0$$

$$\varphi'' = -\frac{3c}{r^4} \quad \varphi' = -\frac{3c}{2r^3}$$

$$r^3 \varphi' = c$$

$$d\varphi = \frac{c}{r^3} dr$$

$$\varphi = -\frac{c}{2r^2} + b$$

III Szybkie rozwiązanie:

$$-\varphi^2 x = -\frac{\partial f}{\partial x} = \mu (\varphi'' y + 3\varphi' \frac{y}{r}) \quad \left\| \quad \frac{x}{2} \quad \frac{\partial}{\partial y}\right.$$

$$-\varphi^2 y = -\frac{\partial f}{\partial y} = \mu (\varphi'' x + 3\varphi' \frac{x}{r}) \quad \left\| \quad \frac{y}{2} \quad -\frac{\partial}{\partial x}\right.$$

$$-\varphi^2 \cdot \frac{x^2 + y^2}{r} = -\frac{d\mu}{dr} = -\varphi^2 \cdot r$$

$$-2\varphi \varphi' \frac{xy}{r} + 2\varphi \varphi' \frac{xy}{r} = \dots$$

zatem to samo rozwiązanie co przedtem

hydrozje p. twoz hydrozje inne

$$\varphi = -\frac{c}{2r^2} + b$$

$$\varphi' = \frac{c}{r^3}$$

$$\varphi'' = -\frac{3c}{r^4}$$

Kianowicz: $\frac{dp}{dr} = 2 \varphi^2$

$$p = \int_0^r \underbrace{\left(b - \frac{c}{2r^2}\right)^2}_{b^2 - \frac{bc}{r^2} + \frac{c^2}{4r^2}} dr$$

$$p = \left[b^2 \frac{r^2}{2} - bc \ln r - \frac{c^2}{8r^2} \right] + p_0$$

Wzrost
3 stadi: b, c, p₀!

Pytanie: czy ten wyrażenie spełnia warunki wcale nie wychodzi z rachunków
czy ten sam układ musi być w ustroniu (2 osiem) dla ciężej z większą niż ten tarcia

[czy przez warunki: "niektóre nie tarcia" równoważenie hydrostatyczne z osiem osiem dla
danych z

Wzrost: $\left\{ u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = - \frac{\partial \Phi}{\partial x} + \mu \nabla^2 u \right.$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

Energia potencjalna: $\Phi = \mu \left\{ 2 \left[\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial y} \right)^2 + \left(\frac{\partial w}{\partial z} \right)^2 \right] + \left[\left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} \right)^2 \right] \right\}$

Dwa przypadki: albo u w w nie zmienia się wzdłuż osi x

albo ruch tarczy w $\Phi = 0$

to statycznie tyłko małe przesunięcia $\frac{\partial u}{\partial x} = \dots = 0$ jeżeli μ stała
albo też μ małe małe

Działamy przepadku rozkładu i potęg μ w której coraz mniejsze
 i myślenie:

złoty rozkład: $u = u_0 + \mu u_1 + \frac{\mu^2}{2} u_2 + \dots$

zinde w głu mailek taki rozkład

$$\frac{\partial u}{\partial x} = \frac{\partial u_0}{\partial x} + \mu \frac{\partial u_1}{\partial x}$$

zawszebyśmy mogli wyjąć potęg μ i wyjąć pierwszy: 0

$$u_0 \frac{\partial u_0}{\partial x} + v_0 \frac{\partial u_0}{\partial y} + w_0 \frac{\partial u_0}{\partial z} = - \frac{\partial p_0}{\partial x}$$

$$u_0 \frac{\partial u_1}{\partial x} + v_0 \frac{\partial u_1}{\partial y} + w_0 \frac{\partial u_1}{\partial z} + u_1 \frac{\partial u_0}{\partial x} + v_1 \frac{\partial u_0}{\partial y} + w_1 \frac{\partial u_0}{\partial z} = - \frac{\partial p_1}{\partial x} + \nabla^2 u_0$$

$$\frac{u_0 \frac{\partial (u_0 + u_1)}{\partial x} + v_0 \frac{\partial (u_0 + u_1)}{\partial y} + w_0 \frac{\partial (u_0 + u_1)}{\partial z} + (u_0 + u_1) \frac{\partial u_0}{\partial x} + (v_0 + v_1) \frac{\partial u_0}{\partial y} + (w_0 + w_1) \frac{\partial u_0}{\partial z}}{\partial x} = - \frac{\partial (p_0 + p_1)}{\partial x} + \nabla^2 u_0$$

$$u_\mu = (u)_0 + \mu \left(\frac{\partial u}{\partial \mu} \right)_0 + \frac{\mu^2}{1.2} \left(\frac{\partial^2 u}{\partial \mu^2} \right)_0 + \dots$$

$$u_1 = \left(\frac{\partial u}{\partial \mu} \right)_0 \text{ etc.}$$

$$\left(\frac{\partial}{\partial \mu} \left[u_\mu \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right] \right)_0 = - \left(\frac{\partial p}{\partial x \partial \mu} \right)_0 + \nabla^2 u$$

Ještě nutkající od μ to rovnováha:

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = - \frac{\partial p}{\partial x}$$

$$\Delta^2 u = 0$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

$$u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} = - \frac{\partial p}{\partial y}$$

$$\Delta^2 v = 0$$

$$\Delta^2 w = 0$$

$$u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} = - \frac{\partial p}{\partial z}$$

$$\underbrace{v \frac{\partial^2 u}{\partial x^2} - u \frac{\partial^2 v}{\partial x^2}}_0 + \underbrace{v \frac{\partial^2 u}{\partial y^2} - u \frac{\partial^2 v}{\partial y^2}}_0 = 0$$

kyž $\frac{\partial p}{\partial y}$:

$$u \frac{\partial u}{\partial x} + v \left(\frac{\partial u}{\partial y} - u \frac{\partial v}{\partial x} \right) + w \left(\frac{\partial u}{\partial z} - \frac{\partial w}{\partial x} \right) + v \frac{\partial v}{\partial x} + w \frac{\partial v}{\partial x}$$

$$\frac{1}{2} \frac{\partial}{\partial x} (u^2 + v^2 + w^2) + v \left(u - u \frac{\partial v}{\partial x} \right) = - \frac{\partial p}{\partial x}$$

$$\cancel{u \frac{\partial u}{\partial x} + u \frac{\partial v}{\partial y} + u \frac{\partial w}{\partial z}}$$

$$\frac{1}{2} \frac{\partial}{\partial y} (u^2 + v^2 + w^2) + w \left(\frac{\partial v}{\partial x} - u \frac{\partial w}{\partial x} \right) = - \frac{\partial p}{\partial y}$$

$$\cancel{u \frac{\partial u}{\partial x} - u \frac{\partial v}{\partial y} - u \frac{\partial w}{\partial z}}$$

$$\frac{1}{2} \frac{\partial}{\partial z} (u^2 + v^2 + w^2) + u \frac{\partial w}{\partial x} - v \frac{\partial w}{\partial x} = - \frac{\partial p}{\partial z}$$

$$V(u, \text{curl } v) = -V\left(\mu + \frac{u^2 + v^2 + w^2}{2}\right)$$

podle toho:

včetně:

može rovnováha:

$$\left\{ \begin{array}{l} \text{curl } V(u, \text{curl } v) = 0 \\ \Delta^2 v = 0 \\ \text{div } v = 0 \end{array} \right.$$

$$\Delta^2 v = 0$$

$$\text{div } v = 0$$

$$\pm \frac{\partial v}{\partial z}$$

$$\pm v \frac{\partial v}{\partial z}$$

$$\frac{\partial v}{\partial y} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) - \frac{\partial u}{\partial y} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + v \frac{\partial v}{\partial y} - w \frac{\partial v}{\partial y} - \frac{\partial v}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + \frac{\partial u}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) - v \frac{\partial v}{\partial x} + u \frac{\partial v}{\partial x} = 0$$

$$\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) - \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) - \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = 0$$

~~$$\text{curl}(\vec{V} \times \text{curl} \vec{V}) = \nabla(\nabla \cdot \text{curl} \vec{V}) - \nabla^2 \text{curl} \vec{V}$$~~

$$u \Delta u = u \frac{\partial^2 u}{\partial x^2} + u \frac{\partial^2 u}{\partial y^2} + u \frac{\partial^2 u}{\partial z^2} \neq$$

$$+ \left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial y} \right)^2 + \left(\frac{\partial u}{\partial z} \right)^2 = \frac{\partial}{\partial x} \left(u \frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left(u \frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial z} \left(u \frac{\partial u}{\partial z} \right) - \left[\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial y} \right)^2 + \left(\frac{\partial u}{\partial z} \right)^2 \right]$$

$$= \frac{1}{2} \Delta(u^2) - \left[\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial y} \right)^2 + \left(\frac{\partial u}{\partial z} \right)^2 \right]$$

Strommische Ladung:

$$u = \frac{\partial}{\partial z} = f = g = 0$$

$$\left\{ \begin{array}{l} u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = - \frac{\partial f}{\partial x} \\ u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} = - \frac{\partial f}{\partial y} \end{array} \right. \quad \left\{ \begin{array}{l} \Delta^2 u = 0 \\ \Delta^2 v = 0 \\ \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} = 0 \end{array} \right. \quad \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} = 0$$

$$u \left(\frac{\partial^2 u}{\partial x \partial y} - \frac{\partial^2 v}{\partial x^2} \right) + v \left(\frac{\partial^2 u}{\partial y^2} - \frac{\partial^2 v}{\partial x \partial y} \right) = 0$$

$$u \left(\frac{\partial^2 u}{\partial x \partial y} + \frac{\partial^2 v}{\partial y^2} \right) - v \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial x \partial y} \right) = 0$$

$$u \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) - v \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = 0$$

wie to wianianie: tak spelnione jest \uparrow spelnione

$$\Delta^2 u = 0$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0$$

$$\Delta^2 v = 0$$

$$u = f_1(x+iy) + \varphi(x,y) + i\psi(x,y)$$

$$\frac{\partial u}{\partial x} = f_1'$$

$$\frac{\partial u}{\partial y} = i f_1'$$

$$\frac{\partial^2 u}{\partial x^2} = f_1''$$

$$\frac{\partial^2 u}{\partial y^2} = -f_1''$$

$$v = i f_2(x+iy) = i f_2'(x,y) = h_2(x,y)$$

$$\frac{\partial v}{\partial x} = -h_2'$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$f_1' + h_2' = 0$$

$$f_1(2) = f_1(2) + c$$

$$f(x+iy) = \varphi(x,y) + i\psi(x,y)$$

$$\Delta^2 \varphi = 0 \quad \Delta^2 \psi = 0$$

$$u = \varphi(x,y)$$

$$\frac{\partial u}{\partial x} = \frac{\partial \varphi}{\partial x} = \frac{\partial \psi}{\partial y} = -\frac{\partial v}{\partial x}$$

$$\left. \begin{aligned} f' &= \frac{\partial \varphi}{\partial x} + i \frac{\partial \psi}{\partial x} \\ i f' &= \frac{\partial \varphi}{\partial y} + i \frac{\partial \psi}{\partial y} \end{aligned} \right\}$$

$$v = -\psi(x,y) + f_2(x)$$

$$\frac{\partial \varphi}{\partial x} = + \frac{\partial \psi}{\partial y}$$

$$\frac{\partial \varphi}{\partial y} = - \frac{\partial \psi}{\partial x}$$

~~2. d.h. $\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0$ ist erfüllt.~~

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = - \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2}$$

$$\frac{\partial^2 u}{\partial x^2} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = \frac{\partial^2 f_1(x)}{\partial x^2} = 0$$

$$\frac{\partial^2 u}{\partial x^2} = \frac{\partial^2 \varphi}{\partial x^2} = - \frac{\partial^2 \psi}{\partial x^2} = \frac{\partial^2 \psi}{\partial x^2}$$

$$\frac{\partial v}{\partial x} = - \frac{\partial \psi}{\partial x} + \frac{df_2}{dx}$$

$$\frac{\partial^2 v}{\partial x^2} = \frac{\partial^2 \psi}{\partial x^2} + \frac{d^2 f_2}{dx^2} = \frac{\partial^2 \psi}{\partial x^2} + \frac{d^2 f_2}{dx^2} = 0$$

$$\frac{\partial^2 v}{\partial y^2} = - \frac{\partial^2 \psi}{\partial y^2}$$

Pytanie: o ile warunki przeliczone mogą być dowolniebrane?

$$z = re^{i\varphi} = x + iy$$

$$\overline{z} = re^{-i\varphi} = x - iy$$

$$z(\cos\varphi + i\sin\varphi) = ze^{i\varphi}$$

$$\log z(\cos\varphi + i\sin\varphi) = i\varphi + \log z$$

$$z^2 = r^2(\cos 2\varphi + i\sin 2\varphi)$$

$$= r^2 e^{2i\varphi} = r^2 \cos 2\varphi + i r^2 \sin 2\varphi$$

I. $\log z = \log r + i\varphi$

$$u = \log r + b_1 y + c_1$$

$$v = -\varphi + b_2 x + c_2 = -\arctan \frac{y}{x} + b_2 x + c_2$$

$$\left\| \begin{array}{l} \frac{\partial u}{\partial x} = \frac{x}{r^2} \quad \frac{\partial^2 u}{\partial x^2} = \frac{1}{r^2} - \frac{2x^2}{r^4} \\ \frac{\partial u}{\partial y} = \frac{y}{r^2} + b_1 \quad \frac{\partial^2 u}{\partial y^2} = \frac{1}{r^2} - \frac{2y^2}{r^4} \end{array} \right\| \quad \begin{array}{l} \\ \end{array}$$

$$\Sigma = 0$$

$$\frac{\partial v}{\partial x} = + \frac{\frac{y}{x^2} + b_2}{1 + \frac{y^2}{x^2}} = \frac{y}{x^2 + y^2} + b_2 = \frac{y}{r^2} + b_2$$

$$\frac{\partial v}{\partial y} = \frac{-\frac{1}{x}}{1 + \frac{y^2}{x^2}} = -\frac{1}{x} \cdot \frac{x^2}{x^2 + y^2} = -\frac{x}{r^2}$$

$$\frac{\partial^2 v}{\partial x^2} = -2 \frac{yx}{r^4}$$

$$\frac{\partial^2 v}{\partial y^2} = \frac{2yx}{r^4}$$

$$\Sigma = 0$$

Jako kromok linij před neresolucí $\sigma \mu$

$$\frac{\partial}{\partial \mu} \left(\frac{u}{v} \right) = 0 \quad \frac{1}{v} \frac{\partial u}{\partial \mu} - \frac{u}{v^2} \frac{\partial v}{\partial \mu} = 0$$

$$\frac{1}{u} \frac{\partial u}{\partial \mu} = \frac{1}{v} \frac{\partial v}{\partial \mu} = \frac{1}{w} \frac{\partial w}{\partial \mu}$$

$$\frac{\partial}{\partial \mu} \left[u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} \right] = \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial \mu} \right) + \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial \mu} \right) + \mu$$

$$\frac{\partial}{\partial \mu} \left[u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} \right] = \frac{\partial}{\partial x} \left(\frac{\partial v}{\partial \mu} \right) + \frac{\partial}{\partial y} \left(\frac{\partial v}{\partial \mu} \right) + \mu$$

$$\mu \frac{\partial u}{\partial \mu} = -\frac{\partial u}{\partial x} + \mu \nabla^2 u$$

$$\mu \frac{\partial v}{\partial \mu} = -\frac{\partial v}{\partial y} + \mu \nabla^2 v$$

$$\mu \frac{\partial w}{\partial \mu} = -\frac{\partial w}{\partial z} + \mu \nabla^2 w$$

$$\frac{\partial}{\partial y} D_u - \frac{\partial}{\partial x} D_v = \mu \nabla^2 \left(\frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right)$$

$$\text{curl } (\nabla \cdot \text{curl } v) = \mu \nabla^2 \text{curl } v = -\mu \text{curl }^3 v$$

we neresolucii $\sigma \mu$ porotaj tykto samnik :

$$\mathcal{U} \text{curl } (\nabla \cdot \text{curl } v) = \mathcal{U} \nabla^2 \text{curl } v$$

$$\frac{\partial}{\partial y} (v \xi - w \eta) - \frac{\partial}{\partial x} (u \xi - v \eta) : \frac{\partial}{\partial z} (w \xi - u \eta) - \frac{\partial}{\partial y} (u \eta - v \xi) : \dots$$

$$= \frac{\partial^2 \xi}{\partial x^2} + \frac{\partial^2 \xi}{\partial y^2} + \frac{\partial^2 \xi}{\partial z^2} : \frac{\partial^2 \xi}{\partial x^2} + \frac{\partial^2 \xi}{\partial y^2} + \frac{\partial^2 \xi}{\partial z^2} : -$$

porivni dva strom krotiti $\frac{\partial}{\partial}$ rat $\frac{\partial}{\partial \mu}$

$$\frac{\partial}{\partial \mu} \left[\frac{\partial}{\partial y} (v \xi - w \eta) - \frac{\partial}{\partial x} (u \xi - v \eta) \right] = \Delta^2 \xi$$

$$\frac{\partial}{\partial \mu} \left[\frac{\partial}{\partial z} (w \xi - u \eta) - \frac{\partial}{\partial y} (u \eta - v \xi) \right] = \Delta^2 \eta$$

$$\Delta^2 \xi \left[\frac{\partial^2}{\partial x \partial y} (\mu \tilde{u}_1) - \frac{\partial^2}{\partial x^2} (\mu \tilde{v}_1) \right] =$$

$$= \nabla^2 \xi + \mu$$

Następnie udamy:

$$\frac{\partial}{\partial \mu} (v \tilde{f} - v \tilde{g}) = - \frac{\partial \tilde{f}}{\partial x \partial \mu} + \nabla^2 \tilde{u} + \mu \frac{\partial \tilde{u}}{\partial \mu}$$

$$\nabla^2 \tilde{u} = \frac{\partial}{\partial \mu} \left[\frac{\partial \tilde{f}}{\partial x} - (v \tilde{f} - v \tilde{g}) \right]$$

Powierzchnie, gdzie dwie cięce z trzecim granicą zerotą:

$$\frac{D u_1}{D t} = - \frac{\partial p_1}{\partial x} + \mu_1 \nabla^2 u_1$$

$$\frac{D v_1}{D t} = - \frac{\partial p_1}{\partial y} + \mu_1 \nabla^2 v_1$$

$$\frac{D w_1}{D t} = - \frac{\partial p_1}{\partial z} + \mu_1 \nabla^2 w_1$$

$$\frac{\partial u_1}{\partial x} + \frac{\partial v_1}{\partial y} + \frac{\partial w_1}{\partial z} = 0$$

$$D u_2 = - \frac{\partial p_2}{\partial x} + \mu_2 \nabla^2 u_2$$

$$D v_2 = - \frac{\partial p_2}{\partial y} + \mu_2 \nabla^2 v_2$$

$$D w_2 = - \frac{\partial p_2}{\partial z} + \mu_2 \nabla^2 w_2$$

$$\frac{\partial u_2}{\partial x} + \frac{\partial v_2}{\partial y} + \frac{\partial w_2}{\partial z} = 0$$

Stąd powierzchnie, gdzie dwie cięce z trzecim granicą zerotą:

$u_1 = u_2$

to ujemnie zero jest bieżni

$$\frac{\partial}{\partial t} + u_1 \frac{\partial}{\partial x} + v_1 \frac{\partial}{\partial y} + w_1 \frac{\partial}{\partial z} = 0 \quad \left| \frac{\partial}{\partial t} + u_2 \frac{\partial}{\partial x} + \right.$$

$= 0$

co tyłko możemy mieć

$u_1 = u_2 \quad \parallel \quad v_1 = v_2 \quad \parallel \quad w_1 = w_2$ na powierzchni

opinia tego tak samo:

$$l_{p_{xx}} + m_{p_{xy}} + n_{p_{xz}} = l_{p_{xx}} + m_{p_{xy}} + n_{p_{xz}} \quad \text{itd.}$$

Pełki podłoga w cięciu

Tak samo jak płyty parcie γ to również jest - 2

$$\frac{Du_1}{Dt} = -\frac{\partial p}{\partial x} + \mu_1 \nabla^2 u_1 \quad \left| \quad \frac{Du_2}{Dt} = -\frac{1}{\rho_2} \frac{\partial p}{\partial x} + \frac{\mu_2}{\rho_2} \nabla^2 u_2 \right.$$

$$\mu_1 = \cancel{0.017} \\ = 0.017$$

$$\left. \begin{array}{l} \rho_2 = 0.0013 \\ \mu_2 = 0.00017 \end{array} \right\} \frac{\mu_2}{\rho_2} = \frac{0.17}{1.3} = 0.13$$

$$\left. \begin{array}{l} \text{Głównie } \rho_2 = 0.00009 \\ \mu_2 = 0.00009 \end{array} \right\} \frac{\mu_2}{\rho_2} = 1.0$$

Wzrost:

Wzrost płyty w kierunku x i y nie występuje to jest bardzo $\sim H_2$

Na powierzchni:

Wskazywało OX i x

OY i $z \perp$

OZ i $z \parallel$

$$\left. \begin{array}{l} z=0 \\ u_1 = u_2 = 0 \\ v_1 = v_2 \\ w_1 = w_2 = 0 \end{array} \right\}$$

$$-p + 2\mu_1 \frac{\partial u_1}{\partial x} = -p + 2\mu_2 \frac{\partial u_2}{\partial x}$$

$$\mu_1 \left(\frac{\partial u_1}{\partial y} + \frac{\partial v_1}{\partial x} \right) = \mu_2 \left(\frac{\partial u_2}{\partial y} + \frac{\partial v_2}{\partial x} \right)$$

$$\mu_1 \left(\frac{\partial u_1}{\partial z} + \frac{\partial w_1}{\partial x} \right) = \mu_2 \left(\frac{\partial u_2}{\partial z} + \frac{\partial w_2}{\partial x} \right)$$

$$w=0$$

Stąd:

$$\mu_1 \frac{\partial v_1}{\partial x} = \mu_2 \frac{\partial v_2}{\partial x}$$

$\mu_1 \Delta u_1$ i $\mu_2 \Delta u_2$ będące rot. typ sążn. ujęd. włkón.

$$\frac{\partial u_1}{\partial x} \dots \frac{\partial u_2}{\partial x}$$

2. ten możliwy jest $\frac{Du_1}{Dt}$ mianem prędkości zmiennych $\rho_2 \frac{Du_2}{Dt}$

1. to w typ sążn. ujęd. włkón

Kierując się do wól:

$$\left. \begin{aligned} u &= c \left[1 + \frac{a^2}{2r^3} \left(1 - \frac{3x^2}{r^2} \right) \right] \\ v_\omega &= -\frac{3c \cdot a^3}{2r^3} \times \omega \end{aligned} \right\} \begin{aligned} &= \frac{\partial \varphi}{\partial x} \\ \varphi &= c \left(x + \frac{a^3 x}{2r^3} \right) = c x \left[1 + \frac{a^3}{2r^3} \right] \\ &= c r \cos \theta \left[1 + \frac{a^3}{2r^3} \right] \end{aligned}$$

H_2

wzdłuż pro. drógów: $v_\theta = \left(\frac{\partial \varphi}{\partial \theta} \right)_{r=\text{const}} = -c r \sin \theta \left[1 + \frac{a^3}{2r^3} \right]$

$$\left. \frac{\partial v_\theta}{\partial r} \right|_{r=a} = -c \sin \theta \left[1 + \frac{a^3}{2r^3} - \frac{a^3}{r^3} \right] = -\frac{c}{2} \sin \theta \quad \left|_{r=a} \right.$$

$$v_\theta \Big|_{r=a} = -\frac{3}{2} a c \sin \theta$$

Do prądu badano rozrzedzonych przy wysokim temp.

Np. $\rho = 1 \text{ m}$

$\rho = 1.5 \cdot 10^{-6}$

$\mu = 0.00017$

$\frac{\mu}{\rho} = 100 !$

$\rho \frac{Du}{Dt} = - \frac{\partial p}{\partial x} + \mu \nabla^2 u$ tutaj ρ badano male

Zatem przy braniu $\nabla^2 u = 0$

$\nabla^2 v = 0$

$\nabla^2 w = 0$

$\left. \begin{array}{l} \nabla^2 u = 0 \\ \nabla^2 v = 0 \\ \nabla^2 w = 0 \end{array} \right\} \nabla^2 v = 0$ ale to nie ma sensu
stare = curl² 0

~~przez~~ bo $\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$

Nie zmieniaj $\frac{\partial}{\partial t}$

Zatem przy danych warunkach granicznych nie zmienia się 2 czoła
Wzrost i ustalenie się natężenia strumienia / nie ma zjawisk składowych

Patrz Le b p 526 / dowiedzieć warunki $\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$

Np. kula dla μ ma $u = c, v = w = 0$

μ

$z = 0$

$u = v = w = 0$

Z tego wynika, że $v = w = 0$ wszędzie
 $\left\{ \begin{array}{l} u = c \left[1 - \frac{a}{r} \right] \end{array} \right.$

Wojciech jechał i nie powstaje w kółkach prądów, i tak to można
rozważać graniczne warunki $u = c_1, v = c_2, w = c_3$ ale przy tym ~~nie~~ porównać

$w = c_3$

$$\frac{\partial \theta}{\partial x} + \theta X_1 = X_2$$

~~$$\theta = a e^{\int X_1 dx}$$~~ $\theta = 2y$

$$y \frac{dz}{dx} + X_1 2y + 2 \frac{dy}{dx} = X_2$$

$$X_1 y + \frac{dy}{dx} = 0$$

$$\theta = e^{-\int X_1 dx} \left[C + \int X_2 e^{\int X_1 dx} dx \right]$$

$$y = e^{-\int X_1 dx}$$

$$X_1 = (k-1) \frac{2}{x} \log \frac{r-a}{2}$$

$$\int X_1 dx = (k-1) \log \frac{r-a}{2} \quad \varphi(y, z) = \log \left(\frac{r-a}{2} \right)^{k-1}$$

$$e^{\int X_1 dx} = \left(\frac{r-a}{2} \right)^{k-1}$$

$$X_2 = \frac{2 \mu (k-1)}{R} \frac{u_0 a^2}{\rho_0} \frac{r^2 - \frac{x^2}{3}}{2^6}$$

$$\theta = \left(\frac{r}{r-a} \right)^{k-1} \left[C + \frac{2 \mu (k-1) u_0 a^2}{R \rho_0} \int_0^x \frac{r^2 - \frac{x^2}{3}}{2^6} \left(\frac{r-a}{2} \right)^{k-1} dx \right]$$

~~Es muss ein typischer Wert für θ gewählt werden, um die Integration zu ermöglichen.~~

So kann man folgern:

$$\text{Da } x = -\infty: \quad \theta = \theta_0 \quad \text{muss. at } y, z$$

$$\int_0^{\infty} \frac{r^2 - \frac{x^2}{3}}{2^6} \left(\frac{r-a}{2} \right)^{k-1} dx = \varphi(y, z)$$

$$\theta_{-\infty} = f(y, z) + \frac{2 \mu (k-1) u_0 a^2}{R \rho_0} \varphi(y, z)$$

$$f(y, z) = \theta_{-\infty} + \frac{2 \mu (k-1) u_0 a^2}{R} \varphi(y, z)$$

$$\theta = \left(\frac{r}{r-a}\right)^{k-1} \left[\theta_{\infty} + \frac{2\mu(k-1)u_0 a^2}{2\rho_0} \int_{-\infty}^x \frac{r^2 - \frac{x^2}{3}}{2b} \left(\frac{r-a}{r}\right)^{k-1} dx \right]$$

wie in der Vorlesung
zu prüfen

$$p_{xx} = \frac{4}{3}\mu \frac{\partial u}{\partial x}$$

$$p_{rz} = 0$$

$$p_{yy} = p_{zz} = -\frac{2}{3}\mu \frac{\partial u}{\partial x}$$

$$p_{xy} = \mu \frac{\partial u}{\partial y}$$

$$p_{xz} = \mu \frac{\partial u}{\partial z}$$

$$\frac{\partial u}{\partial x} = \frac{u_0 a x}{r^3}$$

$$\frac{\partial u}{\partial y} = \frac{u_0 a y}{r^3}$$

$$\frac{\partial u}{\partial z} = \frac{u_0 a z}{r^3}$$

$$p_{xx} = \frac{u_0 a \mu}{r^4} \left(\frac{4}{3} x^2 + y^2 + z^2 \right) = \frac{u_0 a \mu}{r^4} \left(r^2 + \frac{x^2}{3} \right)$$

$$p_{xy} = \frac{u_0 a \mu}{r^4} \left(xy - \frac{2}{3} yx \right) = \frac{u_0 a \mu}{r^4} \frac{xy}{3}$$

$$p_{xz} = \frac{u_0 a \mu}{r^4} \left(xz - \frac{2}{3} xz \right) = \frac{u_0 a \mu}{r^4} \frac{xz}{3}$$

$$\sum p_{xy} = 0 \quad \sum p_{xz} = 0$$

$$\sum p_{xx} = \frac{u_0 a \mu}{a^4} a^2 \int_0^{2\pi} \int_0^{\pi} \left(1 + \frac{\cos^2 \theta}{3} \right) 2\pi a^2 \sin \theta d\theta$$

$$= u_0 a \mu \cdot 2\pi \left(-\cos \theta - \frac{\cos^3 \theta}{9} \right) \Big|_0^{\pi} = 2\pi u_0 a \mu \cdot \frac{20}{9} = \frac{40}{9} a \pi u_0 \mu$$

Wise zu korrekten Ergebnissen mit dieser Formel:

$$\frac{4}{3} a^3 \pi \rho g = \frac{40}{9} a \pi u_0 \mu$$

$$u_0 = \frac{3}{10} a^2 \frac{\rho g}{\mu}$$

Przy tym samym przybliżeniu dla węzła nie występuje żadne ruch żużla u.v.v na powierzchni $z=0$.

Niech w zarysowanym naszym otęgnięciu ruch, który uwzględniamy: $\frac{\partial u}{\partial x}$ ~~stwierdzenie~~
 wtedy jednak żużel nie porusza się, ponieważ uwzględniamy $\frac{\partial u}{\partial x}$ etc.

$$\rho \frac{\partial u}{\partial t} = -\frac{\partial p}{\partial x} + \mu \nabla^2 u \quad \left. \begin{array}{l} \rho = \rho_0 \end{array} \right\}$$

$$\rho \frac{\partial v}{\partial t} = -\frac{\partial p}{\partial y} + \mu \nabla^2 v \quad \left. \begin{array}{l} \text{z uwzględnieniem} \end{array} \right\}$$

$$\rho \frac{\partial w}{\partial t} = -\frac{\partial p}{\partial z} + \mu \nabla^2 w$$

$$\frac{\partial}{\partial x}(\rho \frac{\partial u}{\partial t}) + \frac{\partial}{\partial y}(\rho \frac{\partial v}{\partial t}) + \frac{\partial}{\partial z}(\rho \frac{\partial w}{\partial t}) = \mu \nabla^2 (\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}) = 0$$

$$\frac{\partial \rho}{\partial t} + \frac{\partial (\rho u)}{\partial x} + \frac{\partial (\rho v)}{\partial y} + \frac{\partial (\rho w)}{\partial z} = 0$$

$$\rho \frac{\partial}{\partial t} \left[\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right] + \left[\frac{\partial \rho}{\partial x} \frac{\partial u}{\partial t} + \frac{\partial \rho}{\partial y} \frac{\partial v}{\partial t} + \frac{\partial \rho}{\partial z} \frac{\partial w}{\partial t} \right] = 0$$

$$\frac{\partial \rho}{\partial t} + \rho \left[\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right] + u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} = 0$$

$$\frac{\partial \rho}{\partial t} + \rho \left[\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right] + \rho \left[\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right] + \frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} = 0$$

Stożek statyczny test:

$$\mu \nabla^2 u = \frac{\partial p}{\partial x}$$

$$\frac{c}{A} \rho \frac{\partial \theta}{\partial t} + \rho \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = 2 \rho \left[\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right]$$

$$\mu \nabla^2 v = \frac{\partial p}{\partial y}$$

$$\mu \nabla^2 w = \frac{\partial p}{\partial z}$$

$$\frac{1}{\rho} \frac{\partial \rho}{\partial t} + \left[\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right] = 0$$

$$\frac{\partial}{\partial t} (\log \rho) + \log \rho = \log \rho - \log \theta - \log R$$

Ja znowu ρ w rachunku nie ma, tylko θ i R i ich pochodne
 znowu terminy? Zauważymy: imitacja terminu:

$$v = u = 0$$

$$\mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) = \frac{\partial f}{\partial x}$$

$$\frac{\partial}{\partial x} (\rho u) = 0 \Rightarrow \rho u = \text{const} = f(y, z)$$

$$\frac{c}{A} \rho u \frac{\partial \theta}{\partial x} + R \rho \theta \frac{\partial u}{\partial x} = 2\mu \left[-\frac{1}{3} \left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial z} \right)^2 + \left(\frac{\partial u}{\partial y} \right)^2 \right]$$

Stąd mamy:

$$\mu \nabla^2 u = \frac{\partial f}{\partial x} \quad f = f(x)$$

$$\frac{\rho u}{\theta} = f(y, z)$$

$$\frac{c}{AR} u \frac{1}{\theta} \frac{\partial \theta}{\partial x} + \rho \frac{\partial u}{\partial x} = 2\mu \left[\frac{2}{3} \left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial y} \right)^2 + \left(\frac{\partial u}{\partial z} \right)^2 \right]$$

$$\rho(x) \frac{u}{\theta} = f(y, z) \quad \mu = \frac{\theta}{u} f(y, z)$$

$$\frac{u}{\theta} \frac{\partial \rho}{\partial x} + \rho \frac{\partial}{\partial x} \left(\frac{u}{\theta} \right) = 0 \quad \mu \nabla^2 u = \frac{\partial f}{\partial x} = f(y, z) \frac{\partial}{\partial x} \left(\frac{\theta}{u} \right)$$

$$\mu \nabla^2 u = R \left(\theta \frac{\partial \rho}{\partial x} + \rho \frac{\partial \theta}{\partial x} \right)$$

$$\mu \left| \begin{array}{l} \rho u = f(y, z) \\ \rho \theta = \rho(x) \end{array} \right.$$

$$\frac{c}{A} \rho u \frac{\partial \theta}{\partial x} + R \rho \theta \frac{\partial u}{\partial x} = 2\mu \left[\frac{2}{3} \left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial y} \right)^2 + \left(\frac{\partial u}{\partial z} \right)^2 \right]$$

$$\left(\frac{c}{A} + R \right) \rho u \frac{\partial \theta}{\partial x} + R \left(\theta u \frac{\partial \rho}{\partial x} + \rho \theta \frac{\partial u}{\partial x} \right) = \mu \left[u \nabla^2 u + 2 \left(\frac{2}{3} \left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial y} \right)^2 + \left(\frac{\partial u}{\partial z} \right)^2 \right) \right]$$

by motion equations from $\theta = f(r)$?

$$\text{rot } \rho = \varphi(r) = \frac{k}{R f(r)}$$

$$\left. \begin{aligned} \mu \nabla^2 u &= \frac{\partial f}{\partial x} \\ \mu \nabla^2 v &= \frac{\partial f}{\partial y} \\ \mu \nabla^2 w &= \frac{\partial f}{\partial z} \end{aligned} \right\} \quad \begin{aligned} &\frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} = 0 \\ &\downarrow \\ \text{I). } \rho \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} &= 0 \end{aligned}$$

$$\text{II). } \frac{c}{A} \rho \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) + f \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = 2\mu \dots$$

$$\text{III). } \frac{c}{A} \varphi(r) f(r) \left(u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + w \frac{\partial f}{\partial z} \right) + f \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = \dots$$

$$\text{I). } \varphi(r) \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + \varphi'(r) \left(u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + w \frac{\partial f}{\partial z} \right) = 0 \quad f(r) = \frac{k}{R \varphi(r)}$$

$$\text{I). } u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} = \mu (u \nabla^2 u + v \nabla^2 v + w \nabla^2 w) \quad f'(r) = \frac{1}{R} \left[\frac{1}{\varphi(r)} - \frac{r \varphi'(r)}{\varphi(r)^2} \right]$$

$$\frac{\varphi'(r)}{\varphi(r)} = - \frac{\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}}{\mu (u \nabla^2 u + v \nabla^2 v + w \nabla^2 w)}$$

$$\frac{c}{A} \varphi(r) f(r) \mu (u \nabla^2 u + v \nabla^2 v + w \nabla^2 w) \pm \mu \mu [u \Delta u + \dots] \frac{\varphi'(r)}{\varphi(r)} = 2\mu [\dots]$$

$$(u \nabla^2 u + v \nabla^2 v + w \nabla^2 w) \left[\frac{c}{A} \varphi(r) f(r) - \mu \frac{\varphi'(r)}{\varphi(r)} \right] = 2\mu \left[-\frac{1}{3} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)^2 + \frac{\partial^2 u}{\partial x^2} \mu \right]$$

$$\left[\frac{c}{AR} \left(1 - \frac{r \varphi'(r)}{\varphi(r)} \right) - \frac{r \varphi'(r)}{\varphi(r)} \right]$$

$$AR = C - c$$

$$\frac{c}{C-c} = \frac{1}{k-1}$$

$$\left[\frac{1}{k-1} - \frac{k}{k-1} \frac{r \varphi'(r)}{\varphi(r)} \right]$$

Zalozenie Klein sie robi ~~z~~ w tenyż Hall-Thomson: $\theta = \text{const}$
 $f = \theta_0$

$$\varphi = \frac{f}{R \theta_0}$$

$$\varphi' = \frac{1}{R \theta_0}$$

$$f \cdot \varphi' = 1$$

$$\left[\frac{1 - \frac{f}{R}}{R^2} \right]$$

Wtedy:

$$-(u \nabla^2 u + v \nabla^2 v + w \nabla^2 w) = 2 \left[-\frac{1}{3} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)^2 + \dots \right]$$

$$\begin{aligned} 3(u \nabla^2 u + v \nabla^2 v + w \nabla^2 w) - 2 \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)^2 + 6 \left[\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial y} \right)^2 + \left(\frac{\partial w}{\partial z} \right)^2 \right] + \\ + 3 \left[\left(\frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} \right)^2 + \left(\frac{\partial u}{\partial z} + \frac{\partial v}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)^2 \right] = 0 \end{aligned}$$

W jednowymiarowej przy założeniu $v = w = 0$:

$$3 u \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) - 2 \left(\frac{\partial u}{\partial x} \right)^2 + 6 \left(\frac{\partial u}{\partial x} \right)^2 + 3 \left(\frac{\partial u}{\partial z} \right)^2 + 3 \left(\frac{\partial u}{\partial y} \right)^2 = 0$$

$$4 \left(\frac{\partial u}{\partial x} \right)^2 + 3 u \frac{\partial^2 u}{\partial x^2} + 3 \left[u \frac{\partial^2 u}{\partial y^2} + \left(\frac{\partial u}{\partial y} \right)^2 + u \frac{\partial^2 u}{\partial z^2} + \left(\frac{\partial u}{\partial z} \right)^2 \right] = 0$$

$$\frac{\partial}{\partial y} \left(u \frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial z} \left(u \frac{\partial u}{\partial z} \right)$$

Jednowymiarowa przy założeniu:

$$4 \left(\frac{\partial u}{\partial x} \right)^2 + 3 u \frac{\partial^2 u}{\partial x^2} = 0$$

$$4 \frac{\frac{\partial u}{\partial x}}{u} + 3 \frac{\frac{\partial^2 u}{\partial x^2}}{\frac{\partial u}{\partial x}} = 0$$

$$\text{czy } \left[u \cdot \left(\frac{\partial u}{\partial x} \right)^3 \right] = \text{const}$$

$$\frac{du}{dx} \cdot u^{\frac{4}{3}} = C$$

$$\frac{3}{7} u^{\frac{7}{3}} = Cx + C_0$$

✓ pages 1 rec

$$\frac{\partial f}{\partial x} = \mu \nabla^2 u$$

tylko przez J. pxx w d. 12. 18. 18.

$$\iiint_V \left(u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + w \frac{\partial f}{\partial z} \right) dV = \iint_S u f dy dz + v f dx dz + w f dx dy - \iiint_V f \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) dx dy dz$$

$$= \int_V f(u \cos \alpha x + v \sin \alpha x + w) dV - \iint_T f\left(\frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + \frac{\partial u}{\partial y} \frac{\partial v}{\partial x}\right) dV$$

$$2 \text{ at } \left(\frac{\partial u}{\partial x} + \dots \right) + u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} = 0$$

$$\mu \int_V (\Delta u + \dots) dv = W_p -$$

The first of these premises ~~are~~ ^{are} given & I shall assume the rest
 necessary, to obtain the proposition before us as a consequence.

$$W_{PI} = \mu \iiint (\mathbf{u} \Delta^2 \mathbf{u} + \dots) d\mathbf{v} + \iiint p \left(\frac{\partial \mathbf{u}}{\partial x} + \dots \right) d\mathbf{v}$$

$$= \iiint p (\mathbf{u} \cdot \mathbf{l} + \mathbf{v} \cdot \mathbf{m} + \mathbf{w} \cdot \mathbf{n}) dS$$

also tis ~~pres~~ ~~frankly~~ Φ :

$W_{II} = \iint \Phi \, d\mathbf{r}$ to obtain same value

II III

W_{PI} first principle isoperimetry = $p_2 \int_2^3 (u + v + w) ds - p_1 \int_1^2 (u + v) ds$

joint

47. Równanie węgloni daje dla dowolnego przekroju prędkość uprządkowaną
 $\rho_0 dV$:

$$\int \rho(u + v + w) dV = \text{const} = m$$

gdyż ρ tylko $\rho(p)$, ^{$\rho = \rho(p)$} stąd ~~przekroju~~ dla tego samego przekroju: ^(invariant)

$$\rho_1 \int_1 = \rho_2 \int_2$$

$$\rho_1 \int_1 - \rho_2 \int_2 = 0 \quad f(p)_1 \int_1 - f(p)_2 \int_2 = 0$$

skąd z tego samego niezmiennika: $\rho_1 \int_1 - \rho_2 \int_2 = 0$

czyli $f(p) \sim p$, to energia w układzie inercyjnym

Inercyj ^{$W_{p=0}$} równanie to musi być spełnione tylko w szczególnym
 przypadku.

$$\sqrt{1-x^2} = \int \frac{1}{\sqrt{1-x^2}} dx = \arcsin x + C$$

$$= \left[\frac{1}{2} \ln \left| \frac{1+x}{1-x} \right| \right]_{-1}^1$$

$$= \frac{1}{2} \left[\ln \left| \frac{1+1}{1-1} \right| - \ln \left| \frac{1-1}{1+1} \right| \right]$$

$$= \frac{1}{2} \left[\ln \left| \frac{2}{0} \right| - \ln \left| \frac{0}{2} \right| \right]$$

$$= \left[\ln \left| \frac{1+x}{1-x} \right| \right]_{-1}^1$$

$$= \ln \left| \frac{1+1}{1-1} \right| - \ln \left| \frac{1-1}{1+1} \right|$$

$$= \ln \left| \frac{2}{0} \right| - \ln \left| \frac{0}{2} \right|$$

$$= \ln \left| \frac{2}{0} \right| - \ln \left| \frac{0}{2} \right|$$

$$= \ln \left| \frac{2}{0} \right| - \ln \left| \frac{0}{2} \right|$$

$$= \ln \left| \frac{2}{0} \right| - \ln \left| \frac{0}{2} \right|$$

$$\ln \sqrt{1-x^2} = \frac{1}{2} \ln(1-x^2)$$

$$= \frac{1}{2} \ln(1-x^2)$$

$$\iint_V \rho \, dV = \iint_V \rho \, dV - \iint_V \rho \, dV = 0$$

100

$$\int \Phi \, dV = \mu \, dx \, dy \, dz \left\{ -\frac{2}{3} \left[\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial y} \right)^2 + \left(\frac{\partial w}{\partial z} \right)^2 + 2 \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + 2 \frac{\partial u}{\partial x} \frac{\partial w}{\partial z} + 2 \frac{\partial v}{\partial y} \frac{\partial w}{\partial z} \right] + \right.$$

$$2 \left(\frac{\partial u}{\partial x} \right)^2 + 2 \left(\frac{\partial v}{\partial y} \right)^2 + 2 \left(\frac{\partial w}{\partial z} \right)^2 + \left. \frac{\partial u}{\partial y} \right)^2 + 2 \frac{\partial u}{\partial y} \frac{\partial v}{\partial x} + \left(\frac{\partial v}{\partial x} \right)^2 + \dots \right.$$

$$+ \frac{1}{3} \left[\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial y} \right)^2 + \left(\frac{\partial w}{\partial z} \right)^2 \right] + \left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial y} \right)^2 + \left(\frac{\partial w}{\partial z} \right)^2 + \dots +$$

$$+ 2 \left[\frac{\partial u}{\partial y} \frac{\partial v}{\partial x} + \frac{\partial u}{\partial z} \frac{\partial w}{\partial x} + \frac{\partial v}{\partial z} \frac{\partial w}{\partial y} - \frac{2}{3} \left(\frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + \frac{\partial v}{\partial y} \frac{\partial w}{\partial z} + \frac{\partial w}{\partial z} \frac{\partial u}{\partial x} \right) \right]$$

$$= \iint \left[\frac{1}{3} \left(u \frac{\partial u}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial w}{\partial z} \right) + \dots \right] dV + \underbrace{\iint u \left(\frac{\partial u}{\partial x} l + \frac{\partial u}{\partial y} m + \frac{\partial u}{\partial z} n \right) + \dots}_{= \iint \frac{1}{2} \frac{\partial(u^2 + v^2 + w^2)}{\partial n} dS} dV$$

$$+ 2 \left[u \frac{\partial v}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial u}{\partial z} - \frac{2}{3} \left(u \frac{\partial v}{\partial y} + v \frac{\partial w}{\partial z} + w \frac{\partial u}{\partial x} \right) \right] dV$$

$$- \iint \frac{1}{3} \left(u \frac{\partial u}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial w}{\partial z} \right) dV = \iint \frac{1}{3} (u \nabla^2 u + v \nabla^2 v + w \nabla^2 w) dV =$$

$$- 2 \iint \left[u \frac{\partial v}{\partial x \partial y} + v \frac{\partial w}{\partial y \partial z} + w \frac{\partial u}{\partial z \partial x} - \frac{2}{3} \left(u \frac{\partial v}{\partial x \partial y} + v \frac{\partial w}{\partial y \partial z} + w \frac{\partial u}{\partial z \partial x} \right) \right] dV =$$

$$= \frac{1}{3} \iint \left(u \frac{\partial u}{\partial x} l + v \frac{\partial v}{\partial y} m + w \frac{\partial w}{\partial z} n \right) dS + \frac{1}{2} \iint \left(l^2 + m^2 + n^2 \right) dS +$$

$$\left\{ \iint \left[u \frac{\partial v}{\partial x} m + v \frac{\partial w}{\partial y} n + w \frac{\partial u}{\partial z} l + v \frac{\partial u}{\partial y} l + u \frac{\partial v}{\partial z} m + u \frac{\partial w}{\partial x} n \right] - \right. \\ \left. \iint \left[-\frac{2}{3} \left[u \frac{\partial v}{\partial y} l + v \frac{\partial w}{\partial z} m + w \frac{\partial u}{\partial x} n + v \frac{\partial u}{\partial x} m + u \frac{\partial v}{\partial y} n + u \frac{\partial w}{\partial z} l \right] \right] dS \right\}$$

$$- \frac{1}{3} \iiint \left(u \frac{\partial^2 u}{\partial x^2} + v \frac{\partial^2 v}{\partial y^2} + w \frac{\partial^2 w}{\partial z^2} \right) dv - \iiint \left(u \nabla^2 u + v \nabla^2 v + w \nabla^2 w \right) dv -$$

$$- \iiint \left[u \frac{\partial^2 v}{\partial x \partial y} + v \frac{\partial^2 w}{\partial y \partial z} + w \frac{\partial^2 u}{\partial z \partial x} + v \frac{\partial^2 u}{\partial x \partial y} + u \frac{\partial^2 v}{\partial y \partial z} + u \frac{\partial^2 w}{\partial z \partial x} - \right. \\ \left. - \frac{2}{3} \left[u \frac{\partial^2 v}{\partial x \partial y} + v \frac{\partial^2 w}{\partial y \partial z} + w \frac{\partial^2 u}{\partial z \partial x} + v \frac{\partial^2 u}{\partial x \partial y} + u \frac{\partial^2 v}{\partial y \partial z} + u \frac{\partial^2 w}{\partial z \partial x} \right] \right] dv$$

$$\iiint = -\frac{1}{3} \iiint \left[u \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial x \partial y} + \frac{\partial^2 w}{\partial x \partial z} \right) + v \left(\frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 u}{\partial x \partial y} + \frac{\partial^2 w}{\partial y \partial z} \right) + w \left(\frac{\partial^2 w}{\partial z^2} + \frac{\partial^2 u}{\partial z \partial x} + \frac{\partial^2 v}{\partial y \partial z} \right) \right] dv \\ - \iiint \left(u \nabla^2 u + v \nabla^2 v + w \nabla^2 w \right) dv$$

$$\iiint = -\frac{1}{3} \iiint \left(u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) dv \\ - \iiint \left(u \nabla^2 u + v \nabla^2 v + w \nabla^2 w \right) dv$$

$$\iiint = \frac{1}{2} \iint \frac{\partial}{\partial n} (l^2 + m^2 + n^2) dS + \iiint \left[u \left[l \frac{\partial u}{\partial x} + m \frac{\partial v}{\partial x} + n \frac{\partial w}{\partial x} \right] + v \left[l \frac{\partial u}{\partial y} + m \frac{\partial v}{\partial y} + n \frac{\partial w}{\partial y} \right] + w \left[l \frac{\partial u}{\partial z} + m \frac{\partial v}{\partial z} + n \frac{\partial w}{\partial z} \right] \right. \\ \left. - \frac{2}{3} \left[u l \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + v m \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + w n \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) \right] \right] dS$$

$$\int \Phi d\sigma = \frac{1}{2} \int \frac{\partial}{\partial n} (u+v+w) d\sigma + \iint (u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z}) (u+v+w) d\sigma -$$

$$- \frac{2}{3} \iint (u+v+w) (\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}) d\sigma -$$

$$- \iiint (u \nabla^2 u + v \nabla^2 v + w \nabla^2 w) dv - \frac{1}{3} \iint (u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z}) (\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}) d\sigma$$

~~The identity used in the last step is: $w_{PI} = w_{PI}$ for total volume~~

$$\frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} = 0$$

$$u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} + \rho (\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}) = 0$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = - \left[u \frac{\partial(\log \rho)}{\partial x} + v \frac{\partial(\log \rho)}{\partial y} + w \frac{\partial(\log \rho)}{\partial z} \right]$$

$$\log \rho = \log r - \log R - \log \theta$$

$$\int \Phi d\sigma = \dots - \iiint (u \nabla^2 u + v \nabla^2 v + w \nabla^2 w) dv -$$

~~$$+ \frac{1}{3} \iint (\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}) (\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}) d\sigma = \frac{1}{\theta} u \frac{\partial \theta}{\partial x}$$~~

$$+ \frac{1}{3} \iint (u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z}) \underbrace{u \frac{\partial(\log r - \log \theta)}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z}}_{\dots} dv$$

$$\frac{1}{r} (u \frac{\partial r}{\partial x} + v \frac{\partial r}{\partial y} + w \frac{\partial r}{\partial z}) - \frac{1}{\theta} (u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z})$$

$$= - (\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z})$$

$$\iint r (\frac{\partial u}{\partial x} + \dots) d\sigma = - \iiint (u \frac{\partial r}{\partial x} + v \frac{\partial r}{\partial y} + w \frac{\partial r}{\partial z}) dv + \iint \rho (u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z}) dv$$

$$W_{PI} = R \iiint \rho \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) dv = \text{scribbled out}$$

$$\begin{aligned} &= R \iint \rho (u \theta_l + v \theta_m + w \theta_n) dS - R \iiint \theta \left[\frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} \right] dv \\ &= R \iint \rho \theta (u_l + v_m + w_n) dS = \iint (\rho u_l + \dots) \end{aligned}$$

$$\rho \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + \left(u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} \right) = R \rho \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right)$$

$$IV. \rho \left(\frac{\partial u}{\partial x} + \dots \right) + \frac{c}{A} \rho \left(u \frac{\partial \theta}{\partial x} + \dots \right) = \Phi$$

$$\underbrace{\iint \rho \left(\frac{\partial u}{\partial x} + \dots \right) dv}_{\dots} + \underbrace{\frac{c}{A} \iint \rho \left(u \frac{\partial \theta}{\partial x} + \dots \right) dv}_{\dots} = \iiint \Phi dv$$

$$\begin{aligned} &= \iint \rho (u_l + v_m + w_n) dS + \frac{c}{A} \iint \rho \theta (u_l + v_m + w_n) dS \\ &- \iiint \left(\left(u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} \right) - \frac{c}{A} \theta \left[\frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} \right] \right) dv \end{aligned}$$

$$\left(1 + \frac{c}{AR} \right) \iint \rho (u_l + v_m + w_n) dS = \iint (u \nabla u + v \nabla v + \dots) dS + \Phi dv$$

$$u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} = \text{scribbled out}$$

$$\begin{aligned} \frac{k}{k-1} W_{PI} &= \iiint (u \nabla u + v \nabla v + \dots) + \Phi dv \\ \frac{1}{k-1} W_{PI} &= \Phi_r \end{aligned}$$

$$h_{12} = - \iint (\mu \nabla u + \nu \nabla v + \omega \nabla w) d\mathbf{r} \quad || ?$$

$$\begin{aligned} \iint \Phi d\mathbf{r} &= \frac{1}{2} \iint \frac{\partial}{\partial u} (u + v + w) d\mathbf{r} + \iint \left(-\frac{\partial}{\partial x} + \frac{\partial}{\partial y} + \frac{\partial}{\partial z} \right) v d\mathbf{r} - \frac{1}{2} \iint (\mu + \nu + \omega) \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) d\mathbf{r} - \\ &= \iint (\mu \nabla u + \nu \nabla v + \omega \nabla w) d\mathbf{r} + \frac{1}{2} \iint \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)^2 d\mathbf{r} \end{aligned}$$

$$\begin{aligned} V(v, \text{curl } v) &= -V\left(\mu + \frac{\mu + v^2 + w^2}{2}\right) + \underbrace{\mu \nabla v^2}_{= -\mu \text{curl}^2 v} \\ &= -\mu \text{curl}^2 v \end{aligned}$$

$$\text{curl } V(v, \text{curl } v) = -\mu \text{curl}^3 v = \cancel{\mu \text{curl}^2 v} = \mu \nabla^2 \text{curl } v$$

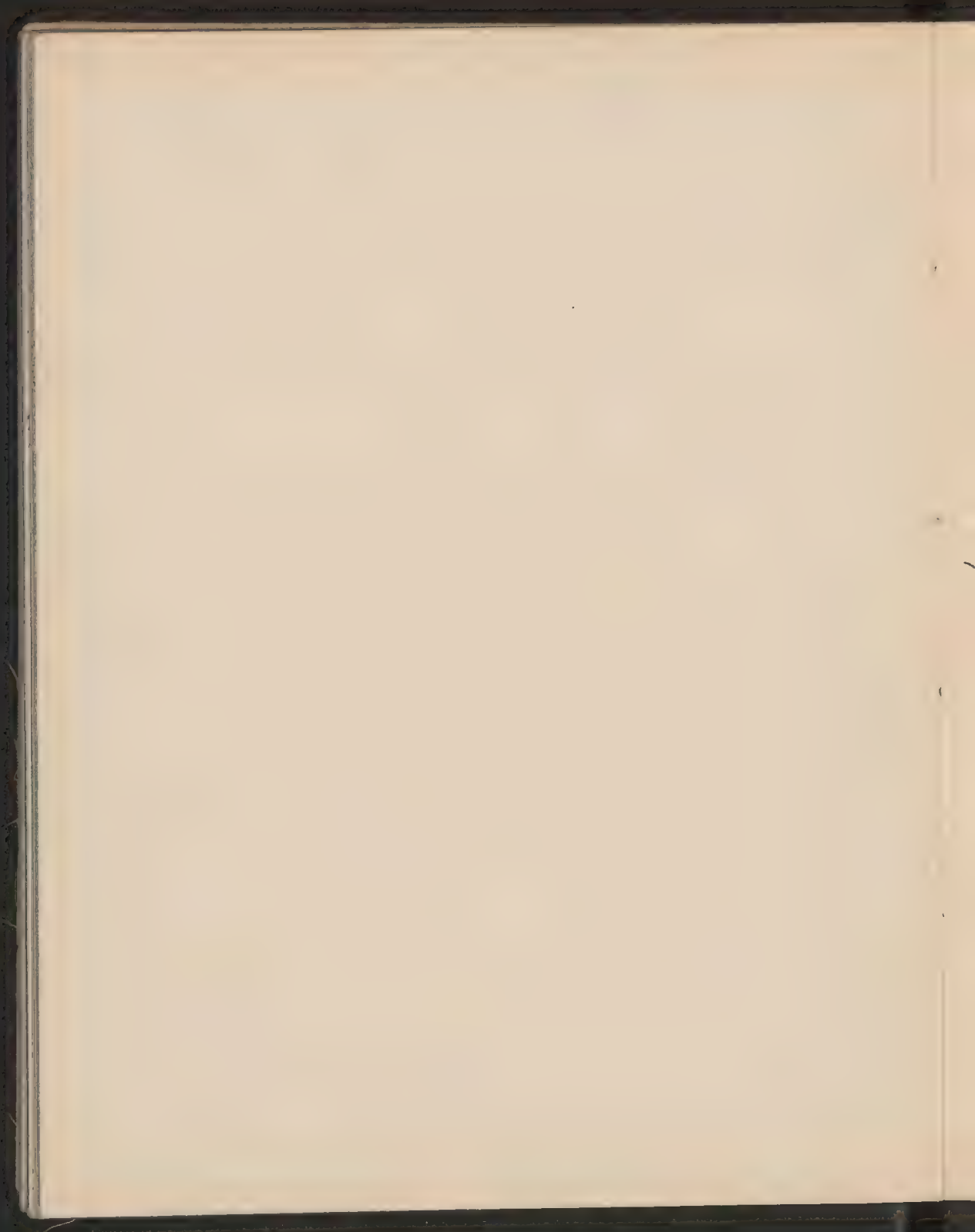
$$\text{div } V(v, \text{curl } v) = (\text{curl } v)^2 - \nabla v, \text{curl}^2 v = -V\left(\mu + \frac{v^2}{2}\right)$$

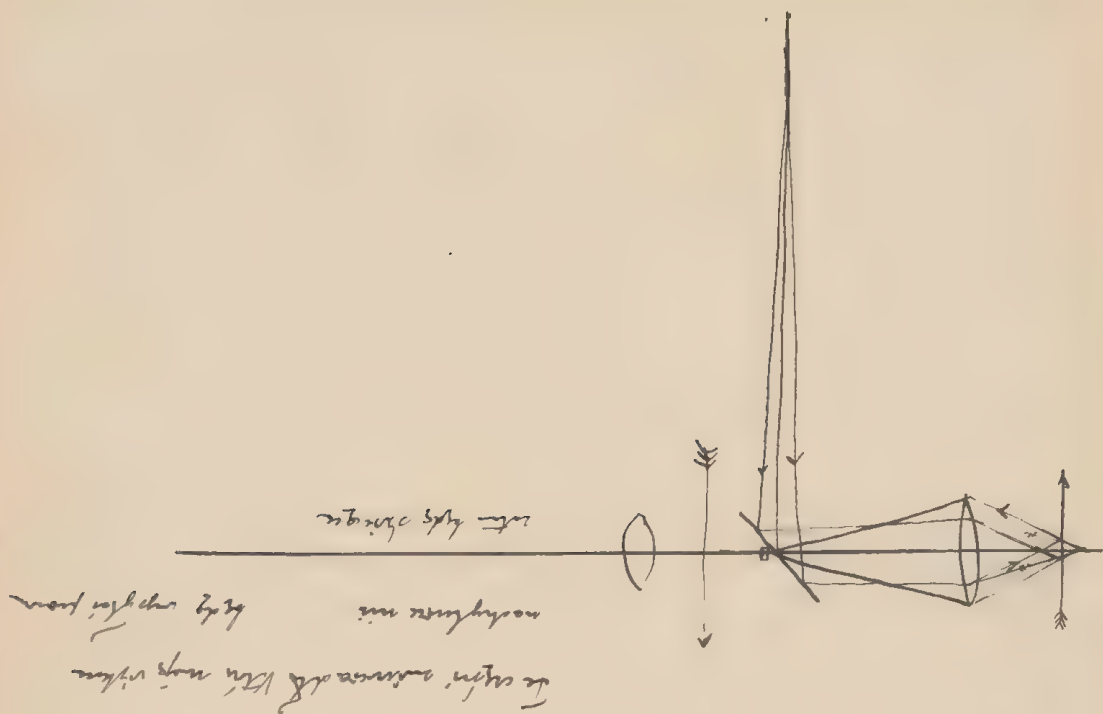
$$\text{Dla tego: } \text{curl } V(v, \text{curl } v) = 0$$

$$V(v, \text{curl } v) = \nabla \mathcal{U}$$

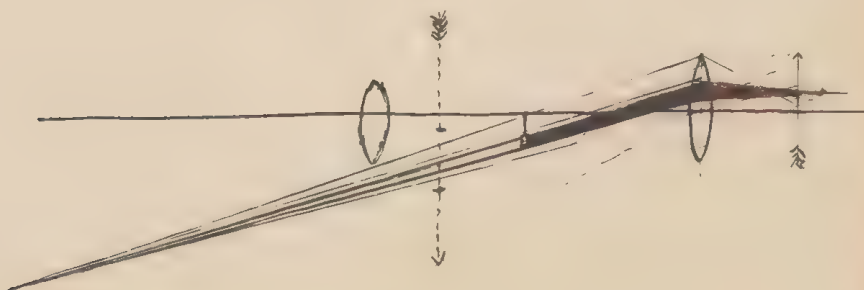
Łączy to jest jedyną unicatyczną funkcję na powierzchni?

Na powierzchni: curl v jest w postaci skalarnej, $v < 0$, ale v kierunek strumienia
gdzie $\nabla \mathcal{U}$ musi się stać $= 0$ na powierzchni nielaminarnej

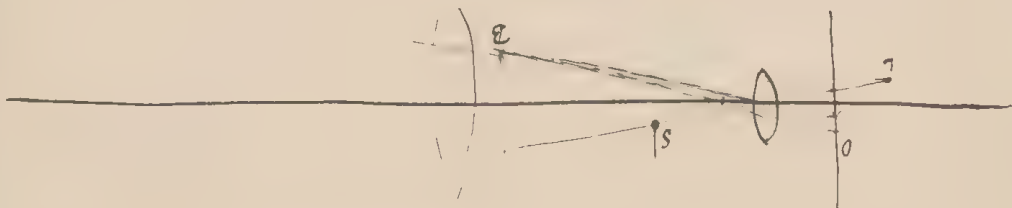




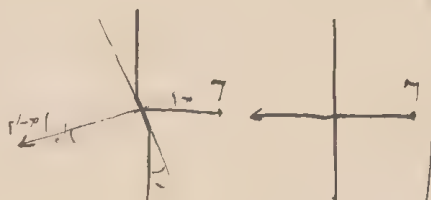
Depositing image in the eye:



then since L is a convex surface, the O point is O type of the point
 of intersection.



$$\begin{aligned} \text{then } n &= n \\ \text{and } da &= n \, dp \\ da &= n \, dp \\ d(x-p) &= (n-1) \, dp \end{aligned}$$

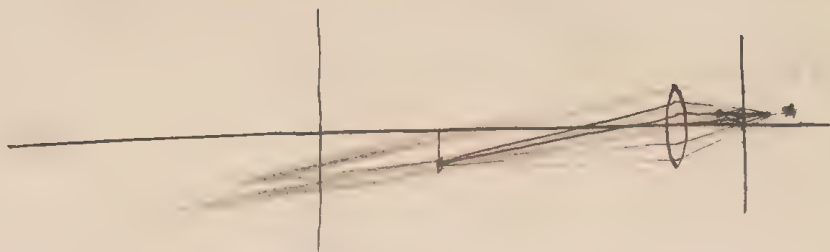


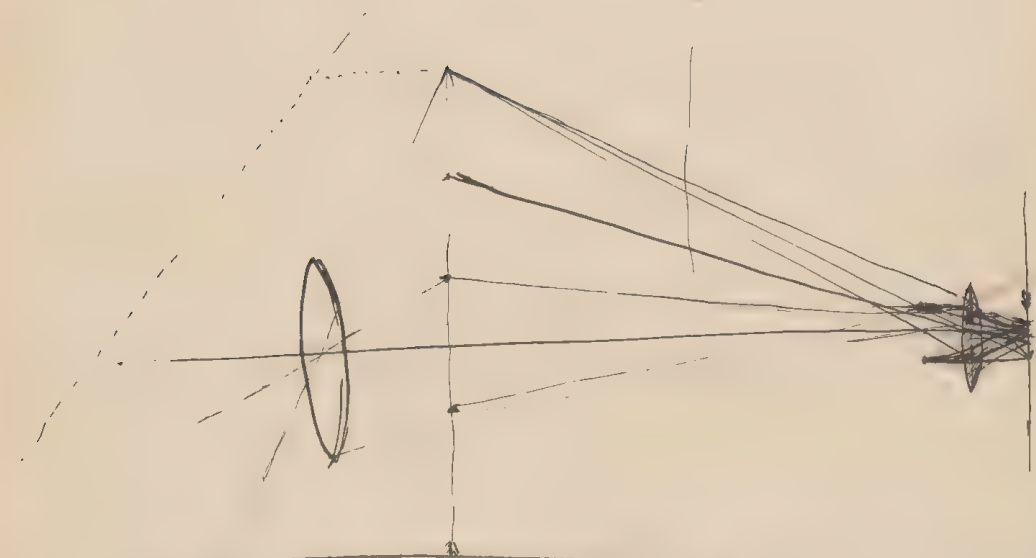
So the ray is refracted at the surface of the lens.

2. In the case of a convex surface, the ray is refracted at the surface of the lens.

(The ray is refracted at the surface of the lens, and the ray is refracted at the surface of the lens.)

then the lens:





Wage with measuring θ of rays & change from θ to θ'

$$= 204 \quad \text{so } 2 \text{ of } \theta' = \frac{10^6}{100} \text{ against } 20\%$$

$$\text{Opt } \Delta u \text{ is max } \frac{z}{2} = z = 0.01 \text{ cm}$$

$$u = 63.4 \text{ cm}$$

to be in position 100 m, for some u

Not. Summary: A. i. p. 100 km

Wage with measuring θ of rays & change from θ to θ'

N. f. pink $\epsilon = 0.01 \text{ cm}$

$$\gamma = 0.00017$$

$$L = 10$$

$$u_1 = a = 0.6 \text{ cm}$$

$$\Delta u = Lc = \frac{Lc}{1.2} = \frac{1.2}{1.2}$$

$$\gamma \Delta u = 0.00017 \cdot 12 \cdot 10^6 = 2.04$$

$$= 20 \cdot 10^{-6} \text{ cm} =$$

$$= 17 \frac{1}{2} = 20$$

$$k - q_2 = 2 \gamma \Delta u = \frac{2 \cdot 20 \cdot 0.00017 \cdot 0.6}{10^{-4}}$$

$$\text{freq } \epsilon = 0.001 \text{ cm}$$

$$\text{freq } \epsilon = 204 \text{ with } 10^6$$

$$\text{freq } \epsilon = 0.0001 \text{ cm} = 1 \mu \quad \gamma \Delta u = 20400 = 2\%$$

the coupling between ϵ and γ is not (at least in this case)

the coupling between ϵ and γ is not (at least in this case)

$$\text{N. f. } u = \text{radial power } u = 4 \cdot 10^{-6} \left(\frac{\text{cm}}{\text{sec}} \right)$$

$$\text{freq } u = \text{radial power } 1 \text{ cm} \cdot 0.001 \text{ cm}$$

$$\gamma = 4 \gamma \cdot 4 \cdot 10^{-6} = 16 \cdot \gamma = 0.18 \cdot 16 = 0.3$$

the coupling between ϵ and γ is not (at least in this case)

$$\text{freq } u = \text{radial power } 1 \text{ cm} \cdot 0.001 \text{ cm}$$

$$\text{freq } u = \text{radial power } 1 \text{ cm} \cdot 0.001 \text{ cm}$$

$$u_0 = a = -c z^2 = \frac{1}{2} \frac{\partial^2 u}{\partial z^2}$$

$$\int_{-z}^z u dy = \frac{1}{2} \frac{\partial^2 u}{\partial y^2} (z^2 y - \frac{1}{3} y^3) \Big|_{-z}^z = \frac{1}{2} \frac{\partial^2 u}{\partial y^2} \frac{2}{3} (z^3 - (-z^3)) = \frac{2}{3} \frac{\partial^2 u}{\partial y^2} z^3$$

$$2 \frac{\partial^2 u}{\partial y^2} z^3 = \frac{1}{2} \frac{\partial^2 u}{\partial y^2} (z^2 - (-z^2)) = \frac{1}{2} \frac{\partial^2 u}{\partial y^2} (2z^2)$$

$$\begin{cases} 0 = a + b z + c z^2 \\ 0 = a - b z + c z^2 \\ b = 0 \\ a = -c z^2 \end{cases}$$

$$u = 0 \quad y = \pm z$$

$$u = a + b y + c y^2 \quad \frac{\partial^2 u}{\partial y^2} = 2c = 2c$$

$$c = \begin{cases} \frac{1}{2} \frac{\partial^2 u}{\partial y^2} \\ \frac{1}{2} \frac{\partial^2 u}{\partial y^2} \\ \frac{1}{2} \frac{\partial^2 u}{\partial y^2} \end{cases}$$

$$\frac{\partial^2 u}{\partial y^2} = \frac{\partial^2 u}{\partial y^2} \quad u = f(x)$$

$$u = f(x) \quad \frac{\partial^2 u}{\partial x^2} = 0 \quad \frac{\partial^2 u}{\partial y^2} = 0$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0$$

$$\begin{cases} \frac{\partial^2 u}{\partial x^2} = \eta \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) \\ \frac{\partial^2 u}{\partial x^2} = 0 \end{cases} \quad \frac{\partial^2 u}{\partial x^2} = 0$$

$$f = R \theta p \quad p = \frac{r}{20}$$

These people must be who don't understand the meaning of the word 'justice'.

$$\frac{7e}{4e} = \frac{7}{4}$$

$$k \frac{1}{\frac{\partial x}{\partial t}} = u' - u$$

Study $u_1 = u_2 = -k$

also jekt' gredt in m'foda to na Ht: jekt: vammud p = jekt = endt

2000-1900

$$u = a + by + cy^2$$

1. $\lambda = 0.3 \text{ mm}$

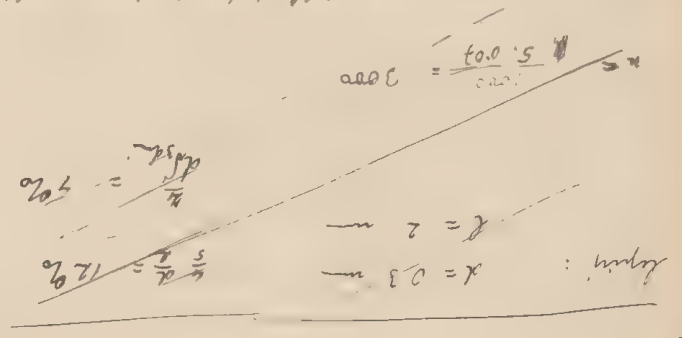
$\lambda = 3 \text{ mm}$

$$p = \frac{0.3^2}{2} \cdot \frac{28.26}{1} = 0.07$$

$$\frac{2}{\lambda} = \frac{2}{0.3} = 6.67$$

$$\frac{\lambda}{2} = \frac{0.3}{2} = 0.15 \text{ mm}$$

$$r = 3000$$



$$\frac{\lambda}{2} = 0.15 \text{ mm}$$

$$p = \frac{0.005}{5.007} = 0.000998$$

Concentration maximum in center of
 ring spot radius: $\lambda = 0.3 \text{ mm}$ and $\lambda = 3 \text{ mm}$
 ring spot radius: $\lambda = 0.3 \text{ mm}$ and $\lambda = 3 \text{ mm}$
 ring spot radius: $\lambda = 0.3 \text{ mm}$ and $\lambda = 3 \text{ mm}$

$$u_2 = 0$$

H₂O



$$u_1 \neq 0.1$$

$$dS = k q \frac{\partial u}{\partial x} dt$$

$$\frac{\partial u}{\partial x} = \frac{u_1 - u_0}{0.1} = \frac{1}{0.1} = 0.1$$

$$k = 40 \cdot 10^{-7}$$

$$= 1 \text{ cm}^2 \text{ packing} = 1 \text{ mm}^2$$

While not within packing, pink dye is not

At the do membrane dyeing

$$dS = 0.01 \cdot 0.1 \cdot 40 \cdot 10^{-7} \cdot 60 \cdot 60 = 4.6 \cdot 6 \cdot 10^{-7} = \frac{144}{36.4} \cdot 10^{-7} \text{ g}$$

$$= 1.4 \cdot 10^{-5} \text{ g}$$

$$dS \text{ per division} = \frac{1.44 \cdot 10^{-5}}{5.76} = 3.5 \cdot 10^{-7} = 3.5 \text{ mg per 3 dm} = 105 \text{ mg}$$

2 = "saturated" units: $0.01 \cdot 0.1 = 1 \text{ mg}$; also meaning dye making per population

$$\frac{dS}{dt} = \frac{100\%}{2} \text{ per unit time}$$

All the stationary making dye units are at the boundary of the unit

the "saturated" units; pink dye is $1 \text{ mm} \cdot \frac{1}{2} \text{ per 10} = 1\%$

which makes a small number in the stationary making the packing population

2 = "saturated" units: dye making $x + \frac{1}{2} x$

$$\frac{dS}{dt} = 0.1 \text{ mm} = \frac{1}{2} x = 8\%$$

which makes a small number in the stationary making the packing population

$$10^3 \cdot 10 = 10^4 \text{ units}$$

2. type photomicro. ok. 10:10

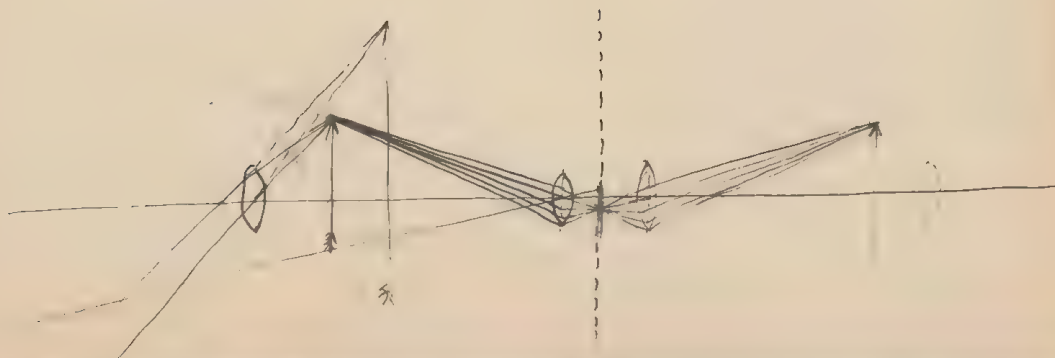
ok. 10:10

1000 500 10.1 10.507 10.507

$\alpha = 0.36$
 $\alpha = 0.9$
 $\alpha = 0.9$

$\alpha' = 0.08$

No. 27 cm : 10 = 5 mm



$$\begin{aligned} a &= 280 \\ b &= 102.3 \\ c &= 9.3 \end{aligned}$$

$$\frac{1}{2} \log \left(\frac{669.3}{655.3} \right)$$

$$\begin{aligned} 102.3 \\ 204.6 \\ 306.9 \\ 409.2 \\ 511.5 \\ 613.8 \\ 716.1 \\ 818.4 \\ 920.7 \\ 1023.0 \end{aligned}$$

$$\begin{aligned} 82.562 \\ - 41.644 \\ \hline 40.918 \end{aligned}$$

$$\begin{aligned} 96.284 - 3 \\ + 36.212 \\ \hline 132.496 - 2 \\ - 0.84510 \\ \hline 131.6509 - 3 \end{aligned}$$

$$\begin{aligned} \mu &= 252.004 \\ - 251.322 \\ \hline 0.00682 \end{aligned}$$

$$1.016$$

The μ/λ instrument is highly: 1.6% probably the instrument is (the μ/λ instrument is highly: 1.33%)

Dr. J. K. Thompson, M.D., M.P.H.

N.P. y = 0.002 standardizing within 1 - x = 1

$$1 + \rho \frac{z}{\theta} (1 - \frac{z}{x}) = 1 + 0.002 \cdot 100 \frac{z}{1} \approx 1 + 0.05$$

mg. count $\theta_1 = \theta_3 \dots 98$

98	326.5	278	280
57749	44716	13033	
0.11504	0.6222	2.53388	1.99115
			0.00009
			1.99114

Dr. J. K. Thompson, M.D., M.P.H.

$$\int_0^1 \frac{dx}{280 + \frac{x}{\theta} \theta_1 [1 + \rho \frac{z}{\theta} (1 - \frac{z}{x})]} \neq \int_0^1 \frac{dx}{280 + \frac{x}{\theta} \theta_1 [1 + 0.1 (1 - \frac{z}{x})]}$$

$$= \int_0^1 \frac{dx}{280 + 1.1 \theta_1 x - 0.1 \theta_1 x^2} = k \int_1^0 \frac{dz}{280 + 1.1 \theta_1 z - 0.1 \theta_1 z^2}$$

$$\int \frac{dx}{a + bx - cx^2} = \frac{1}{\sqrt{b^2 - 4ac}} \ln \frac{b + 2cx - \sqrt{b^2 - 4ac}}{b + 2cx + \sqrt{b^2 - 4ac}} = \frac{1}{\sqrt{b^2 - 4ac}} \ln \frac{b + 2c - \sqrt{b^2 - 4ac}}{b + 2c + \sqrt{b^2 - 4ac}}$$

$$\frac{kx + 26c - 2c\sqrt{b^2 - 4ac}}{kx + 26c + 2c\sqrt{b^2 - 4ac}} = \frac{b - \sqrt{b^2 - 4ac}}{b + \sqrt{b^2 - 4ac}} + 2a$$

To get minimum value of obj. function

$$k = 0.9932 \text{ } \mu$$

$$\begin{array}{r} 1.96848 \\ -1.97144 \\ \hline 0.99704 \end{array}$$

$$\begin{array}{r} 0.9534 - 1 \\ 0.36222 \\ 2.51388 \\ \hline 1.97144 \end{array}$$

$$\begin{array}{r} 57171 \\ 44716 \\ \hline 0.12455 \end{array}$$

$$\begin{array}{r} 326.5 \\ 290 \\ \hline \frac{1}{2} = 465 \end{array}$$

$$\begin{array}{r} 93 \\ 326.57 \\ \hline 323 \end{array}$$

$$\theta_1 = 93$$

$$= \mu_0 \frac{1}{\frac{1}{280+50} - \frac{1}{2} \frac{1}{\theta_1} + \dots} = \mu_0 \frac{1}{1} \frac{(280+50)}{1} \left[\frac{1}{250} - \frac{1}{2} \frac{1}{\theta_1} \right] - \dots$$

$$k = \mu_0 \frac{1}{\theta_1} \frac{1}{\log \left(\frac{280+\theta_1}{280} \right)} \log \left(1 + \frac{280}{\theta_1} \right) = \frac{1}{\theta_1} \frac{1}{280} - \frac{1}{2} \frac{1}{\theta_1^2} + \dots$$

Integration formulae:
$$\frac{R}{k} \int \frac{dx}{280 + \frac{x}{\theta_1}} = \frac{R}{k} \frac{1}{\theta_1} \log (280 + \frac{x}{\theta_1}) \Big|_0^k = \frac{R}{k} \frac{1}{\theta_1} \log \left(\frac{280+\theta_1}{280} \right) = \frac{R}{k} \frac{1}{\theta_1}$$

$$= \frac{R}{k} \int \frac{dx}{280 + \frac{x}{\theta_1}} = \frac{R}{k} \frac{1}{\theta_1} \log (280 + \frac{x}{\theta_1}) \Big|_0^k = \frac{R}{k} \frac{1}{\theta_1} \log \left(\frac{280+\theta_1}{280} \right) = \frac{R}{k} \frac{1}{\theta_1}$$

$$\int_0^k p dx = \frac{R}{k} \int_0^k \frac{dx}{280 + \frac{x}{\theta_1}} = \frac{R}{k} \frac{1}{\theta_1} \log \left(\frac{280+\theta_1}{280} \right) = \frac{R}{k} \frac{1}{\theta_1}$$

$$= \frac{R}{k} \theta_1 \left[1 + \log \frac{280}{\theta_1} \right] = \frac{R}{k} \theta_1 \left[1 + \log \frac{280}{\theta_1} \right]$$

$$\theta = \frac{R}{k} \theta_1 \left[1 + \log \frac{280}{\theta_1} \right] = \frac{R}{k} \theta_1 \left[1 + \log \frac{280}{\theta_1} \right]$$

$$\theta [1 + \rho \frac{z}{\theta}] = \frac{z}{\theta} \theta [1 + \rho \frac{z}{\theta}]$$

$$k_0 (\theta + \rho \frac{z}{\theta^2}) = k_0 \frac{z}{\theta} (\theta + \rho \frac{z}{\theta})$$

$$\theta - \theta_0 = \frac{k_0}{c} [1 - \frac{z}{\theta} (2\theta + (\theta - \theta_0) \frac{z}{\theta})]$$

$$\text{minimum: } \theta = \theta_0 + \frac{c}{k_0} = \theta_0 + (\theta - \theta_0) \frac{z}{\theta}$$

$$\theta - \theta_0 = \frac{c}{k_0} [1 + \frac{z}{\theta} (\theta + \theta_0)]$$

$$k_0 (\theta - \theta_0) [1 + \rho \frac{z}{\theta} (\theta + \theta_0)] = c \cdot x$$

$$\theta [1 + \rho \frac{z}{\theta}] = \frac{z}{\theta} \theta [1 + \rho \frac{z}{\theta}]$$

$$\rho = \frac{z}{\theta}$$

$$\int \rho dx = \frac{z}{\theta} \int \frac{dx}{\theta} = \frac{z}{\theta} \int \frac{dx}{\theta + 280}$$

$$\int \rho dx = \rho_0 \cdot x \quad \frac{1}{\theta} = \frac{1}{\theta_0} = \frac{1}{\theta_0 + 280}$$

$$\frac{1}{\theta} = \frac{1}{\theta_0 + 280} \Rightarrow \theta = \theta_0 + 280$$

$$\left\{ \begin{aligned} k_0 (\theta + \rho \frac{z}{\theta^2}) &= \theta + \rho \\ k_0 (\theta - \theta_0) [1 + \rho \frac{z}{\theta} (\theta + \theta_0)] &= c \cdot x \end{aligned} \right.$$

$$k_0 (\theta + \rho \frac{z}{\theta^2}) = c \cdot x + \rho$$

$$k_0 (1 + \rho \frac{z}{\theta}) \frac{d\theta}{dx} = c \cdot dx$$

$$d\theta \cdot x = 0 : \theta = 0$$

$$c = \frac{z}{k_0} (\theta + \rho \frac{z}{\theta})$$

$$\begin{array}{r} 0.99110 \\ - 0.30993 \\ \hline 0.68117 \end{array}$$

$$\begin{array}{r} 0.30103 \\ + 0.30993 \\ \hline 0.61096 \end{array}$$

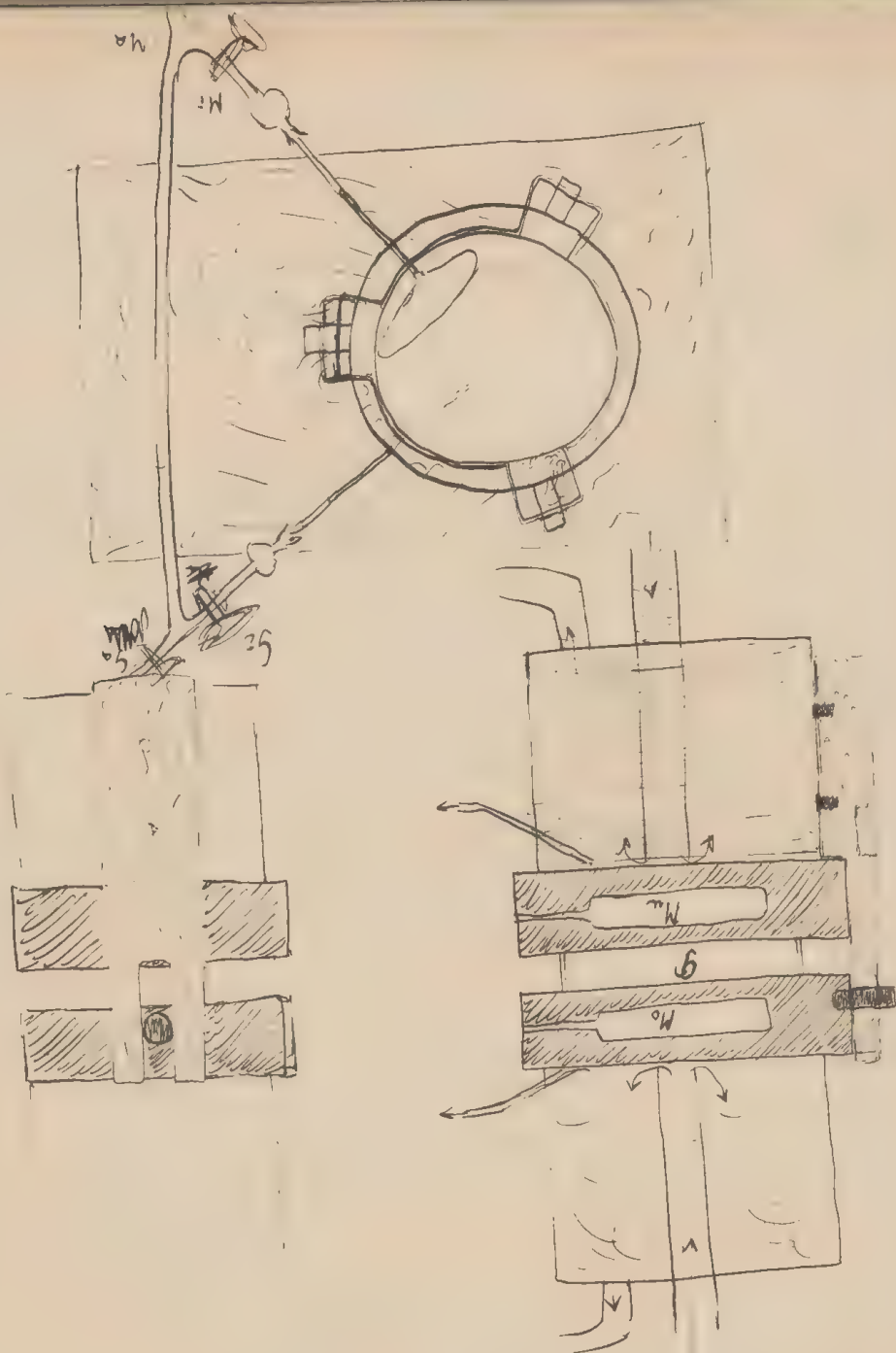
$$\frac{1}{2} \left(\frac{1}{280} + \frac{1}{373} \right) = \frac{1}{2} \cdot \frac{373 + 280}{280 \cdot 373}$$

$$\rho = \frac{z}{\theta} \left(\frac{1}{280} + \frac{1}{373} \right) = \frac{z}{\theta} \cdot 0.001263$$

$$\rho_0 = \frac{z}{\theta_0} = \frac{z}{280}$$

$$\frac{z}{\theta} = 2.373$$

$$\frac{z}{\theta} = 2.280$$



engelsk språk:

1). Dampkraft ved 50° og 55°

2). Dampkraft ved 50° og 55°

[i tabell 50. 1st Ma no drøyt vidt skilsmisse mellom
med 1/2 vinge av skruen.]

3). Dampkraft ved 50° og 55°

4). Dampkraft ved 50° og 55° (Kjøper i kjøkkenet og kjøper ikke kjøkkenet)

5). Dampkraft ved 50° og 55° (Kjøper i kjøkkenet og kjøper ikke kjøkkenet)

6). Dampkraft ved 50° og 55° (Kjøper i kjøkkenet og kjøper ikke kjøkkenet)

7). Dampkraft ved 50° og 55° (Kjøper i kjøkkenet og kjøper ikke kjøkkenet)

8). Dampkraft ved 50° og 55° (Kjøper i kjøkkenet og kjøper ikke kjøkkenet)

9). Dampkraft ved 50° og 55° (Kjøper i kjøkkenet og kjøper ikke kjøkkenet)

10). Dampkraft ved 50° og 55° (Kjøper i kjøkkenet og kjøper ikke kjøkkenet)

11). Dampkraft ved 50° og 55° (Kjøper i kjøkkenet og kjøper ikke kjøkkenet)

12). Dampkraft ved 50° og 55° (Kjøper i kjøkkenet og kjøper ikke kjøkkenet)

9408

11

52

$$\frac{1}{\sqrt{2}} > \frac{g\alpha}{\omega} \sin \varphi = 2.24 \omega^2$$

$$2.24 \omega^2 \frac{g\alpha}{\omega} = 2.24 g\alpha \omega$$

$$2.24 = 2.29 \omega^2$$

1

1

50

75

100

15

20

30

50

100

CO₂

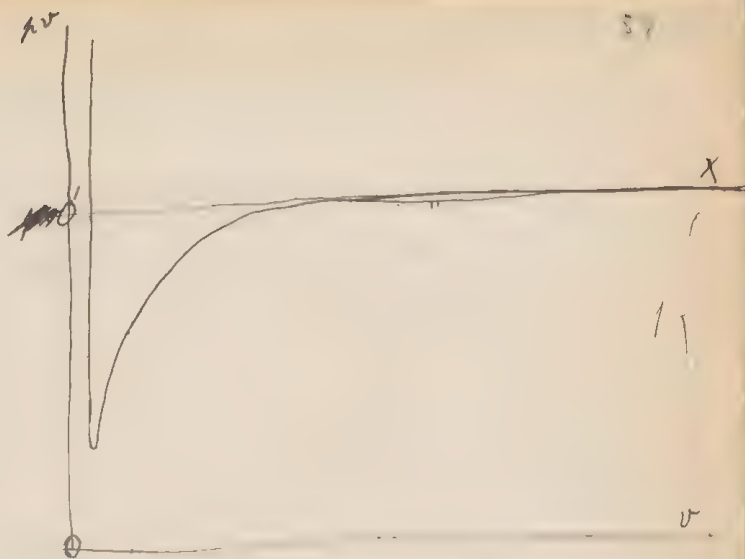
$t = 40^\circ$

r	ρv	v
1	1.000	1.000
50	0.8560	0.0170
75	0.6200	0.0082
100	0.3090	0.0031
150	0.3770	0.0025
200	0.4075	0.0023
300	0.6485	0.00216
500	0.9900	0.00198
1000	1.7800	0.00178

$$\frac{1}{2} \sum m \bar{v}^2 = \frac{3}{2} (\rho v) + \sum \sum R_n$$

Summen der verschiedenen \bar{v} (wie $\frac{1}{T}$ daher $\sum \bar{v}$ wie $\frac{1}{T^2}$) die mittleren Distanzen
~~des~~ \bar{v} wegen verchieden sein wie $T^{\frac{1}{2}}$

Nun also $R = f(r) = f(\sqrt{v})$ gesetzt wird so ist $\sum \sum R_n = \frac{1}{T^2} \sum T^{\frac{1}{2}} f(T^{\frac{1}{2}})$



Nun man die Sache auf $0'x$ besetzt so hat
man direkt den Wert von $\sum R_n = \sum R \sqrt{v}$
^{in allen}
Diese Curven werden ^{bei} verschiedenen Temperaturen verzeichnet,
in, denn bei gleichem v wird die Anzahl der

Spez. Wärme inhomog. Gas.

Wie wenn sie nur unendlich wenig von Kugelgestalt abweichen? Dann wird es doch ¹⁸⁶ sein

Was aber wenn man voraussetzt dass eine Rotation überhaupt nicht eintreten kann, dadurch dass v.d. Erhaltung der Rotations Ebene

Wie wenn als Uebel angesehen?

Stöckung?

Wenn ein Kreis in eine Kugel eingeschlossen wird, so kann man doch auf ~~die~~ seine Existenz schließen zufolge des eigenthümlichen Verhaltens der Kugel.

Wenn aber zwei in entgegengesetzter Richtung rotirende Kreise von gleichem Trägheitsmoment in einander gesetzt werden so kann sich durch Wirkung nach aussen nicht bemerkbar machen

55
Methode zur Messung der Wärmeleitfähigkeitszunahme mit der Temperatur.

2 unendliche Platten $\pm \left\{ \begin{array}{l} \vartheta_1 \\ \vartheta_0 \end{array} \right.$

1). Falls κ constant wäre, so wäre Gesdruck entsprechend $\frac{\vartheta_0 + \vartheta_1}{2}$

II) Dagegen wenn $\kappa = \kappa_0 (1 + \beta \vartheta)$:

$$\kappa_0 (1 + \beta \vartheta) \frac{d\vartheta}{dx} = \text{const.} = a$$

$$\vartheta + \beta \frac{\vartheta^2}{2} = ax + b$$

$$b = \vartheta_0 + \beta \frac{\vartheta_0^2}{2}$$

$$a = \frac{\vartheta_1 - \vartheta_0 + \beta \frac{\vartheta_1^2 - \vartheta_0^2}{2}}{h}$$

Oder wenn $\vartheta_0 = 0$ gesetzt wird:

$$\vartheta + \beta \frac{\vartheta^2}{2} = \frac{\kappa}{h} (\vartheta_1 + \beta \frac{\vartheta_1^2}{2})$$

$$\text{Mittlere Temperatur } \Theta = \frac{1}{h} \int_0^h \vartheta dx = \frac{1}{h} \int_0^h \vartheta \frac{d\vartheta (1 + \beta \vartheta)}{a} = \frac{1}{h} \frac{\vartheta_1^2 + \beta \frac{\vartheta_1^3}{3}}{a}$$

$$\Theta = \frac{1}{a h} \left(\frac{\vartheta_1^2}{2} + \beta \frac{\vartheta_1^3}{3} \right) = \frac{\frac{\vartheta_1^2}{2} + \beta \frac{\vartheta_1^3}{3}}{\vartheta_1 + \beta \frac{\vartheta_1^2}{2}} = \frac{\vartheta_1}{2} \frac{1 + \frac{2}{3} \beta \vartheta_1}{1 + \frac{1}{2} \beta \vartheta_1} \neq \frac{\vartheta_1}{2} [1 + \frac{1}{6} \beta \vartheta_1]$$

Wenn also z.B. $\vartheta_0 = 20$

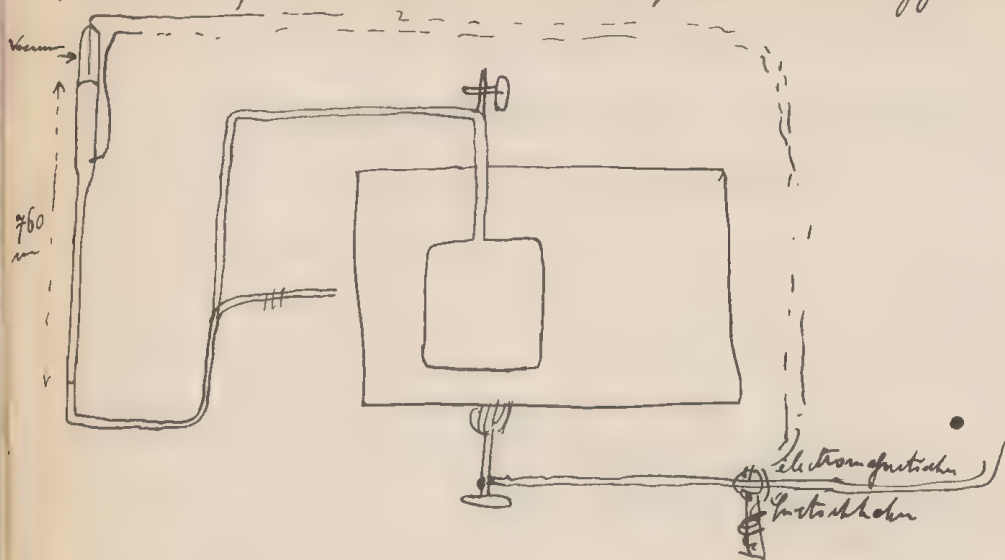
$\vartheta_1 = 100$

$\beta = 0.0018$

$$\Theta = 50 [1 + 0.03] = 50^\circ + 1.5^\circ$$

und zwar unabhängig von Distanz der Platten, unabhängig von Strahlung

Thermometer, welches von äusserem Luftdruck unabhängig ist:



Correctionsformel für Differentialthermometer:

$$w i^2 dx = \frac{2\pi dx}{\log \frac{r}{R}} K \log \frac{r}{\theta} + q \kappa' \frac{\partial^2 \theta}{\partial x^2}$$

$$C \# = \frac{\partial^3 \theta}{\partial x^3} = \frac{\partial}{\partial x} \left(\frac{\partial^2 \theta}{\partial x^2} \right) = \frac{\partial \theta}{\partial x} \frac{\partial^2 \theta}{\partial x^2} = \frac{\partial}{\partial x} \left[\theta \frac{\partial^2 \theta}{\partial x^2} - \frac{1}{2} \left(\frac{\partial \theta}{\partial x} \right)^2 \right]$$

$$C_2 + C_1 = \underbrace{\theta \frac{\partial^2 \theta}{\partial x^2} - \frac{1}{2} \left(\frac{\partial \theta}{\partial x} \right)^2}_{= \frac{\partial}{\partial x} \left(\theta \frac{\partial \theta}{\partial x} \right) - \left(\frac{\partial \theta}{\partial x} \right)^2}$$

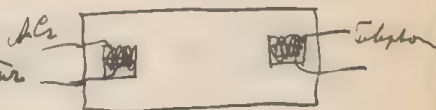
Scheinbarer Widerstand Verminderung von Wechselströmen in Umgebung von O_2 ; wegen Arbeit die zur Oxidierung verbraucht wird.

Is anderen Gasen nicht? Wie bei Erwärmung?

Hydromechanik verdünnter Gase; ^{Reibungsdruckmoment,} Planetenatmosphären / Abkühlung verschiedener Gase, Diffusion, Stoney's Hypothesen; Sternschuppen; ^{als 2×10^{10} 10^{11} 10^{12} 10^{13} 10^{14} 10^{15} 10^{16} 10^{17} 10^{18} 10^{19} 10^{20} 10^{21} 10^{22} 10^{23} 10^{24} 10^{25} 10^{26} 10^{27} 10^{28} 10^{29} 10^{30} 10^{31} 10^{32} 10^{33} 10^{34} 10^{35} 10^{36} 10^{37} 10^{38} 10^{39} 10^{40} 10^{41} 10^{42} 10^{43} 10^{44} 10^{45} 10^{46} 10^{47} 10^{48} 10^{49} 10^{50} 10^{51} 10^{52} 10^{53} 10^{54} 10^{55} 10^{56} 10^{57} 10^{58} 10^{59} 10^{60} 10^{61} 10^{62} 10^{63} 10^{64} 10^{65} 10^{66} 10^{67} 10^{68} 10^{69} 10^{70} 10^{71} 10^{72} 10^{73} 10^{74} 10^{75} 10^{76} 10^{77} 10^{78} 10^{79} 10^{80} 10^{81} 10^{82} 10^{83} 10^{84} 10^{85} 10^{86} 10^{87} 10^{88} 10^{89} 10^{90} 10^{91} 10^{92} 10^{93} 10^{94} 10^{95} 10^{96} 10^{97} 10^{98} 10^{99} 10^{100} 10^{101} 10^{102} 10^{103} 10^{104} 10^{105} 10^{106} 10^{107} 10^{108} 10^{109} 10^{110} 10^{111} 10^{112} 10^{113} 10^{114} 10^{115} 10^{116} 10^{117} 10^{118} 10^{119} 10^{120} 10^{121} 10^{122} 10^{123} 10^{124} 10^{125} 10^{126} 10^{127} 10^{128} 10^{129} 10^{130} 10^{131} 10^{132} 10^{133} 10^{134} 10^{135} 10^{136} 10^{137} 10^{138} 10^{139} 10^{140} 10^{141} 10^{142} 10^{143} 10^{144} 10^{145} 10^{146} 10^{147} 10^{148} 10^{149} 10^{150} 10^{151} 10^{152} 10^{153} 10^{154} 10^{155} 10^{156} 10^{157} 10^{158} 10^{159} 10^{160} 10^{161} 10^{162} 10^{163} 10^{164} 10^{165} 10^{166} 10^{167} 10^{168} 10^{169} 10^{170} 10^{171} 10^{172} 10^{173} 10^{174} 10^{175} 10^{176} 10^{177} 10^{178} 10^{179} 10^{180} 10^{181} 10^{182} 10^{183} 10^{184} 10^{185} 10^{186} 10^{187} 10^{188} 10^{189} 10^{190} 10^{191} 10^{192} 10^{193} 10^{194} 10^{195} 10^{196} 10^{197} 10^{198} 10^{199} 10^{200} 10^{201} 10^{202} 10^{203} 10^{204} 10^{205} 10^{206} 10^{207} 10^{208} 10^{209} 10^{210} 10^{211} 10^{212} 10^{213} 10^{214} 10^{215} 10^{216} 10^{217} 10^{218} 10^{219} 10^{220} 10^{221} 10^{222} 10^{223} 10^{224} 10^{225} 10^{226} 10^{227} 10^{228} 10^{229} 10^{230} 10^{231} 10^{232} 10^{233} 10^{234} 10^{235} 10^{236} 10^{237} 10^{238} 10^{239} 10^{240} 10^{241} 10^{242} 10^{243} 10^{244} 10^{245} 10^{246} 10^{247} 10^{248} 10^{249} 10^{250} 10^{251} 10^{252} 10^{253} 10^{254} 10^{255} 10^{256} 10^{257} 10^{258} 10^{259} 10^{260} 10^{261} 10^{262} 10^{263} 10^{264} 10^{265} 10^{266} 10^{267} 10^{268} 10^{269} 10^{270} 10^{271} 10^{272} 10^{273} 10^{274} 10^{275} 10^{276} 10^{277} 10^{278} 10^{279} 10^{280} 10^{281} 10^{282} 10^{283} 10^{284} 10^{285} 10^{286} 10^{287} 10^{288} 10^{289} 10^{290} 10^{291} 10^{292} 10^{293} 10^{294} 10^{295} 10^{296} 10^{297} 10^{298} 10^{299} 10^{300} 10^{301} 10^{302} 10^{303} 10^{304} 10^{305} 10^{306} 10^{307} 10^{308} 10^{309} 10^{310} 10^{311} 10^{312} 10^{313} 10^{314} 10^{315} 10^{316} 10^{317} 10^{318} 10^{319} 10^{320} 10^{321} 10^{322} 10^{323} 10^{324} 10^{325} 10^{326} 10^{327} 10^{328} 10^{329} 10^{330} 10^{331} 10^{332} 10^{333} 10^{334} 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Druck unterbrochene in Gitter-Röhren; Druck im Funkenfelde; Schallfortpflanzung; Reibungsströme;

Stachelbildung von Gasen

Hydromechanik von Gasen bei kritischer Temperatur

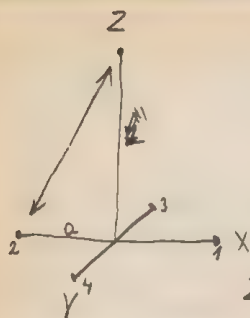


Anwendung zur Bestimmung derselben dadurch dass kein Schallfortpflanzung.

Thermal diffusion und ~~von~~ Thomson-Joule Effekt hängen ~~zusammen~~ sind innere

Phänomene? Gibt es Thermal diffusion in Lösungen?

Die Connection



$$V = \frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_3} + \frac{1}{r_4}$$

$$\frac{\partial V}{\partial x} = -\frac{1}{r_1} \frac{\partial r_1}{\partial x} \dots$$

$$\Sigma X = \frac{1}{r_1} \frac{\partial r_1}{\partial x} + \dots$$

$$r_1^2 = z^2 + (a-x)^2 + y^2$$

$$r_2^2 = z^2 + (a+x)^2 + y^2$$

$$r_3^2 = z^2 + (a+y)^2 + x^2$$

$$r_4^2 = z^2 + (a-y)^2 + x^2$$

$$\frac{\partial}{\partial x} \Sigma X = -\frac{\partial V}{\partial x} = -\frac{1}{r_1^2} \left(\frac{\partial r_1}{\partial x} \right)^2 + \frac{1}{r_1} \frac{\partial^2 r_1}{\partial x^2} \dots$$

$$\frac{a-x}{2}$$

$$-\frac{x^2}{2^3} - \frac{1}{2}$$

$$= -\frac{(a-x)^2}{[z^2 + (a-x)^2]^{3/2}} - \frac{(a+x)^2}{[z^2 + (a+x)^2]^{3/2}} - \frac{x^2}{[z^2 + a^2 + x^2]^{3/2}} - \frac{x^2}{[z^2 + a^2 + x^2]^{3/2}} + \dots$$

$$\Sigma X = -\frac{(a-x)}{[z^2 + (a-x)^2]^{3/2}} + \frac{a+x}{[z^2 + (a+x)^2]^{3/2}} + \frac{2x}{[z^2 + a^2 + x^2]^{3/2}}$$

$$-\frac{\partial V}{\partial x} = -3 \frac{(a-x)^2}{[z^2 + (a-x)^2]^{5/2}} + 3 \frac{(a+x)^2}{[z^2 + (a+x)^2]^{5/2}} - \frac{6x^2}{[z^2 + a^2 + x^2]^{5/2}}$$

$$+ \frac{1}{[z^2 + (a-x)^2]^{3/2}} + \frac{1}{[z^2 + (a+x)^2]^{3/2}} + \frac{2}{[z^2 + a^2 + x^2]^{3/2}}$$

$$Z = -\frac{\partial V}{\partial z} = -\frac{2}{[z^2 + (a-x)^2]^{3/2}} + \frac{2}{[z^2 + (a+x)^2]^{3/2}} + \frac{2z}{[z^2 + a^2 + x^2]^{3/2}}$$

$$\frac{\partial}{\partial x} \frac{\partial V}{\partial z} = -\frac{3 \cdot 2^2}{[z^2 + (a-x)^2]^{5/2}} + \frac{3 \cdot 2^2}{[z^2 + (a+x)^2]^{5/2}} - \frac{6 \cdot 2^2}{[z^2 + a^2 + x^2]^{5/2}} +$$

$$+ \frac{1}{[z^2 + (a-x)^2]^{3/2}} + \frac{1}{[z^2 + (a+x)^2]^{3/2}} + \frac{2}{[z^2 + a^2 + x^2]^{3/2}}$$

~~$$-\frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial z^2} = \frac{-3}{[2 + 4(1-x)^2]} x_L - \dots$$

$$+ \frac{2}{[2 + 4(1-x)^2]} y_L$$~~

$$-\frac{\partial V}{\partial x} = -\frac{3}{[2^2 + a^2]^{5/2}} \left\{ \frac{(a-x)^2}{\left[1 + \frac{2ax + x^2}{a^2 + 2^2}\right]^{5/2}} + \frac{(a+x)^2}{\left[1 + \frac{2ax + x^2}{a^2 + 2^2}\right]^{5/2}} + \frac{2x^2}{\left[1 + \frac{x^2}{a^2 + 2^2}\right]^{5/2}} \right\} +$$

$$+ \frac{1}{[a^2 + 2^2]^{3/2}} \left\{ \frac{1}{\left[1 + \frac{-2ax + x^2}{a^2 + 2^2}\right]^{3/2}} + \dots \dots \dots \right\}$$

für $\lim_{x \rightarrow 0} : -\frac{\partial V}{\partial x} = \frac{-6a^2}{(a^2+x^2)^{3/2}} + \frac{4}{(a^2+x^2)^{1/2}}$

$$-\frac{\partial V}{\partial z^2} = \frac{-12z^2}{(z^2+z^2)^{5/2}} + \frac{4}{(z^2+z^2)^{3/2}}$$

$\frac{\partial V}{\partial x^2} < 0$: $-\frac{6a^2}{a^2+2^2} + 4 < 0$ $\quad \quad \quad -\frac{12z^2}{a^2+2^2} + 4 < 0$
 $-2a^2 + 4z^2 < 0$ $\quad \quad \quad -8z^2 + 4a^2 < 0$
 $2z^2 < a^2$ $\quad \quad \quad a^2 < 2z^2$ daher höchstens:

$$\frac{\partial V}{\partial x^L} = 0 \quad \text{und} \quad \frac{\partial V}{\partial z^L} = 0 \quad \text{für} \quad z^L = \frac{a^L}{2}$$

$$-\frac{\partial V}{\partial x^3} = -15 \frac{(a-x)^3}{[2^2 + (a-x)^2]^{7/2}} + 15 \frac{(a+x)^3}{[2^2 + (a+x)^2]^{7/2}} + \frac{30x^2}{[2^2 + a^2 + x^2]^{7/2}} \bigg|_{x=0} = ()$$

$$\begin{aligned}
 -\frac{\partial^4 V}{\partial x^4} = & -3.5.7 \frac{(a-x)^4}{[2+(a-x)]^{9/2}} - 3.5.7 \frac{(a+x)^4}{\dots} - 2.3.5.7 \frac{x^4}{\dots} \\
 & + 45 \frac{(a-x)^2}{[2+(a-x)]^{7/2}} + 45 \frac{(a+x)^2}{\dots} + 2.45 \frac{x^2}{\dots} \\
 & + 45 \frac{(a-x)^2}{[2+(a-x)]^{7/2}} + 45 \frac{(a+x)^2}{\dots} + 2.45 \frac{x^2}{\dots} \\
 & - 9 \frac{(a-x)}{[2+(a-x)]^{5/2}} - 9 \frac{(a+x)}{\dots} - 2.9 \frac{1}{\dots}
 \end{aligned}$$

$$\text{für } x=0: \quad -\frac{\partial^4 V}{\partial x^4} = - \frac{4 \cdot 3 \cdot 5 \cdot 7 \cdot a^4}{(2+a)^{9/2}} + 2 \cdot 90 \frac{a^2}{(a^2+2)^{7/2}} - \frac{36}{(a^2+2)^{5/2}}$$

$$= \frac{1}{(a^2+2)^{5/2}} \left\{ - \frac{420}{456} a^4 + 180(a^4 + a^2 \cdot 2) - 36(a^4 + 2a^2 \cdot 2 + 2^2) \right\}$$

$$= \frac{1}{(a^2+2)^{5/2}} \left\{ -276 a^4 + 108 a^2 \cdot 2 - 36 \cdot 2^2 \right\}$$

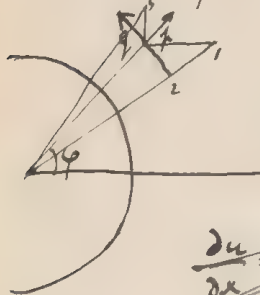
$$= \frac{12}{(a^2+2)^{5/2}} \left\{ -23 a^4 + 9 a^2 \cdot 2 - 3 \cdot 2^2 \right\} < 0$$

$$\text{Wenn } a^2 = 22^2 \quad \sqrt{-92 + 18 - 3} = -77 \cdot 2^2$$

Two-dimensional, incompressible

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + \cancel{w \frac{\partial u}{\partial z}} = u \left(\frac{\partial \tilde{u}}{\partial x} + \frac{\partial \tilde{u}}{\partial y} \right) + \cancel{\frac{\partial \tilde{u}}{\partial z}} - \frac{1}{\rho} \frac{\partial P}{\partial x} \quad \left| \frac{\partial}{\partial y} \right.$$

$$u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + \cancel{w \frac{\partial v}{\partial z}} = u \left(\frac{\partial \tilde{v}}{\partial x} + \frac{\partial \tilde{v}}{\partial y} \right) + \cancel{\frac{\partial \tilde{v}}{\partial z}} - \frac{1}{\rho} \frac{\partial P}{\partial y} \quad \left| \frac{\partial}{\partial x} \right.$$



$$r = u \cos \varphi + v \sin \varphi$$

$$\varphi = -u \sin \varphi + v \cos \varphi$$

$$u = r \cos \varphi - \varphi \sin \varphi$$

$$v = r \sin \varphi + \varphi \cos \varphi$$

$$x = r \cos \varphi$$

$$\frac{\partial u}{\partial x} = \frac{\partial u}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial u}{\partial \varphi} \frac{\partial \varphi}{\partial x}$$

$$= \frac{\partial u}{\partial r} \frac{1}{\cos \varphi} - \frac{\partial u}{\partial \varphi} \frac{1}{r \sin \varphi}$$

$$\frac{\partial u}{\partial x} = \frac{u_1 - u_0}{\Delta x} = \frac{u_1 - u_2}{\Delta x} + \frac{u_2 - u_0}{\Delta x} = \frac{u_1 - u_2}{\Delta r \cos \varphi} + \frac{u_2 - u_0}{r \Delta \varphi}$$

$$= \frac{\partial u}{\partial r} \cos \varphi - \frac{\partial u}{\partial \varphi} \frac{\sin \varphi}{r} =$$

$$\frac{\partial^2 u}{\partial x^2} = \frac{\partial^2 u}{\partial r^2} \cos^2 \varphi - \frac{\partial^2 u}{\partial r \partial \varphi} \frac{\cos \varphi \sin \varphi}{r} + \frac{\partial u}{\partial \varphi} \frac{\sin \varphi \cos \varphi}{r^2} - \frac{\partial^2 u}{\partial r \partial \varphi} \frac{\cos \varphi \sin \varphi}{r} -$$

$$+ \frac{\partial u}{\partial r} \frac{\sin^2 \varphi}{r} + \frac{\partial^2 u}{\partial \varphi^2} \frac{\sin^2 \varphi}{r^2} + \frac{\partial u}{\partial \varphi} \frac{\sin \varphi \cos \varphi}{r^2}$$

$$= \frac{\partial^2 u}{\partial r^2} \cos^2 \varphi - 2 \frac{\partial^2 u}{\partial r \partial \varphi} \frac{\sin \varphi \cos \varphi}{r} + \frac{\partial^2 u}{\partial \varphi^2} \frac{\sin^2 \varphi}{r^2} + \frac{\partial u}{\partial r} \frac{\sin^2 \varphi}{r} + 2 \frac{\partial u}{\partial \varphi} \frac{\sin \varphi \cos \varphi}{r^2}$$

$$\frac{\partial u}{\partial y} = \frac{u_3 - u_0}{\Delta y} = \frac{u_3 - u_4}{\Delta y} + \frac{u_4 - u_0}{\Delta y} = \frac{\partial u}{\partial r} \sin \varphi + \frac{\partial u}{\partial \varphi} \frac{\cos \varphi}{r}$$

$$\frac{\partial^2 u}{\partial y^2} = \frac{\partial^2 u}{\partial r^2} \sin^2 \varphi + \frac{\partial^2 u}{\partial r \partial \varphi} \frac{\sin \varphi \cos \varphi}{r} - \frac{\partial u}{\partial \varphi} \frac{\sin \varphi \cos \varphi}{r^2} + \frac{\partial^2 u}{\partial \varphi^2} \frac{\sin^2 \varphi}{r^2} + \frac{\partial u}{\partial r} \frac{\sin^2 \varphi}{r} + \frac{\partial^2 u}{\partial \varphi^2} \frac{\cos^2 \varphi}{r^2} - \frac{\partial u}{\partial \varphi} \frac{\sin \varphi \cos \varphi}{r^2}$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{\partial^2 u}{\partial r^2} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \varphi^2} + \frac{1}{r} \frac{\partial u}{\partial r}$$

$$\frac{\partial u}{\partial z} = \frac{\partial k}{\partial z} \omega \varphi - \frac{\partial \rho}{\partial z} \omega \varphi \quad \left| \begin{array}{l} \omega \varphi \end{array} \right.$$

$$\frac{\partial u}{\partial \varphi} = \frac{\partial k}{\partial \varphi} \omega \varphi - \frac{\partial \rho}{\partial \varphi} \omega \varphi - \mu \omega \varphi - \rho \omega \varphi \quad \left| \begin{array}{l} -\frac{\omega \varphi}{2} \end{array} \right.$$

$$\frac{\partial u}{\partial x} =$$

$$\nabla \delta^2 - V \delta \text{ und } \delta \\ \text{und } (V \delta \text{ und } \delta - \mu \nabla \delta^2) = 0$$

kurze Ableitungen!

$$\frac{\partial u}{\partial x} \frac{\partial u}{\partial y} + u \frac{\partial^2 u}{\partial x \partial y} + \frac{\partial v}{\partial y} \frac{\partial u}{\partial y} + v \frac{\partial^2 u}{\partial y^2} - \frac{\partial u}{\partial x} \frac{\partial v}{\partial x} - u \frac{\partial^2 v}{\partial x^2} - \frac{\partial v}{\partial x} \frac{\partial v}{\partial y} - v \frac{\partial^2 v}{\partial x \partial y}$$

$$= \mu \left(\frac{\partial^3 u}{\partial x^2 \partial y} + \frac{\partial^3 u}{\partial y^3} - \frac{\partial^3 v}{\partial x^3} - \frac{\partial^3 v}{\partial x \partial y^2} \right)$$

$$\zeta = \frac{\partial u}{\partial y} - \frac{\partial v}{\partial x}$$

$$\frac{\partial \zeta}{\partial x} = \frac{\partial^2 u}{\partial x \partial y} - \frac{\partial^2 v}{\partial x^2} = - \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right)$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2}$$

$$u \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right) + v \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right) = \mu \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \left(\frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right)$$

$$u \frac{\partial \zeta}{\partial x} + v \frac{\partial \zeta}{\partial y} = \mu \left(\frac{\partial^2 \zeta}{\partial x^2} + \frac{\partial^2 \zeta}{\partial y^2} \right)$$

$$\frac{\partial u}{\partial x} \frac{\partial \zeta}{\partial x} + \frac{\partial v}{\partial x} \frac{\partial \zeta}{\partial y} + u \frac{\partial^2 \zeta}{\partial x^2} + v \frac{\partial^2 \zeta}{\partial x \partial y} =$$

$$\frac{\partial(u \zeta)}{\partial x} + \frac{\partial(v \zeta)}{\partial y} = \nearrow$$

$$\frac{\partial}{\partial x} \left[u \zeta - \mu \frac{\partial \zeta}{\partial x} \right] + \frac{\partial}{\partial y} \left[v \zeta - \mu \frac{\partial \zeta}{\partial y} \right] = 0$$

$$\text{div } \zeta = \mu \nabla^2 \zeta$$

$$\mathbf{a} = \nabla V + \text{curl } \mathbf{a}$$

$$u = \frac{\partial V}{\partial x} + -\frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z}$$

$$v = \frac{\partial V}{\partial y} + -\frac{\partial A_3}{\partial x} + \frac{\partial A_1}{\partial z}$$

$$w = \frac{\partial V}{\partial z} + -\frac{\partial A_1}{\partial y} + \frac{\partial A_2}{\partial x}$$

Also zweidimensional:

$$u = \frac{\partial \varphi}{\partial x} + \frac{\partial \psi}{\partial y}$$

$$v = \frac{\partial \varphi}{\partial y} + \frac{\partial \psi}{\partial x}$$

$$\frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} = 0 \quad \psi = \frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y}$$

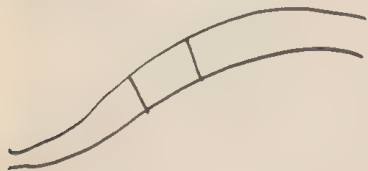
φ und ψ ganz unabhängig

Wenn ψ ^{fest} willkürlich gewählt, wie muss φ gewählt werden?

$$\left(\frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y}\right) \left(\frac{\partial^3 \varphi}{\partial x^3} + \frac{\partial^3 \varphi}{\partial x \partial y^2}\right) + \left(\frac{\partial \varphi}{\partial y} - \frac{\partial \varphi}{\partial x}\right) \left(\frac{\partial^3 \varphi}{\partial x^2 \partial y} + \frac{\partial^3 \varphi}{\partial y^3}\right) = \mu \frac{\partial^4 \varphi}{\partial x^4} + \dots$$

Flüssigkeits Gleichungen bezogen auf ~~Dichte~~ Stromlinien
(ohne Reibung)

In zwei Dimensionen:



$$m \frac{dv}{dt} = F_t = m \frac{dv}{ds} \frac{ds}{dt} = m v \frac{dv}{ds}$$

$$m \frac{v^2}{R} = F_n = \frac{1}{2} \frac{d}{ds} (m v^2) = \frac{dE}{ds}$$

$$m v^2 = 2 \int F_n ds$$

$$F_n = \frac{1}{q} \frac{\partial \mathcal{P}}{\partial r}$$

$$F_n = \frac{\partial \mathcal{P}}{\partial R} + \frac{\mathcal{P}}{R}$$

$$\frac{1}{R} = \frac{1}{R} \frac{\partial (R \mathcal{P})}{\partial R}$$

$$R = 2 \frac{\int F_n ds}{F_n}$$

$$= 2 \frac{E}{F_n}$$

$$2E = \mathcal{P} + R \frac{\partial \mathcal{P}}{\partial R}$$

$$\frac{\partial \mathcal{P}}{\partial R} = \frac{2E - \mathcal{P}}{R}$$

$$(\nabla \cdot) \vec{b} = \nabla P + \mu \nabla^2 \vec{b} = \nabla \phi^2 + \nabla \phi \text{curl} \vec{b}$$

$$\text{curl} = \mu \nabla^2 \text{curl} \vec{b} = \text{curl} \nabla \phi \text{curl} \vec{b}$$

$$\nabla \frac{\partial P}{\partial \mu} + \nabla^2 \vec{b} + \mu \nabla^2 \frac{\partial \vec{b}}{\partial \mu} = \nabla \frac{\partial \phi^2}{\partial \mu} + \frac{\partial}{\partial \mu} \nabla \phi \text{curl} \vec{b}$$

Stationäre Strömung ohne Kräfte, mit Reibz

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) - \frac{1}{\rho} \frac{\partial P}{\partial x}$$

$$\frac{x}{\mu} = \xi \quad \frac{\partial u}{\partial x} = \frac{1}{\mu} \frac{\partial u}{\partial \xi} \quad \frac{\partial^2 u}{\partial x^2} = \frac{1}{\mu^2} \frac{\partial^2 u}{\partial \xi^2}$$

$$u \frac{\partial u}{\partial \xi} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial \xi} = \frac{\partial^2 u}{\partial \xi^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial \xi^2} - \frac{1}{\rho} \frac{\partial P}{\partial \xi} \quad \text{etc.}$$

Wenn man also diese Gleichungen auflösen kann, so hat man auch die Lösung für ein beliebiges μ und umgekehrt

Wenn die Änderung von μ auf u, v, w ohne Einfluss sein soll, so muss

$$\nabla \frac{\partial P}{\partial \mu} + \nabla^2 \vec{b} = 0 \quad \text{sein.}$$

Also: $\text{curl} \nabla^2 \vec{b} = 0$

$$\begin{aligned} (\nabla \cdot) \vec{b} &= \nabla P + \mu \nabla^2 \frac{\partial \vec{b}}{\partial \mu} = \nabla \phi^2 + \nabla \phi \text{curl} \vec{b} \\ &= \nabla \left[P - \mu \frac{\partial P}{\partial \mu} \right] = -\nabla_{\mu} \mu \frac{\partial}{\partial \mu} \left(\frac{P}{\mu} \right) = \nabla \Pi \end{aligned}$$

Also nur Druck wird geändert

$$f(x, y, z, \mu) - \mu \frac{\partial f(x, y, z, \mu)}{\partial \mu} = F(x, y, z)$$

$$\frac{\partial f}{\partial \mu} - \frac{\partial f}{\partial \mu} - \mu \frac{\partial^2 f}{\partial \mu^2} = 0$$

$$\frac{\partial f}{\partial \mu} = \varphi(x, y, z)$$

$$f = \mu \varphi(x, y, z) + \psi(x, y, z)$$

$$\mu \varphi(x, y, z) + \psi(x, y, z) - \mu \varphi(x, y, z) = F(x, y, z)$$

$$P = \mu \varphi(x, y, z) + \Pi$$

$$\nabla P = \mu \nabla \varphi + \nabla \Pi$$

$$(67) \left. \begin{aligned} \nabla P + \mu \nabla^2 \varphi &= \mu \nabla \varphi + \nabla \Pi + \mu \nabla^2 \varphi \\ \nabla \Pi &= \nabla \Pi \end{aligned} \right\}$$

$$(67) \nabla \Pi$$

$$[-\nabla \varphi = \nabla^2 \varphi]$$

$\varphi = \text{willkürliche Funktion}$

$$\left. \begin{aligned} \text{curl } \nabla^2 \varphi &= -\text{curl } \nabla^2 \varphi \\ \text{curl } \nabla^2 \varphi &= 0 \end{aligned} \right\} !$$

$$\text{curl } \nabla a b = a \text{ div } b - b \text{ div } a + (\nabla a) b - (a \nabla) b$$

$$\begin{aligned} (\nabla a) b &= \nabla_a a b + \nabla \text{curl } a \cdot b \parallel = \nabla (\text{curl } a \cdot b - \text{curl } b \cdot a) + \\ &\quad + \nabla_a a b - \nabla_b a b \end{aligned}$$

$$\mathbf{b} = \nabla u + \text{curl } \mathbf{v}$$

$$\text{curl } \mathbf{b} = \text{curl}^2 \mathbf{v}$$

$$\text{curl}^2 \mathbf{b} = \text{curl}^3 \mathbf{v} = + \nabla \varphi \quad \text{Somit: } \mathbf{b} = \int \frac{\nabla \varphi \, dv}{4\pi k}$$

$$\nabla \mathbf{b} \cdot \text{curl } \mathbf{b} = \nabla (\nabla u + \text{curl } \mathbf{v}) \cdot \text{curl}^2 \mathbf{v} = \nabla \Phi$$

$$\text{curl } \mathbf{b} = \text{curl} \int \frac{\nabla \varphi \, dv}{4\pi k} = \int \frac{\text{curl } \nabla \varphi \, dv}{4\pi k} \neq 0$$

$$\left. \begin{aligned} \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} &= \frac{\partial \varphi}{\partial x} \\ \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} &= \frac{\partial \varphi}{\partial y} \\ \frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} &= \frac{\partial \varphi}{\partial z} \end{aligned} \right| \quad \begin{aligned} u &= \int \frac{\partial \varphi}{\partial x} \, dv \\ v &= \\ w &= \end{aligned}$$

$$\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} = \frac{\partial \varphi}{\partial y}$$

$$\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} = \frac{\partial \varphi}{\partial z}$$

$$\text{curl}^4 \mathbf{v} = \text{curl}^3 \mathbf{b} = 0$$

$$\left. \begin{aligned} \text{curl } \mathbf{b} &= i A_1 + j A_2 + k A_3 \\ \nabla^2 A_1 &= 0 = \nabla^2 A_2 = \nabla^2 A_3 \end{aligned} \right\} = \text{curl } \tilde{\mathbf{v}} = i \nabla^2 \tilde{\mathbf{v}}, \dots$$

$$\nabla (i A_1 + j A_2 + k A_3)$$

wenn $\text{curl } a = \nabla b$ $\nabla^2 b = 0$ ~~NAU~~

$\text{curl } a = 0 = \nabla \text{div } a - \nabla^2 a$

$a = \nabla \int \frac{\text{div } a}{r} dr + \underbrace{\text{curl} \int \frac{\text{curl } a}{r} dr}_{\dots\dots\dots} + \dots\dots\dots$ $\nabla^2 A = 0$
 $= \text{curl} \int \frac{\nabla b}{r} dr$
 ist $\text{div} = 0$?

dann muss $\nabla b = 0 = \text{curl } a = 0$

Somit in obigen Falle: $\text{curl } b = 0$

$\text{curl } b = \nabla \text{pot} = 0$

$b = \nabla \text{pot}$ also immer Potentialbewegung

Dann auch Druck durch alle

$\nabla^2 \phi = \nabla P + \mu \nabla^2 b$ $\nabla^2 u = 0 = \nabla^2 v = \nabla^2 w$

$\nabla^2 \phi = \nabla P$

$u = \frac{\partial \phi}{\partial x}$

$\nabla^3 \phi = 0$ mit $\nabla^2 \phi = 0$

$\nabla^2 b = 0$ *? von nicht erfüllt

stationäre

Somit besteht jede Potentialbewegung auch bei beliebig innerer Reibung?

10. $u = -\frac{ax}{r^2} - \frac{ay}{r^2}$

$\frac{\partial u}{\partial x} = 2 \frac{ax}{r^4}$

$\frac{\partial v}{\partial y} = \frac{2axy}{r^4}$

$v = \frac{ay}{r^2}$

$\frac{\partial u}{\partial y} = -\frac{a}{r^2} + \frac{2axy^2}{r^4}$

$\frac{\partial v}{\partial x} = \frac{a}{r^2} - \frac{2ax^2}{r^4}$

$\frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} = 0$

$\frac{\partial^2 u}{\partial x^2} = \frac{2ay}{r^4} - \frac{8ax^2y}{r^6}$

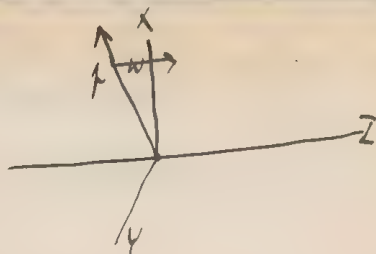
$\frac{\partial^2 u}{\partial y^2} = +\frac{2ay}{r^4} + \frac{4ay}{r^4} - \frac{8ay^3}{r^6}$

$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{8ay}{r^4} - \frac{8ay(x^2+y^2)}{r^6} = 0$

$z = \text{Rotations are } \omega$

$$u = \rho \cos(\phi) = \rho \cos \varphi$$

$$v = \rho \sin(\phi) = \rho \sin \varphi$$



$$\mu \frac{\partial u}{\partial x} = \mu \frac{\partial u}{\partial r} \cos \varphi - \frac{\partial u}{\partial \varphi} \frac{\sin \varphi}{r} = \frac{\partial u}{\partial r} \cos \varphi + \mu \frac{\sin \varphi}{r}$$

$$\frac{\partial u}{\partial x} = \frac{\partial \tilde{u}}{\partial r} \cos \varphi + \frac{\tilde{u}}{r} \sin \varphi$$

$$\left\| \frac{\partial v}{\partial x} = \frac{\partial \tilde{v}}{\partial r} \sin \varphi - \frac{\tilde{v}}{r} \cos \varphi \right.$$

$$\frac{\partial \tilde{u}}{\partial x} = \frac{\partial \tilde{u}}{\partial r^2} \cos \varphi + \frac{\partial \tilde{u}}{\partial r} \frac{\sin^2 \varphi}{r} = \frac{\partial \tilde{u}}{\partial r^2} \cos \varphi + \frac{\partial \tilde{u}}{\partial r} \frac{\sin^2 \varphi}{r}$$

$$\frac{\partial u}{\partial y} = \frac{\partial u}{\partial r} \sin \varphi = \frac{\partial \tilde{u}}{\partial r} \sin \varphi - \frac{\tilde{u}}{r} \sin \varphi \cos \varphi$$

$$\frac{\partial \tilde{u}}{\partial y} = \frac{\partial \tilde{u}}{\partial r^2} \sin \varphi + \frac{\partial \tilde{u}}{\partial r} \frac{\cos^2 \varphi}{r} = \frac{\partial \tilde{u}}{\partial r^2} \sin \varphi + \frac{\partial \tilde{u}}{\partial r} \frac{\cos^2 \varphi}{r}$$

$$\frac{\partial^2 \tilde{u}}{\partial x^2} + \frac{\partial^2 \tilde{u}}{\partial y^2} = \frac{\partial^2 \tilde{u}}{\partial r^2} \cos^2 \varphi + \frac{\partial \tilde{u}}{\partial r} \frac{\cos^2 \varphi}{r} + \frac{\partial^2 \tilde{u}}{\partial r^2} \sin^2 \varphi + \frac{\partial \tilde{u}}{\partial r} \frac{\sin^2 \varphi}{r}$$

$$\left\| \frac{\partial \tilde{v}}{\partial y} = \frac{\partial \tilde{v}}{\partial r} \sin \varphi + \frac{\tilde{v}}{r} \cos \varphi \right.$$

$$+ \frac{\partial^2 \tilde{v}}{\partial x^2} + \frac{\partial^2 \tilde{v}}{\partial y^2} = \frac{\partial^2 \tilde{v}}{\partial r^2} \sin^2 \varphi + \frac{\partial \tilde{v}}{\partial r} \frac{\sin^2 \varphi}{r} + \frac{\partial^2 \tilde{v}}{\partial r^2} \cos^2 \varphi + \frac{\partial \tilde{v}}{\partial r} \frac{\cos^2 \varphi}{r}$$

$$\mu \left[\frac{\partial \tilde{u}}{\partial r^2} \cos^2 \varphi + \frac{\partial \tilde{u}}{\partial r} \frac{\cos^2 \varphi}{r} + \frac{\partial \tilde{u}}{\partial r^2} \sin^2 \varphi + \frac{\partial \tilde{u}}{\partial r} \frac{\sin^2 \varphi}{r} \right] + \mu \left[\frac{\partial \tilde{v}}{\partial r^2} \sin^2 \varphi + \frac{\partial \tilde{v}}{\partial r} \frac{\sin^2 \varphi}{r} + \frac{\partial \tilde{v}}{\partial r^2} \cos^2 \varphi + \frac{\partial \tilde{v}}{\partial r} \frac{\cos^2 \varphi}{r} \right] = \mu \left[\frac{\partial^2 \tilde{u}}{\partial r^2} \cos^2 \varphi + \frac{\partial \tilde{u}}{\partial r} \frac{\cos^2 \varphi}{r} + \frac{\partial^2 \tilde{u}}{\partial r^2} \sin^2 \varphi + \frac{\partial \tilde{u}}{\partial r} \frac{\sin^2 \varphi}{r} \right]$$

$$- \frac{1}{\rho} \frac{\partial P}{\partial r} \cos \varphi$$

$$\mu \left[\frac{\partial \tilde{u}}{\partial r^2} + \frac{1}{r} \frac{\partial \tilde{u}}{\partial r} \right] - \frac{1}{\rho} \frac{\partial P}{\partial r} \cos \varphi = \frac{\partial \tilde{u}}{\partial r^2}$$

$$\mu \left[\frac{\partial \tilde{v}}{\partial r^2} \sin^2 \varphi + \frac{\partial \tilde{v}}{\partial r} \frac{\sin^2 \varphi}{r} + \frac{\partial \tilde{v}}{\partial r^2} \cos^2 \varphi + \frac{\partial \tilde{v}}{\partial r} \frac{\cos^2 \varphi}{r} \right] = \frac{\partial \tilde{v}}{\partial r^2}$$

$$\mu \left[\frac{\partial \tilde{v}}{\partial r^2} + \frac{1}{r} \frac{\partial \tilde{v}}{\partial r} \right] - \frac{1}{\rho} \frac{\partial P}{\partial r} \sin \varphi = \frac{\partial \tilde{v}}{\partial r^2}$$

$$\frac{\partial p}{\partial r} \frac{\partial r}{\partial \rho} + \rho \frac{\partial \tilde{p}}{\partial r \partial z} - \frac{\partial p}{\partial r} \frac{\partial w}{\partial \rho} \frac{\partial w}{\partial z} + \frac{\partial w}{\partial z} \frac{\partial p}{\partial z} + \rho \frac{\partial \tilde{p}}{\partial z^2} - \frac{\partial w}{\partial r} \frac{\partial w}{\partial z} - \rho \frac{\partial \tilde{w}}{\partial r \partial z} =$$

$$\approx \mu \text{ Continuity's slowly: } \frac{\partial p}{\partial z} \omega r \rho + \frac{\partial p}{\partial z} r^2 \rho \omega + \frac{\partial p}{\partial z} = 0$$

$$\frac{\partial p}{\partial z} + \frac{\partial w}{\partial z} = 0 \quad \frac{\partial p}{\partial z} + \frac{p}{r} + \frac{\partial w}{\partial z} = 0 \quad \frac{\partial}{\partial r}(r p) + \frac{\partial}{\partial z}(r w) = 0$$

$$= \frac{1}{2} \frac{\partial(r p)}{\partial r} = \frac{\partial}{\partial z} \frac{1}{2} \frac{\partial(r w)}{\partial z} = -\frac{\partial w}{\partial z \partial z}$$

$$\rho \frac{\partial p}{\partial r} + \rho \frac{\partial w}{\partial z} = \mu \left[\frac{\partial^2 p}{\partial z^2} + \frac{1}{2} \frac{\partial p}{\partial z} - \frac{p}{r} + \frac{\partial^2 p}{\partial z^2} \right] - \frac{1}{\rho} \frac{\partial p}{\partial z}$$

$$\rho \frac{\partial w}{\partial z} + \rho \frac{\partial w}{\partial z} = \mu \left[\frac{\partial^2 w}{\partial z^2} + \frac{1}{2} \frac{\partial w}{\partial z} + \frac{\partial^2 w}{\partial z^2} \right] - \frac{1}{\rho} \frac{\partial p}{\partial z}$$

ohne Röhre:

$$T_t = \frac{\partial}{\partial t}(P \rho)$$

Continuity:

$$\frac{\partial}{\partial t}(v \rho) = 0$$

$$= \rho \frac{\partial v}{\partial t} = \frac{\partial v}{\partial t} \cdot v = \frac{1}{2} \frac{\partial v^2}{\partial t}$$

$$v \frac{\partial \rho}{\partial t} + \rho \frac{\partial v}{\partial t} = 0$$

$$v_1 - v_2 = \int F_t dt =$$

$$v_1 - v_2 = 2 \int F_t dt = 2(P_1 - P_2)$$

Doran fol 1: $P = P_0 + \frac{v^2}{2}$ für bestimmte Strömung

$$\rho = r \delta \varphi \delta s$$

$$\rho \delta s \frac{v^2}{R} = F_n = \frac{\partial(P r)}{\partial \Delta} \delta \varphi \delta s \delta \Delta$$

$$r \frac{v^2}{R} = \frac{\partial(P r)}{\partial \Delta} = \frac{\partial(P r)}{\partial r}$$

$$\frac{\partial(P r)}{\partial \Delta} = \frac{\partial(P r)}{\partial r} \sin \vartheta$$

$$\Delta s = \frac{\Delta r}{\sin \vartheta}$$

$$R = \frac{\partial s}{\partial \vartheta} = \frac{\partial r}{\partial \vartheta} \frac{1}{\sin \vartheta}$$

$$r v^2 \frac{\partial \vartheta}{\partial s} = \frac{\partial(P r)}{\partial r} \sin \vartheta = r v^2 \frac{\partial \vartheta}{\partial r} \sin \vartheta$$

$$r v^2 \frac{\partial \vartheta}{\partial r} = \frac{\partial(P r)}{\partial r}$$

Nun die Richtung der Stromlinien gegeben ist:

$$\frac{f}{w} = f(r, z)$$

$$\rho = w f(r, z)$$

$$\frac{\partial w}{\partial r} f + w \frac{\partial f}{\partial r} + \frac{w}{r} f + \frac{\partial w}{\partial z} = 0$$

$$\frac{\partial w}{\partial r} f + \frac{\partial w}{\partial z} + w \frac{\partial f}{\partial r} + \frac{w}{r} f = 0$$

$$w f \left(w \frac{\partial f}{\partial r} + \frac{\partial w}{\partial r} f \right) + w \left(\frac{\partial w}{\partial z} f + w \frac{\partial f}{\partial z} \right) = -\frac{1}{\rho} \frac{\partial P}{\partial r} +$$

$$+ \mu \left[\frac{\partial^2 w}{\partial r^2} \frac{\partial f}{\partial r} + w \frac{\partial^2 f}{\partial r^2} + \frac{\partial^2 w}{\partial r^2} f + \frac{w}{r} \frac{\partial f}{\partial r} + \frac{f}{r} \frac{\partial w}{\partial r} - \frac{f}{r^2} w + \frac{\partial^2 w}{\partial z^2} f + 2 \frac{\partial w}{\partial z} \frac{\partial f}{\partial z} + w \frac{\partial^2 f}{\partial z^2} \right]$$

$$w f \frac{\partial w}{\partial r} + w \frac{\partial w}{\partial z} = \mu \left[\frac{\partial^2 w}{\partial r^2} + \frac{1}{r} \frac{\partial w}{\partial r} + \frac{\partial^2 w}{\partial z^2} \right] - \frac{1}{\rho} \frac{\partial P}{\partial r} \quad || f$$

$$w f \frac{\partial f}{\partial r} + w^2 \frac{\partial f}{\partial z} = \mu \left[w \frac{\partial^2 f}{\partial r^2} + 2 \frac{\partial w}{\partial r} \frac{\partial f}{\partial z} + \frac{w}{r} \frac{\partial f}{\partial r} - f \frac{w}{r^2} + 2 \frac{\partial w}{\partial z} \frac{\partial f}{\partial z} + w \frac{\partial^2 f}{\partial z^2} \right] + - \frac{1}{\rho} \left(\frac{\partial P}{\partial r} + f \frac{\partial P}{\partial z} \right)$$

$$\frac{\partial^2 w}{\partial r^2} f + 2 \frac{\partial w}{\partial r} \frac{\partial f}{\partial z} + w \frac{\partial^2 f}{\partial r^2} + \frac{\partial w}{\partial z} \frac{f}{r} + \frac{w}{r} \frac{\partial f}{\partial r} + - \frac{w f}{r^2} + \frac{\partial^2 w}{\partial z^2} = 0$$

$$\text{Hyp.} = \mu \left[\frac{\partial^2 w}{\partial r^2} f + 2 \frac{\partial w}{\partial r} \frac{\partial f}{\partial z} - \frac{\partial^2 w}{\partial r^2} + w \frac{\partial^2 f}{\partial z^2} \right] - \frac{1}{\rho} \frac{\partial P}{\partial r} =$$

$$= w^2 \frac{\partial f}{\partial z^2} - \frac{w}{r} f^2$$

$$\frac{1}{12} - \frac{1}{12} = 0$$

$$\frac{1}{12} - \frac{1}{12} = \frac{1}{12} - \frac{1}{12} = 0$$

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$$\left\{ \begin{aligned} &\frac{1}{12} - \frac{1}{12} = \frac{1}{12} - \frac{1}{12} = 0 \\ &\frac{1}{12} - \frac{1}{12} = \frac{1}{12} - \frac{1}{12} = 0 \end{aligned} \right\}$$

$$\frac{1}{12} - \frac{1}{12} = \frac{1}{12} - \frac{1}{12} = 0$$

$$\frac{1}{\sqrt{1-\beta^2}} = \gamma$$

$$\frac{1}{\sqrt{1-\beta^2}} = \gamma$$

$$\frac{1}{\sqrt{1-\beta^2}} = \gamma$$

$$\gamma \left[\frac{1}{\sqrt{1-\beta^2}} + \frac{1}{\sqrt{1-\beta^2}} - \frac{1}{\sqrt{1-\beta^2}} - \frac{1}{\sqrt{1-\beta^2}} \right]$$

ϕ sei eine Lösung

$$(\phi \nabla) \phi = \frac{1}{2} \nabla \phi^2 + \nabla \phi \text{ curl } \phi = \nabla \phi^2 - \frac{1}{2} \nabla P$$

Dann ist $\frac{1}{2} \phi^2$ auch eine Lösung für denselben Fall, aber hier ϕ mit

$\frac{P_c^2}{\rho}$ ~~Umlauf~~ Druck $\phi = \phi_c \quad \gamma = \gamma_c \quad P = P_c^2 \quad \checkmark$

$$c \left(\frac{1}{2} \nabla \phi^2 + \nabla \phi \text{ curl } \phi \right) = c \frac{P_c^2}{\rho} \nabla \phi - \frac{1}{2} \nabla P_c$$

Angenommen u, v, w sei ein Lösung, unter welcher Umständen wird u, v, w ein Lösung sein?

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} - \frac{1}{\rho} \frac{\partial P}{\partial x}$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} - \frac{1}{\rho} \frac{\partial P}{\partial x}$$

$$+ u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z}$$

Wenn $\rho, u, v, w = \text{const}$ } a

$$-\frac{1}{\rho} \frac{\partial (P - P_1)}{\partial x} = \nabla a \nabla u_1$$

ist.

$$-\frac{1}{\rho} \nabla (P - P_1) = \nabla a \nabla$$

$$u \left(\frac{\partial^2 u}{\partial x \partial y} - \frac{\partial^2 v}{\partial x^2} \right) + v \left(\frac{\partial^2 u}{\partial y^2} - \frac{\partial^2 v}{\partial y \partial x} \right) + w \left(\frac{\partial^2 u}{\partial y \partial z} - \frac{\partial^2 v}{\partial x \partial z} \right) = 0$$

$$u \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right) + v \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right) + w \frac{\partial}{\partial z} \left(\frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right) = 0$$

$$\left\{ \begin{array}{l} u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + w \frac{\partial f}{\partial z} = 0 \\ u \frac{\partial g}{\partial x} + \dots = 0 \\ u \frac{\partial h}{\partial x} + \dots = 0 \end{array} \right\} \begin{array}{l} \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0 \\ \text{Daher} \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial x \partial y} + \frac{\partial^2 w}{\partial x \partial z} = 0 \\ \text{in } \text{Hilf} \text{ dann:} \end{array}$$

$$(\phi, \nabla) \phi_1 = \frac{1}{2} \nabla \phi_1^2 + \nabla \phi_1 \text{curl} \phi_1 = \nabla^2 \phi_1 - \frac{1}{\rho} \nabla P_1$$

$$\nabla (\phi_1 + \phi)^2 + \nabla (\phi_1 + \phi) \text{curl} (\phi_1 + \phi) = \nabla (\phi_1^2 + \phi^2) - \frac{1}{\rho} \nabla P_1$$

~~1766~~

$$\nabla b_1^2 + \underbrace{\nabla(b, b + b b_1)}_{2\nabla S b b_1} + \nabla b^2 + \nabla b_1 \operatorname{curl} b + \nabla b \operatorname{curl} b_1 + \nabla b \operatorname{curl} b_1 + \nabla b \operatorname{curl} b$$

$$= \nabla b^2 + \cancel{\nabla b^2} - \frac{1}{\rho} \nabla(P - P_1)$$

Wenn auch b_1 ein L_0 -ist:

$$2\nabla b b_1 + \nabla(b_1 \operatorname{curl} b + b \operatorname{curl} b_1) = -\frac{1}{\rho} \nabla(P - P_1 - C')$$

P' kann daraus genügend bestimmt werden falls überhaupt:

$$\operatorname{curl} \nabla(b_1 \operatorname{curl} b + b \operatorname{curl} b_1) = 0$$

Also wenn $\underbrace{\quad}_{= \tau \operatorname{curl} \tau}$ positiv ist so muss τ eine mögliche (Neben-) Lösung sein

$$\operatorname{curl} \nabla a b = a \operatorname{div} b - b \operatorname{div} a + (b \nabla) a - (a \nabla) b$$

$$(\operatorname{curl} b \nabla) b_1 - (b_1 \nabla) \operatorname{curl} b + (\operatorname{curl} b_1 \nabla) b - (b \nabla) \operatorname{curl} b_1 = 0$$

$$x = \sqrt{\frac{1}{2}} \quad y = y \sqrt{2} \quad z = \sqrt{\frac{1}{2}} \quad P = \pi^2$$

$$\frac{\partial u}{\partial x} = \frac{\partial u}{\partial \xi} \frac{\partial \xi}{\partial x}$$

$$= 2\sqrt{\xi} \frac{\partial u}{\partial \xi}$$

$$\frac{\partial \xi}{\partial x} = 2x = 2\sqrt{\xi}$$

$$\frac{\partial^2 u}{\partial x^2} = \left[2\sqrt{\xi} \frac{\partial^2 u}{\partial \xi^2} + \frac{1}{\sqrt{\xi}} \frac{\partial u}{\partial \xi} \right] 2\sqrt{\xi} = 2\xi \frac{\partial^2 u}{\partial \xi^2} + 2 \frac{\partial u}{\partial \xi}$$

$$\frac{2n-1}{\sqrt{x}} = \frac{n-2}{\sqrt{x}} \quad u = u^{-1} = \frac{1}{u} \quad P = \pi^{-2}$$

$$n = -1 \quad \frac{\partial u}{\partial x} = -\frac{1}{u} \cdot \frac{\partial u}{\partial x} \quad \frac{\partial^2 u}{\partial x^2} = +\frac{2}{u^3} \left(\frac{\partial u}{\partial x} \right)^2 - \frac{1}{u} \frac{\partial^3 u}{\partial x^3}$$

Wenn man also ein Lösung der Aufgabe hat, so erhält man eine andere wenn man x, y, z m mal größer macht, aber u, v, w m mal kleiner & die Konstanten m^2 mal kleiner (siehe Tabelle u).

I	x, y, z	u, v, w	μ	P	Daraus folgt x, y, z m mal u, v, w $m\mu$ $m^2 P$ sind also nur zwei dann willkürliche Transformation
II	$m x, y, z$	u, v, w	m, μ	P	
III	x, y, z	$m u, v, w$	m, μ	$m^2 P$	
IV	$\frac{1}{m} x, y, z$	$\frac{1}{m} u, v, w$	$\frac{1}{m}, \mu$	$\frac{1}{m^2} P$	

III ist nicht notwendig gegeben

$$\nabla \cdot (\epsilon \nabla \phi) = F - \frac{1}{\rho} \nabla P + \frac{\mu}{3\rho} \nabla^2 \text{div} \phi + \frac{\mu}{\rho} \nabla^2 \phi$$

$$\text{div}(\epsilon \nabla \phi) = 0 = \rho \text{div} \nabla \phi + \nabla \cdot (\epsilon \nabla \phi) = 0$$

$$P = f(\rho) \quad \parallel \quad \text{div} \nabla \phi + \rho \nabla \text{div} \phi + \nabla (\epsilon \nabla \phi) = 0$$

$$\begin{aligned} \nabla \cdot \mathbf{A} &= a \text{div} \mathbf{b} + b \text{div} \mathbf{a} \\ \left[\begin{matrix} i & j & k \\ \partial_1 & \partial_2 & \partial_3 \end{matrix} \right] \cdot \left[\begin{matrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{matrix} \right] \\ &= a_1 (\partial_1 b_1 + \partial_2 b_2 + \partial_3 b_3) + b_1 (\partial_1 a_1 + \partial_2 a_2 + \partial_3 a_3) \end{aligned}$$

$$\rho \left[\frac{1}{2} \nabla^2 \phi^2 + \nabla \phi \text{curl} \phi \right] = - \frac{1}{\rho} \nabla P + \frac{\mu}{\rho} \nabla^2 \phi + \frac{\mu}{3\rho} \nabla^2 \text{div} \phi$$

curl:

$$\frac{1}{2} \left[\rho \text{curl} \nabla^2 \phi^2 + \nabla \cdot \nabla^2 \phi^2 \nabla \phi \right] + \rho \text{curl} \nabla \phi \text{curl} \phi = \mu \text{curl} \nabla^2 \phi$$

~~We can also do~~

$$-\nabla \cdot \nabla \rho \left[\frac{1}{2} \nabla^2 \phi^2 + \nabla \phi \text{curl} \phi \right] + \rho \text{curl} (\nabla \phi \text{curl} \phi) = \mu \text{curl} \nabla^2 \phi$$

$$= -\frac{\nabla P}{\rho} + \frac{\mu}{3\rho} \nabla^2 \text{div} \phi + \frac{\mu}{\rho} \nabla^2 \phi$$

$$= -\nabla \cdot \nabla \rho \left[-\frac{\nabla P}{\rho} + \frac{\mu}{3\rho} \nabla^2 \text{div} \phi + \frac{\mu}{\rho} \nabla^2 \phi \right]$$

$$\text{curl} \cdot \nabla \phi \text{curl} \phi = \text{curl} \left[-\frac{\nabla P}{\rho} + \frac{\mu}{3\rho} \nabla^2 \text{div} \phi + \frac{\mu}{\rho} \nabla^2 \phi \right]$$

$$= \frac{\mu}{3\rho} \text{curl} \nabla^2 \text{div} \phi + \frac{\mu}{3\rho^2} \nabla \nabla \rho \nabla^2 \text{div} \phi$$

$$+ \frac{\mu}{\rho} \text{curl} \nabla^2 \phi + \frac{\mu}{\rho^2} \nabla \nabla \rho \nabla^2 \phi$$

$$= \frac{\mu}{\rho} \text{curl} \nabla^2 \phi + \nabla \cdot \nabla \rho \left[\frac{\mu}{3\rho^2} \nabla^2 \text{div} \phi + \frac{\mu}{\rho^2} \nabla^2 \phi \right]$$

$$\nabla Sab = i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z} : (a, b, + a_z b_z + a_y b_y)$$

$$\text{curl } mb = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ m b_1 & m b_2 & m b_3 \end{vmatrix} = i m \left(\frac{\partial b_3}{\partial y} - \frac{\partial b_2}{\partial z} \right) +$$

$$+ i (b_3 \frac{\partial m}{\partial y} - b_2 \frac{\partial m}{\partial z}) + \dots$$

$$= m \text{ curl } b + V \cdot b \nabla m$$

$$\text{curl } \frac{\nabla P}{\rho} = \text{curl } \frac{\nabla P}{\rho} \cdot \frac{1}{\rho} \nabla T + \dots$$

∇P und $\nabla \rho$ sind gleichgerichtet

V ist ...

$$\nabla \times \frac{\nabla P}{\rho} = \frac{1}{\rho} \nabla P \times \nabla T + \dots$$

$$\text{da } \rho \text{ und } T \text{ sind ...}$$

...

∇P und $\nabla \rho$ gleichgerichtet

also falls V ...

und ...

$\nabla P = \dots$

...

also falls V ...

$$\text{da } \rho = \dots$$

$$= - \int \dots$$

$$\vec{\omega} = -\nabla \log \rho$$

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$$\vec{\omega} = -\nabla \log \rho$$

$$\vec{\omega} \cdot \rho = \frac{1}{\rho} \int \nabla^2 \log \rho \, d\tau$$

$$\vec{\omega} \cdot \rho = \frac{1}{\rho} \int \nabla^2 \log \rho \, d\tau$$

$$\nabla \log \rho = \frac{1}{\rho} \nabla \rho = \frac{1}{\rho} \frac{\partial \rho}{\partial x} \hat{x} + \frac{1}{\rho} \frac{\partial \rho}{\partial y} \hat{y} + \frac{1}{\rho} \frac{\partial \rho}{\partial z} \hat{z}$$

$$\vec{\omega} \cdot \rho = \frac{1}{\rho} \int \nabla^2 \log \rho \, d\tau$$

$$\nabla^2 \log \rho = \frac{1}{\rho} \nabla^2 \rho - \frac{1}{\rho^2} (\nabla \rho)^2$$

$$\rho = \frac{1}{\rho}$$

$$\rho = \frac{1}{\rho}$$

$$\rho = \frac{1}{\rho}$$

$$\nabla \rho = \frac{1}{\rho} \nabla \rho$$

$$\rho = \frac{1}{\rho}$$

$$\rho = \frac{1}{\rho}$$

$$\rho = \frac{1}{\rho}$$

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Let us now consider the effect of the

$$\vec{\omega} \cdot \rho = \frac{1}{\rho} \int \nabla^2 \log \rho \, d\tau$$

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$$\vec{\omega} \cdot \rho = \frac{1}{\rho} \int \nabla^2 \log \rho \, d\tau$$

$$\begin{aligned} \frac{\partial}{\partial t} \left(\frac{1}{2} \rho v^2 \right) &= \frac{1}{2} \rho \frac{d}{dt} v^2 \\ &= \frac{1}{2} \rho \left(v \frac{dv}{dt} + \frac{dv}{dt} v \right) \\ &= \rho v \frac{dv}{dt} \end{aligned}$$

$$\begin{aligned} \frac{d}{dt} \left(\frac{1}{2} \rho v^2 \right) &= \frac{1}{2} \rho \frac{d}{dt} v^2 \\ &= \frac{1}{2} \rho \left(v \frac{dv}{dt} + \frac{dv}{dt} v \right) \\ &= \rho v \frac{dv}{dt} \end{aligned}$$

$$\nabla \cdot (\rho \mathbf{v}) = \frac{d}{dt} \left(\frac{1}{2} \rho v^2 \right) - \frac{1}{2} \rho \frac{d}{dt} v^2$$

$$= \frac{1}{2} \rho \frac{d}{dt} v^2$$

$$= \frac{1}{2} \rho \left(v \frac{dv}{dt} + \frac{dv}{dt} v \right)$$

$$= \rho v \frac{dv}{dt}$$

$$= \rho \left(\frac{1}{2} v^2 + \frac{1}{2} v^2 \right) = \rho v^2$$

$$= \frac{1}{2} \rho \frac{d}{dt} v^2$$

$$\frac{d}{dt} \left(\frac{1}{2} \rho v^2 \right) = \frac{1}{2} \rho \frac{d}{dt} v^2$$

$$= \frac{1}{2} \rho \frac{d}{dt} v^2$$

$$\frac{1}{2} \rho \frac{d}{dt} v^2$$

$$= \frac{1}{2} \rho \frac{d}{dt} v^2$$

$$\frac{\partial}{\partial x} \left(\frac{x}{y} \right) = \frac{1}{y} - \frac{x}{y^2} \frac{\partial y}{\partial x}$$

$$\frac{\partial}{\partial y} \left(\frac{x}{y} \right) = -\frac{x}{y^2}$$

$$\frac{\partial}{\partial x} \left(\frac{x}{y} \right) = \frac{1}{y} - \frac{x}{y^2} \frac{\partial y}{\partial x}$$

$$\frac{\partial}{\partial y} \left(\frac{x}{y} \right) = -\frac{x}{y^2}$$

$$\left(\frac{\partial f}{\partial x} \right) + \left(\frac{\partial f}{\partial y} \right) = 0$$

20. $f = x(y - \sqrt{a^2 - x^2})$

$$\frac{\partial f}{\partial x} = y - \sqrt{a^2 - x^2} + \frac{x^2}{\sqrt{a^2 - x^2}}$$

$$\frac{\partial f}{\partial y} = x$$

$$\frac{\partial^2 f}{\partial x^2} = \frac{x}{\sqrt{a^2 - x^2}} + \frac{2x}{\sqrt{a^2 - x^2}} + \frac{x^3}{\sqrt{a^2 - x^2}^3}$$

$$\frac{\partial^2 f}{\partial y^2} = 0$$

$$f = (y - \sqrt{a^2 - x^2})^n$$

$$\frac{\partial f}{\partial x} = \frac{x n}{\sqrt{a^2 - x^2}} (y - \sqrt{a^2 - x^2})^{n-1}$$

$$\frac{\partial^2 f}{\partial x^2} = \frac{n}{\sqrt{a^2 - x^2}} (y - \sqrt{a^2 - x^2})^{n-1} + \frac{x^2 n}{\sqrt{a^2 - x^2}^3} (y - \sqrt{a^2 - x^2})^{n-1} + \frac{n(n-1) x^2}{\sqrt{a^2 - x^2}} (y - \sqrt{a^2 - x^2})^{n-2}$$

$$\frac{\partial}{\partial x} \left(u \xi - \mu \frac{\partial \xi}{\partial x} \right) + \frac{\partial}{\partial y} \left(v \xi - \mu \frac{\partial \xi}{\partial y} \right) + \frac{\partial}{\partial z} \left(w \xi - \mu \frac{\partial \xi}{\partial z} \right) = 0 \quad k$$

$$\frac{\partial}{\partial x} \left(u \xi - \mu \frac{\partial \xi}{\partial x} \right) + \frac{\partial}{\partial y} \left(v \xi - \mu \frac{\partial \xi}{\partial y} \right) + \frac{\partial}{\partial z} \left(w \xi - \mu \frac{\partial \xi}{\partial z} \right) = 0 \quad i$$

$$\frac{\partial}{\partial x} \left(u \eta - \mu \frac{\partial \eta}{\partial x} \right) = \dots \quad j$$

$$\frac{\partial f}{\partial y} = n (y - \sqrt{\dots})^{n-1}$$

$$\frac{\partial^2 f}{\partial y^2} = n(n-1) (y - \sqrt{\dots})^{n-2}$$

$$\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} = \frac{n(a^2 - x^2 + x^2)(y - \sqrt{\dots})^{n-1}}{\sqrt{\dots}^3} + \frac{n(n-1)x^2(y - \sqrt{\dots})^{n-2}}{a^2 - x^2} + \frac{n(n-1)(y - \sqrt{\dots})^{n-2}}{\dots}$$

$$= n(y - \sqrt{\dots})^{n-2} \left[\frac{a^2 y - a}{\sqrt{\dots}^3} + \frac{n x^2}{a^2 - x^2} + n - 2 \right]$$

$n > 2$

$$\text{ex. } y = x^2(y-a)^3$$

$$f = 2(y-a)^3 + 6x^2(y-a)$$

$$\frac{\partial f}{\partial x} = 12x(y-a) \quad \frac{\partial f}{\partial y} = 6(y-a)^2 + 6x^2$$

$$\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} = 12(y-a) + 12(y-a) = 24(y-a)$$

$$\frac{\partial \varphi}{\partial x} [2x(y-a)] + \frac{\partial \varphi}{\partial y} [(y-a)^2 + x^2] = 4(y-a) -$$

$$+ 3x^2(y-a)^2 [2x(y-a) + 2x(y-a) [(y-a)^2 + x^2]]$$

$$\frac{\partial \varphi}{\partial x} 2x(y-a) + \frac{\partial \varphi}{\partial y} [(y-a)^2 + x^2] = 4(y-a) - 6x^3(y-a)^3 + 2x(y-a)^3 + 2x^3(y-a)$$

$$= 2(y-a) [2 + [(y-a)^2 + x^2 - 3x^2(y-a)^2] x]$$

$$P \frac{\partial \varphi}{\partial x} + Q \frac{\partial \varphi}{\partial y} = R$$

$$\frac{dx}{P} = \frac{dy}{Q} = \frac{d\varphi}{R}$$

$$\frac{dx}{2x(y-a)} = \frac{dy}{(y-a)^2 + x^2} \quad \left[\frac{y-a}{2x} + \frac{x}{2(y-a)} \right] dx = dy$$

$$\frac{y-a}{x} = 2 \quad y-a = 2x \quad dy = 2dx + x dz$$

$$(2 + \frac{1}{2}) dx = 2(x dx + x dz)$$

$$dx = 2^2 dx + 2x 2 dz$$

$$(1-2^2) dx = 2x 2 dz$$

$$\frac{dx}{x} = \frac{2z dz}{1-2^2}$$

$$2y x = 2y (1-2^2)$$

$$\frac{A}{x} = [1 - (\frac{y-a}{x})^2]$$

$$A = [x^2 - y^2 + 2ay - a^2]$$

$$x^2 - (y-a)^2 = Ax$$

$$x dx = (y-a) dy$$

$$(2x - A) dx = 2(y-a) dy$$

$$\frac{dx}{dy} = \frac{y-a}{2x}$$

$$\frac{dx}{dy} = \frac{(y-a) 2x}{2x^2 + \frac{y-a}{2} 2ay + a^2}$$

$$(y-a)^2 = x^2 - Ax \quad A = f(y)$$

$$R = 2\sqrt{x^2 - Ax} \left[2 + x \left[-Ax - 3x^2(x^2 - Ax) \right] \right]$$

$$= 2\sqrt{x^2 - Ax} \left[2 - Ax^2 - 3x^5 + 3Ax^3 \right]$$

$$\frac{dx}{2x\sqrt{x^2 - Ax}} = \frac{dy}{\left[2 - \right]}$$

$$dy = dx \left[\frac{2}{x} - Ax - 3x^4 + 3Ax^3 \right] \text{ jisch } A = \text{const}$$

$$y = \ln x - \frac{Ax^2}{2} - \frac{3}{5}x^5 + \frac{3}{4}Ax^4 + D = f(y)$$

$$u = \frac{1}{x} + 3x^2(y-a)^2$$

$$\frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} = 0!$$

$$\text{Limit} := -\frac{1}{x^2} + \frac{\partial^2 D}{\partial y^2} = 0$$

$$D = \frac{y^4}{2x^2}$$

$$v = \frac{y}{x^2} - 2x(y-a)^3$$

$$\frac{u}{v} = \frac{\frac{y}{x^2} - 2x(y-a)^3}{\frac{1}{x} + 3x^2(y-a)^2} = \frac{y - 2x^3(y-a)^3}{x^2 + 3x^4(y-a)^2}$$

$$\sqrt{u^2 + v^2} =$$

angenommen, u und v werden an der Kreisperipherie $= 0$ von ~~der~~ ^{abhängen} ~~der~~ ^{Ordy}

$$u = (a-r)^n f(x,y) \quad \text{2. par. in } x, y$$

$$v = (a-r)^m F(x,y) \quad \text{Für } x, y = \infty: \quad u = c \quad \text{sonst } f(x,y) = \frac{c}{r^n}$$

$$\text{(unpar.)} - x^2 \quad v = 0 \quad \text{Für } x, y = \infty \quad F(x,y) = \frac{1}{r^{m+k}}$$

$$\{ = \frac{\partial u}{\partial y} - \frac{\partial v}{\partial x}$$

$$\{ = -n(a-r)^{n-1} \frac{y}{r} f(x,y) + (a-r)^n \frac{\partial f}{\partial y} -$$

$$+ m(a-r)^{m-1} \frac{x}{r} F(x,y) - (a-r)^m \frac{\partial F}{\partial x}$$

2. B. Probe mit: $n = m = 1$

$$\{ = -\frac{y}{r} f + (a-r) \frac{\partial f}{\partial y}$$

$$+ \frac{x}{r} F - (a-r) \frac{\partial F}{\partial x}$$

Denn $\{ \geq 0$ an der Oberkante
 $\{ = 0$ für $y = 0$

$$\frac{\partial \{ }{\partial x} = \frac{x y}{r^3} f - \frac{y}{r} \frac{\partial f}{\partial x} - \frac{x}{r} \frac{\partial f}{\partial y} + (a-r) \frac{\partial^2 f}{\partial x \partial y} +$$

$$+ \frac{1}{r} F - \frac{x^2}{r^3} F + 2 \frac{x}{r} \frac{\partial F}{\partial x} - (a-r) \frac{\partial^2 F}{\partial x^2}$$

$$\underbrace{\quad}_{\frac{\partial^2}{\partial x^2} F}$$

$$\frac{\partial^2 \{ }{\partial x^2} = \frac{y}{r^3} f - 3 \frac{x^2 y}{r^5} f + \frac{x y}{r^3} \frac{\partial f}{\partial x} + \frac{x y}{r^3} \frac{\partial f}{\partial x} - \frac{y}{r} \frac{\partial^2 f}{\partial x^2} - \frac{1}{r} \frac{\partial f}{\partial y} + \frac{x^2}{r^3} \frac{\partial f}{\partial y} -$$

$$- \frac{x}{r} \frac{\partial^2 f}{\partial x \partial y} - \frac{x}{r} \frac{\partial^2 f}{\partial x \partial y} + (a-r) \frac{\partial^3 f}{\partial x^2 \partial y} - \frac{3 y^2 x}{r^5} F + \frac{y^2}{r^3} \frac{\partial F}{\partial x} + \frac{2}{r} \frac{\partial F}{\partial x} -$$

$$- \frac{2 x^2}{r^3} \frac{\partial F}{\partial x} + \frac{2 x}{r} \frac{\partial^2 F}{\partial x^2} + \frac{x}{r} \frac{\partial^2 F}{\partial x^2} - (a-r) \frac{\partial^3 F}{\partial x^3}$$

$$= \frac{(y^2 - 2xy)}{r^5} f + \frac{2xy}{r^3} \frac{\partial f}{\partial x} - \frac{y}{r} \frac{\partial^2 f}{\partial x^2} - \frac{y^2}{r^3} \frac{\partial^2 f}{\partial y^2} - \frac{2x}{r} \frac{\partial^2 f}{\partial x \partial y} + (a-r) \frac{\partial^3 f}{\partial x^2 \partial y} -$$

$$- \frac{3y^2 x}{r^5} F + \frac{(x^2 + 2xy)}{r^3} \frac{\partial F}{\partial x} + \frac{3x}{r} \frac{\partial^2 F}{\partial x^2} - (a-r) \frac{\partial^3 F}{\partial x^2 \partial y}$$

$$\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} = -\frac{f}{r^3} + \frac{2xy}{r^3} \left(\frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} \right) - \frac{y}{r} \frac{\partial^2 f}{\partial x^2} - \frac{x}{r} \frac{\partial^2 f}{\partial y^2} - \frac{y^2}{r^3} \frac{\partial^2 f}{\partial y^2} - \frac{x^2}{r^3} \frac{\partial^2 f}{\partial x^2} -$$

$$- \frac{2(x+y)}{r} \frac{\partial^2 f}{\partial x \partial y} + (a-r) \left(\frac{\partial^3 f}{\partial x^2 \partial y} + \frac{\partial^3 f}{\partial y^2 \partial x} \right) - \frac{3(y+x)xy}{r^5} F +$$

$$+ \frac{2y^2 - x^2}{r^3} \frac{\partial^2 F}{\partial x^2} + \frac{2x^2 - y^2}{r^3} \frac{\partial^2 F}{\partial y^2} + \frac{3x}{r} \frac{\partial^2 F}{\partial x^2} + \frac{3y}{r} \frac{\partial^2 F}{\partial y^2} - (a-r) \left(\frac{\partial^3 F}{\partial x^3} + \frac{\partial^3 F}{\partial y^3} \right)$$

$$u = (a-r) f \quad v = (a-r) F$$

$$= \frac{\partial \varphi}{\partial x} + \frac{\partial \psi}{\partial y} \quad = \frac{\partial \varphi}{\partial y} - \frac{\partial \psi}{\partial x}$$

$$(a-r) \left(\frac{\partial f}{\partial x} + \frac{\partial F}{\partial y} \right) = \frac{x f + y F}{r} \quad \left. \vphantom{\frac{x f + y F}{r}} \right\} \text{Irrecompressibility}$$

$$\varphi = \text{real part of } \Phi(x+iy)$$

~~General problem in two dimensions~~

$$\frac{\partial \varphi}{\partial x} = \frac{\mu \left(\frac{\partial^2 \varphi}{\partial x^2} + 2 \frac{\partial^2 \varphi}{\partial x \partial y} + \frac{\partial^2 \varphi}{\partial y^2} \right) - \frac{\partial \varphi}{\partial y} \left(\frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial x \partial y} \right) + \frac{\partial \varphi}{\partial x} \left(\frac{\partial^2 \varphi}{\partial x \partial y} + \frac{\partial^2 \varphi}{\partial y^2} \right)}{\underbrace{\frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial x \partial y}}_{\Phi_1}} - \frac{\frac{\partial \varphi}{\partial y} \left(\frac{\partial^2 \varphi}{\partial x \partial y} + \frac{\partial^2 \varphi}{\partial y^2} \right)}{\underbrace{\frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial x \partial y}}_{\Phi_2}}$$

$$\frac{\partial^2 \varphi}{\partial x^2} = \frac{\partial \Phi_1}{\partial x} - \frac{\partial^2 \varphi}{\partial x \partial y} \Phi_2 - \frac{\partial \varphi}{\partial y} \frac{\partial \Phi_2}{\partial x}$$

$$u = \frac{\mu \left(\frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} \right) - v \frac{\partial^2 \varphi}{\partial x \partial y}}{\frac{\partial \varphi}{\partial x}} = -\xi + \frac{\partial u}{\partial y}$$

$$\frac{\partial u}{\partial x} = \frac{\partial \Phi_1}{\partial x} - v \frac{\partial \Phi_2}{\partial x} - \Phi_2 \frac{\partial v}{\partial x}$$

$$\frac{\partial u}{\partial y} = \frac{\partial \Phi_1}{\partial y} - v \frac{\partial \Phi_2}{\partial y} - \Phi_2 \frac{\partial v}{\partial y}$$

$$\frac{\partial u}{\partial x} = \frac{\partial \Phi_1}{\partial x} - v \frac{\partial \Phi_2}{\partial x} + \Phi_2 \xi - \Phi_2 \frac{\partial \Phi_1}{\partial y} + v \Phi_2 \frac{\partial \Phi_2}{\partial y} - \Phi_2 \frac{\partial v}{\partial y} = \frac{\partial u}{\partial x}$$

$$\frac{\partial u}{\partial x} [1 - \Phi_2] = \frac{\partial \Phi_1}{\partial x} + \Phi_2 \xi - \Phi_2 \frac{\partial \Phi_1}{\partial y} + v \left[\Phi_2 \frac{\partial \Phi_2}{\partial y} - \frac{\partial \Phi_2}{\partial x} \right]$$

$$\nabla^2 v = 0$$

$$\zeta = \frac{\partial u}{\partial y}$$

$$\frac{\partial u}{\partial x} = 0$$

~~$$\nabla^2 u = 0$$~~

~~$$u \frac{\partial^2 u}{\partial x^2 \partial y} + \frac{\partial^3 u}{\partial y^3} = 0$$~~

$$u = Ay^2 + By + C$$

With neglect of inertia-
terms:

$$\nabla p - \mu \nabla^2 \zeta = 0$$

$$\frac{\partial p}{\partial x} = \mu \left(\frac{\partial^2 \zeta}{\partial x^2} + \frac{\partial^2 \zeta}{\partial y^2} \right)$$

$$\frac{\partial p}{\partial y} = \mu \left(\frac{\partial^2 \zeta}{\partial x^2} + \frac{\partial^2 \zeta}{\partial y^2} \right)$$

$$\left. \begin{aligned} \frac{\partial^3 \zeta}{\partial x^2 \partial y} + \frac{\partial^3 \zeta}{\partial y^3} - \frac{\partial^2 \zeta}{\partial x^2} - \frac{\partial^2 \zeta}{\partial y^2} &= 0 \end{aligned} \right\}$$

$$= \frac{\partial^2 \zeta}{\partial x^2} + \frac{\partial^2 \zeta}{\partial y^2} = 0$$

$$\zeta = \text{Re } \Phi(x+iy) = \frac{\partial \psi}{\partial x} + \frac{\partial \psi}{\partial y}$$

↑
will work

above:

$$\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} = 0$$

~~$$u = \frac{\partial \psi}{\partial y} \quad v = -\frac{\partial \psi}{\partial x}$$~~

$$\frac{\partial \psi}{\partial x} = \int \frac{f(x,y)}{r^2} dx dy$$

~~$$(a-r)f = 2 \frac{\partial f}{\partial y} \quad \frac{\partial \psi}{\partial x} = (a-r) \frac{\partial f}{\partial x} + \frac{r}{2} f = (a-r) \frac{\partial f}{\partial y} - \frac{r}{2} f$$~~

~~$$F = \frac{\partial \psi}{\partial y} \quad a-r$$~~

~~$$\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y}$$~~



$$\int \frac{dx}{\sqrt{x^2 - r^2}} = \ln \left| \frac{dx}{\sqrt{1 + \frac{2}{\sqrt{-1}}}} \right| = \ln(z + \sqrt{x^2 - r^2}) = \ln(z + r)$$

$$\int \log r \cdot f(x,y) dx dy$$

$$V = \frac{1}{2} \int \log(x+iy) \cdot f(x,y) dx dy$$

$$\frac{\partial V}{\partial x} = \frac{1}{2} \int \frac{x \cdot f}{r^2} + \log r \cdot \frac{\partial f}{\partial x}$$

$$\frac{\partial V}{\partial x} = \frac{1}{2} \left(\frac{f}{r^2} + \frac{1}{r^3} + 2x \frac{\partial f}{\partial x} + \log r \cdot \frac{\partial f}{\partial x} \right)$$

$$\frac{1}{r} \frac{\partial(rv)}{\partial r} = \frac{\partial v}{\partial r} + \frac{v}{r} = \frac{c g a^2}{r^2}$$

$$r v^k = \frac{c}{r^k}$$

$$r = c \rho^k$$

$$c k \rho^{k-1} \frac{\partial \rho}{\partial r} + \frac{c \rho^k}{r} = \frac{c g a^2}{r^2}$$

$$c k \rho^{k-2} \frac{d\rho}{dr} + \frac{c \rho^{k-1}}{r} = \frac{g a^2}{r^2}$$

$$c k \rho^{k-1} d\rho = \left(\frac{g a^2}{r^2} - \frac{c \rho^k}{r} \right) dr = \frac{dr}{r^2} (g a^2 - c r \rho^k)$$

$$\rho^{k-1} = z$$

$$\frac{k}{k-1} \frac{dz}{dr} + \frac{z}{r} = \frac{g a^2}{c r^2}$$

$$\frac{z}{r} = \frac{A}{r}$$

$$z = \frac{A}{r} + \frac{1}{r} \ln r + \frac{C r^2}{2} + D$$

$$\frac{dz}{dr} = \frac{A}{r^2} + \frac{1}{r} + C r$$

$$-\frac{k}{k-1} A + A = \frac{g a^2}{c}$$

$$A = \frac{g a^2}{c} \frac{1}{1 - \frac{k}{k-1}}$$

$$= \frac{g a^2}{c} (1 - k)$$

$$\rho^{k-1} = \frac{g a^2 (1-k)}{c} \frac{1}{r}$$

$$\rho = \left(\frac{g a^2 (1-k)}{c} \right)^{\frac{1}{k-1}} \frac{1}{r^{\frac{1}{k-1}}} + 2 C r \ln r + \frac{C}{2} + \frac{A}{r^2} + \ln r + C r \ln r + \frac{D}{r} = \frac{g a^2}{c r^2}$$

$$2 = u v \quad \frac{du}{dr} v + u \frac{dv}{dr}$$

$$\underbrace{\left(\frac{k}{k-1} \frac{dv}{dr} + \frac{v}{r} \right) u + \frac{k}{k-1} v \frac{du}{dr}}_{=0} = \frac{g a^2}{c r^2}$$

$$\frac{k}{k-1} \frac{dv}{v} + \frac{dr}{r} = 0$$

$$v^{\frac{k}{k-1}} r^{\frac{k-1}{k}} = b$$

$$v = b^{\frac{k-1}{k}} r^{\frac{k-1}{k}}$$

$$du = \frac{k-1}{k} \frac{g a^2}{c} b^{\frac{k-1}{k}} \frac{1}{r^{\frac{k+1}{k}}} dr$$

$$u = \frac{k-1}{k} \frac{g a^2}{c} b^{\frac{k-1}{k}} \frac{1}{-\frac{k+1}{k} r^{\frac{k+1}{k}}} + C$$

$$2 = \frac{(k-1)}{k} \frac{g a^2}{c} \frac{1}{r} + C r^{\frac{1-k}{k}} = p^{k-1}$$

~~$$\frac{k}{k-1} \left(-\frac{k-1}{k} \frac{g a^2}{c} \frac{1}{r^2} + C \frac{1-k}{r^{\frac{k+1}{k}}} \right) + \frac{k-1}{k} \frac{g a^2}{c} \frac{1}{r} + C r^{\frac{1-k}{k}} = \frac{g a^2}{c r^2}$$~~

~~$$\frac{k}{k-1} \left(-\frac{k-1}{k} \frac{g a^2}{c} \frac{1}{r^2} + C \frac{1-k}{r^{\frac{k+1}{k}}} \right) + \frac{k-1}{k} \frac{g a^2}{c} \frac{1}{r} + C r^{\frac{1-k}{k}} = \frac{g a^2}{c r^2}$$~~

~~$$p_0^{k-1} = (1-k) \frac{g a^2}{c} + C a^{\frac{k-1}{k}}$$~~

$$C = \left[p_0^{k-1} + (k-1) \frac{g a^2}{c} \right] a^{\frac{k-1}{k}}$$

$$p^{k-1} = (1-k) \frac{g a^2}{c} \frac{1}{r} + \left[p_0^{k-1} + (k-1) \frac{g a^2}{c} \right] \left(\frac{r}{a} \right)^{\frac{1-k}{k}}$$

$$= p_0^{k-1} \left(\frac{r}{a} \right)^{\frac{1-k}{k}} + (1-k) \frac{g a^2}{c} \left[\frac{a}{r} - \left(\frac{r}{a} \right)^{\frac{1-k}{k}} \right]$$

$$= p_0^{k-1} \left(\frac{r}{a} \right)^{\frac{1-k}{k}} + (1-k) \frac{g a^2}{c r} \left[1 - \left(\frac{r}{a} \right)^{\frac{1}{k}} \right]$$

$$RT = p v = \frac{p}{\rho} = c p^{k-1} = \uparrow$$

~~$$n \propto \sqrt{T} \Rightarrow n \propto p^{\frac{k-1}{2k}} = \frac{1}{\sqrt{p}} \Rightarrow p \propto \frac{1}{n^2}$$~~

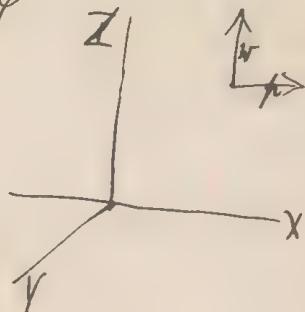
Transformation of general special equations (for rotational ~~body~~ symmetry) in polar coordinates r, θ, φ

$$z = \text{axis of symmetry} = r \cos \theta$$

$$x = r \sin \theta \cos \varphi$$

$$y = r \sin \theta \sin \varphi$$

Note: ~~$\frac{\partial u}{\partial \varphi} = \frac{\partial u}{\partial \varphi} = \frac{\partial u}{\partial \varphi}$~~



Equation of Continuity: $\frac{\partial u}{\partial r} + \frac{\partial v}{\partial \theta} + \frac{\partial w}{\partial \varphi} = 0$

$$\frac{\partial u}{\partial r} \sin \theta \cos \varphi + \frac{\partial u}{\partial \theta} \frac{\cos \theta \cos \varphi}{r} - \frac{\partial u}{\partial \varphi} \frac{\sin \varphi}{r \sin \theta} = \frac{\partial u}{\partial x}$$

$$u = 6 \sin \theta \cos \varphi$$

$$\frac{\partial u}{\partial r} \sin \theta \sin \varphi + \frac{\partial u}{\partial \theta} \frac{\cos \theta \sin \varphi}{r} + \frac{\partial u}{\partial \varphi} \frac{\cos \varphi}{r \sin \theta} = \frac{\partial u}{\partial y}$$

$$v = 6 \sin \theta \sin \varphi$$

$$\frac{\partial u}{\partial r} \cos \theta - \frac{\partial u}{\partial \theta} \frac{\sin \theta}{r} = \frac{\partial u}{\partial z}$$

$$w = 6 \cos \theta$$

New variable: $\rho = \sqrt{u^2 + v^2}$ $\frac{\partial \rho}{\partial \varphi} = 0$

$$u = \rho \cos \varphi$$

$$v = \rho \sin \varphi$$

$$\frac{\partial w}{\partial \varphi} = 0$$

$$\frac{\partial u}{\partial x} = \frac{\partial \rho}{\partial r} \sin \theta \cos \varphi - \frac{\partial \rho}{\partial \theta} \frac{\cos \theta \cos \varphi}{r} + \frac{\partial \rho}{\partial \varphi} \frac{\sin \varphi}{r \sin \theta} + \rho \frac{\sin \varphi}{r \sin \theta}$$

$$\frac{\partial u}{\partial y} = \frac{\partial \rho}{\partial r} \sin \theta \sin \varphi + \frac{\partial \rho}{\partial \theta} \frac{\cos \theta \sin \varphi}{r} - \frac{\partial \rho}{\partial \varphi} \frac{\cos \varphi}{r \sin \theta} - \rho \frac{\cos \varphi}{r \sin \theta}$$

$$\frac{\partial u}{\partial z} = \frac{\partial \rho}{\partial r} \cos \theta - \frac{\partial \rho}{\partial \theta} \frac{\sin \theta}{r}$$

$$\frac{\partial v}{\partial x} = \frac{\partial}{\partial r} \sin \theta \cos \varphi \sin \rho + \frac{\partial}{\partial \theta} \cos \theta \cos \varphi \sin \rho - \frac{\partial}{\partial \varphi} \sin \theta \sin \rho \cos \rho$$

$$\frac{\partial v}{\partial y} = \frac{\partial}{\partial r} \sin \theta \sin \varphi + \frac{\partial}{\partial \theta} \cos \theta \sin \varphi + \frac{\partial}{\partial \varphi} \sin \theta \cos \rho$$

$$\frac{\partial v}{\partial z} = \frac{\partial}{\partial r} \cos \theta \sin \varphi - \frac{\partial}{\partial \theta} \sin \theta \sin \varphi$$

$$\frac{\partial w}{\partial x} = \frac{\partial w}{\partial r} \sin \theta \cos \varphi + \frac{\partial w}{\partial \theta} \cos \theta \cos \varphi$$

$$\frac{\partial w}{\partial y} = \frac{\partial w}{\partial r} \sin \theta \sin \varphi + \frac{\partial w}{\partial \theta} \cos \theta \sin \varphi$$

$$\frac{\partial w}{\partial z} = \frac{\partial w}{\partial r} \cos \theta - \frac{\partial w}{\partial \theta} \sin \theta$$

$$\frac{\partial u}{\partial x} = \frac{\partial \phi}{\partial r} \sin \theta \cos \varphi + \frac{\phi}{r} \cos \theta \cos \varphi + \frac{\phi}{r} \sin \theta \sin \varphi$$

$$\frac{\partial u}{\partial y} = \frac{\partial \phi}{\partial r} \sin \theta \sin \varphi + \frac{\phi}{r} \cos \theta \sin \varphi + \frac{\phi}{r} \sin \theta \cos \varphi$$

$$\frac{\partial u}{\partial z} = \frac{\partial \phi}{\partial r} \cos \theta + \frac{\phi}{r} \sin \theta$$

$$\frac{\partial u}{\partial y} = \frac{\partial \phi}{\partial r} \sin \theta \sin \varphi + \frac{\phi}{r} (\cos \theta \sin \varphi - \sin \theta \cos \varphi)$$

$$= \sin \theta \sin \varphi \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right)$$

$$\frac{\partial v}{\partial x} = \frac{\partial \phi}{\partial r} \cos \theta \cos \varphi + \frac{\phi}{r} \sin \theta \cos \varphi - \frac{\phi}{r} \sin \theta \sin \varphi$$

$$\frac{\partial v}{\partial y} = \frac{\partial \phi}{\partial r} \cos \theta \sin \varphi + \frac{\phi}{r} \sin \theta \sin \varphi + \frac{\phi}{r} \sin \theta \cos \varphi$$

$$\frac{\partial v}{\partial z} = \frac{\partial \phi}{\partial r} \sin \theta - \frac{\phi}{r} \cos \theta$$

$$\frac{\partial w}{\partial x} = \frac{\partial \phi}{\partial r} \sin \theta \cos \varphi + \frac{\phi}{r} \cos \theta \cos \varphi - \frac{\phi}{r} \sin \theta \sin \varphi$$

$$\frac{\partial u}{\partial x} = \left[\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right] \sin \theta \cos \varphi + \frac{\phi}{r}$$

$$\frac{\partial u}{\partial y} = \left[\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right] \sin \theta \sin \varphi + \frac{\phi}{r}$$

$$\frac{\partial u}{\partial z} = \left[\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right] \cos \theta + \frac{\phi}{r}$$

$$\frac{\partial v}{\partial x} = \left[\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right] \cos \theta \cos \varphi$$

$$\frac{\partial v}{\partial y} = \left[\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right] \cos \theta \sin \varphi$$

$$\frac{\partial v}{\partial z} = \left[\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right] \sin \theta$$

Reduction of general equations to one differential equation

$$\mathbf{b} = \nabla u + \text{curl } \varphi$$

$$\frac{1}{2} \nabla^2 \mathbf{b}^2 + \nabla \mathbf{b} \text{curl } \mathbf{b} = \nabla P - \mu \nabla \text{curl}^2 \mathbf{b}$$

$$\text{curl } \nabla \mathbf{b} \text{curl } \mathbf{b} = -\mu \text{curl}^3 \mathbf{b}$$

$$= (\text{curl } \mathbf{b} \nabla) \mathbf{b} - (\mathbf{b} \nabla) \text{curl } \mathbf{b}$$

$$(\mathbf{b} \nabla) \mathbf{a} = \nabla (\text{curl } \mathbf{a} \cdot \mathbf{b}) - \nabla_a \mathbf{a} b$$

$$\text{curl } \nabla \mathbf{b} \text{curl } \mathbf{b} = \nabla (\text{curl } \mathbf{b} \cdot \mathbf{b}) - \nabla (\text{curl } \mathbf{b})^2 - \nabla_{\text{curl } \mathbf{b}} \mathbf{b} \text{curl } \mathbf{b} + \nabla_{\mathbf{b}} \text{curl } \mathbf{b}$$

~~$$\nabla_{\text{curl } \mathbf{b}} \mathbf{b} = \nabla \left(\frac{1}{2} \mathbf{b}^2 \right) = \nabla \left(\frac{1}{2} (\mathbf{b}_x^2 + \mathbf{b}_y^2 + \mathbf{b}_z^2) \right) = \mathbf{b}_x \nabla \mathbf{b}_x + \mathbf{b}_y \nabla \mathbf{b}_y + \mathbf{b}_z \nabla \mathbf{b}_z = \frac{1}{2} \nabla \mathbf{b}^2$$~~

$$\nabla \frac{\mathbf{b} \text{curl } \mathbf{b}}{\mathbf{b}^2} = \mathbf{b} \text{curl } \mathbf{b} \nabla \frac{1}{\mathbf{b}^2} + \frac{1}{\mathbf{b}^2} \nabla \mathbf{b} \text{curl } \mathbf{b}$$

~~$$= 2 \frac{\mathbf{b} \text{curl } \mathbf{b} \nabla \mathbf{b}}{\mathbf{b}^3}$$~~

$$\nabla \frac{1}{\mathbf{b}^2} = -\frac{2 \mathbf{b} \nabla \mathbf{b}}{\mathbf{b}^3}$$

$$\rho \frac{\partial p}{\partial r} = -\rho \frac{g a^2}{r^2} \quad | \quad \rho v^k = c \quad p = c \rho^k \quad c = \rho_0 v_0^k = \rho_0 \rho_0^{-k}$$

$$k c \rho^{k-1} \frac{\partial p}{\partial r} = -\left(\frac{c}{r^2}\right) g a^2$$

$$k c \rho^{k-2} dp = -\frac{dr}{r^2} g a^2$$

$$k c \frac{\rho^{k-1}}{k-1} = \frac{g a^2}{r} + \text{const}$$

$$k c \frac{\rho_0^{k-1}}{k-1} = g a r + \text{const}$$

$$\frac{k c}{k-1} (\rho^{k-1} - \rho_0^{k-1}) = g a \left(\frac{a}{r} - 1\right)$$

$$R \frac{dT}{dr} = -\frac{k-1}{k} \frac{g a^2}{r^2}$$

$$R(T - T_0) = \frac{k-1}{k} g a \left(\frac{a}{r} - 1\right)$$

$$\text{für } r \rightarrow \infty: \quad \rho^{k-1} = \rho_0^{k-1} - \frac{k-1}{k c} g a$$

$$= \rho_0^{k-1} \left[1 - \frac{k-1}{k \rho_0} g a \right]$$

nicht möglich!

$$\rho_0 = 0.0013$$

$$\mu_0 = 9.8 \times 136 \times 0.76$$

$$g = 9.8$$

$$a = 6366200$$

$$\frac{0.0013 \cdot 9.8 \cdot 6366200}{9.8 \cdot 136 \cdot 0.76}$$

$$r = \frac{a}{1.15}$$

$$\text{Für } p = 0: \quad \frac{k c \rho_0^{k-1}}{k-1} = g a \left(1 - \frac{a}{r}\right)$$

$$\frac{1}{g a} \frac{k}{k-1} \frac{\rho_0}{\rho} = \frac{9.8 \cdot 136 \cdot 0.76}{0.0013 \cdot 9.8 \cdot 6366200} \cdot 1.15$$

$$\delta = \frac{76.7}{126000} = \frac{1}{210}$$

Falls dagegen die Abnahme der Föhne wegen Centrifugalkraft
derselbe wäre (mit wachsender Höhe) wie am Äquator

$$\frac{1}{\rho} \frac{\partial \rho}{\partial r} = - \frac{g a^2}{r^2} + \omega (n-a) = k c \rho^{k-2} \frac{\partial \rho}{\partial r}$$

$$\frac{k c}{k-1} (\rho^{k-1} - \rho_0^{k-1}) = \cancel{\frac{g a^2}{r^2}} + \frac{\omega}{2} (n-a)^2$$

$$= g a \left(\frac{a}{n} - 1 \right)$$

$$= (a-n) \left[\frac{g a}{n} - \frac{\omega}{2} (a+n) \right]$$

$$\omega = \frac{\pi}{2} \frac{1}{365 \cdot 24 \cdot 60 \cdot 60}$$

$$\omega a = \frac{\pi}{2} \frac{6366 \text{ km} \cdot 1066 \text{ km}}{365 \cdot 24 \cdot 3600 \cdot 11} = 53$$

$$= \frac{38 \cdot 55}{22 \cdot 24} = \frac{27}{88} = 0.40$$

Nacht sehr wenig aus.

Obiges nicht ganz genau; eigentlich:

$$\frac{1}{\rho} \frac{\partial \rho}{\partial r} = - \frac{g a^2}{r^2} + \omega r = k c \rho^{k-2} \frac{\partial \rho}{\partial r}$$

$$\frac{k c}{k-1} (\rho^{k-1} - \rho_0^{k-1}) = g a \left(\frac{a}{n} - 1 \right) + \frac{\omega}{2} (n^2 - a^2)$$

Damit p für $r \rightarrow \infty$ $p \rightarrow 0$ wird müsste sein:

75

$$\frac{k-1}{k} a g \frac{p_0}{p_\infty} = 1 \quad \frac{p_0}{p_\infty} = R T_0 = \frac{0.0013}{100} = 0.000013 = 1.3 \cdot 10^{-5}$$

$$\frac{k-1}{k} a g = \frac{0.4}{1.4} \frac{6,366000}{4456} \cdot 98^7 = 17,800,000$$

$$= 18 \cdot 10^6$$

$$\frac{1}{18} 10^{-6} = 5.5 \cdot 10^{-8}$$

Es müsste also die Temperatur $\frac{1}{1200}$ der jetzigen betragen

Dissipation of energy per unit of time:

$$\Phi = -\frac{2}{3} \mu \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)^2 + \mu \left\{ 2 \left[\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial y} \right)^2 + \left(\frac{\partial w}{\partial z} \right)^2 \right] + \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right)^2 + \dots \right\}$$

$$\frac{\partial \rho u}{\partial x} + \dots = 0$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = \frac{1}{\rho} \left[\mu \frac{\partial \rho}{\partial x} + \mu \frac{\partial \rho}{\partial y} + \mu \frac{\partial \rho}{\partial z} \right]$$

$$\text{div}(\rho \mathbf{v}) = \frac{\partial(\rho v)}{\partial r} + 2 \frac{\rho v}{r} = 0 = \rho \underbrace{\left[\frac{d}{dr} \frac{v}{r} + \frac{2v}{r^2} \right]}_{\text{div } \mathbf{v}} + v \frac{d\rho}{dr} = 0$$

$$\frac{d \ln v}{dr} + \frac{2}{r} + \frac{d \ln \rho}{dr} = 0$$

$$\text{div } \mathbf{v} = -\frac{v}{\rho} \frac{d\rho}{dr}$$

$$6\rho + r^2 = \text{const}$$

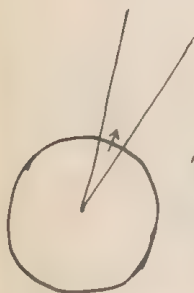
Falls man annimmt, dass der Unterschied zwischen aerostatischen und aerodynamischen Druck vernachlässigbar ist; dagegen der Temperatureinfluss der Bewegung zu berücksichtigen:

$$\left. \begin{aligned} \frac{1}{\rho} \frac{\partial p}{\partial r} &= \frac{g a^2}{r^2} \\ \frac{p}{\rho} &= R \theta \end{aligned} \right\}$$

Betreff θ Annahme:

Es bewege sich von der Erdoberfläche aus ein Luftstrahl mit der Geschw. c aufwärts; welche Temp.verteilung erhält?
 $b = \text{Radius der Schale} \quad b_{\text{a}} = c$

Arbeit = Ausdehnungsarbeit + Reibungsarbeit und Schwerkraft



Falls keine Reibung wäre, so wäre die Arbeit gleich

$$\rho g a^2 dr = \rho \frac{\partial v}{\partial r} + c \frac{\partial \theta}{\partial r} + \mu \frac{\partial}{\partial r}$$

~~Annahme: $\frac{dp}{dr} = \rho g$...~~

$$\frac{dp}{dr} = \frac{\partial p}{\partial r} b$$

$$\frac{R}{\rho} \left[\frac{\partial \theta}{\partial r} \rho + \theta \frac{\partial \rho}{\partial r} \right] = \frac{g a^2}{r^2} \quad \text{I)}$$

$$\begin{aligned} \frac{\partial \theta}{\partial r} &= \frac{A R \theta}{c \rho^2} \frac{\partial \rho}{\partial r} - \frac{\frac{4}{3} \mu \left(\frac{b}{\rho^2 r^2} \right)^2 \left[\frac{\partial \rho}{\partial r} + \frac{3 \rho}{r} \right]^2}{c \rho b} \rho r^2 \\ &= \frac{A R \theta}{c \rho} \frac{\partial \rho}{\partial r} - \frac{4}{3} \frac{A \mu}{c} \frac{b}{r^2 \rho^4} \left[\frac{\partial \rho}{\partial r} + \frac{3 \rho}{r} \right]^2 \quad \text{II)} \end{aligned}$$

Work done by internal friction:

$$\Phi = -\frac{2}{3}\mu \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)^2 + \mu \left[2 \left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial y} \right)^2 + \left(\frac{\partial w}{\partial z} \right)^2 + \dots \right]$$

$$2 \left[\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right]^2 \left[\sin^4 \theta (\omega^4 \varphi + \sin^2 \varphi) + \omega^4 \theta \right] + 6 \frac{\phi^2}{r^2} + 4 \frac{\phi}{r} \left[\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right] \dots$$

$$+ 4 \left[\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right]^2 \left[\sin^4 \theta \cos^2 \theta + \sin^4 \theta \sin^2 \varphi \omega^2 \varphi \right] - \frac{2}{3} \left[\frac{\partial \phi}{\partial r} + 2 \frac{\phi}{r} \right]^2$$

$$= 2 \left[\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right]^2 \left[\underbrace{\sin^4 \theta [\omega^4 \varphi + 2 \sin^2 \varphi \omega^2 \varphi + \sin^4 \varphi] + 2 \sin^2 \theta \cos^2 \theta + \omega^4 \theta}_{=1} \right] + \dots$$

$$= 2 \left[\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right]^2 + 6 \frac{\phi^2}{r^2} + 4 \frac{\phi}{r} \left[\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right] - \frac{2}{3} \left[\frac{\partial \phi}{\partial r} + 2 \frac{\phi}{r} \right]^2$$

$$= \left(\frac{\partial \phi}{\partial r} \right)^2 \left[2 - \frac{2}{3} \right] + \frac{\partial \phi}{\partial r} \cdot \frac{\phi}{r} \left[-4 + 4 - \frac{8}{3} \right] + \frac{\phi^2}{r^2} \left[2 + 6 - 4 - \frac{8}{3} \right]$$

$$= \left(\frac{\partial \phi}{\partial r} \right)^2 \frac{4}{3} - \frac{\partial \phi}{\partial r} \cdot \frac{\phi}{r} \frac{8}{3} + \frac{\phi^2}{r^2} \frac{4}{3} = \frac{4}{3} \left[\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right]^2$$

Equation of continuity: $\rho \phi \cdot r^2 = \text{const} = \rho_0 \phi_0 a^2 = b$

$$\phi = \frac{b}{\rho r^2} \quad \frac{\partial \phi}{\partial r} = -\frac{b}{\rho^2 r^2} \frac{\partial \rho}{\partial r} - 2 \frac{b}{\rho r^3}$$

$$\Phi = -\frac{4}{3} \mu \left[\frac{b}{\rho^2 r^2} \frac{\partial \rho}{\partial r} + \frac{2b}{\rho r^3} + \frac{b}{\rho r^3} \right]^2 = -\frac{4}{3} \left(\frac{b}{\rho^2 r^2} \right)^2 \mu \left[\frac{\partial \rho}{\partial r} + 3 \frac{\rho}{r} \right]^2$$

$$\frac{\partial \rho}{\partial r} + 3 \frac{\rho}{r} = \frac{1}{r^3} \frac{\partial (\rho r^3)}{\partial r}$$

Transformations of Motion ~~for~~ for spherical symmetry:

Continuity: $\rho \delta r^2 = \text{const.}$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = \lambda \frac{1}{\rho} \frac{\partial \rho}{\partial x} + \frac{\mu}{\rho} \frac{\partial \rho}{\partial y} + \frac{\nu}{\rho} \frac{\partial \rho}{\partial z}$$

$$\delta \left(\frac{\partial \delta}{\partial r} - \frac{\delta}{r} \right) \sin^3 \theta \cos \varphi + \dots$$

$$+ \frac{\delta^2}{r} \sin \theta \cos \varphi = \delta \left(\frac{\partial \delta}{\partial r} - \frac{\delta}{r} \right) \sin \theta \cos \varphi + \frac{\delta^2}{r} \sin \theta \cos \varphi$$

$$= \delta \frac{\partial \delta}{\partial r} \sin \theta \cos \varphi$$

$$\text{div } \delta = -\frac{\delta}{\rho} \frac{\partial \rho}{\partial r}$$

$$\frac{\partial \text{div } \delta}{\partial x} = \frac{\partial \text{div } \delta}{\partial r} \frac{\partial r}{\partial x} \sin \theta \cos \varphi$$

$$= -\frac{\partial}{\partial r} \left(\frac{\delta}{\rho} \frac{\partial \rho}{\partial r} \right)$$

$$\frac{\partial^2 u}{\partial x^2} = \sin \theta \cos \varphi \left[\frac{\partial^2 \delta}{\partial r^2} - \frac{1}{r} \frac{\partial \delta}{\partial r} + \frac{\delta}{r^2} \right] \sin^2 \theta \cos \varphi + \frac{\partial \delta}{\partial r} \frac{1}{r} - \frac{\delta}{r^2}$$

$$\frac{\partial^2 u}{\partial y^2} = \sin \theta \sin \varphi \left[\frac{\partial^2 \delta}{\partial r^2} - \frac{1}{r} \frac{\partial \delta}{\partial r} + \frac{\delta}{r^2} \right] \sin^2 \theta \sin \varphi \cos \varphi$$

$$\frac{\partial^2 u}{\partial z^2} = \cos \theta \left[\dots \right] \sin \theta \cos \theta \cos \varphi$$

$$\nabla^2 u = \left[\frac{\partial^2 \delta}{\partial r^2} - \frac{1}{r} \frac{\partial \delta}{\partial r} + \frac{\delta}{r^2} \right] \sin^2 \theta \cos \varphi + \dots$$

$$= \frac{\partial^2 \delta}{\partial r^2} \sin \theta \cos \varphi$$

$$+ \left[\frac{\partial^2 \delta}{\partial r^2} - \frac{1}{r} \frac{\partial \delta}{\partial r} + \frac{\delta}{r^2} \right] \sin^2 \theta \sin \varphi \cos \varphi + \dots$$

Equation of Motion:



$$\sigma \frac{\partial \sigma}{\partial r} = R - \frac{1}{\rho} \frac{\partial \mu}{\partial r} - \frac{\mu}{3\rho} \frac{\partial}{\partial r} \left(\frac{\sigma}{\rho} \frac{\partial \rho}{\partial r} \right) + \frac{\mu}{\rho} \left[\frac{\partial^2 \sigma}{\partial r^2} + \frac{2}{r} \frac{\partial \sigma}{\partial r} \right]$$

$$+ \left[\frac{2\sigma \omega^2 \sin^2 \theta \cos \theta}{r} \right] \quad \rho \sigma r^2 = c$$

$$\sigma = \frac{c}{\rho r^2}$$

$$\frac{\partial \sigma}{\partial r} = -\frac{2c}{\rho r^3} - \frac{c}{\rho r^2} \frac{\partial \rho}{\partial r}$$

$$\frac{\partial^2 \sigma}{\partial r^2} = + \frac{6c}{\rho r^4} \quad \frac{\partial}{\partial r} \left(\frac{\sigma}{\rho} \frac{\partial \rho}{\partial r} \right) = \frac{\partial \sigma}{\partial r} \frac{1}{\rho} \frac{\partial \rho}{\partial r} - \frac{\sigma}{\rho^2} \left(\frac{\partial \rho}{\partial r} \right)^2 + \frac{\sigma}{\rho} \frac{\partial^2 \rho}{\partial r^2} \dots$$

$$-\frac{2c^2}{\rho^2 r^5} = R - \frac{1}{\rho} \frac{\partial \mu}{\partial r} - \frac{\mu}{3\rho} \left(\frac{\partial}{\partial r} \left(\frac{\sigma}{\rho} \frac{\partial \rho}{\partial r} \right) - \frac{c}{\rho^2 r^2} \left(\frac{\partial \rho}{\partial r} \right)^2 + \frac{c}{\rho^2 r^2} \frac{\partial^2 \rho}{\partial r^2} \right) + \frac{\mu}{\rho} \left(\frac{\partial^2 \sigma}{\partial r^2} + \frac{2}{r} \frac{\partial \sigma}{\partial r} \right)$$

When $\mu \rightarrow 0$: $\rho = \frac{a}{\rho^k} \rho^k \quad \frac{\partial \rho}{\partial r} = \frac{1}{k} \rho^{k-1} \frac{\partial \rho}{\partial r}$

$$\frac{c^2}{\rho^2 r^5} = \frac{1}{2} \frac{\partial^2 \sigma}{\partial r^2} = - \frac{1}{k} \rho^{k-2} \frac{\partial \rho}{\partial r} = - \frac{a k}{k-1} \frac{\partial}{\partial r} (\rho^{k-1})$$

$$\frac{1}{2} \frac{c^2}{\rho^2 r^5} = - \frac{a k}{k-1} \rho^{k-1} + \text{const} \quad \frac{c^2}{2} \left(\frac{1}{\rho^2 r^5} - \frac{1}{\rho^2 r^5} \right) = \frac{1}{k-1} (\rho^{k-1} - \rho_0^{k-1})$$

$$\frac{1}{2} \frac{c^2}{\rho^2 r^5} = \frac{1}{k-1} (\rho^{k-1} - \rho_0^{k-1})$$

$$\sin^3 \theta \cos \theta$$

$$\sin \theta \cos \theta$$

$$\sin \theta \cos^2 \theta$$

$$= \left[\frac{\partial \sigma}{\partial r} - \frac{\sigma}{r} \right] \frac{1}{2} \left[2(\sin \theta \cos^2 \theta \sin^3 \theta \cos \theta + \sin \theta \cos^2 \theta \sin^2 \theta \cos \theta) + \cos \theta (\sin^3 \theta - \sin \theta \cos^2 \theta) + \frac{1}{\sin \theta} (\sin^2 \theta \sin \theta \cos \theta + \sin \theta (\cos^2 \theta - \cos \theta \sin \theta)) \right] =$$

$$\nabla^2 u = \frac{\partial^2 u}{\partial r^2} + \frac{2}{r} \frac{\partial u}{\partial r} + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 u}{\partial \varphi^2} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2} + \frac{\cos \theta}{r^2 \sin \theta} \frac{\partial u}{\partial \theta}$$

$$u = \frac{6}{r^2} \cos \theta$$

$$\nabla^2 u = \cos \theta \sin \theta \left[\frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} \right] + \frac{\cos \theta}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \varphi^2} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} + \frac{\cos^2 \theta}{r^2 \sin \theta} \frac{\partial}{\partial \theta}$$

$$\frac{6}{r^2} \frac{\cos \theta}{\sin^2 \theta} [\cos^2 \theta - 1 - \sin^2 \theta] = -2 \frac{6}{r^2} \cos \theta$$

$$\nabla^2 u = \cos \theta \sin \theta \left[\frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} - \frac{2}{r^2} \right]$$

$$\frac{\partial^2}{\partial r^2} + 2 \frac{\partial}{\partial r} \left(\frac{6}{r} \right) = \frac{\partial}{\partial r} \left(\frac{\partial}{\partial r} + \frac{2}{r} \right) \frac{6}{r} = -\frac{6}{r^3} \frac{\partial}{\partial r}$$

Equation of Motion for spherical symmetry:

$$6 \frac{\partial \phi}{\partial r} = R - \frac{1}{\rho} \frac{\partial \rho}{\partial r} - \frac{\mu}{3\rho} \frac{\partial}{\partial r} \left(\frac{6}{\rho} \frac{\partial \rho}{\partial r} \right) + \frac{\mu}{\rho} \left[\frac{\partial^2 \phi}{\partial r^2} + \frac{2}{r} \frac{\partial \phi}{\partial r} - \frac{2\phi}{r^2} \right]$$

$$\rho \phi r^2 = \text{const}$$

$$> = -\frac{\partial}{\partial r} \left(\frac{6}{\rho} \frac{\partial \rho}{\partial r} \right)$$

$$6 \frac{\partial \phi}{\partial r} = R - \frac{1}{\rho} \frac{\partial \rho}{\partial r} - \frac{4\mu}{3\rho} \frac{\partial}{\partial r} \left(\frac{6}{\rho} \frac{\partial \rho}{\partial r} \right)$$

$$\frac{\partial \theta}{\partial r} + \frac{\theta}{\rho} \frac{\partial \rho}{\partial r} = \frac{g a^2}{R r^2}$$

$$\frac{\partial \theta}{\partial r} = \frac{A R}{c} \frac{\theta}{\rho} \frac{\partial \rho}{\partial r} - \frac{4}{3} \frac{A \mu}{c} \frac{b}{r^2 \rho^4} \left[\frac{\partial \rho}{\partial r} + \frac{3\rho}{r} \right]^2$$

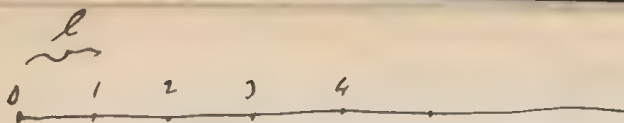
$$\frac{\theta}{\rho} \frac{\partial \rho}{\partial r} \left[1 + \frac{A R}{c} \right] = \frac{g a^2}{R r^2} + \frac{4}{3} \frac{A \mu}{c} \frac{b}{r^2 \rho^4} \left[\frac{\partial \rho}{\partial r} + \frac{3\rho}{r} \right]^2$$

$$\theta = \frac{\rho}{c} \left[\frac{\dots}{\frac{\partial \rho}{\partial r}} \right]$$

$$\frac{\partial \theta}{\partial r} = \frac{1}{c} \left[\dots \right] + \frac{\rho}{c} \left[\frac{\frac{\partial \rho}{\partial r}}{\left(\frac{\partial \rho}{\partial r} \right)^2} + \frac{\rho}{c} \frac{\partial}{\partial r} \left[\dots \right] \right]$$

$$= \frac{g a^2}{R r^2} - \frac{1}{c} \left[\dots \right]$$

$$\left[\frac{g a^2}{R r^2} + \frac{4}{3} \frac{A \mu}{c} \frac{b}{r^2 \rho^4} \left[\frac{\partial \rho}{\partial r} + \frac{3\rho}{r} \right]^2 \right] \left[2 + \rho \frac{\frac{\partial \rho}{\partial r}}{\left(\frac{\partial \rho}{\partial r} \right)^2} \right] + \frac{\rho}{\frac{\partial \rho}{\partial r}} \frac{\partial}{\partial r} \left[\dots \right] - \frac{g a^2}{R r^2} c = 0$$



A cord stretching out from 0 to ∞ ; equal masses 1, 2, ... in equal distances; point 0 begins to move: $G = a \sin t$; how will the motion of agitation ~~represent itself~~ spread out on the chord?

$\frac{d^2 G_0}{dt^2} = f(t)$ the law of force: ~~the~~ attracting forces between the said points

$$\frac{d^2 G_1}{dt^2} = \cancel{f(t)} - f(x_1 - x_0) + f(x_2 - x_1)$$

$$= -k(G_0 - G_1) + k(G_1 - G_2) = k(2G_1 - G_0 - G_2)$$

$$\frac{d^2 G_2}{dt^2} = k(2G_2 - G_1 - G_3) = -k(G_1 - G_2) + k(G_2 - G_3)$$

$$\frac{d^2 G_3}{dt^2} = k(2G_3 - G_2 - G_4) = -k(G_2 - G_3) + k(G_3 - G_4)$$

$$\sum \frac{d^2 G_n}{dt^2} = k(G_1 - G_0)$$

$$\frac{d^4 (G_0 - G_1)}{dt^4} = f + k(G_0 - G_1) - k(G_1 - G_2)$$

$$\frac{d^4 (G_1 - G_2)}{dt^4} = k(-G_0 + 3G_1 - 3G_2 + G_3) = k[-(G_0 - G_1) + 2(G_1 - G_2) - (G_2 - G_3)]$$

$$\frac{d^4 (G_0 - G_1)}{dt^4} = \frac{d^4 f}{dt^4} + k \frac{d^4 (G_0 - G_1)}{dt^4} + k(G_0 - G_1) + 2 \frac{d^4 (G_1 - G_2)}{dt^4} - 2k(G_0 - G_1) - k(G_2 - G_3)$$

$$2 \frac{d^4 G_2}{dt^4} - \frac{d^4 G_1}{dt^4} - \frac{d^4 G_3}{dt^4} = k(4G_2 - 2G_1 - 2G_3 - 2G_0 + G_1 + G_2 - 2G_3 + G_2 + G_4)$$

$$= k(G_0 - 4G_1 + 6G_2 - 4G_3 + G_4) = \frac{1}{k} \frac{d^4 G_2}{dt^4}$$

$$\int \left(\frac{d\delta_n}{dt} \right)^2 dt = ? = t \left(\frac{d\delta_n}{dt} \right)^2 - 2 \int t \frac{d\delta}{dt} \frac{d^2\delta}{dt^2} dt$$

$$= t \left(\frac{d\delta_n}{dt} \right)^2 - 2 t \delta \frac{d^2\delta}{dt^2} + 2 \int \delta \frac{\partial}{\partial t} \left(t \frac{d^2\delta}{dt^2} \right) dt$$

$$\delta_2 \frac{d^2\delta_2}{dt^2} = k (2\delta_2^2 - \delta_1\delta_2 - \delta_2\delta_3)$$

$$\leq \delta \frac{d^2\delta_n}{dt^2} = k (2\delta_2^2 - 2\delta_2\delta_{n-1})$$

$$\delta_3 \frac{d^2\delta_3}{dt^2} = k (2\delta_3^2 - \delta_2\delta_3 - \delta_3\delta_4)$$

$$\delta_3 \frac{d^2\delta_2}{dt^2} = k (2\delta_2\delta_3 - \delta_1\delta_3 - \delta_3^2)$$

$$\delta_2 \frac{d^2\delta_3}{dt^2} = k (2\delta_2\delta_3 - \delta_2^2 - \delta_2\delta_4)$$

$$\int \delta_3 \frac{d^2\delta_2}{dt^2} dt = \left. \delta_3 \frac{d\delta_2}{dt} \right| - \int \frac{d\delta_2}{dt} \frac{d\delta_3}{dt} dt = \left. \delta_3 \frac{d\delta_2}{dt} \right| - \left. \delta_2 \frac{d\delta_3}{dt} \right| + \int \delta_2 \frac{d^2\delta_3}{dt^2} dt$$

$$\leq \int \left(\frac{d\delta}{dt} \right)^2 dt$$

$$\frac{d^2\delta_n}{dt^2} = k (2\delta_n - \delta_{n-1} - \delta_{n+1})$$

$$\frac{d\delta_n}{dt} = k \int (2\delta_n - \delta_{n-1} - \delta_{n+1}) dt = k t (2\delta_n - \delta_{n-1} - \delta_{n+1}) - k \int t \left(2 \frac{d\delta_n}{dt} - \dots \right)$$

$$= k t (2\delta_n - \delta_{n-1} - \delta_{n+1}) - k \frac{t^2}{2} \left(2 \frac{d\delta_n}{dt} - \frac{d\delta_{n-1}}{dt} - \frac{d\delta_{n+1}}{dt} \right) +$$

$$+ k \frac{t^2}{2} \left(2 \frac{d^2\delta_n}{dt^2} - \dots \right) dt$$

$$k [\delta_n - 4(\delta_{n-1} + \delta_{n+1}) + \delta_{n-2} + \delta_{n+2}]$$

$$= k t (2\delta_n - \delta_{n-1} - \delta_{n+1}) \dots + k$$

$$\frac{d\delta_n}{dt} \frac{d^2\delta_n}{dt^2} = k \left[2\delta_n \frac{d\delta_n}{dt} - \delta_{n-1} \frac{d\delta_n}{dt} - \delta_{n+1} \frac{d\delta_n}{dt} \right]$$

$$\frac{1}{2} \frac{d}{dt} \left(\frac{d\delta_n}{dt} \right)^2 = k \left[\frac{d}{dt} (\delta_n^2) - \frac{d\delta_n}{dt} (\delta_{n-1} + \delta_{n+1}) \right]$$

$$\frac{1}{2} \left(\frac{d\delta_n}{dt} \right)^2 = k \left[\frac{\delta_n^2}{\Delta} - \delta_n (\delta_{n-1} + \delta_{n+1}) + \int \delta_n \left(\frac{d\delta_{n-1}}{dt} + \frac{d\delta_{n+1}}{dt} \right) dt \right]$$

$$\leq \frac{1}{2} \left(\frac{d\delta_n}{dt} \right)^2 = k \leq \delta_n^2 - k \left[\underbrace{\left\{ \begin{aligned} &\frac{d\delta_{n-1}}{dt} \delta_{n-2} + \frac{d\delta_{n+1}}{dt} \delta_n \\ &\frac{d\delta_n}{dt} \delta_{n-1} + \frac{d\delta_n}{dt} \delta_{n+1} \\ &\frac{d\delta_{n+1}}{dt} \delta_n + \frac{d\delta_{n+1}}{dt} \delta_{n+2} \\ &\dots \end{aligned} \right\}}_{\geq \delta_n \delta_{n-1}} \right] dt$$

$$\leq \frac{1}{2} \left(\frac{d\delta_n}{dt} \right)^2 = k \left[\leq \delta_n^2 - \leq \delta_n \delta_{n-1} \right] = \Delta$$

$$\leq \delta_n \frac{d^2\delta_n}{dt^2} = 2k \left[\leq \delta_n^2 - \leq \delta_n \delta_{n-1} \right]$$

$$\left| \begin{aligned} \leq \left(\frac{d\delta_n}{dt} \right)^2 - \delta_n \frac{d^2\delta_n}{dt^2} &= 0 \\ \frac{d\delta}{dt} \frac{d^2\delta}{dt^2} - \frac{d\delta}{dt} \frac{d^2\delta}{dt^2} &\leq \delta \frac{d^3\delta}{dt^3} = 0 \end{aligned} \right| \quad \left| \begin{aligned} \frac{\partial L}{\partial x} &\leq \frac{d\delta}{dt} \frac{d^2\delta}{dt^2} \\ &= k \left[\leq 2\delta_n \frac{d\delta_n}{dt} - \dots \right] \end{aligned} \right|$$

$$\begin{aligned} \frac{\partial L}{\partial x} &= 2k \left[\leq \delta_{n+1}^2 - \leq \delta_{n+1} \delta_n - \leq \delta_n^2 + \leq \delta_n \delta_{n-1} \right] \\ &= 2k (\delta_n^2 - \delta_n \delta_{n+1}) \end{aligned}$$

$$\frac{\delta L}{\delta t^2} = k \sum \underbrace{2\left(\frac{d\delta_n}{dt}\right)^2 + 2\delta_n\left(\frac{d\delta_n}{dt}\right)^2}_{- \frac{d\delta_{n-1}}{dt} \frac{d\delta_n}{dt} - \delta_{n-1} \frac{d^2\delta_n}{dt^2} - \frac{d\delta_{n+1}}{dt} \frac{d\delta_n}{dt} - \delta_{n+1} \frac{d^2\delta_n}{dt^2}}$$

$$\begin{aligned} &= 8kL - \sum \frac{d\delta_n}{dt} \left(\frac{d\delta_{n-1}}{dt} + \frac{d\delta_{n+1}}{dt} \right) + \delta_{n-1}(2\delta_{n-2} - \delta_{n-1} - \delta_{n+1}) \\ &\quad + \delta_{n-2}(2\delta_{n-1} - \delta_{n-2} - \delta_n) + \delta_n(2\delta_{n-1} - \delta_{n-2} - \delta_n) \\ &\quad - \sum \delta_{n-1}(2\delta_n - \delta_{n-1} - \delta_{n+1}) + \delta_{n+1}(2\delta_n - \delta_{n-1} - \delta_{n+1}) \\ &\quad + \delta_n(2\delta_{n+1} - \delta_n - \delta_{n+2}) + \delta_{n+2}(2\delta_{n+1} - \delta_n - \delta_{n+2}) \\ &\quad + \delta_{n+1}(2\delta_{n+2} - \delta_{n+1} - \delta_{n+3}) + \delta_{n+3}(2\delta_{n+2} - \delta_{n+1} - \delta_{n+3}) \\ &\quad + \delta_{n+2}(2\delta_{n+3} - \delta_{n+2} - \delta_{n+4}) + \delta_{n+4}(\dots) \end{aligned}$$

$$= 2 \leq \delta_n \delta_{n+1} - \delta_n^2 - \delta_n \delta_{n+2} + 2\delta_n \delta_{n+1} - \delta_n \delta_{n+2} - \delta_n^2$$

$$g_1 = f_1(t) = f_1(0) + t f_1'(0) + \frac{t^2}{2} f_1''(0) + \dots$$

$$= \cancel{g_1(0)} + t \frac{dg_1(0)}{dt} + \frac{t^2}{2} \frac{d^2 g_1(0)}{dt^2} + \frac{t^3}{3!} \frac{d^3 g_1(0)}{dt^3} + \frac{t^4}{4!} \frac{d^4 g_1(0)}{dt^4} + \dots$$

$$\frac{d^2 g_1(0)}{dt^2} = -k g_0(0)$$

$$\frac{d^3 g_1(0)}{dt^3} = -k \left(2 \frac{dg_0(0)}{dt} - \frac{dg_0(0)}{dt} - \frac{dg_0(0)}{dt} \right) = -k \frac{dg_0(0)}{dt}$$

$$\frac{d^4 g_1(0)}{dt^4} = -k \left(2 \frac{d^2 g_0(0)}{dt^2} - \frac{d^2 g_0(0)}{dt^2} - \frac{d^2 g_0(0)}{dt^2} \right) =$$

$$= +2 k^2 g_0(0) + k \frac{d^2 g_0(0)}{dt^2}$$

$$\frac{d^5}{dt^5} = 2 k^2 \frac{dg_0}{dt} + k \frac{d^3 g_0}{dt^3}$$

$$\frac{d^6}{dt^6} = k \left[2 \frac{d^3 g_0}{dt^3} - \frac{d^3 g_0}{dt^3} - \frac{d^3 g_0}{dt^3} \right] = 4 k^3 g_0 + 2 k^2 \frac{d^2 g_0}{dt^2} - k \frac{d^4 g_0}{dt^4}$$

$$\frac{d^2 g_1(0)}{dt^2} = \cancel{0} = \frac{d^2 g_3(0)}{dt^2} \quad \text{etc.} \quad = 3 k^3 g_0 + 2 k^2 \frac{d^2 g_0}{dt^2} - k \frac{d^4 g_0}{dt^4}$$

$$\frac{d^7}{dt^7} = k \left[2 \frac{d^4 g_0}{dt^4} - \frac{d^4 g_0}{dt^4} - \frac{d^4 g_0}{dt^4} \right] = 4 k^3 \frac{dg_0}{dt} + 2 k^2 \frac{d^3 g_0}{dt^3} - k \frac{d^5 g_0}{dt^5} - k^3 \frac{dg_0}{dt}$$

$$= 3 k^3 \frac{dg_0}{dt} + 2 k^2 \frac{d^3 g_0}{dt^3} - k \frac{d^5 g_0}{dt^5}$$

$$\frac{d^8}{dt^8} = k \left[2 \frac{d^5 g_0}{dt^5} - \frac{d^5 g_0}{dt^5} - \frac{d^5 g_0}{dt^5} \right] = 6 k^4 g_0 + 4 k^3 \frac{d^2 g_0}{dt^2} - 2 k^2 \frac{d^4 g_0}{dt^4} + k^3 \frac{d^3 g_0}{dt^3} - k \frac{d^6 g_0}{dt^6}$$

$$= 6 k^4 g_0 + 5 k^3 \frac{d^2 g_0}{dt^2} - 2 k^2 \frac{d^4 g_0}{dt^4} - k \frac{d^6 g_0}{dt^6}$$

$$\frac{d^2 \delta_2}{dt^2}(0) = 0$$

$$\frac{d^3 \delta_2}{dt^3}(0) = k \left(2 \frac{d\delta_1}{dt} - \frac{d\delta_1}{dt} - \frac{d\delta_1}{dt} \right) = 0$$

$$\frac{d^4 \delta_2}{dt^4}(0) = k \left(2 \frac{d^2 \delta_1}{dt^2} - \frac{d^2 \delta_1}{dt^2} - \frac{d^2 \delta_1}{dt^2} \right) = +k^2 \delta_0(0)$$

$$\frac{d^5 \delta_2}{dt^5}(0) = k \left(2 \frac{d^3 \delta_1}{dt^3} - \frac{d^3 \delta_1}{dt^3} - \frac{d^3 \delta_1}{dt^3} \right) = +k^2 \frac{d\delta_0}{dt}(0)$$

$$\frac{d^6 \delta_2}{dt^6}(0) = k \left(2 \frac{d^4 \delta_1}{dt^4} - \frac{d^4 \delta_1}{dt^4} - \frac{d^4 \delta_1}{dt^4} \right) = 2k^3 \delta_0(0) - 2k^3 \delta_0(0) - k^2 \frac{d^2 \delta_0}{dt^2}(0)$$

$$d7 = k \left(2 \frac{d^5 \delta_1}{dt^5} - \frac{d^5 \delta_1}{dt^5} - \frac{d^5 \delta_1}{dt^5} \right) = 2k^3 \frac{d\delta_0}{dt} - 2k^3 \frac{d\delta_0}{dt} - k^2 \frac{d^3 \delta_0}{dt^3}$$

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$$\frac{d^5 \phi_3}{dt^5} = 0$$

$$d^6 = \cancel{k} k d^4(2\phi_3 - \phi_2 - \phi_4) = -k^3 \phi_0$$

$$d^7 = k d^5(2\phi_3 - \phi_2 - \phi_4) = -k^4 \frac{d\phi_0}{dt}$$

$$d^8 = k d^6(2\phi_3 - \phi_2 - \phi_4) = -2k^4 \phi_0$$

66

Let $x = \frac{1}{t}$ and $dx = -\frac{1}{t^2} dt$

$$600 = 1 - \frac{1}{t} + \frac{1}{2t^2} - \frac{1}{3t^3} + \frac{1}{4t^4} - \frac{1}{5t^5} + \dots$$

$$\frac{1}{t} = 1 - 600 + \frac{1}{2t^2} - \frac{1}{3t^3} + \frac{1}{4t^4} - \frac{1}{5t^5} + \dots$$

$$\frac{1}{t} = 1 - 600 + \frac{1}{2t^2} - \frac{1}{3t^3} + \frac{1}{4t^4} - \frac{1}{5t^5} + \dots$$

$$\frac{1}{t} = 1 - 600 + \frac{1}{2t^2} - \frac{1}{3t^3} + \frac{1}{4t^4} - \frac{1}{5t^5} + \dots$$

$$\frac{1}{t} = 1 - 600 + \frac{1}{2t^2} - \frac{1}{3t^3} + \frac{1}{4t^4} - \frac{1}{5t^5} + \dots$$

$$\frac{1}{t} = 1$$

$$\frac{1}{t} = 1$$

$$\frac{1}{t} = 1$$

$$\frac{1}{t} = 1$$

$$\frac{1}{t} = 1$$

$$= -\rho \frac{1}{r^2} \rho$$

$$\rho \frac{1}{r^2}$$

$$= -\rho \frac{1}{r^2} \rho$$

$$= -2 \frac{\rho^2}{r^2} = -\frac{9 \rho^2}{r^2}$$

$$\frac{1}{r} + \frac{1}{r} = -\frac{9 \rho^2}{r^2}$$

$$\frac{1}{r} = -\frac{9 \rho^2}{r^2}$$

$$= -\frac{1}{r^2} \rho \frac{1}{r^2} dr$$

$$\frac{1}{r^2} = -\frac{9 \rho^2}{r^2} \frac{1}{r^2} dr$$

$$\frac{1}{r^2} = -\frac{9 \rho^2}{r^2}$$

$$\frac{1}{r^2} = -\frac{9 \rho^2}{r^2}$$

$$\frac{1}{r^2} = -\frac{9 \rho^2}{r^2}$$

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$$\frac{1}{r^2} = -\frac{9 \rho^2}{r^2}$$

$$\frac{1}{r^2} = -\frac{9 \rho^2}{r^2}$$

$$\frac{1}{x} = \frac{1}{x}$$

$$\frac{1}{x} = \frac{1}{x}$$

$$\frac{1}{x} = \frac{1}{x}$$

$$\frac{1}{x} = -\frac{1}{x^2} + \frac{1}{x^2}$$

$$\frac{1}{x} = -\frac{1}{x^2} + \frac{1}{x^2}$$

$$\frac{1}{x} = -\frac{1}{x^2} + \frac{1}{x^2}$$

$$\frac{1}{x} = -\frac{1}{x^2} + \frac{1}{x^2}$$

$$\frac{1}{x} = -\frac{1}{x^2} + \frac{1}{x^2}$$

$$\frac{1}{x} = -\frac{1}{x^2} + \frac{1}{x^2}$$

$$\frac{1}{x} = -\frac{1}{x^2} + \frac{1}{x^2}$$

$$\frac{xk}{k-1} \frac{\partial \alpha}{\partial x} (\theta_0 - \theta) = -\frac{g \alpha^2}{n} \tan \theta$$

$$-\frac{d\theta}{dx} = \frac{g}{2k} \frac{k-1}{k} \frac{\alpha^2}{k^2}$$

$$\frac{1}{\rho} \frac{d\rho}{dt} = \dots$$

$$\left(\frac{d\rho}{dt} \right)^{1/k} = \dots$$

$$\frac{d\rho}{dt} = \dots$$

$$\rho^{k-1} = \dots$$

$$\theta = \dots$$

$$\theta = \frac{1}{1-k}$$

$$\frac{d\theta}{dt} = \frac{1}{1-k} \theta^{\frac{k}{1-k}}$$

$$\theta = \dots$$

$$\frac{1}{\frac{1}{k+1}} \frac{1}{\rho_0} \left(\frac{1}{\rho} \right)^{\frac{k}{k+1}} \frac{1}{\rho} = \dots$$

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$$p = 8 \frac{m^2}{n^3}$$

$$C = \frac{1}{11} = 0.0909$$

$$2 \frac{d}{dt} = 2 \cdot 1/2$$

$$3 = -2 \cdot 1/2 = -1$$

$$p = \frac{1}{100} = 0.01 \quad \left(\frac{1}{100} = \frac{1}{10^2} = \left(\frac{1}{10} \right)^2 \right)$$

$$n = \frac{1}{10} = 0.1$$

$$\frac{d}{dt}$$

$$\frac{1}{10} = \frac{1}{10} = 0.1$$

$$p = 8 = \frac{8 \cdot 1}{1} = \frac{8}{1}$$

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$$1. \text{ Let } A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}, B = \begin{pmatrix} 4 & 3 \\ 2 & 1 \end{pmatrix}$$

$$\frac{A+B}{2} = \frac{1}{2} \begin{pmatrix} 1+4 & 2+3 \\ 3+2 & 4+1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 5 & 5 \\ 5 & 5 \end{pmatrix}$$

$$\frac{A-B}{2} = \frac{1}{2} \begin{pmatrix} 1-4 & 2-3 \\ 3-2 & 4-1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} -3 & -1 \\ 1 & 3 \end{pmatrix}$$

$$A+B = \begin{pmatrix} 5 & 5 \\ 5 & 5 \end{pmatrix}$$

$$A-B = \begin{pmatrix} -3 & -1 \\ 1 & 3 \end{pmatrix}$$

$$A+B = \begin{pmatrix} 5 & 5 \\ 5 & 5 \end{pmatrix}$$

$$A-B = \begin{pmatrix} -3 & -1 \\ 1 & 3 \end{pmatrix}$$

$$A+B = \begin{pmatrix} 5 & 5 \\ 5 & 5 \end{pmatrix}$$

$$A-B = \begin{pmatrix} -3 & -1 \\ 1 & 3 \end{pmatrix}$$

$$\frac{A+B}{2} = \begin{pmatrix} 2.5 & 2.5 \\ 2.5 & 2.5 \end{pmatrix}$$

$$A-B = \begin{pmatrix} -3 & -1 \\ 1 & 3 \end{pmatrix}$$

Przepraszam, ale nie wiem, czy to jest możliwe do rozwiązania. Proszę o pomoc.

$$1. \rho \cdot b \cdot r^2 = \text{const} = \rho_0 \cdot b_0 \cdot r^2 = b$$

$$2. \rho = \frac{b}{r^2} \cdot \rho_0$$

$$\frac{b}{r^2} \cdot \frac{d\rho}{dr} \parallel \alpha = \frac{0.76 \cdot 98 \cdot 13.6}{0.0013 \cdot 280} = \frac{98}{0.36} = 270$$

$$3. 0 = -\frac{g \cdot a^2}{r^2} - \frac{1}{\rho} \frac{d\rho}{dr} - \frac{4\mu}{3\rho} \frac{d}{dr} \left(\frac{b}{\rho} \frac{d\rho}{dr} \right)$$

$$4. \rho \cdot b \cdot r^2 \left[c \frac{d\theta}{dr} + A \cdot \frac{d(\frac{1}{\rho})}{dr} \right] = \frac{4\mu}{3} \left(\frac{b}{\rho} \frac{d\rho}{dr} \right)^2 + \frac{3\rho}{2} \left(\frac{d\rho}{dr} + \frac{3\rho}{r} \right)^2$$

$$3. \frac{g \cdot a^2}{r^2} + \alpha \frac{1}{\rho} \frac{d[\rho \theta]}{dr} - \frac{4\mu}{3\rho} \frac{d}{dr} \left[\frac{b}{\rho^2 r^2} \frac{d\rho}{dr} \right] = 0$$

$$4. b \cdot c \frac{d\theta}{dr} = A \cdot b \cdot \alpha \frac{\theta}{\rho} \frac{d\rho}{dr} = \frac{4\mu}{3} \left(\frac{b}{\rho^2 r^2} \right)^2 \left(\frac{d\rho}{dr} + \frac{3\rho}{r} \right)^2$$

$$\frac{1}{\rho^2 r^2} \left(\frac{d\rho}{dr} + \frac{3\rho}{r} \right) = \frac{d(\rho r^3)}{dr \cdot \rho^2 r^5} = \left| \frac{1}{\rho^2 r^2} \frac{d}{dr} \log(\rho r^3) \right| = - \alpha \frac{d}{dr} \left(\frac{1}{\rho r^3} \right)$$

$$\mu = \rho \theta$$

$$3. \frac{g \cdot a^2}{r^2} + \frac{\alpha}{\rho} \frac{d(\rho \theta)}{dr} - \frac{4\mu}{3\rho} \frac{d}{dr} \left[\frac{b}{\rho^2 r^2} \frac{d\rho}{dr} \right] = 0$$

$$4. c \frac{d\theta}{dr} = A \cdot \alpha \frac{\theta}{\rho} \frac{d\rho}{dr} - \frac{4\mu}{3} \frac{b \theta}{\rho^2 r^2} \left[\frac{d\rho}{dr} + \frac{3\rho}{r} \right]^2 = 0$$

$$4. c \frac{d\theta}{dr} \frac{1}{\theta} = A \cdot \alpha \frac{d\rho}{dr} \frac{1}{\rho} + \frac{4\mu}{3} \frac{b}{\rho^2 r^2} \left[\frac{d\rho}{dr} + \frac{3\rho}{r} \right]^2$$

$$c \log \theta + \text{const} = \int \frac{d\rho}{\rho} \quad \uparrow \quad dr$$

$$c \log \theta + \omega r^2 = A \alpha \log \rho + \frac{4\mu b}{3} \int \left[\frac{1}{\rho^2 n^2} \left(\frac{d\rho}{dr} + \frac{3\rho}{n} \right)^2 \right] dr$$

Lösung der ^{2te} Randw. in (3):

$$\frac{\rho^2}{n^2} + \frac{1}{\rho} \frac{d}{dr} (\rho \theta) = 0 = \frac{g a^2}{r^2} + \alpha \frac{d\theta}{dr} + \alpha \frac{\theta}{\rho} \frac{d\rho}{dr}$$

$$\text{const } \theta^c = \rho^{\alpha A} \frac{4\mu b}{3} \int \left(\frac{\theta}{\rho} \right)^c = \left(\frac{1}{\rho^c} \right)^{\alpha A}$$

$$\text{const } \rho^c \rho^{-c} = \rho^{\alpha A} \quad \text{const } \rho^c = \rho^{\alpha A + c} \quad \text{const } \rho = \rho \quad \begin{matrix} = 1.5 \\ \frac{\alpha A}{c} = 0.5 \\ \frac{\alpha A}{c} - 1 = -\frac{1}{2} \end{matrix}$$

$$\text{const } \theta = \rho^{\frac{\alpha A}{c}} \frac{4\mu b}{3c} \int$$

$$0 = \frac{g a^2}{r^2} + \left\{ \frac{A \alpha^2}{c} \frac{1}{\rho} \frac{d\rho}{dr} + \frac{4\mu b \alpha}{3 \rho^2 n^2 c} \left[\frac{d\rho}{dr} + \frac{3\rho}{n} \right]^2 + \frac{\alpha}{\rho} \frac{d\rho}{dr} \right\} \rho^{\frac{\alpha A}{c}} e$$

$$= \frac{g a^2}{r^2} + \rho^{\frac{\alpha A}{c} - 1} \frac{d\rho}{dr} \left(\frac{A \alpha^2}{c} + 1 \right) \frac{4\mu b}{3c} + \frac{4\mu b \alpha}{3c} \frac{d\rho}{dr} + \frac{3\rho}{n^2} \rho^{\frac{\alpha A}{c} - 1}$$

$$g a^2 e^{-\frac{4\mu b}{3c}} + r^2 \rho^{\frac{\alpha A}{c} - 1} \frac{d\rho}{dr} \left(\frac{A \alpha^2}{c} + 1 \right) + \frac{4\mu b \alpha}{3c} r^2 \left(\frac{1}{\rho^2 n^2} \left(\frac{d\rho}{dr} + \frac{3\rho}{n} \right)^2 \right) = 0$$

$$\sqrt{\left[r \frac{d}{dr} \left(\frac{1}{r^3 \rho} \right) \right]^2} = f(r) \log r$$

$$\frac{1}{r^3 \rho} = \left[f' \log r + \frac{f}{r} \right]^{\frac{1}{2}} = \frac{\frac{dp}{dr} + \frac{3\rho}{r}}{\rho^2 r} = \frac{dp}{\sqrt{r}} / \frac{r}{\rho^2}$$

$$\frac{1}{r^3 \rho} = \int \frac{1}{r} \left[\right]^{\frac{1}{2}} dr$$

$$\frac{d}{dr} \left(\frac{1}{r^3 \rho} \right) = k / r^{\frac{5}{2}} \frac{dr}{dr}$$

$$\frac{1}{r^3 \rho} = k r^{\frac{5}{2}} + k'$$

$$\rho = \frac{1}{k r^{\frac{5}{2}} + k'}$$

$$\int \dots = f(\log r)$$

$$\frac{1}{r} \frac{d}{dr} \left(\frac{1}{r^3 \rho} \right) = \frac{f'(\log r)}{r}$$

$$\int \dots dr = k^2 \log r$$

$$\frac{1}{r^3 \rho} = \int \left[r^{\frac{1}{2}} f'(\log r) \right]^{\frac{1}{2}} dr \quad - k \log r = r^{-m}$$

$$M e^{-m \log r}$$

$$M r^{-m} + r^2 N r^{-\frac{9}{2}} r^{-\frac{11}{2}} + P r^2 r^{-1} = 0$$

$$\frac{d}{dr} \left(\frac{1}{r^3 \rho} \right) = f$$

$$\frac{d}{dr} \left(\frac{1}{r^3 \rho} \right) = f$$

$$\frac{d}{dr} \left(\frac{1}{r^3 \rho} \right) = \frac{f}{r}$$

$$\frac{1}{r^3 \rho} = \int \frac{f}{r} dr$$

$$M e^{-\int f^2 r^2 dr}$$

$$\rho = \frac{1}{r^3 \int f dr}$$

$$\rho r^3 = z$$

$$\rho = r^3 z$$

$$\frac{dp}{dr} = 3 r^2 z + r^3 \frac{dz}{dr}$$

$$\frac{dp}{dr} = \frac{3}{r^4} + \dots$$

$$e^{-\int \left[r \frac{d}{dr} \left(\frac{1}{\rho r^3} \right) \right]^2 dr} = F$$

$$\frac{d}{dr} \left(\frac{1}{\rho r^3} \right) = \frac{1}{r} \left| \frac{F'}{F} \right|$$

$$-\int \left[r \frac{d}{dr} \left(\frac{1}{\rho r^3} \right) \right]^2 dr = \ln F$$

$$\frac{1}{\rho r^3} = \int \frac{dr}{r} \sqrt{\frac{F'}{F}}$$

$$\left[r \frac{d}{dr} \left(\frac{1}{\rho r^3} \right) \right]^2 = \frac{F'}{F}$$

Jak drugi z bliskim a $\frac{-1}{e} = 1$

$$g a^2 + r^2 \rho \frac{d\rho}{dr} \left(\frac{A\alpha}{c} + 1 \right) \alpha + \frac{4\pi b \alpha}{3c a^2} \underbrace{\left(\frac{1}{\rho^2} \frac{d\rho}{dr} + \frac{3}{\rho a} \right)^2}_{\frac{1}{a^2} \left[\frac{d}{dr} \left(\frac{1}{\rho} \right) \right]^2} = 0$$

$$\frac{4\pi b \alpha}{3c a^2 \rho^4 \theta} \left(\frac{d\rho}{dr} \right)^2$$

Zauważmy - wpływ termu α 4 a. niepłynności α 3:

$$\left(\frac{\theta}{\theta_0} \right)^{\frac{1}{\alpha}} = \left(\frac{\rho}{\rho_0} \right)^{\frac{\alpha A}{c}}$$

$$\theta = \theta_0 \left(\frac{\rho}{\rho_0} \right)^{\frac{\alpha A}{c}} = \beta \rho^{\frac{\alpha A}{c}}$$

$$3. \quad g a^2 + \frac{\alpha}{\beta} \beta \left(\frac{\alpha A}{c} + 1 \right) \rho^{\frac{\alpha A}{c} - 1} \left(\frac{d\rho}{dr} \right) - \frac{4\pi b}{3} \beta \rho^{\frac{\alpha A}{c} - 1} \frac{d}{dr} \left[\frac{b}{\rho^2} \frac{d\rho}{dr} \right] = 0$$

$$\frac{A}{c} = 1$$

$$1). \quad \rho = \alpha \theta$$

$$2). \quad \frac{d\delta}{dx} = -\frac{g\alpha^2}{x^2} - \frac{1}{\rho} \frac{d\rho}{dx} + \frac{4}{3} \frac{\mu}{\rho} \left(\frac{d\delta}{dx} + \frac{d\delta}{dy} + \frac{d\delta}{dz} \right)$$

$$3). \quad \left[c \frac{d\theta}{dx} + A \rho \frac{d(\frac{1}{\rho})}{dx} \right] = \mu \left(\frac{du}{dx} \right)^2 + \left(\frac{du}{dy} \right)^2$$

$$4). \quad \rho \delta = \text{const} = b \quad = \frac{4}{3} \mu \left[\left(\frac{du}{dx} \right)^2 + \left(\frac{du}{dy} \right)^2 + \left(\frac{du}{dz} \right)^2 \right] + \frac{1}{3} \mu \left(\frac{du}{dx} \right)^2$$

$$\delta = \rho \cdot \alpha$$

$$\frac{1}{\rho} = \frac{\alpha \theta}{\rho}$$

$$1). \quad \rho = \alpha \theta$$

$$2). \quad 0 = -\frac{g\alpha^2}{x^2} - \frac{1}{\rho} \frac{d\rho}{dx} + \frac{4}{3} \frac{\mu}{\rho} \frac{d\delta}{dx}$$

$$3). \quad \left[c \frac{d\theta}{dx} + A \rho \frac{d(\frac{1}{\rho})}{dx} \right] = \frac{4}{3} \mu \left(\frac{d\delta}{dx} \right)^2$$

"j" θ

$$4). \quad \rho \delta = b$$

$$3). \quad \left[\frac{c}{A} \frac{d\theta}{dx} + \frac{\alpha \theta}{\rho} \frac{d\rho}{dx} \right] = \frac{4}{3} \mu \theta \frac{b^2}{\rho^4} \left(\frac{d\rho}{dx} \right)^2$$

$$2). \quad 0 = -\frac{g\alpha^2}{x^2} - \frac{\alpha}{\rho} \left(\theta \frac{d\rho}{dx} + \rho \frac{d\theta}{dx} \right) + \frac{4}{3} \frac{\mu \theta}{\rho} \frac{d^2}{dx^2} \left(\frac{1}{\rho} \right)$$

$$-\frac{g\alpha^2}{x^2} \frac{d\rho}{dx} = \frac{\alpha \theta}{\rho} \frac{d\rho}{dx}$$

$$0 = -g \frac{a^2}{x^2} - \frac{c}{A} \frac{d\theta}{dx} - \alpha \frac{d\theta}{dx} + \gamma \theta \left[\frac{b}{\rho^3} \frac{d^2}{dx^2} \left(\frac{1}{\theta} \right) + \frac{4}{3} \frac{b^4}{\rho^2} \left(\frac{d\rho}{dx} \right) \right]$$

bei vollständiger Vernachlässigung von γ

$$\text{const} = \frac{g a^2}{b x} - \left(\frac{c}{A} + \alpha \right) \theta + \int dx \gamma \theta \left[\right]$$

$$\frac{1}{\rho} = \frac{b}{b} \quad \rho = \frac{\alpha b \theta}{b}$$

$$2). 0 = -g \frac{a^2}{x^2} - \frac{b}{b} \frac{d}{dx} \left(\frac{\alpha \theta b}{b} \right) - \gamma \frac{\theta b}{b} \frac{d^2 b}{dx^2}$$

$$3). \frac{c}{A} \frac{d\theta}{dx} + \frac{\alpha b}{b} \frac{d}{dx} \left(\frac{b}{b} \right) = \frac{4}{3} \gamma \theta \left(\frac{d^2 b}{dx^2} \right)^2$$

$$3). \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dx} + \alpha \frac{1}{b} \frac{db}{dx} = \frac{4}{3} \gamma \left(\frac{db}{dx} \right)^2$$

$$2). 0 = -g \frac{a^2}{x^2} - \frac{\alpha}{b} \frac{d\theta}{dx} + \frac{\alpha}{b} \theta \frac{db}{dx} + \frac{4}{3} \gamma \frac{\theta b}{b} \frac{d^2 b}{dx^2}$$

$$0 = -g \frac{a^2}{x^2} - \left(\alpha + \frac{c}{A} \right) \frac{d\theta}{dx} + \frac{4}{3} \gamma \theta \left[\frac{b}{b} \frac{d^2 b}{dx^2} + \frac{4}{3} \gamma \left(\frac{db}{dx} \right)^2 \right]$$

$$\frac{\alpha A}{c} = k-1$$

$$\frac{c}{A} \log \theta + \alpha \log b = \frac{4}{3} \gamma \int \left(\frac{db}{dx} \right)^2 dx$$

$$\text{const} \times \theta^{\frac{c}{A}} \cdot b^{\alpha} = e^{\frac{4}{3} \gamma \int \dots}$$

$$\rightarrow f(x) > 1 \text{ wächst mit } x$$

$$\theta = \text{const} \cdot \rho$$

$$\left(\frac{\theta}{\theta_0} \right)^{\frac{c}{A}} \left(\frac{b}{b_0} \right)^{\alpha} = \left(\frac{\theta}{\theta_0} \right)^{\frac{c}{A}} \left(\frac{\rho}{\rho_0} \right)^{\alpha}$$

$$\frac{g \varrho^2}{x^2} = \left(\alpha + \frac{c}{A}\right) \frac{d\theta}{dx} + f\theta \left[- \right] \quad \theta'$$

$$0 = \left(\alpha + \frac{c}{A}\right) \frac{d\theta'}{dx} + f\theta' \left[- \right] \quad \theta'$$

$$\frac{\frac{g \varrho^2}{x^2}}{\theta'} = \left(\alpha + \frac{c}{A}\right) \left(\frac{\frac{d\theta}{dx}}{\theta'} - \frac{\theta}{\theta'^2} \frac{d\theta'}{dx} \right)$$

$$= \frac{d}{dx} \left(\frac{\theta}{\theta'} \right)$$

$$\frac{g \varrho^2}{x^2} = \left(\alpha + \frac{c}{A}\right) \frac{d\theta'}{dx}$$

θ' und θ' hundertmal

$$-\frac{g \varrho^2}{x} = \left(\alpha + \frac{c}{A}\right) \theta' + \text{const}$$

$$\theta' = M - \frac{N}{x} \quad \frac{d\theta'}{dx} = \frac{N}{x^2}$$

$$\frac{d}{dx} \left(\frac{\theta}{\theta'} \right) = \frac{N}{A x^2} + \frac{\alpha}{6} \left(M - \frac{N}{x} \right) \frac{d\theta}{dx} = \frac{4}{3} f \left(M - \frac{N}{x} \right) \left(\frac{d\theta}{dx} \right)^2$$

$$\frac{4}{3} f \left(\frac{d\theta}{dx} \right)^2 - \frac{\alpha}{6} \frac{d\theta}{dx} = \frac{cN}{A} \frac{1}{x^2 \left(M - \frac{N}{x} \right)}$$

$$\left(\alpha + \frac{c}{A} \right) \theta = \left(\alpha + \frac{c}{A} \right) \frac{c}{x} \theta' = c \left(\alpha + \frac{c}{A} \right) \frac{1}{x}$$

$$U = \theta_0 \left[\left(\frac{b_0}{b} \right)^\alpha f(x) \right]^{\frac{A}{c}}$$

$$\frac{dU}{dx} = \theta_0 \frac{A}{c} \left[\left(\frac{b_0}{b} \right)^\alpha f(x) \right]^{\frac{A}{c}-1} \left[\left(\frac{b_0}{b} \right)^{-\alpha} \frac{db}{dx} - \alpha f \left(\frac{b_0}{b} \right)^{-\alpha} \frac{df}{dx} \right]$$

$$= \theta_0 \frac{A}{c} \left[\left(\frac{b_0}{b} \right)^{-\alpha} f \right]^{\frac{A}{c}} \left[\frac{1}{f} \frac{db}{dx} - \alpha \left(\frac{b_0}{b} \right)^{-1} \frac{df}{dx} \right]$$

$$g \frac{a^2}{x^2} + \left(\frac{c}{A} + \alpha \right) \frac{4}{3} \frac{r}{b} \left[+ b \frac{db}{dx^2} + \frac{1}{b} \left(\frac{db}{dx} \right)^2 \right] \theta_0 \left[\left(\frac{b_0}{b} \right)^\alpha f \right]^{\frac{A}{c}}$$

$$f(x) = e^{\frac{4}{3} \frac{r}{b} \int_0^x \left(\frac{db}{dx} \right)^2 dx}$$

$$\frac{1}{f} \frac{df}{dx} = \frac{d}{dx} \ln f(x) = \frac{4}{3} \frac{r}{b} \frac{db}{dx}$$

$$g \frac{a^2}{x^2} = \frac{4}{3} \frac{r}{b} \left[\left(\frac{db}{dx} \right)^2 + b \frac{db}{dx^2} \right] \theta_0 \left[\left(\frac{b_0}{b} \right)^\alpha f \right]^{\frac{A}{c}} - \left(\frac{c}{A} + \alpha \right) \theta_0 \frac{A}{c} \left[\left(\frac{b_0}{b} \right)^\alpha f \right]^{\frac{A}{c}} \left[\frac{4}{3} \frac{r}{b} \left(\frac{db}{dx} \right)^2 - \alpha \frac{b_0}{b} \frac{df}{dx} \right]$$

$$= \left[\left(\frac{b_0}{b} \right)^\alpha f \right]^{\frac{A}{c}} \theta_0 \left\{ \frac{4}{3} \frac{r}{b} \left(\frac{db}{dx} \right)^2 + \frac{4}{3} \frac{r}{b} b \frac{db}{dx^2} - \left(1 + \frac{\alpha A}{c} \right) \left[\frac{4}{3} \frac{r}{b} \left(\frac{db}{dx} \right)^2 - \alpha \frac{b_0}{b} \frac{df}{dx} \right] \right\}$$

$$= \left[\left(\frac{b_0}{b} \right)^\alpha f \right]^{\frac{A}{c}} \theta_0 \left\{ - \frac{4}{3} \frac{r}{b} \frac{\alpha A}{c} \left(\frac{db}{dx} \right)^2 + \frac{4}{3} \frac{r}{b} b \frac{db}{dx^2} + \alpha \frac{b_0}{b} \left(1 + \frac{\alpha A}{c} \right) \frac{df}{dx} \right\}$$

$$g \frac{a^2}{x^2} = \left(\frac{b_0}{b} \right)^{\frac{\alpha A}{c}} \theta_0 \left[\frac{4}{3} \frac{r}{b} \left[- \frac{\alpha A}{c} \left(\frac{db}{dx} \right)^2 + b \frac{db}{dx^2} \right] + \alpha \frac{b_0}{b} \left(1 + \frac{\alpha A}{c} \right) \frac{df}{dx} \right] e^{\frac{4}{3} \frac{r}{b} \frac{A}{c} \int_0^x \left(\frac{db}{dx} \right)^2 dx}$$

$$g \frac{a^2}{x^2} = \frac{d\Phi}{dx} e^{\dots} + \Phi \frac{4}{3} \frac{r}{b} \frac{A}{c} \left(\frac{db}{dx} \right)^2 e^{\dots} \Phi$$

$$-\frac{2}{x} = \frac{d\Phi}{dx} + \frac{4}{3} \frac{A}{b} \left(\frac{db}{dx}\right)^2 \Phi$$

Voraussetzungen:

$$b = x^n$$

$$\frac{c}{A} \frac{1}{\theta} \frac{\partial \theta}{\partial x} + \frac{\alpha n}{x} = \frac{4}{3} \frac{A}{b} n^2 x^{2n-2}$$

$$\frac{c}{A} \log \theta + \alpha n \log x = \frac{4}{3} \frac{A}{b} n^2 \frac{x^{2n-1}}{2n-1}$$

$$\theta = \dots x^{-\frac{nA}{c}} \dots x^{2n-1}$$

$$\frac{d\theta}{dx} = \dots \left[x^{-\frac{nA}{c}-1} + x^{-\frac{nA}{c}} \frac{2n-1}{x} \right]$$

$$\frac{1}{x^2} = e^{2n}$$

$$b = e^x$$

$$\frac{1}{b} \frac{db}{dx} = e^{2x}$$

$$\log b = e^{2x}$$

$$\theta = \dots$$

$$b = \log x$$

$$\frac{db}{dx} = \frac{1}{x}$$

$$\int \dots = \frac{1}{x}$$

$$b \frac{d^2 b}{dx^2} = x^{-1}$$

$$\left(\frac{db}{dx}\right)^2 = x^{-1}$$

$$\int \frac{db}{dx} = x = \log x$$

$$\left(\frac{db}{dx}\right)^2 = \frac{1}{x}$$

$$\frac{db}{dx} = x^{-\frac{1}{2}}$$

$$b = x^{\frac{1}{2}}$$

$$\frac{d^2 b}{dx^2} = x^{-\frac{3}{2}}$$

$$\theta = b^{-\frac{\alpha A}{c}} \int \dots = \dots x^{-\frac{\alpha A}{2c}} \cdot x^{\frac{2}{3}}$$

$$0 = \frac{g a^2}{x} + m - \left(\alpha + \frac{c}{A}\right) \theta + \frac{\mu}{b} \theta \frac{d\theta}{dx}$$

$$\theta = 0$$

$$\theta = u + v$$

$$0 = \frac{g a^2}{x} + m - u v \left(\alpha + \frac{c}{A}\right) + \frac{\mu}{b} \left(u v \frac{dv}{dx} + u v \frac{du}{dx}\right)$$

$$u \left[-v \left(\alpha + \frac{c}{A}\right) + \frac{\mu}{b} \left(u v \frac{dv}{dx} + v \frac{du}{dx}\right) \right]$$

$$\theta = u + v$$

$$0 = \frac{g a^2}{x} + m - \left(\alpha + \frac{c}{A}\right) (u + v) + \frac{\mu}{b} (u + v) \left(\frac{du}{dx} + \frac{dv}{dx}\right)$$

$$0 = \frac{g a^2}{x} + m - \left(\alpha + \frac{c}{A}\right) u + \frac{\mu}{b} u \left(\frac{du}{dx} + \frac{dv}{dx}\right) + v \left[\left(\alpha + \frac{c}{A}\right) + \frac{\mu}{b} \left(\frac{du}{dx} + \frac{dv}{dx}\right)\right]$$

$$\frac{\mu}{b} \frac{d\theta}{dx} - \left(\alpha + \frac{c}{A}\right) \theta + \frac{m}{\theta} + \frac{g a^2}{\theta x} = 0$$

$$\frac{\mu}{b} \frac{d\theta}{dx} - \left(\alpha + \frac{c}{A}\right) \theta + \frac{m}{\theta} + \frac{g a^2}{\theta x} = 0$$

$$\frac{\mu}{b} \left(\theta \frac{d\theta}{dx} - \theta_1 \frac{d\theta_1}{dx} \right) - \left(\alpha + \frac{c}{A}\right) \theta + \frac{m}{\theta} + \frac{g a^2}{\theta x} = 0$$

$$\theta \frac{d\theta}{dx} - \frac{d}{dx} \left(\left(\alpha + \frac{c}{A}\right) \theta \right) + \frac{m}{\theta} + \frac{g a^2}{\theta x} = 0$$

$$\frac{\mu}{b} \frac{d}{dx} (\theta - \theta_1)$$

$$\frac{\mu}{2} \frac{d^2 \theta}{dx^2} + \frac{m}{\theta^2} \frac{d\theta}{dx} - \frac{g a^2}{\theta^2} \frac{d\theta}{dx} - \frac{g a^2}{\theta^2} = 0$$

$$u = (\log f)^2 \quad \frac{du}{dx} = 2 \log f \cdot \frac{f'}{f}$$

$$\left(\frac{g a^2}{x} - \left(\alpha + \frac{c}{A} \right) \log f + \frac{\mu}{2b} \frac{f'}{f} \log f + m \right)$$

$$\log f \left(\frac{\mu}{2b} \frac{f'}{f} - \alpha + \frac{c}{A} \right)$$

$$f = e^{\frac{1}{x}}$$

$$\frac{\mu}{2b} \frac{du}{dx} - \left(\alpha + \frac{c}{A} \right) u^{\frac{1}{2}} + \frac{g a^2}{x} + m = 0$$

$$\left(\alpha + \frac{c}{A} \right)^2 u = \left[\frac{\mu}{2b} \frac{du}{dx} + \frac{g a^2}{x} + m \right]^2$$

$$\frac{du}{dx} = p$$

$$\left(\alpha + \frac{c}{A} \right)^2 p = 2 \left[\frac{\mu}{2b} p + \frac{g a^2}{x} + m \right]$$

$$\left[\frac{\mu}{2b} \frac{dp}{dx} - \frac{g a^2}{x^2} \right]$$

$$\frac{1}{2} \left(\alpha + \frac{c}{A} \right)^2 p$$

$$\frac{1}{2} \left(\alpha + \frac{c}{A} \right)^2 p + \frac{g a^2}{x^2} = \frac{\mu}{2b} \frac{dp}{dx}$$

$$\frac{g a^2}{x^2} = \left(\alpha + \frac{c}{A} \right) u^{\frac{1}{2}} - m - \frac{\mu}{2b} \frac{du}{dx}$$

$$x = \frac{\frac{g a^2}{x^2} \frac{dx}{du}}{\left[\left(\alpha + \frac{c}{A} \right) u^{\frac{1}{2}} - m \right] \frac{du}{dx} \frac{\mu}{2b}} \quad \parallel \quad 1 =$$

$$\left[\left(\alpha + \frac{c}{A} \right) u^{\frac{1}{2}} - m - \frac{\mu}{2b} \frac{du}{dx} \right]^2 = \frac{g a^2}{x^2} \left[\left(\alpha + \frac{c}{A} \right) \frac{1}{2} \frac{du}{dx} \frac{1}{u} - \frac{\mu}{2b} \frac{d^2 u}{dx^2} \right]$$

$$g \frac{dx}{x} + m - \left(\alpha + \frac{c}{A}\right) \sqrt{u} + \frac{n}{2b} \frac{du}{dx} = 0$$

$$\frac{dx}{du} = p$$

$$g \frac{dx}{x} + m - \left(\alpha + \frac{c}{A}\right) \sqrt{u} + \frac{n}{2b} \frac{1}{p} = 0$$

$$g \frac{dx}{x} - \left(\alpha + \frac{c}{A}\right) \frac{1}{2} \frac{1}{\sqrt{u}} - \frac{n}{2b} \frac{1}{p} \frac{dp}{du} = 0$$

$$p \text{ Simms } \dots \frac{1}{\sqrt{u}}$$

$$p = \frac{2}{\sqrt{u}} \quad \frac{dp}{du} = \frac{dz}{du} \frac{1}{\sqrt{u}} - \frac{2}{2u\sqrt{u}}$$

$$g \frac{2}{\sqrt{u}} - \left(\alpha + \frac{c}{A}\right) \frac{1}{2} \frac{1}{\sqrt{u}} - \frac{n}{2b} \frac{u}{2^2} \left(\frac{dz}{du} \frac{1}{\sqrt{u}} - \frac{2}{2u\sqrt{u}} \right)$$

$$g \frac{2}{\sqrt{u}} - \frac{1}{2} \left(\alpha + \frac{c}{A}\right) + \frac{n}{4b} \frac{1}{2} = \frac{n}{2b} \frac{u}{2^2} \frac{dz}{du}$$

$$\frac{du}{u} = \frac{n}{2b} \frac{dz}{\left[g \frac{2}{\sqrt{u}} - \frac{1}{2} \left(\alpha + \frac{c}{A}\right) + \frac{n}{4b} \frac{1}{2} \right]}$$

$$\log u = f(z)$$

$$p = \frac{dx}{du}$$

$$\log u = f_c(p\sqrt{u})$$

$$= f_c \left(\frac{dx}{du} \sqrt{u} \right)$$

$$2 \log \theta = f_c \left[\frac{dx}{d(\theta^2)} \theta \right]$$

$$\log u = \log \frac{z^2}{2^2 - \frac{1}{2g} \left(\frac{1}{2g} \right) + \frac{1}{4bg}} \left(\frac{2 - \frac{1}{2g}}{2 - \frac{1}{2g}} \right)^{-\frac{1}{2g} \left(\frac{1}{2g} \right)}$$

$$\theta = \psi + n$$

$$0 = \frac{g a^2}{x} + m - \left(\alpha + \frac{c}{A}\right) \psi - \left(\alpha + \frac{c}{A}\right) n + \frac{\mu}{b} (\psi + n) \frac{d\psi}{dx}$$

$$m - \left(\alpha + \frac{c}{A}\right) n = 0 \quad \therefore n = \frac{m}{\alpha + \frac{c}{A}}$$

$$0 = \frac{g a^2}{x} - \left(\alpha + \frac{c}{A}\right) \psi + \frac{\mu}{b} n \frac{d\psi}{dx} + \left(\frac{\mu}{b}\right) \psi \frac{d\psi}{dx}$$

$$\frac{dn}{n} = \frac{2}{x} \left[\frac{dz}{z} + \frac{-gz + \frac{1}{2} \left(\alpha + \frac{c}{A}\right)}{g z^2 - \frac{1}{2} \left(\alpha + \frac{c}{A}\right) z + \frac{\mu}{4b}} dz \right]$$

$$= 2 \left[\frac{dz}{z} - \frac{\left[z - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right) \right] dz}{z^2 - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right) z + \frac{\mu}{4bg}} \right]$$

$$= 2 \frac{dz}{z} - \frac{2z - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right)}{z^2 - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right) z + \frac{\mu}{4bg}} + \frac{1}{2g} \left(\alpha + \frac{c}{A}\right) \frac{dz}{z^2 - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right) z + \frac{\mu}{4bg}}$$

$$= 2 \log z - \log \left(z^2 - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right) z + \frac{\mu}{4bg} \right) + \frac{1}{2g} \left(\alpha + \frac{c}{A}\right) \int \frac{dz}{z^2 - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right) z + \frac{\mu}{4bg}}$$

$$\int \frac{1}{\left[z^2 - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right) z + \frac{\mu}{4bg} \right]^2 - \left[\frac{1}{4g} \left(\alpha + \frac{c}{A}\right) \right]^2 - \frac{\mu}{4bg}} dz = \int \frac{d \frac{z - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right)}{\sqrt{\left[\frac{1}{4g} \left(\alpha + \frac{c}{A}\right) \right]^2 - \frac{\mu}{4bg}}}}{\left[\frac{z - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right)}{\sqrt{\left[\frac{1}{4g} \left(\alpha + \frac{c}{A}\right) \right]^2 - \frac{\mu}{4bg}}} \right]^2 - 1} \cdot \frac{1}{\sqrt{\left[\frac{1}{4g} \left(\alpha + \frac{c}{A}\right) \right]^2 - \frac{\mu}{4bg}}}$$

$$= \frac{1}{2} \frac{1}{\sqrt{\left[\frac{1}{4g} \left(\alpha + \frac{c}{A}\right) \right]^2 - \frac{\mu}{4bg}}} \log \left(\frac{z - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right) + \sqrt{\left[\frac{1}{4g} \left(\alpha + \frac{c}{A}\right) \right]^2 - \frac{\mu}{4bg}}}{z - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right) - \sqrt{\left[\frac{1}{4g} \left(\alpha + \frac{c}{A}\right) \right]^2 - \frac{\mu}{4bg}}} \right)$$

$$g x = \alpha - \left(\alpha + \frac{c}{A} \right) \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}} - \left(\frac{1}{2A} \right) \frac{v^2}{c^2}$$

$$g x = \left(\alpha + \frac{c}{A} \right) \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}} - \left(\frac{1}{2A} \right) \frac{v^2}{c^2} \quad \frac{dx}{dt} = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}} \quad \frac{dv}{dt} = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$2 \left[\alpha + \frac{c}{A} - \left(\frac{1}{2A} \right) \frac{v^2}{c^2} \right] = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}} \left[\frac{1}{\sqrt{1 - \frac{v^2}{c^2}}} - \left(\frac{1}{2A} \right) \frac{v^2}{c^2} \right]$$

$$\frac{dx}{dt} = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$\frac{dx}{dt} = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$\frac{dx}{dt} = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$\alpha + \frac{c}{A} - \left(\frac{1}{2A} \right) \frac{v^2}{c^2} = 1$$

$$x = \frac{1}{g} \left[\left(\alpha + \frac{c}{A} \right) \theta - \frac{m}{g} - \frac{2\theta}{g} \right]$$

$$\theta = \frac{m - g x}{\alpha + \frac{c}{A}}$$

$$\ln \theta = \ln \left(\alpha + \frac{c}{A} \right) - \ln \left(\alpha + \frac{c}{A} \right)$$

$$\frac{1}{\theta} \frac{d\theta}{dt} = \frac{g}{g x - m} - \frac{1}{\alpha + \frac{c}{A}} \frac{dv}{dt} = \frac{g}{\alpha + \frac{c}{A}} \left(\frac{1}{g} - \frac{2}{g} \right)$$

$$\frac{dx}{dt} = \alpha + \frac{c}{A} - \frac{m}{g} - \frac{2\theta}{g}$$

$$x = \frac{1}{g} \left(\alpha + \frac{c}{A} \right) \theta + \frac{m}{g} - \frac{2\theta}{g}$$

$$\frac{dx}{dt} = \frac{1}{g} \left(\alpha + \frac{c}{A} \right) - \frac{2}{g} - \frac{\theta}{g} \frac{d\theta}{dt}$$

$$\frac{2c}{A} z = \frac{d}{dz} \left[\frac{\alpha + \frac{c}{A}}{g} \theta - \frac{z}{g} \theta - \frac{\theta^2}{g} \frac{dz}{d\theta} \right] \left[z(2-\alpha) \right]$$

$$\frac{2c}{A} z \frac{dz}{d\theta} = \frac{d}{d\theta} \left[\dots \right]$$

$$\frac{2c}{A} z \left[\frac{\alpha + \frac{c}{A}}{g} - \frac{z}{g} - \theta \frac{dz}{d\theta} \right] = z(2-\alpha) \left[\left(\alpha + \frac{c}{A} \right) \frac{d\theta}{dz} - z - \theta^2 \frac{dz}{d\theta} \right]$$

$$+ \left[2z - \alpha \right] \frac{dz}{d\theta} \left[\left(\alpha + \frac{c}{A} \right) \theta - z \theta - \theta^2 \frac{dz}{d\theta} \right]$$

$$\frac{dz}{d\theta} = \frac{1}{g} \left[\left(\alpha + \frac{c}{A} - z \right) \frac{d\theta}{dz} - \theta \right]$$

$$\frac{2c}{A} z \frac{dz}{dz} = \frac{d}{dz} \left[\frac{1}{g} \left(\alpha + \frac{c}{A} \right) - \frac{z}{g} - \theta \frac{dz}{d\theta} \right]$$

$$= \frac{d}{dz} \left[\theta \frac{dz}{d\theta} z(2-\alpha) \frac{1}{g} \left[\left(\alpha + \frac{c}{A} - z \right) \frac{d\theta}{dz} - \theta \right] \right]$$

$$= \frac{d}{dz} \left[\theta z(2-\alpha) \left[\alpha + \frac{c}{A} - z - \theta \frac{dz}{d\theta} \right] \right]$$

$$\frac{2c}{A} z \left[\left(\alpha + \frac{c}{A} - z \right) \frac{d\theta}{dz} - \theta \right] = z(2-\alpha) \left[\left(\alpha + \frac{c}{A} \right) \frac{d\theta}{dz} - z \frac{d\theta}{dz} - \theta \right] +$$

$$+ \theta (2-\alpha) \left[\alpha + \frac{c}{A} - z - \theta \frac{dz}{d\theta} \right] +$$

findet man $2(2-\alpha) = 2^2$ positiv:

$$\frac{2c}{A} = \frac{d}{dx} \left[\frac{2 \cancel{\frac{c^2}{A^2}}}{\frac{1}{\theta} \frac{d\theta}{dx}} \right]$$

$$\frac{2c}{A} \cdot 1 = \cancel{\frac{2c}{A}} \frac{\frac{dx}{dx}}{\frac{1}{\theta} \frac{d\theta}{dx}} - 2 \frac{\frac{d}{dx} \left(\frac{1}{\theta} \frac{d\theta}{dx} \right)}{\left(\frac{1}{\theta} \frac{d\theta}{dx} \right)^2}$$

$$\frac{2c}{A} \frac{1}{\theta} \frac{d\theta}{dx} = 2 \frac{dx}{dx} - 2 \frac{d}{dx} \left(\ln \frac{1}{\theta} \frac{d\theta}{dx} \right)$$

$$\frac{2c}{A} \frac{1}{\theta} \frac{d\theta}{dx} = 2 - 2 \frac{d}{dx} \left(\ln \frac{1}{\theta} \frac{d\theta}{dx} \right)$$

$$\frac{d(\ln \theta)}{dx}$$

$$\left[\frac{c^2}{A^2} + \frac{c\alpha}{A} + \frac{\alpha}{u} - \frac{1}{u^2} \right]$$

$$\left(u + \frac{du}{dx} \right)^2 \left[\frac{2c\alpha}{A} + \frac{1c^2}{A^2} - \frac{2c}{A} - \frac{\alpha}{A} + \frac{\alpha}{u} + \frac{c}{A^2} + \frac{1c}{A\alpha} - \frac{1}{u^2} \right]$$

Integration: $\frac{g x^2}{x^2} = g \theta$

$$\frac{2c}{A} \left[\alpha + \frac{c}{A} + \frac{m}{\theta} - \frac{g x}{\theta} \right] = \frac{d}{dx} \left[\frac{\left[\alpha + \frac{c}{A} + \frac{m}{\theta} - \frac{g x}{\theta} \right] \left[\frac{c}{A} + \frac{m}{\theta} - \frac{g x}{\theta} \right]}{\frac{1}{\theta} \frac{d\theta}{dx}} \right]$$

$$g x - m = y$$

$$g dx = dy$$

$$\frac{2c}{A} \left[\alpha + \frac{c}{A} - \frac{y}{\theta} \right] = \frac{d}{dy} \left[\frac{\left[\alpha + \frac{c}{A} - \frac{y}{\theta} \right] \left[\frac{c}{A} - \frac{y}{\theta} \right]}{\frac{1}{\theta} \frac{d\theta}{dy}} \right]$$

$$= \frac{- \left[\alpha + \frac{2c}{A} - \frac{2y}{\theta} \right] \frac{d}{dy} \left[\frac{y}{\theta} \right]}{\frac{1}{\theta} \frac{d\theta}{dy}} - \frac{\left[\alpha + \frac{c}{A} - \frac{y}{\theta} \right] \left[\frac{c}{A} - \frac{y}{\theta} \right] \frac{d}{dy} \left(\frac{1}{\theta} \frac{d\theta}{dy} \right)}{\left(\frac{1}{\theta} \frac{d\theta}{dy} \right)^2}$$

$$\frac{2c}{A} \left[\alpha + \frac{c}{A} - \frac{y}{\theta} \right] \left(\frac{1}{\theta} \frac{d\theta}{dy} \right)^2 = - \left[\alpha + \frac{2c}{A} - \frac{2y}{\theta} \right] \frac{1}{\theta} \frac{d\theta}{dy} \left[\frac{1}{\theta} - \frac{y}{\theta^2} \frac{d\theta}{dy} \right] -$$

$$- \frac{\left[\alpha + \frac{c}{A} - \frac{y}{\theta} \right] \left[\frac{c}{A} - \frac{y}{\theta} \right] \left[\frac{1}{\theta} \frac{d^2\theta}{dy^2} - \frac{1}{\theta^2} \left(\frac{d\theta}{dy} \right)^2 \right]}{\left(\frac{1}{\theta} \frac{d\theta}{dy} \right)^2}$$

$$y = e^z$$

$$g = u e^z$$

$$\frac{d\theta}{dy} = \left(u + \frac{du}{dz} \right)$$

$$\frac{d\theta}{dy} = \left(\frac{du}{dz} + \frac{d^2u}{dz^2} \right) e^{-z}$$

$$\frac{2c}{A} \left[\alpha + \frac{c}{A} - \frac{1}{u} \right] \left(u + \frac{du}{dz} \right)^2 = - \left[\alpha + \frac{2c}{A} - \frac{2}{u} \right] \left[1 - \frac{1}{u} \left(u + \frac{du}{dz} \right) \right] \left(u + \frac{du}{dz} \right) -$$

$$- \left[\alpha + \frac{c}{A} - \frac{1}{u} \right] \left[\frac{c}{A} - \frac{1}{u} \right] \left[u \left(\frac{du}{dz} + \frac{d^2u}{dz^2} \right) - \left(u + \frac{du}{dz} \right)^2 \right]$$

$$\left[\alpha + \frac{c}{A} - \frac{1}{u} \right] \left[1 - \frac{1}{u} \left(u + \frac{du}{dz} \right) \right] \left(u + \frac{du}{dz} \right) = - \left[\alpha + \frac{2c}{A} - \frac{2}{u} \right] \left[1 - \frac{1}{u} \left(u + \frac{du}{dz} \right) \right] \left(u + \frac{du}{dz} \right) -$$

$$- \left[\alpha + \frac{c}{A} - \frac{1}{u} \right] \left[\frac{c}{A} - \frac{1}{u} \right] \left[u \left(\frac{du}{dz} + \frac{d^2u}{dz^2} \right) - \left(u + \frac{du}{dz} \right)^2 \right]$$

$$\left[\frac{c^2}{A^2} + \frac{c\alpha}{A} + \frac{\alpha}{u} - \frac{1}{u^2} \right] \left[u + \frac{du}{dz} \right]^2 = \left[\alpha + \frac{2c}{A} - \frac{2}{u} \right] \left[u + \frac{du}{dz} \right] \frac{1}{u} \frac{du}{dz} -$$

$$- \left[\alpha + \frac{c}{A} - \frac{1}{u} \right] \left[\frac{c}{A} - \frac{1}{u} \right] \left[\frac{du}{dz} + \frac{d^2u}{dz^2} \right] u = 0$$

$$\frac{du}{dz} = p$$

$$\left[\left(\frac{c^2}{A^2} + \frac{c\alpha}{A} \right) u^2 + \alpha u - 1 \right] + \frac{du}{dz} \left[\frac{2c^2}{A^2} u + \frac{2c\alpha}{A} u + \frac{2}{u} - \frac{2c}{A} + \frac{2}{u} + \right.$$

$$\left. + \frac{\alpha c}{A} u + \frac{c^2}{A^2} u - \frac{c}{A} - \frac{c}{A} + \frac{1}{u} \right]$$

$$+ \left(\frac{du}{dz} \right)^2 \left[\frac{c^2}{A^2} + \frac{c\alpha}{A} + \frac{\alpha}{u} - \frac{1}{u^2} - \frac{2c}{A} + \frac{2}{u} \right]$$

$$+ \frac{d^2u}{dz^2} \left[\frac{\alpha c}{A} u + \frac{c^2}{A^2} u - \frac{c}{A} - \alpha - \frac{c}{A} + \frac{1}{u} \right] = 0$$

$$\left[\left(\frac{c^2}{A^2} + \frac{c\alpha}{A} \right) u^2 + \alpha u - 1 \right] + \frac{du}{dz} \left[\left(\frac{c^2}{A^2} + \frac{c\alpha}{A} \right) u - \frac{4c}{A} + \frac{1}{u} \right] +$$

$$+ \left(\frac{du}{dz} \right)^2 \left[\frac{c^2}{A^2} + \frac{c\alpha}{A} - \frac{2c}{A} \frac{1}{u} + \frac{1}{u^2} \right] + \frac{d^2u}{dz^2} \left[\frac{c^2}{A^2} + \frac{c\alpha}{A} \right] u - \alpha - \frac{2c}{A} + \frac{1}{u} = 0$$

$$\frac{du}{dz} = p \quad \frac{d^2u}{dz^2} = p \frac{dp}{du}$$

$$U_0 + p U_1 + p^2 U_2 + p \frac{dp}{du} U_3 = 0$$

$$\alpha + \frac{c}{A} = \frac{1}{\theta_0} = \alpha \left(1 + \frac{c}{\alpha A}\right) = \alpha \left(1 + \frac{1}{k-1}\right) = \frac{\alpha k}{k-1}$$

$$\frac{\alpha A}{c} = k-1 \quad \frac{c}{A} = \frac{\alpha}{k-1}$$

$$\frac{dq}{du} \underbrace{\left(\alpha + \frac{c}{A} - u\right)\left(\frac{c}{A} - u\right)}_{U_0} + q \underbrace{\left[\frac{c}{A}\left(\alpha + \frac{c}{A}\right) - 2u\left(\alpha + \frac{2c}{A}\right) + 3u^2\right]}_{U_1} = \underbrace{\left[\frac{2c}{A}\left(\alpha + \frac{c}{A}\right) - u\left(\alpha + \frac{4c}{A}\right) + 2u^2\right]}_{U_2}$$

$$q = e^{-\int \frac{U_1}{U_0} du} \left[C + \int \frac{U_2}{U_0} e^{\int \frac{U_1}{U_0} du} du \right]$$

$$\frac{U_1}{U_0} = \frac{\frac{c}{A}\left(\alpha + \frac{c}{A}\right) - 2u\left(\alpha + \frac{2c}{A}\right) + 3u^2}{\left(\alpha + \frac{c}{A} - u\right)\left(\frac{c}{A} - u\right)} = 3 - \frac{2\frac{c}{A}\left(\alpha + \frac{c}{A}\right) - u\left(\alpha + \frac{2c}{A}\right)}{\frac{c}{A}\left(\alpha + \frac{c}{A}\right) - \left(\alpha + \frac{2c}{A}\right)u + u^2}$$

$$= 3 - \left[\frac{\left(\alpha + \frac{c}{A}\right)}{\alpha + \frac{c}{A} - u} + \frac{\frac{c}{A}}{\frac{c}{A} - u} \right]$$

$$\int \frac{U_1}{U_0} du = 3u + \log \left[\left(\alpha + \frac{c}{A} - u\right)^{+\left(\alpha + \frac{c}{A}\right)} \left(\frac{c}{A} - u\right)^{+\frac{c}{A}} \right]$$

$$\frac{U_2}{U_0} = \frac{\frac{2c}{A}\left(\alpha + \frac{c}{A}\right) - u\left(\alpha + \frac{4c}{A}\right) + 2u^2}{\frac{c}{A}\left(\alpha + \frac{c}{A}\right) - \left(\alpha + \frac{2c}{A}\right)u + u^2} = 2 -$$

u_0

$$\frac{dq}{du} (\alpha + \frac{c}{A} - u) (\frac{c}{A} - u) + q \left[\frac{(\alpha + \frac{c}{A} - u) (\frac{c}{A} - u)}{u} - \frac{(\alpha + \frac{c}{A} - u) (\frac{c}{A} - u)}{u} \right] = 2x$$

$$q \left[(\alpha + \frac{c}{A} - u) (\frac{c}{A} - u) - u (\alpha + \frac{2c}{A} - 2u) \right]$$

$$= \frac{2c}{A} (\alpha + \frac{c}{A} - u) - u (\alpha + \frac{2c}{A} - 2u)$$

u_1

$$u_1 = (\alpha + \frac{c}{A} - u) \left[(\frac{c}{A} - u) - u (\alpha + \frac{c}{A} - u + \frac{c}{A} - u) \right]$$

$$\frac{u_1}{u_0} = 1 - u \left[\frac{1}{\frac{c}{A} - u} + \frac{1}{\alpha + \frac{c}{A} - u} \right]$$

$$= 1 + \frac{u}{u - \frac{c}{A}} + \frac{u}{u - \alpha - \frac{c}{A}} = 3 - \frac{\frac{c}{A}}{\frac{c}{A} - u} - \frac{\alpha + \frac{c}{A}}{\alpha + \frac{c}{A} - u}$$

$$\frac{u_2}{u_0} = \frac{2c}{A} (\alpha + \frac{c}{A} - u) - u (\alpha + \frac{c}{A} - u + \frac{c}{A} - u)$$

$$\frac{u_2}{u_0} = \frac{\frac{2c}{A} - u}{\frac{c}{A} - u} - \frac{u}{\alpha + \frac{c}{A} - u} = 1 + \frac{\frac{c}{A}}{\frac{c}{A} - u} + 1 - \frac{\frac{c}{A}}{\alpha + \frac{c}{A} - u}$$

$$= 2 + \frac{\frac{c}{A}}{\frac{c}{A} - u} - \frac{\alpha + \frac{c}{A}}{\alpha + \frac{c}{A} - u}$$

$$\int \frac{u_1}{u_0} du = 3u + \log \left(\frac{\alpha + \frac{c}{A} - u}{\frac{c}{A} - u} \right)$$

$$\int \frac{u_2}{u_0} du = \frac{3u}{\alpha + \frac{c}{A} - u} + \log \left(\frac{\alpha + \frac{c}{A} - u}{\frac{c}{A} - u} \right)$$

$$\left. \begin{aligned} \int -\frac{\frac{c}{A}}{\frac{c}{A}-u} du &= \frac{c}{A} \log\left(\frac{c}{A}-u\right) = \log\left(\frac{c}{A}-u\right)^{\frac{c}{A}} \\ &= \int \frac{\frac{c}{A}}{u-\frac{c}{A}} du = \frac{c}{A} \log\left(u-\frac{c}{A}\right) = \log\left(u-\frac{c}{A}\right)^{\frac{c}{A}} \end{aligned} \right\} \cdot 2$$

$$\begin{aligned} \int_{u_0}^{u_1} \frac{u}{u_0} e^{\int_{u_0}^u \frac{c}{A} du} du &= \int \left[2 \frac{\alpha + \frac{c}{A}}{\alpha + \frac{c}{A} - u} + \frac{\frac{c}{A}}{\frac{c}{A} - u} \right] e^{\int_{u_0}^u \frac{c}{A} du} du \\ &= 2 \int_0^1 e^{\left(\alpha + \frac{c}{A} - u\right)^{\frac{c}{A}}} \left(\frac{c}{A} - u\right)^{\frac{c}{A}-1} du - \left(\alpha + \frac{c}{A}\right) \int_0^1 e^{\left(\alpha + \frac{c}{A} - u\right)^{\frac{c}{A}}} \left(\frac{c}{A} - u\right)^{\frac{c}{A}-1} du \\ &\quad + \frac{c}{A} \int_0^1 e^{\left(\alpha + \frac{c}{A} - u\right)^{\frac{c}{A}}} \left(\frac{c}{A} - u\right)^{\frac{c}{A}-1} du \end{aligned}$$

$$\left(\alpha + \frac{c}{A} - u\right) \left(\frac{c}{A} - u\right) = z$$

$$2 \left(\frac{dq}{du} + q \right) - (q-1)u \frac{dz}{du} = \frac{2c}{A} \left(\alpha + \frac{c}{A} - u\right)$$

$$2 \frac{dq}{du} + q \frac{dz}{u du} + 2q + \dots = f(u)$$

$$\frac{1}{2} \frac{dq}{du} - \frac{q}{2} \frac{dz}{u du} + \frac{q}{2} = \frac{c}{A} \left(\alpha + \frac{c}{A} - u\right) - \frac{dz}{du} = \frac{u_2}{2^2}$$

$$\frac{q}{2} = t$$

$$\begin{aligned} \int_0^1 \left(\alpha + \frac{c}{A} - u \right)^{\frac{c}{A}-1} du &= \int_0^1 \left(\alpha + \frac{c}{A} - u \right)^{\frac{c}{A}-1} du - \int_0^1 \left(\alpha + \frac{c}{A} - u \right)^{\frac{c}{A}-1} \frac{d}{du} \left[e^{\left(\alpha + \frac{c}{A} - u\right)^{\frac{c}{A}}} \right] du \\ &= 3 \int_0^1 - \frac{c}{A} \int_0^1 \end{aligned}$$

$$(\alpha + \frac{c}{A}) J_1 + \frac{c}{A} J_2 - 3J_0 + e^{3u} (\alpha + \frac{c}{A} - u)^{\frac{\alpha+c}{A}} (\frac{c}{A} - u)^{\frac{c}{A}} = 0$$

$$J_0 = \int e^{3u} (\alpha + \frac{c}{A} - u)^{\frac{\alpha+c}{A}} (\frac{c}{A} - u)^{\frac{c}{A}} du = u e^{3u} (\alpha + \frac{c}{A} - u)^{\frac{\alpha+c}{A}} (\frac{c}{A} - u)^{\frac{c}{A}} -$$

$$-3J_0 + (\alpha + \frac{c}{A}) J_1 + \frac{c}{A} J_2$$

$$4J_0 - (\alpha + \frac{c}{A}) J_1 - \frac{c}{A} J_2 = u e^{3u} (\alpha + \frac{c}{A} - u)^{\frac{\alpha+c}{A}} (\frac{c}{A} - u)^{\frac{c}{A}}$$

$$-3J_0 + (\alpha + \frac{c}{A}) J_1 + \frac{c}{A} J_2 = -e^{3u} (\alpha + \frac{c}{A} - u)^{\frac{\alpha+c}{A}} (\frac{c}{A} - u)^{\frac{c}{A}}$$

$$J_0 = e^{3u} (\alpha + \frac{c}{A} - u)^{\frac{\alpha+c}{A}} (\frac{c}{A} - u)^{\frac{c}{A}} (u-1) ?$$

$$\frac{d}{du} = e^{3u} (\alpha + \frac{c}{A} - u)^{\frac{\alpha+c}{A}-1} (\frac{c}{A} - u)^{\frac{c}{A}-1} [(u-1) [3(\alpha + \frac{c}{A} - u)(\frac{c}{A} - u) -$$

$$-(\alpha + \frac{c}{A})(\frac{c}{A} - u) - (\alpha + \frac{c}{A} - u) \frac{c}{A}] + (\alpha + \frac{c}{A} - u)(\frac{c}{A} - u)]$$

$$[3\alpha\frac{c}{A} + 3\frac{c^2}{A^2} - 6\frac{c}{A}u - 3u\alpha - 3u^2 - \alpha\frac{c}{A} + \alpha u + \frac{c}{A}u - \frac{c^2}{A^2} - \frac{\alpha c}{A} - \frac{c^2}{A^2} + \frac{u c}{A}]$$

$$= \frac{\alpha c}{A} + \frac{c^2}{A^2} - 4\frac{c}{A}u - 2\alpha u + 3u^2$$

$$= (\alpha + \frac{c}{A})\frac{c}{A} - 2(\alpha + \frac{c}{A})u - 2\frac{c}{A}u + 3u^2 \parallel -\alpha\frac{c}{A} - \frac{c^2}{A^2} + \frac{2c}{A}u + \alpha u - u^2$$

$$= -\frac{2c}{A}u - \alpha u + 2u^2$$

$$3u^3 - 4\frac{c}{A}u^2 - 2\alpha u^2 + \frac{\alpha c}{A}u + \frac{c}{A}u + \frac{2c}{A}u + \alpha u - 2u^2$$

$$-3 \int u e^{3u} (\alpha + \frac{c}{A} - u)^{\frac{\alpha+c}{A}} (\frac{c}{A} - u)^{\frac{c}{A}} du + \int u e^{3u} (\alpha + \frac{c}{A}) (\alpha + \frac{c}{A} - u)^{\frac{\alpha+c}{A}-1} (\frac{c}{A} - u)^{\frac{c}{A}} du$$

$$+ \int u e^{3u} (\frac{c}{A} (\alpha + \frac{c}{A} - u)^{\frac{\alpha+c}{A}} (\frac{c}{A} - u)^{\frac{c}{A}-1} du$$

$$q = f(u) = \frac{1}{1-f} = \frac{1}{1-\frac{1}{u}} \frac{du}{dz}$$

$$u = \frac{y}{\theta} \quad z = \log y$$

$$\frac{du}{dz} = y \frac{du}{dy}$$

$$\frac{du}{dz} = u \left[1 - \frac{1}{fu} \right]$$

$$\int \frac{du}{u \left[1 - \frac{1}{fu} \right]} = \int dz = \int \frac{dy}{y} \quad \left. \vphantom{\int} \right\} u = f(y)$$

$$0 = g \theta x - m - \left(\alpha + \frac{c}{A} \right) \theta + \frac{4}{3} \frac{K}{b} \theta \delta \frac{d\delta}{dx}$$

$$0 = y - \left(\alpha + \frac{c}{A} \right) \theta + \frac{4}{3} \frac{K}{b} \theta \delta \frac{d\delta}{dy}$$

$$0 = u - \left(\alpha + \frac{c}{A} \right) + \frac{2}{3} \frac{K}{b} \frac{d}{dy} (\delta^2)$$

~~$$0 = u - \left(\alpha + \frac{c}{A} \right) + \frac{2}{3} \frac{K}{b} \frac{d}{dy} (\delta^2) = \left(\alpha + \frac{c}{A} \right) y - \int f(y) dy$$~~

$$\frac{2}{3} \frac{K}{b} \delta^2 + \text{const} = \left(\alpha + \frac{c}{A} \right) y - \int f(y) dy = \left(\alpha + \frac{c}{A} \right) y - \int f(y) dy$$

$$\frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dx} + \frac{1}{2} \frac{\alpha}{\delta^2} \frac{d(\delta^2)}{dx} = \frac{2}{3} \frac{K}{b} \frac{1}{\delta^2} \left[\frac{d(\delta^2)}{dx} \right]^2$$

ok maybe byi omarene 3 state puz b, \theta, ?

System of equations eliminate:

$$\left. \begin{aligned} \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dx} + \alpha \frac{1}{\theta} \frac{d\theta}{dx} &= \frac{4}{3} \frac{\mu}{b} \left(\frac{d\theta}{dx} \right)^2 \quad \frac{d}{dx} \left[\frac{4}{3} \frac{\mu}{b} \theta \frac{d\theta}{dx} \right] \\ g + \cancel{\alpha} \left(\alpha + \frac{c}{A} \right) \frac{d\theta}{dx} &= \frac{4}{3} \frac{\mu}{b} \left[\theta \frac{d}{dx} \left(\theta \frac{d\theta}{dx} \right) + \theta \left(\frac{d\theta}{dx} \right)^2 \right] \\ g + \alpha \frac{d\theta}{dx} - \alpha \frac{\theta}{b} \frac{d\theta}{dx} &= \frac{4}{3} \frac{\mu}{b} \theta \frac{d}{dx} \left(\theta \frac{d\theta}{dx} \right) \\ &= \frac{4}{3} \frac{\mu}{b} \theta \frac{d\theta}{dx} \frac{d\theta}{dx} + \frac{4}{3} \frac{\mu}{b} \theta \frac{d^2\theta}{dx^2} \end{aligned} \right\}$$

$$\frac{d\theta}{dx} = v$$

$$\frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dx} = \frac{4}{3} \frac{\mu}{b} v^2 - \alpha \frac{v}{\theta}$$

$$g + \alpha \frac{d\theta}{dx} - \alpha \frac{\theta}{b} v = \frac{4}{3} \frac{\mu}{b} \theta v \frac{dv}{dx} + \frac{4}{3} \frac{\mu}{b} \theta \frac{d^2\theta}{dx^2}$$

I). $\frac{d\theta}{dx} = v$

II). $\frac{d\theta}{dx} = \frac{\theta}{\frac{c}{A}} \frac{4}{3} \frac{\mu}{b} v^2 - \frac{\alpha}{\frac{c}{A}} \frac{\theta v}{\theta}$

$$\begin{aligned} \frac{4}{3} \frac{\mu}{b} \theta \frac{dv}{dx} &= g - \alpha \frac{\theta v}{b} + \left[\alpha - \frac{4}{3} \frac{\mu}{b} \theta v \right] \left[\frac{\frac{4}{3} \frac{\mu}{b} \theta v^2 - \frac{\alpha}{\frac{c}{A}} \frac{\theta v}{\theta}}{\frac{c}{A}} \right] \\ &= g - \left(\alpha + \frac{\alpha^2}{\frac{c}{A}} \right) \frac{\theta v}{b} + \frac{\frac{4}{3} \frac{\mu}{b} \alpha}{\frac{c}{A}} \theta v^2 - \left(\frac{\frac{4}{3} \frac{\mu}{b}}{\frac{c}{A}} \right) \theta v^3 \end{aligned}$$

III). $\frac{dv}{dx} = \frac{g}{\frac{4}{3} \frac{\mu}{b} \theta} \frac{1}{\theta} - \frac{\alpha (1 + \frac{\alpha}{\frac{c}{A}})}{\frac{4}{3} \frac{\mu}{b}} \frac{v}{\theta^2} + \frac{2\alpha}{\frac{c}{A}} \frac{v^2}{\theta} - \left(\frac{\frac{4}{3} \frac{\mu}{b}}{\frac{c}{A}} \right) v^3$

$$g x + \left(\alpha - \frac{4}{3} \frac{\theta}{\delta} \frac{d\delta}{dx} \right) \frac{d\theta}{dx} = \alpha \frac{\theta}{\delta} \frac{d\delta}{dx} + \frac{4}{3} \frac{\theta}{\delta} \theta \frac{d\delta}{dx}$$

$$= - \frac{c}{\bar{A}} \frac{1}{\theta} \frac{d\theta}{dx} \cdot \frac{\delta}{\frac{d\delta}{dx}}$$

~~$$\frac{c}{\bar{A}} \frac{1}{\theta} \frac{d^2\theta}{dx^2} - \frac{c}{\bar{A}} \frac{1}{\theta^2} \left(\frac{d\theta}{dx} \right)^2 + \alpha \frac{\theta}{\delta} \frac{d^2\delta}{dx^2} - \frac{\alpha}{\delta} \left(\frac{d\delta}{dx} \right)^2 = \frac{8}{3} \frac{\theta}{\delta} \frac{d\delta}{dx} \frac{d\theta}{dx}$$~~

~~$$\frac{c}{\bar{A}} \theta \frac{d\theta}{dx} + \alpha \frac{\theta^2}{\delta} \cdot \theta \frac{d\delta}{dx} = \frac{4}{3} \frac{\theta}{\delta} \left(\theta \frac{d\delta}{dx} \right)^2$$~~

~~$$\left(\theta \frac{d\delta}{dx} \right)^2 - \frac{\alpha}{\frac{4}{3} \frac{\theta}{\delta}} \frac{\theta}{\delta} \theta \frac{d\delta}{dx} = \frac{c}{\frac{4}{3} \frac{\theta}{\delta}} \theta \frac{d\theta}{dx}$$~~

~~$$\theta \frac{d\delta}{dx} = \frac{\alpha}{\frac{8}{3} \frac{\theta}{\delta}} \frac{\theta}{\delta} \pm \sqrt{\left(\frac{\alpha}{\frac{8}{3} \frac{\theta}{\delta}} \right)^2 \left(\frac{\theta}{\delta} \right)^2 + \frac{\bar{A}}{\frac{4}{3} \frac{\theta}{\delta}} \theta \frac{d\theta}{dx}}$$~~

~~$$g + \left(\alpha + \frac{c}{\bar{A}} \right) \frac{d\theta}{dx} = \frac{d}{dx} \left[\frac{\alpha}{2} \frac{\theta}{\delta} \pm \sqrt{\frac{\alpha^2}{4} \left(\frac{\theta}{\delta} \right)^2 + \frac{4}{3} \frac{\theta}{\delta} \frac{c}{\bar{A}} \theta \frac{d\theta}{dx}} \right]$$

$$= \frac{\alpha}{2} \frac{1}{\delta} \frac{d\theta}{dx} - \frac{\alpha}{2} \frac{\theta}{\delta^2} \frac{d\delta}{dx} \pm \frac{1}{2} \sqrt{\frac{2\alpha^2}{4} \left(\frac{\theta}{\delta^2} \frac{d\theta}{dx} \right) - \frac{\theta^2}{\delta^3} \frac{d\delta}{dx}}$$

$$\pm \frac{1}{2} \sqrt{\frac{4}{3} \frac{\theta}{\delta} \frac{c}{\bar{A}} \frac{d}{dx} \left(\theta \frac{d\theta}{dx} \right)}$$~~

~~$$\frac{c}{\bar{A}} \frac{1}{\theta} \frac{d^2\theta}{dx^2} - \frac{c}{\bar{A}} \frac{1}{\theta^2} \left(\frac{d\theta}{dx} \right)^2 + \frac{\alpha}{\delta^2} \left(\frac{d\delta}{dx} \right)^2 = \left[\frac{8}{3} \frac{\theta}{\delta} \frac{d\delta}{dx} - \frac{\alpha}{\delta} \right] \frac{d}{dx} \left[\frac{g + \alpha \frac{d\theta}{dx} - \alpha \frac{\theta}{\delta} \frac{d\delta}{dx}}{\frac{4}{3} \frac{\theta}{\delta} \theta \delta} - \frac{\frac{4}{3} \frac{\theta}{\delta} \frac{d\theta}{dx}}{\theta} \right]$$~~

$$\left[\frac{8}{3} \frac{\gamma}{b} \frac{d\delta}{dx} - \frac{\alpha}{\delta} \right] \frac{d\delta}{dx} + \frac{\alpha}{\delta^2} \left(\frac{d\delta}{dx} \right)^2 = \frac{c}{A} \frac{d}{dx} \left(\frac{1}{\theta} \frac{d\theta}{dx} \right) \quad \left| \frac{4}{3} \frac{\gamma}{b} \theta \delta \right.$$

$$\left. \frac{4}{3} \frac{\gamma}{b} \theta \delta \frac{d\delta}{dx} + 6 \frac{d\delta}{dx} \frac{d\theta}{dx} \right] \frac{4}{3} \frac{\gamma}{b} + \frac{\alpha \theta}{\delta} \frac{d\delta}{dx} = g + \alpha \frac{d\theta}{dx} \quad \left| \frac{8}{3} \frac{\gamma}{b} \frac{d\delta}{dx} - \frac{\alpha}{\delta} \right.$$

$$- \frac{4}{3} \frac{\gamma}{b} \alpha \frac{\theta}{\delta} \left(\frac{d\delta}{dx} \right)^2 + 2 \left(\frac{4}{3} \frac{\gamma}{b} \right)^2 \frac{d\theta}{dx} \left(\frac{d\delta}{dx} \right)^2 \delta - \frac{4}{3} \frac{\gamma}{b} \alpha \frac{d\delta}{dx} \frac{d\theta}{dx} + \frac{8}{3} \frac{\gamma}{b} \frac{\alpha \theta}{\delta} \left(\frac{d\delta}{dx} \right)^2 -$$

$$- \alpha^2 \frac{\theta}{\delta^2} \frac{d\delta}{dx} = \frac{8}{3} \frac{\gamma}{b} g \frac{d\delta}{dx} - \frac{\alpha g}{\delta} + \frac{8}{3} \frac{\gamma}{b} \frac{d\delta}{dx} \frac{d\theta}{dx} - \frac{\alpha^2}{\delta} \frac{d\theta}{dx} - \frac{4}{3} \frac{\gamma}{b} \frac{c}{A} \theta \delta \frac{d}{dx} \left(\frac{1}{\theta} \frac{d\theta}{dx} \right)$$

$$\frac{4}{3} \frac{\gamma}{b} \frac{\alpha}{\delta} \left(\frac{d\delta}{dx} \right)^2 + 2 \left(\frac{4}{3} \frac{\gamma}{b} \right)^2 \frac{d\theta}{dx} \left(\frac{d\delta}{dx} \right)^2 - 4 \frac{\gamma}{b} \frac{\alpha}{\delta} \frac{d\delta}{dx} \frac{d\theta}{dx} - \alpha^2 \frac{\theta}{\delta^2} \frac{d\delta}{dx}$$

$$= \frac{8}{3} \frac{\gamma}{b} g \frac{d\delta}{dx} - \frac{\alpha g}{\delta} - \frac{\alpha^2}{\delta} \frac{d\theta}{dx} - \frac{4}{3} \frac{\gamma}{b} \frac{c}{A} \theta \delta \frac{d}{dx} \left(\frac{1}{\theta} \frac{d\theta}{dx} \right)$$

$$\frac{4}{3} \frac{\gamma}{b} \left(\frac{d\delta}{dx} \right)^2 = \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dx} + \alpha \frac{1}{\delta} \frac{d\delta}{dx}$$

$$\frac{\alpha c}{A} \frac{1}{\delta} \frac{d\theta}{dx} + \frac{\alpha}{\delta^2} \frac{d\delta}{dx} + \frac{4}{3} \frac{\gamma}{b} \frac{d\theta}{dx} \left[\frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dx} + \alpha \frac{1}{\delta} \frac{d\delta}{dx} \right] - 4 \frac{\gamma}{b} \frac{\alpha}{\delta} \frac{d\delta}{dx} \frac{d\theta}{dx} - \frac{\alpha^2}{\delta} \frac{d\theta}{dx}$$

$$= \frac{8}{3} \frac{\gamma}{b} g \frac{d\delta}{dx} - \frac{\alpha g}{\delta} - \frac{\alpha^2}{\delta} \frac{d\theta}{dx} - \frac{4}{3} \frac{\gamma}{b} \frac{c}{A} \theta \delta \left[\frac{1}{\theta} \frac{d\theta}{dx} - \frac{1}{\theta^2} \left(\frac{d\theta}{dx} \right)^2 \right]$$

$$\frac{4}{3} \frac{\gamma}{b} \frac{d\delta}{dx} \left[\alpha \frac{d\theta}{dx} - g \right] + \frac{\alpha g}{\delta} + \left[\alpha^2 + \frac{\alpha c}{A} \right] \frac{1}{\delta} \frac{d\theta}{dx} +$$

$$+ \frac{4}{3} \frac{\gamma}{b} \frac{c}{A} \frac{1}{\theta} \left(\frac{d\theta}{dx} \right)^2 + \frac{4}{3} \frac{\gamma}{b} \frac{c}{A} \theta \frac{d\theta}{dx} = 0$$

$$\frac{2}{3} \frac{\gamma}{b} \frac{d(\delta^2)}{dx} \left[\alpha \frac{d\theta}{dx} - g \right] + \alpha g + \alpha \left(\alpha + \frac{c}{A} \right) \frac{1}{\delta} \frac{d\theta}{dx} + \frac{4}{3} \frac{\gamma}{b} \frac{c}{A} \theta \frac{d}{dx} \left(\frac{1}{\theta} \frac{d\theta}{dx} \right) = 0$$

$$\frac{1}{3} \frac{\gamma}{b} \left[\frac{d(\delta^2)}{dx} \right]^2 - \frac{\alpha}{2} \frac{d(\delta^3)}{dx} = \frac{c}{A} \frac{\delta^2}{\theta} \frac{d\theta}{dx} \quad \left| \frac{4}{3} \frac{\gamma}{b} \right.$$

$$\left[\alpha g + \alpha \left(\alpha + \frac{c}{A} \right) \frac{d\theta}{dx} + \frac{4}{3} \frac{\kappa}{\theta} \frac{c}{A} \frac{6^2}{\theta} \frac{d}{dx} \left(\theta \frac{d\theta}{dx} \right) \right]^2 - \alpha \left[\alpha \frac{d\theta}{dx} - g \right] \left[\alpha g + \alpha \left(\alpha + \frac{c}{A} \right) \frac{d\theta}{dx} + \frac{4}{3} \frac{\kappa}{\theta} \frac{c}{A} \frac{6^2}{\theta} \frac{d}{dx} \left(\theta \frac{d\theta}{dx} \right) \right] -$$

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$$= \frac{4}{3} \frac{\kappa}{\theta} \frac{c}{A} \left[\alpha \frac{d\theta}{dx} - g \right]^2 \frac{6^2}{\theta} \frac{d\theta}{dx}$$

$$\left[\alpha g + \alpha \left(\alpha + \frac{c}{A} \right) \frac{d\theta}{dx} + \frac{4}{3} \frac{\kappa}{\theta} \frac{c}{A} \frac{6^2}{\theta} \frac{d}{dx} \left(\theta \frac{d\theta}{dx} \right) \right]^2 - \alpha^2 \left[\alpha \frac{d\theta}{dx} - g \right] \left[\alpha g + \alpha \left(\alpha + \frac{c}{A} \right) \frac{d\theta}{dx} + \frac{4}{3} \frac{\kappa}{\theta} \frac{c}{A} \frac{6^2}{\theta} \frac{d}{dx} \left(\theta \frac{d\theta}{dx} \right) \right] -$$

$$6^2 = \dots$$

$$\left[\frac{6^2}{\theta} \frac{d}{dx} \left(\theta \frac{d\theta}{dx} \right) \frac{4}{3} \frac{\kappa}{\theta} \frac{c}{A} \right]^2 + \left[\frac{6^2}{\theta} \frac{d}{dx} \left(\theta \frac{d\theta}{dx} \right) \frac{4}{3} \frac{\kappa}{\theta} \frac{c}{A} \right] \left[2\alpha \left[g + \left(\alpha + \frac{c}{A} \right) \frac{d\theta}{dx} \right] - \alpha^2 \frac{d\theta}{dx} + \alpha g \right] -$$

$$- \frac{4}{3} \frac{\kappa}{\theta} \frac{c}{A} \frac{6^2}{\theta} \frac{d\theta}{dx} \left[\alpha \frac{d\theta}{dx} - g \right]^2 = \alpha^2 \left[\alpha \frac{d\theta}{dx} - g \right] \left[g + \left(\alpha + \frac{c}{A} \right) \frac{d\theta}{dx} \right] -$$

$$- \alpha^2 \left[g + \left(\alpha + \frac{c}{A} \right) \frac{d\theta}{dx} \right]^2$$

$$= \alpha^2 \left[g + \left(\alpha + \frac{c}{A} \right) \frac{d\theta}{dx} \right] \left[\alpha \frac{d\theta}{dx} - g - g - \left(\alpha + \frac{c}{A} \right) \frac{d\theta}{dx} \right]$$

Wracając to 6^2 w równanie otrzymamy z równania 3 hydrodynamicznego

(nie uwzględniamy już $\kappa \theta$)

To równanie $6^2 = \dots$ będzie służyć do oznaczenia stałych

Overlying prismatic:

Isolated isothermally:

$$\rho = \frac{\mu}{\alpha \theta}$$

$$\begin{cases} p = \alpha \theta \rho \\ 0 = -g - \frac{1}{\rho} \frac{dp}{dx} + \frac{4}{3} \frac{\mu}{\rho} \frac{d^2 \theta}{dx^2} \\ \rho \theta = b = \rho_0 \theta_0 = \frac{\mu_0 \theta_0}{\alpha \theta_0} \end{cases} \quad \rho = \frac{\mu}{\alpha \theta}$$

$$0 = -g - \alpha \theta \frac{1}{\rho} \frac{dp}{dx} + \frac{4}{3} \frac{\mu}{b} \theta \frac{d^2 \theta}{dx^2}$$

$$0 = -g + \alpha \theta \frac{1}{b} \frac{db}{dx} + \frac{4}{3} \frac{\mu}{b} \theta \frac{d^2 \theta}{dx^2}$$

$$\frac{db}{dx} = u \quad \frac{d^2 \theta}{dx^2} = \frac{d^2 b}{dx^2} = u \frac{du}{db}$$

$$2b \frac{db}{dx} = u \quad \frac{du}{dx} = 2 \left(\frac{db}{dx} \right)^2 + 2b \frac{d^2 b}{dx^2}$$

$$2b \frac{d^2 b}{dx^2} = \frac{du}{dx} \frac{1}{2} \left(\frac{u}{b} \right)^2$$

$$\frac{1}{b} \frac{db}{dx} = \frac{u}{2b^2} \quad \frac{du}{d(b^2)} u = \frac{1}{2} \frac{u^2}{b^2}$$

$$0 = -g + \alpha \theta \frac{u}{b^2} + \frac{4}{3} \frac{\mu}{b} \theta \frac{du}{db}$$

$$\frac{db}{du} (g - \alpha \theta \frac{u}{b}) = \frac{4}{3} \frac{\mu}{b} \theta u$$

$$0 = -g + \alpha \theta \frac{u}{b^2} + \frac{4}{3} \frac{\mu}{b} \theta \left[\frac{du}{dx} - \left(\frac{u}{b} \right)^2 \right]$$

$$0 = -g + \alpha \theta \frac{u}{b^2} + \frac{4}{3} \frac{\mu}{b} \theta \left[\frac{1}{2} \frac{du}{d(b^2)} u - \frac{1}{4} \frac{u^2}{b^2} \right]$$

$$\frac{2}{3} \frac{\mu}{b} \theta \frac{du}{d(b^2)} - \frac{1}{3} \frac{\mu}{b} \theta \frac{u}{b^2} + \frac{\alpha \theta}{2} - \frac{g}{u} = 0$$

$$0 = -g + \alpha \theta \frac{u^2 v}{b^2} + \frac{4}{3} \frac{\mu}{b} \theta \frac{u^2 v}{b^2} \left[u' \frac{dv}{db} + v \frac{du'}{db} \right]$$

$$u^2 v \left[\frac{\alpha \theta}{b^2} + \frac{4}{3} \frac{\mu}{b} \theta \frac{u'}{db} \right]$$

$$\frac{d\rho}{dx} = -\frac{1}{\alpha} \left(\frac{6}{\rho} \frac{d\rho}{dx} \right)$$

$$\rho \frac{d\theta}{dx} + \theta \frac{d\rho}{dx} = 0$$

$$\frac{d\theta}{dx} = -\frac{1}{\alpha} \frac{d\rho}{dx} \frac{6}{\rho}$$

$$u\theta = x \quad \frac{u}{b} = y$$

$$u^2 = x^2 y \quad \frac{x}{y} = b^2$$

$$2u \frac{du}{dx} + \frac{u^2}{b^2} \frac{db}{dx} = \frac{dx}{b^2}$$

$$u^2 + b \frac{du}{dx} = \frac{dx}{b^2}$$

$$\frac{u}{b^2} db + \frac{du}{b} = dy \quad b^2$$

$$2u db = dx - b^2 dy$$

$$2b du = dx + b^2 dy$$

$$\frac{db}{du} = \frac{1 - \frac{dy}{dx} \frac{x}{y}}{1 + \frac{dy}{dx} \frac{x}{y}} \quad \frac{1}{y}$$

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$$b^2 = y$$

$$2b \frac{db}{dx} = \frac{dy}{dx}$$

$$2 \left(\frac{db}{dx} \right)^2 + 2b \frac{d^2b}{dx^2} = \frac{d^2y}{dx^2}$$

$$\frac{1}{2} \frac{dy}{dx} = \frac{d^2y}{dx^2} \quad \frac{1}{4} \left(\frac{dy}{dx} \right)^2$$

$$0 = g + \frac{\alpha \theta}{2y} \frac{dy}{dx} + \frac{4}{3} \frac{\mu}{b} \left[\frac{1}{2} \frac{d^2y}{dx^2} - \frac{1}{4y} \left(\frac{dy}{dx} \right)^2 \right]$$

$$= g + \frac{1}{y} \frac{d}{dx} \left[\frac{1}{4} \left(\frac{dy}{dx} \right)^2 \right] = \frac{dy}{dx}$$

$$= \frac{1}{4} \frac{dy}{dx} - \frac{1}{4y} \left(\frac{dy}{dx} \right)^2$$

$$\frac{2}{3} \frac{d^2y}{dx^2} - \frac{1}{y} \left(\frac{dy}{dx} \right)^2$$

$$0 = -g + \frac{\alpha \theta}{2} \frac{1}{y} \frac{dy}{dx} + \frac{4}{3} \frac{\mu}{b} \frac{\frac{d}{dx} \left[\frac{1}{4} \left(\frac{dy}{dx} \right)^2 \right]}{\frac{1}{y} \frac{dy}{dx}}$$

$$\frac{1}{y} \frac{dy}{dx} = 2$$

$$0 = -g + \frac{\alpha \theta}{2} z + \frac{1}{3} \frac{\mu}{b} \frac{d}{dy} (z^2 y)$$

$$\theta = -\frac{g}{y} + \frac{\alpha \theta}{2} \frac{z}{y} + \frac{1}{3} \frac{\mu}{b} z^2 + \frac{2}{3} \frac{\mu}{b} y z \frac{dz}{dy}$$

$$\alpha \theta \frac{u}{b^2} + \frac{4}{3} \frac{\mu}{b} u \frac{du}{db} = 0$$

$$u = u' + v$$

$$\frac{du}{db} \frac{y}{b} = -\frac{\theta \alpha}{b^2}$$

$$0 = -\frac{g}{b} + \alpha \theta \left[\frac{u'}{b} + \frac{v}{b^2} \right] + \frac{4}{3} \frac{\mu}{b} [u' + v] \left(\frac{du'}{db} + \frac{dv}{db} \right) = 0$$

$$0 = -\frac{g}{b} + \alpha \theta \frac{v}{b^2} + \frac{4}{3} \frac{\mu}{b} u' \frac{dv}{db} + \frac{4}{3} \frac{\mu}{b} v \frac{du'}{db} + \frac{4}{3} \frac{\mu}{b} v \frac{dv}{db} = 0$$

$$u z = t$$

$$-z \frac{du}{dz} = \frac{dt}{dz}$$

$$\frac{dz}{dt} = \frac{1}{t^2}$$

$$0 = -\frac{g}{b} + \frac{4}{3} \frac{\mu}{b} \frac{dv}{db} (u' + v)$$

$$\frac{dz}{dt} = \frac{1}{t^2} \Rightarrow \frac{1}{t^2} = -\frac{1}{t^2} \frac{dt}{dz}$$

$$= -\frac{g}{b} + \frac{4}{3} \frac{\mu}{b} v \frac{dv}{db} + \frac{4}{3} \frac{\mu}{b} \frac{d(u'v)}{db} + v \frac{\theta \alpha}{b^2}$$

$$\frac{1}{b} = 2 \quad \frac{dz}{db} = -\frac{1}{b^2}$$

$$0 = -g + \alpha \theta u z^2 - \frac{4}{3} \frac{\mu}{b} u \frac{du}{dz} z^2$$

$$\frac{4}{3} \frac{\mu}{b} \frac{du}{dz} = \alpha \theta - \frac{g}{u z} \quad \left| \quad u \frac{d}{dz} \left(\frac{4}{3} \frac{\mu}{b} u - \alpha \theta z \right) + \frac{g}{b^2} dz = 0 \right.$$

$$u = \frac{\frac{g}{\theta^6}}{\frac{\alpha \theta}{\theta^2} + \frac{4}{3} \frac{1}{\theta} \uparrow}$$

$$\mu = \frac{-\frac{g}{\theta^2}}{\frac{\alpha \theta}{\theta^2} + \frac{4}{3} \frac{1}{\theta} \uparrow} - \frac{\frac{g}{\theta} \left[\frac{2\alpha \theta}{\theta^3} + \frac{4}{3} \frac{1}{\theta} \frac{d\theta}{dx} \right]}{(\quad)^2}$$

$$h=0 \quad x=a \quad y = \left(\alpha + \frac{c}{A} \right) \theta - 2 \quad u = \left(1 + \frac{c}{A\alpha} \right) - 5$$

$$> 0$$

$$= \frac{k}{k-1} - 5 < \frac{7}{2}$$

$$\frac{2c}{A\alpha} \left[1 + \frac{c}{A\alpha} + \frac{m-gx}{\alpha\theta} \right] = \frac{1}{dx} \left[\frac{\left[1 + \frac{c}{A\alpha} + \frac{m-gx}{\alpha\theta} \right] \left[\frac{c}{A\alpha} + \frac{m-gx}{\alpha\theta} \right]}{\left(\frac{1}{\alpha\theta} \right) \frac{d\theta}{dx}} \right]$$

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$$\frac{\alpha A}{c} = k-1$$

$$gx - m = y = e^z$$

$$\alpha\theta = u e^z$$

$$u = \frac{y}{\alpha\theta}$$

$$\frac{2c}{A\alpha} \left[1 + \frac{c}{A\alpha} - \frac{u}{u} \right] \left(u + \frac{du}{dz} \right)^2 = - \dots$$

$$q = \int \left[2 - \frac{1 + \frac{c}{A\alpha}}{1 + \frac{c}{A\alpha} - u} + \frac{\frac{c}{A\alpha}}{\frac{c}{A\alpha} - u} \right] e^{3u} \left(1 + \frac{c}{A\alpha} - u \right) \left(\frac{c}{A\alpha} - u \right) du$$

$$= \frac{1}{1-p} = f(u)$$

$$\int \frac{du}{u \left[1 - \frac{1}{f(u)} \right]} = \int dz = \int \frac{dy}{y}$$

$$q_{\text{max}} = \int 2 e^{3u} du = \frac{2}{3} e^{3u} - \frac{4}{3} \int e^{3u} u du$$

$$= e^{3u} \left[\frac{2}{3} u - \frac{4}{9} u + \frac{4}{27} \right] = \frac{2}{3} e^{3u} \left[u - \frac{2}{3} u + \frac{2}{9} \right]$$

$$= \frac{2}{3} e^{3u}$$

$$\int \frac{du}{u \left[1 - \frac{2}{3} e^{-3u} \right]}$$

dla wielkich wartości u

$$\int \frac{du}{u \left[1 - \frac{2}{3} e^{-u} \right]}$$

dla małych u
nie ~~można~~ musi się rozwinąć

Względności - energia kinetyczna i nie stała:

$$1). \quad p = \alpha \theta \rho$$

$$2). \quad \theta \frac{d\theta}{dx} = -g - \frac{1}{\rho} \frac{\partial p}{\partial x} = -g - \alpha \frac{\partial \theta}{\partial x} + \frac{\alpha \theta}{\rho} \frac{\partial \rho}{\partial x}$$

$$\rho \theta = h$$

$$\mu = \alpha \frac{\theta h}{\theta}$$

$$3). \quad \frac{c}{A \theta} \frac{\partial \theta}{\partial x} + \alpha \frac{1}{\theta} \frac{\partial \theta}{\partial x} = 0$$

$$\left(\frac{\theta}{\theta_0} \right)^{\frac{\alpha A}{c}} = 1$$

$$\frac{\alpha A}{c} = k-1$$

$$\frac{\theta}{\theta_0} = \left(\frac{\rho}{\rho_0} \right)^{-(k-1)}$$

~~Względności~~

$$2 - \theta 3): \quad \theta \frac{d\theta}{dx} = -g - \left(\alpha + \frac{c}{A} \right) \frac{d\theta}{dx}$$

$$\frac{\theta^2}{2} + g x + \left(\alpha + \frac{c}{A} \right) \theta = \text{const}$$

$$\frac{\theta^2 - \theta_0^2}{2} + g(x-a) + \alpha \frac{k}{k-1} (\theta - \theta_0) = 0$$

$$\frac{\theta^2 - \theta_0^2}{2} + g(x-a) + \frac{\alpha k}{k-1} \theta_0 \left[\left(\frac{\theta}{\theta_0} \right)^{-(k-1)} - 1 \right] = 0$$

$$\frac{\theta^2 - \theta_0^2}{2} + g(x-a) + \frac{\alpha k}{k-1} \frac{\theta_0}{\theta_0^{1-k}} \left[\theta^{-(k-1)} - \theta_0^{-(k-1)} \right] = 0$$

$$20). \quad k-1 = \frac{1}{2}$$

$$\frac{\theta^2 - \theta_0^2}{2} \left(\frac{\theta^2 + \theta_0^2}{\theta^2 - \theta_0^2} \right)$$

$$\frac{\theta^2 - \theta_0^2}{2} + \frac{2k}{k-1} \frac{\alpha \theta_0}{\theta_0^{1-k}} \left[\frac{1}{\sqrt{\theta}} - \frac{1}{\sqrt{\theta_0}} \right] = -g(x-a)$$

$$g(x-a) = (\sqrt{b} - \sqrt{b_0}) \left[\frac{2k}{k-1} \frac{\alpha \theta_0}{b_0^{1-k}} \frac{1}{\sqrt{b b_0}} - (b+b_0)(\sqrt{b} + \sqrt{b_0}) \right]$$

$$\frac{\alpha \theta_0 b}{b_0} = p_0$$

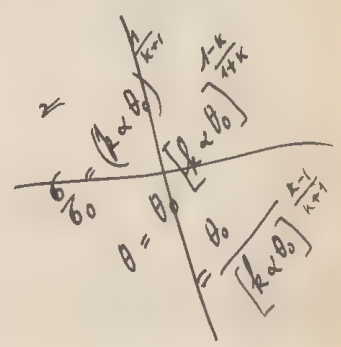
$$\begin{aligned} 2g(x-a) &= \frac{2k}{k-1} \frac{p_0}{b} b_0^{\frac{3}{2}} \left[\frac{1}{\sqrt{b_0}} - \frac{1}{\sqrt{b}} \right] - (b^2 - b_0^2) \\ &= \frac{6 p_0}{b} b_0 \left[1 - \sqrt{\frac{b_0}{b}} \right] - (b^2 - b_0^2) \end{aligned}$$

nie ma nigdy ~~tych~~ osiągnięci wartości $\frac{p_0 b_0}{b} = b \propto \theta_0$

$$\frac{\partial \theta}{\partial x} = \theta_0 \frac{(1-k)}{b_0^{1-k}} b^{-k} \frac{\partial b}{\partial x}$$

$$\left[6 + \left(k + \frac{c}{A} \right) (1-k) \frac{\theta_0}{b_0} \left(\frac{b}{b_0} \right)^{-k} \right] \frac{\partial b}{\partial x} = 0$$

= 0 Max dla x:



$$b^{k+1} + \left(k + \frac{c}{A} \right) (1-k) \theta_0 b_0^{-k} b = 0$$

$$\left(\frac{b}{b_0} \right)^{k+1} = (k-1) \left(k + \frac{c}{A} \right) \theta_0 = k \propto \theta_0$$

$$\begin{aligned} \frac{b}{b_0} &= [k \propto \theta_0]^{\frac{2}{3}} \\ \frac{b_0}{b} &= [k \propto \theta_0]^{-\frac{2}{3}} \end{aligned}$$

$$\begin{aligned} 2g(x-a)_{\text{max}} &= 6 \frac{p_0 b_0}{b} \left[1 - [k \propto \theta_0]^{-\frac{1}{3}} \right] - b_0^2 \left[(k \propto \theta_0)^{\frac{2}{3}} - 1 \right] \\ &= 6 \propto \theta_0 \left[1 - [k \propto \theta_0]^{-\frac{1}{3}} \right] - b_0^2 \left[(k \propto \theta_0)^{\frac{2}{3}} - 1 \right] \\ &= 6 \propto \theta_0 + b_0^2 - 6 \end{aligned}$$

nie tutaj granice już się nie osiąga
 $6 \propto \theta_0 [k \propto \theta_0]^{-\frac{1}{3}} + b_0^2$
 $= -b_0^2 + (k \propto \theta_0)^{\frac{2}{3}} [6 \propto \theta_0 + (k \propto \theta_0)^{\frac{2}{3}}]$

One type ~~of~~ ~~the~~ dla $\theta_0 = 0$: $2g(x-a) = 2 \frac{\alpha k}{k-1} \theta_0 = 6 \propto \theta_0$

Röhrmanni komplettiere:

$$\begin{cases} \frac{\delta^2}{2} = \cancel{g x + m} - g x + m - \left(\alpha + \frac{\epsilon}{A}\right) \theta + \frac{4}{3} \frac{\gamma}{\theta} \theta \delta \frac{d\delta}{dx} \\ \frac{\epsilon}{A} \frac{1}{\theta} \frac{d\theta}{dx} + \frac{\alpha}{\delta} \frac{d\delta}{dx} = \frac{4}{3} \frac{\gamma}{\theta} \left(\frac{d\delta}{dx}\right)^2 \end{cases}$$

$$\frac{\delta_0^2}{2} = m - \left(\alpha + \frac{\epsilon}{A}\right) \theta_0 + \frac{4}{3} \frac{\gamma}{\theta_0} \theta_0 \left(\delta_0 \frac{d\delta_0}{dx}\right)_0$$

$$m = \cancel{\left(\alpha + \frac{\epsilon}{A}\right) \theta_0} + \frac{\delta_0^2}{2} - \frac{4}{3} \frac{\gamma}{\theta_0} \theta_0 \left(\delta_0 \frac{d\delta_0}{dx}\right)_0$$

$$g x - m = y$$

$$\begin{cases} \frac{\delta^2}{2} = -y - \left(\alpha + \frac{\epsilon}{A}\right) \theta + \frac{4}{3} \frac{\gamma}{\theta} \theta \delta \frac{d\delta}{dy} \\ \frac{\epsilon}{A} \frac{1}{\theta} \frac{d\theta}{dy} + \frac{\alpha}{\delta} \frac{d\delta}{dy} = \frac{4}{3} \frac{\gamma}{\theta} \left(\frac{d\delta}{dy}\right)^2 \end{cases}$$

Zaniedlungs- δ^2 :

$$\frac{4}{3} \frac{\gamma}{\theta} \theta \delta \frac{d\delta}{dy} = y + \left(\alpha + \frac{\epsilon}{A}\right) \theta$$

$$\frac{\epsilon}{A} \frac{1}{\theta} \frac{d\theta}{dy} \delta^2 + \alpha \frac{d\delta}{dy} = \frac{4}{3} \frac{\gamma}{\theta} \left(\frac{d\delta}{dy}\right)^2 \quad \left| \frac{4}{3} \frac{\gamma}{\theta} \right|$$

$$\frac{4}{3} \frac{\gamma}{\theta} \delta^2 = \frac{1}{\frac{\epsilon}{A} \frac{1}{\theta} \frac{d\theta}{dy}} \left[-\alpha \left(\frac{\gamma}{\theta} + \alpha + \frac{\epsilon}{A} \right) + \left(\frac{\gamma}{\theta} + \alpha + \frac{\epsilon}{A} \right)^2 \right]$$

$$= \left(\alpha + \frac{\epsilon}{A} + \frac{\gamma}{\theta} \right) \left(\frac{\gamma}{\theta} + \frac{\epsilon}{A} \right)$$

$$2 \left[\alpha + \frac{\epsilon}{A} + \frac{\gamma}{\theta} \right] = \frac{d}{dy} \left[\frac{\left(\alpha + \frac{\epsilon}{A} + \frac{\gamma}{\theta} \right) \left(\frac{\epsilon}{A} + \frac{\gamma}{\theta} \right)}{\frac{\epsilon}{A} \frac{1}{\theta} \frac{d\theta}{dy}} \right]$$

$$\frac{2c}{A\alpha} \left[1 + \frac{c}{A\alpha} + \frac{y}{\alpha\theta} \right] = \frac{d}{dy} \left[\frac{\left(1 + \frac{c}{A\alpha} + \frac{y}{\alpha\theta} \right) \left(\frac{c}{A\alpha} + \frac{y}{\alpha\theta} \right)}{\frac{1}{\theta} \frac{d\theta}{dy}} \right]$$

$$p_0 = 0.00018 \text{ (atm)}$$

$$\frac{c}{A\alpha} = \frac{1}{k-1}$$

$$\frac{2}{k-1} \left[\frac{k}{k-1} + \frac{y}{\alpha\theta} \right] = \frac{d}{dy} \left[\frac{\left(\frac{k}{k-1} + \frac{y}{\alpha\theta} \right) \left(\frac{1}{k-1} + \frac{y}{\alpha\theta} \right)}{\frac{1}{\theta} \frac{d\theta}{dy}} \right]$$

$$(k-1)y = e^2 \quad \left| \frac{(k-1)y}{\alpha\theta} = u \right.$$

$$\alpha\theta = \frac{1}{u} e^2$$

$$\log \theta = \log 2 - \log u$$

$$\frac{1}{\theta} \frac{d\theta}{dz} = 1 - \frac{1}{u} \frac{du}{dz} = \frac{1}{\theta} \frac{d\theta}{dy} \frac{dy}{dz}$$

$$= e^2 \frac{1}{\theta} \frac{d\theta}{dy}$$

$$2(k+u) = \frac{d}{d(e^2)} \left[\frac{(k+u)(1+u)}{\left(1 - \frac{1}{u} \frac{du}{dz} \right) e^{-2}} \right]$$

$$= e^{-2} \frac{d}{dz} \left[\frac{e^2 (k+u)(1+u)}{\left(1 - \frac{1}{u} \frac{du}{dz} \right)} \right]$$

$$(k+u)(1+u) = k + (1+k)u + u^2$$

$$2(k+u) = \frac{d}{dz} \left[\frac{(k+u)(1+u)}{1 - \frac{1}{u} \frac{du}{dz}} \right] + \frac{(k+u)(1+u)}{1 - \frac{1}{u} \frac{du}{dz}}$$

$$2(k+u) \left(1 - \frac{1}{u} \frac{du}{dz} \right)^2 = (k+u)(1+u) \frac{d}{dz} \left(\frac{1}{u} \frac{du}{dz} \right) + \left(1 - \frac{1}{u} \frac{du}{dz} \right) (1+k+2u) \frac{du}{dz}$$

$$+ \left(1 - \frac{1}{u} \frac{du}{dz} \right) (k+u)(1+u)$$

$$\frac{1}{u} \frac{du}{dz} = p$$

$$2(k+u)(1-p)^2 = (k+u)(1+u) \frac{dp}{dz} + p(1-p)(u+uk+2u^2) + (1-p)(k+u)(1+u)$$

$$(k+u)(1+u) \frac{dp}{dz} - p^2(u+ku+2u^2)$$

$$\frac{dp}{dz} = \frac{dp}{du} \frac{du}{dz} = \frac{dp}{du} \frac{1}{p}$$

$$2(k+u)p^2 = -(k+u)(1+u) \frac{dp}{dz} + p(1-p)(u+uk+2u^2) + p(k+u)(1+u)$$

$$p \frac{dp}{dz} + \frac{p^2}{u} \left(2 + \frac{u}{1+u} + \frac{u}{k+u} \right) - \frac{p}{u} \left(1 + \frac{u}{1+u} + \frac{u}{k+u} \right) = 0$$

$$= 2 - \frac{1}{1+u} - \frac{k}{k+u}$$

$$\frac{1}{p} \frac{dp}{dz} + \frac{1}{u} \left(2 + \frac{1}{1+u} - \frac{k}{k+u} \right) - \frac{1}{p} \frac{1}{u} \left(3 - \frac{1}{1+u} - \frac{k}{k+u} \right) = 0$$

$$\frac{1}{p} = q$$

$$q \frac{dq}{dz} + q \left(3 - \frac{1}{1+u} - \frac{k}{k+u} \right) - \frac{1}{u} \left(2 + \frac{1}{1+u} - \frac{k}{k+u} \right) = 0$$

$$2(k+u)(1+p)^2 = (k+u)(1+u)u p \frac{dp}{du} + p(1-p)(u+uk+2u^2) + (1-p)(k+u)(1+u)$$

Jaki $\frac{4}{3} \theta \frac{d\theta}{dx} = \frac{\alpha}{\theta}$ to mamy $\frac{d\theta}{dx} = 0$

i $\frac{4}{3} \theta \frac{d\theta}{dx} \theta = \alpha$ więc: $\frac{d\theta}{dx} \theta \neq \left(\theta + \frac{\alpha}{A} \right) \theta_0 - \frac{\alpha}{A} \theta$

więc różniczkując: $g = \frac{4}{3} \theta \frac{d}{dx} \left(\theta \frac{d\theta}{dx} \right) \Big|_{x=...}$

Gdy α większe niż $g = \left(\theta + \frac{\alpha}{A} \right) \theta_0 - \frac{\alpha}{A} \theta$

to $\frac{4}{3} \theta \frac{d\theta}{dx} > \frac{\alpha}{\theta}$ zatem $\frac{d\theta}{dx} > 0$!

$$(u^2 + 4u + 3k)$$

$$(k+u)(1+u)u p \frac{dp}{du} + p^2 [u+uk+2u^2 - 2k - 2u^2] + p [u+uk+2u^2 + 4k+4u - k - ku - k - u^2] + k+u+ku+u^2 - 2k - 2u$$

$$- p^2 [4u^2 - u(k+1) - 2k]$$

$$u^2 + ku - u - k$$

Tan glin $\frac{d\theta}{dx} = 0$:

$$\frac{4}{3} \theta \frac{d\theta}{dx} = \frac{\alpha}{\theta} \quad \text{wzyc:}$$

$$\left(\frac{\theta^2}{2}\right)' = -y - \left(\alpha + \frac{\epsilon}{A}\right)\theta + \alpha\theta = -y - \frac{\epsilon}{A}\theta$$

Zanieszmyc mnozimy θ $\theta' = -gx + m - \frac{\epsilon}{A}\theta$

$$gx = \left(\alpha + \frac{\epsilon}{A}\right)\theta_0 - \frac{\epsilon}{A}\theta$$

$$0 = -gx + \left(\alpha + \frac{\epsilon}{A}\right)(\theta_0 - \theta) + \frac{4}{3} \theta \frac{d\theta}{dx} \quad \text{I.}$$

$$\frac{\epsilon}{A} \frac{1}{\theta} \frac{d\theta}{dx} + \frac{\alpha}{\theta} \frac{d\theta}{dx} = \frac{4}{3} \theta \left(\frac{d\theta}{dx}\right)' \quad \text{II.}$$

Najpierw $\frac{d\theta}{dx} < 0$, zatem z II: $\frac{d\theta}{dx} > 0$

$$\left(\frac{4}{3} \theta \frac{d\theta}{dx}\right)' < \frac{\alpha}{\theta}$$

Gdy $gx = \left(\alpha + \frac{\epsilon}{A}\right)(\theta_0 - \theta)$ ale z I): θ wzgiz niektore anizeli jedyty $\frac{d\theta}{dx} > 0$
to z II): $\frac{d\theta}{dx} > 0$ [ktady on by nie stalo = 0 przy $gx = \left(\alpha + \frac{\epsilon}{A}\right)\theta_0$

Gdy $gx = \left(\alpha + \frac{\epsilon}{A}\right)(\theta_0 - \theta)$ tutaj jednak przy $gx = \left(\alpha + \frac{\epsilon}{A}\right)\theta_0$ mamy
to z I): $\frac{d\theta}{dx} = 0$ minimal

$$\text{I.} \quad \alpha + \frac{\epsilon}{A} = \frac{4}{3} \theta \frac{d\theta}{dx} \quad \text{z wyzej wyznaczonego:}$$

$$\left(\alpha + \frac{\epsilon}{A}\right) \frac{1}{\theta} \frac{d\theta}{dx} = \frac{4}{3} \theta \left(\frac{d\theta}{dx}\right)' = \frac{\alpha}{\theta} \frac{d\theta}{dx} + \frac{\epsilon}{A} \frac{1}{\theta} \frac{d\theta}{dx}$$

$$\text{wzyc} \quad \frac{1}{\theta} \frac{d\theta}{dx} = \frac{1}{\theta} \frac{d\theta}{dx} \quad \text{minimal}$$

wzyc $\theta = 0$?!

$$y \frac{dy}{dx} + y X_1 + X_2 = 0$$

$$\frac{1}{2} \frac{dz}{dx} + X_1 \sqrt{z} + \bar{X}_2 = 0$$

$$y^2 + \int y X_1 dx + \int X_2 dx = 0$$

$$y + \int X_1 dx + \int X_2 \frac{dx}{y} = 0$$

$$\begin{aligned} \frac{y^2}{2} + \int X_2 dx + y \int X_1 dx - \underbrace{\int dy \int X_1 dx}_{= - \int dx \int X_1 dx \left[X_1 + \frac{X_2}{y} \right]} \\ = + \int X_1 \int X_1 dx dx + \int \frac{X_2}{y} dx \int X_1 dx \end{aligned}$$

$$y = u + v$$

$$(u + v) \left(\frac{du}{dx} + \frac{dv}{dx} \right) + (u + v) X_1 + X_2 = 0$$

$$u \frac{du}{dx} + u \frac{dv}{dx} + v \frac{du}{dx} + v \frac{dv}{dx} + u X_1 + v X_1 + X_2 = 0$$

$$y = u + a$$

$$(y + a) \frac{dy}{dx} + (y + a) X_1 + X_2 = 0$$

$$y \frac{dy}{dx} + y X_1 + X_2 + a \left(\frac{dy}{dx} + X_1 \right) = 0$$

$$y_1 \frac{dy_1}{dx} + y_1 X_1 = 0$$

$$\frac{1}{2} \frac{d(y^2 - y_1^2)}{dx} + (y - y_1) X_1 + X_2 = 0$$

$$\frac{1}{2} \frac{d[(y - y_1)(y + y_1)]}{dx} + \uparrow$$

$$(y - y_1) \left[\frac{1}{2} \frac{d(y + y_1)}{dx} + X_1 \right] + \frac{1}{2} (y + y_1) \frac{d(y - y_1)}{dx} + X_2 = 0$$

$$(y - y_1) \frac{dy}{dx} + (y + y_1) \frac{d(y - y_1)}{dx} + 2X_2 = 0$$

$$y \frac{dy}{dx} - y_1 \frac{dy_1}{dx} + y_1 \frac{dy}{dx} + \cancel{y_1 \frac{dy_1}{dx}} + 2X_2 + y_1 X_1$$

$$2y \frac{dy}{dx} - y_1 \frac{dy_1}{dx} + y_1 X_1 + 2X_2 = 0$$

$$y_1 y \frac{dy}{dx} - y_1 y_1 \frac{dy_1}{dx} + X_2 = 0$$

$$y y_1 \frac{d(y - y_1)}{dx} + X_2 = 0$$

$$(y - y_1 + y_1) y_1 \frac{d(y - y_1)}{dx} + X_2 = 0$$

$$(y - y_1) \frac{d(y - y_1)}{dx} + y_1^2 \frac{d(y - y_1)}{dx} + X_2 = 0$$

$$u \frac{du}{dx} + y_1^2 \frac{du}{dx} + X_2 = 0$$

$$\frac{dy}{dx} + X_1' + \frac{1}{y} X_2' = 0$$

$$\frac{d^2y}{dx^2} + X_1' + \frac{X_2'}{y} - \frac{X_2}{y^2} \frac{dy}{dx} = 0$$

$$\frac{d^2y}{dx^2} + X_1' + \frac{X_2'}{y} + \frac{X_1 X_2}{y^2} + \frac{X_2^2}{y^3} = 0$$

$$y = \frac{-X_2}{\frac{dy}{dx} + X_1}$$

$$\frac{dy}{dx} = \frac{-X_2'}{\frac{dy}{dx} + X_1} + X_2 \frac{\frac{d^2y}{dx^2} + X_1'}{(\frac{dy}{dx} + X_1)^2}$$

$$\frac{dy}{dx} (\frac{dy}{dx} + X_1)^2 = -X_2' (\frac{dy}{dx} + X_1) + X_2 (\frac{d^2y}{dx^2} + X_1')$$

$$p (p + X_1)^2 = -X_2' (p + X_1) + X_2 (\frac{dp}{dx} + X_1')$$

$$\frac{dp}{dx} + f_1(x) p^3 + f_2(x) p^2 + f_3(x) p + f_4(x) = 0$$

Spherical symmetry:

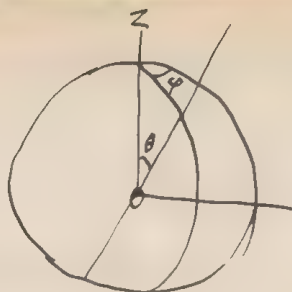
$$u = \frac{\partial \phi}{\partial r} = \frac{\partial \phi}{\partial r}$$

~~the~~

$$u = \frac{\partial \phi}{\partial r} \sin \theta \cos \varphi$$

$$v = \frac{\partial \phi}{\partial r} \sin \theta \sin \varphi$$

$$w = \frac{\partial \phi}{\partial r} \cos \theta$$



$$x = r \sin \theta \cos \varphi$$

$$y = r \sin \theta \sin \varphi$$

$$z = r \cos \theta$$

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$$\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = \frac{\partial}{\partial r} \left[\sin^2 \theta \cos \varphi + \sin^2 \theta \sin \varphi + \cos^2 \theta \right] \\ + \frac{\partial}{\partial \theta} \left[\cos^2 \theta \cos \varphi + \cos^2 \theta \sin \varphi + \sin^2 \theta \right] \\ + \frac{\partial}{\partial \varphi} \left[\frac{\sin^2 \theta \cos \varphi}{\cos \theta} + \frac{\sin^2 \theta \sin \varphi}{\sin \theta} \right]$$

$$= \frac{\partial \phi}{\partial r} + \frac{2\phi}{r}$$

$$\nabla^2 u = \frac{\partial^2 \phi}{\partial r^2} \sin \theta \cos \varphi + \frac{2}{r} \frac{\partial \phi}{\partial r} \sin \theta \cos \varphi - \frac{\phi \sin^2 \theta}{r^2 \sin^2 \theta} \cos \varphi + \frac{\phi \cos^2 \theta}{r^2 \sin^2 \theta} \cos \varphi$$

$$= \left[\frac{\partial^2 \phi}{\partial r^2} + \frac{2}{r} \frac{\partial \phi}{\partial r} - \frac{2\phi}{r^2} \right] \sin \theta \cos \varphi$$

$$\nabla^2 v = \left[\frac{\partial^2 \phi}{\partial r^2} + \frac{2}{r} \frac{\partial \phi}{\partial r} - \frac{2\phi}{r^2} \right] \sin \theta \sin \varphi$$

$$\left(\frac{\partial u}{\partial x}\right)^2 = \frac{\partial \phi}{\partial r} \sin^2 \theta \cos \varphi + \frac{\phi}{r} (\cos^2 \theta \sin^2 \varphi + \sin^2 \varphi)$$

$$= \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r}\right) \sin^2 \theta \cos \varphi + \frac{\phi}{r}$$

$$\frac{\partial u}{\partial y} = \frac{\partial \phi}{\partial r} \sin^2 \theta \sin \varphi \cos \varphi + \frac{\phi}{r} (\cos^2 \theta \sin \varphi \cos \varphi + \frac{\sin \varphi \cos \varphi}{\sin^2 \theta})$$

$$= \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r}\right) \sin^2 \theta \sin \varphi \cos \varphi$$

$$\frac{\partial u}{\partial z} = \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r}\right) \sin^2 \theta \cos \theta \cos \varphi$$

$$\frac{\partial v}{\partial x} = \frac{\partial \phi}{\partial r} \sin^2 \theta \sin \varphi \cos \varphi + \frac{\phi}{r} \cos^2 \theta \sin \varphi \cos \varphi - \frac{\phi \sin \varphi \cos \varphi}{r \sin^2 \theta}$$

$$= \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r}\right) \sin^2 \theta \sin \varphi \cos \varphi$$

$$\frac{\partial v}{\partial y} = \frac{\partial \phi}{\partial r} \sin^2 \theta \sin^2 \varphi + \frac{\phi}{r} (\cos^2 \theta \sin^2 \varphi + \sin^2 \varphi)$$

$$= \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r}\right) \sin^2 \theta \sin^2 \varphi + \frac{\phi}{r}$$

$$\frac{\partial v}{\partial z} = \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r}\right) \sin^2 \theta \cos \theta \sin \varphi$$

$$\frac{\partial w}{\partial x} = \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r}\right) \sin^2 \theta \cos \theta \sin \varphi$$

$$\frac{\partial w}{\partial y} = \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r}\right) \sin^2 \theta \cos \theta \sin \varphi$$

$$\frac{\partial w}{\partial z} = \frac{\partial \phi}{\partial r} \cos^2 \theta + \frac{\phi}{r} \sin^2 \theta = \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r}\right) \cos^2 \theta + \frac{\phi}{r}$$

~~$\frac{1}{2} \sin^2 \theta + \frac{1}{2} \sin^2 \theta$~~

$$2 \left[\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial y} \right)^2 + \left(\frac{\partial u}{\partial z} \right)^2 \right] = 2 \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right)^2 [\sin^4 \theta \cos^4 \varphi + \sin^4 \theta \sin^4 \varphi + \cos^4 \theta] +$$

$$4 \frac{\phi}{r} \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right) [\sin^2 \theta \cos^2 \varphi + \sin^2 \theta \sin^2 \varphi + \cos^2 \theta] + 6 \left(\frac{\phi}{r} \right)^2$$

$$\left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial z} \right)^2 = 4 \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right)^2 \sin^2 \theta \cos^2 \theta \sin^2 \varphi$$

$$\left(\frac{\partial u}{\partial z} + \frac{\partial v}{\partial x} \right)^2 = 4 \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right)^2 \sin^2 \theta \cos^2 \theta \cos^2 \varphi$$

$$\left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)^2 = 4 \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right)^2 \sin^4 \theta \sin^2 \varphi \cos^2 \varphi$$

$$= 2 \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right)^2 [\sin^4 \theta \cos^4 \varphi + \sin^4 \theta \sin^4 \varphi + \cos^4 \theta + \sin^2 \theta \cos^2 \theta +$$

$$+ \sin^4 \theta \sin^2 \varphi \cos^2 \varphi]$$

$$+ 4 \frac{\phi}{r} \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right) \left[\frac{1}{2} + 6 \left(\frac{\phi}{r} \right)^2 \right]$$

$$4 - 2 \sin^2 \theta + \sin^4 \theta$$

$$- \cos^2 \theta \sin^2 \varphi$$

$$\sin^2 \theta (\cos^2 \varphi - \cos^2 \varphi \sin^2 \theta + \sin^2 \theta \sin^2 \varphi - \sin^2 \theta \sin^2 \varphi \cos^2 \varphi) + \cos^2 \theta$$

$$1 - \cos^2 \theta$$

$$= \sin^4 \theta [1 - \sin^2 \varphi \cos^2 \varphi] = \sin^4 \theta [1 - \sin^2 \varphi + \sin^4 \varphi]$$

$$= 2 \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right)^2 [\sin^4 \theta \cos^4 \varphi + \sin^4 \theta \sin^4 \varphi + \cos^4 \theta + 2 \sin^2 \theta \cos^2 \theta + 2 \sin^4 \theta \sin^2 \varphi \cos^2 \varphi]$$

$$+ 4 \frac{\phi}{r} \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right) [\sin^2 \theta \cos^2 \varphi + \sin^2 \theta \sin^2 \varphi + \cos^2 \theta] + 6 \left(\frac{\phi}{r} \right)^2$$

$$\Phi = 2 \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right)^2 + 4 \frac{\phi}{r} \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right) + 6 \left(\frac{\phi}{r} \right)^2 - \frac{2}{3} \left(\frac{\partial \phi}{\partial r} + \frac{2\phi}{r} \right)^2 = \frac{4}{3} \left[\frac{d\phi}{dr} - \frac{\phi}{r} \right]^2$$

$$+v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z}$$

$$u \frac{\partial u}{\partial x} = - \frac{g a^2}{r^2} - \frac{1}{\rho} \frac{\partial p}{\partial x} + \frac{\mu}{3\rho} \frac{\partial}{\partial x} (\text{div}) + \frac{\mu}{\rho} \nabla^2 u$$

$$u \frac{\partial u}{\partial x} = - \frac{g a^2}{r^2} - \frac{1}{\rho} \frac{\partial p}{\partial x} + \frac{\mu}{3\rho} \frac{\partial}{\partial x} \dots$$

$$6 \frac{\partial \phi}{\partial r} \sin^2 \theta \cos \varphi = - \frac{g a^2}{r^2} \sin^2 \theta \cos \varphi - \frac{1}{\rho} \frac{\partial p}{\partial r} + \frac{\mu}{3\rho} \frac{\partial}{\partial r} \left[\frac{\partial \phi}{\partial r} + \frac{2\phi}{r} \right] + \frac{\mu}{\rho} \left[\frac{\partial^2 \phi}{\partial r^2} + \frac{2}{r} \frac{\partial \phi}{\partial r} - \frac{\phi}{r^2} \right]$$

$$6 \frac{\partial \phi}{\partial r} \sin \theta \sin \varphi = - \frac{g a^2}{r^2} \sin \theta \sin \varphi - \frac{1}{\rho} \frac{\partial p}{\partial r} + \frac{\mu}{3\rho} \frac{\partial}{\partial r} \left[\dots \right] + \frac{\mu}{\rho} \left[\dots \right]$$

$$6 \frac{\partial \phi}{\partial r} \sin^2 \theta \sin \varphi + u \frac{\partial u}{\partial x}$$

$$\begin{aligned} & 6 \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right) (\sin^2 \theta \cos^2 \varphi + \sin^2 \theta \sin^2 \varphi + \sin^2 \theta \cos \theta \sin \varphi) + \frac{g}{r} \sin^2 \theta \cos \varphi = \\ & = \left[6 \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right) + \frac{g}{r} \right] \sin^2 \theta \cos \varphi \end{aligned}$$

$$\left[6 \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right) + \frac{g}{r} \right] \sin^2 \theta \sin \varphi =$$

$$6 \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right) \sin^2 \theta \cos^2 \varphi + \sin^2 \theta \cos \theta \sin \varphi + \cos^2 \theta$$

$$\left[6 \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right) + \frac{g}{r} \right] \cos \theta =$$

$$\begin{aligned} \underbrace{\left[6 \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right) + \frac{g}{r} \right]}_{= 6 \frac{\partial \phi}{\partial r}} &= - \frac{g a^2}{r^2} - \frac{1}{\rho} \frac{\partial p}{\partial r} + \frac{\mu}{3\rho} \frac{\partial}{\partial r} \left[\frac{\partial \phi}{\partial r} + \frac{2\phi}{r} \right] + \frac{\mu}{\rho} \left[\frac{\partial^2 \phi}{\partial r^2} + \frac{2}{r} \frac{\partial \phi}{\partial r} - \frac{\phi}{r^2} \right] \\ &= \frac{\partial \phi}{\partial r^2} + \frac{2}{r} \frac{\partial \phi}{\partial r} - \frac{2\phi}{r^2} + 3 \frac{\partial^2 \phi}{\partial r^2} + \frac{6}{r} \frac{\partial \phi}{\partial r} - \frac{6\phi}{r^2} \end{aligned}$$

$$\begin{aligned} & 4 \frac{\partial^2 \phi}{\partial r^2} + \frac{8}{r} \frac{\partial \phi}{\partial r} - \frac{8\phi}{r^2} \\ &= \frac{4}{3} \frac{\partial}{\partial r} \left[\frac{\partial \phi}{\partial r} + \frac{2\phi}{r} \right] \end{aligned}$$

$$\delta \frac{\partial \phi}{\partial r} = -\frac{\partial a^2}{\partial r} - \frac{1}{r} \frac{\partial}{\partial r} + \frac{4\mu}{3r} \frac{\partial}{\partial r} \left[\frac{\partial \phi}{\partial r} + \frac{2\phi}{r} \right]$$

$$\frac{c}{A} \delta \frac{\partial \theta}{\partial r} + \left(\frac{\partial \phi}{\partial r} + \frac{2\phi}{r} \right) \mu = \frac{4\mu}{3} \left[\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right]^2 \bigg| r^2$$

$$r = a r \theta$$

$$\rho \delta r^2 = \rho \cdot \delta a^2 = b$$

$$\mu = \gamma \theta$$

$$\rho = \frac{b}{6r^2} \quad \bigg| \quad \mu = \frac{\theta}{6r^2}$$

$$\left. \begin{aligned} \delta \frac{\partial \phi}{\partial r} &= -\frac{\partial a^2}{\partial r} - \alpha \delta r^2 \frac{\partial}{\partial r} \left(\frac{\theta}{6r^2} \right) + \frac{4\mu \theta}{3b} \delta r^2 \frac{\partial}{\partial r} \left[\frac{\partial \phi}{\partial r} + \frac{2\phi}{r} \right] \\ \frac{c}{A} \frac{\partial \theta}{\partial r} + \alpha \frac{\theta}{6r^2} \left(\frac{\partial \phi}{\partial r} + \frac{2\phi}{r} \right) &= \frac{4\mu \theta}{3b} \left[\frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right]^2 \end{aligned} \right\}$$

$$\frac{\partial}{\partial r} \left[\delta r^2 \left(\frac{\partial \phi}{\partial r} + \frac{2\phi}{r} \right) \right] = \left[\frac{\partial \phi}{\partial r} + \frac{2\phi}{r} \right]^2 + \delta r^2 \left[\frac{\partial^2 \phi}{\partial r^2} + \frac{2}{r} \frac{\partial \phi}{\partial r} - \frac{2\phi}{r^2} \right]$$

$$\delta \mu_{xx} + \dots = -\frac{2}{3} \frac{\partial}{\partial x} (\mu \operatorname{div}) + \frac{\partial}{\partial y} \left[\mu \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right] + \frac{\partial}{\partial z} \left[\mu \left(\frac{\partial v}{\partial y} + \frac{\partial u}{\partial z} \right) \right]$$

$$+ 2 \frac{\partial}{\partial x} \left(\mu \frac{\partial u}{\partial x} \right)$$

$$= -\frac{2}{3} \frac{\partial \mu}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) - \frac{2}{3} \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial x \partial y} + \frac{\partial^2 w}{\partial x \partial z} \right) + \frac{\partial \mu}{\partial y} \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) +$$

$$+ \mu \left(\frac{\partial^2 v}{\partial x \partial y} + \frac{\partial^2 u}{\partial y^2} \right) + \frac{\partial \mu}{\partial z} \left(\frac{\partial u}{\partial y} + \frac{\partial w}{\partial z} \right) + \mu \left(\frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 w}{\partial y \partial z} \right) + 2 \frac{\partial \mu}{\partial x} \frac{\partial u}{\partial x} + 2 \mu \frac{\partial^2 u}{\partial x^2}$$

$$= \mu \left[-\frac{2}{3} \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial x \partial y} + \frac{\partial^2 w}{\partial x \partial z} \right) + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 v}{\partial x \partial y} + \frac{\partial^2 u}{\partial z^2} + \frac{\partial^2 w}{\partial x \partial z} + 2 \frac{\partial^2 u}{\partial x^2} \right]$$

$$+ \frac{\partial \mu}{\partial x} \left[-\frac{2}{3} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + 2 \frac{\partial u}{\partial x} \right] + \frac{\partial \mu}{\partial y} \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) + \frac{\partial \mu}{\partial z} \left(\frac{\partial v}{\partial y} + \frac{\partial u}{\partial z} \right)$$

$$= -\frac{2}{3} \frac{d}{dx} \left[\mu \left(\frac{dv}{dx} + \frac{dv}{dy} + \frac{dv}{dz} \right) \right] + \frac{d}{dx} \left(\mu \frac{dv}{dx} \right) + \frac{d}{dy} \left(\mu \frac{dv}{dy} \right) + \frac{d}{dz} \left(\mu \frac{dv}{dz} \right) + \frac{d}{dx} \left(\mu \frac{dv}{dx} \right) + \frac{d}{dy} \left(\mu \frac{dv}{dy} \right) + \frac{d}{dz} \left(\mu \frac{dv}{dz} \right)$$

$$-\frac{2}{3} \frac{\partial}{\partial x} \left[\mu \left(\frac{dv}{dr} + \frac{2v}{r} \right) \right] + 2 \frac{\partial}{\partial x} \left[\mu \left(\frac{dv}{dr} - \frac{v}{r} \right) \sin^2 \theta \cos \varphi + \frac{v}{r} \right] + 2 \frac{\partial}{\partial y} \left[\mu \left(\frac{dv}{dr} - \frac{v}{r} \right) \sin^2 \theta \sin \varphi + \frac{v}{r} \right] + 2 \frac{\partial}{\partial z} \left[\mu \left(\frac{dv}{dr} - \frac{v}{r} \right) \cos^2 \theta + \frac{v}{r} \right]$$

$$= -\frac{2}{3} \frac{d}{dr} \left[\mu \left(\frac{dv}{dr} + \frac{2v}{r} \right) \right] \sin^2 \theta \cos \varphi +$$

$$2 \frac{d}{dr} \left[\mu \left(\frac{dv}{dr} - \frac{v}{r} \right) \right] \left[\sin^3 \theta \cos^3 \varphi + \sin^3 \theta \sin^2 \varphi \cos \varphi + \sin^2 \theta \cos^2 \theta \cos \varphi \right] \sin \theta \cos \varphi$$

$$+ 2 \frac{d}{dr} \left(\mu \frac{v}{r} \right) \sin^2 \theta \cos \varphi$$

$$= \frac{d}{dr} \left[\mu \left(\frac{dv}{dr} + \frac{2v}{r} \right) + 2 \mu \left(\frac{dv}{dr} - \frac{v}{r} \right) + 2 \mu \frac{v}{r} \right] \sin^2 \theta \cos \varphi$$

$$= \frac{d}{dr} \left[\mu \left(-\frac{2}{3} \frac{dv}{dr} - \frac{4}{3} \frac{v}{r} + 2 \frac{dv}{dr} - \frac{2v}{r} + \frac{2v}{r} \right) \right]$$

$$= \frac{d}{dr} \left[\mu \left(\frac{4}{3} \left(\frac{dv}{dr} - \frac{v}{r} \right) \right) \right] = \frac{4}{3} \frac{d}{dr} \left[\mu \left(\frac{dv}{dr} - \frac{v}{r} \right) \right]$$

$$+ \frac{d}{dy} \left[\mu \left(\frac{dv}{dr} - \frac{v}{r} \right) \right] + \frac{d}{dz} \left[\mu \left(\frac{dv}{dr} - \frac{v}{r} \right) \right]$$

$$+ \frac{d}{dr} \left[-\frac{2}{3} \mu \frac{dv}{dr} + \frac{2}{3} \mu \frac{v}{r} \right]$$

$$+ \frac{d}{dr} \left[\mu \left(\frac{dv}{dr} - \frac{v}{r} \right) \right] + \frac{d}{dr} \left[\mu \left(\frac{dv}{dr} - \frac{v}{r} \right) \right]$$

$$= \frac{d}{dr} \left[\frac{4}{3} \mu \left(\frac{dv}{dr} - \frac{v}{r} \right) \right] + \frac{4}{3} \mu \left[\frac{dv}{dr} - \frac{v}{r} \right] = \frac{4}{3} \mu \left[\frac{d^2 v}{dr^2} - \frac{1}{r} \frac{dv}{dr} + \frac{v}{r^2} + \frac{3}{r} \frac{dv}{dr} - \frac{3v}{r^2} \right] = \frac{4}{3} \mu \left[\frac{d^2 v}{dr^2} + \frac{2}{r} \frac{dv}{dr} - \frac{2v}{r^2} \right]$$

$$\nabla^4 + \frac{d}{dr} (\text{div}) = \frac{d}{dr} \left(\frac{d\phi}{dr} \right) - \dots$$

$$2\theta \sin \varphi \left[\frac{d\phi}{dr} + \frac{2}{r} \frac{d\phi}{dr} - \frac{2\phi}{r^2} + \frac{d}{dr} \left(\frac{d\phi}{dr} + \frac{2\phi}{r} \right) \right]$$

$$\frac{d\phi}{dr} + \frac{2}{r} \frac{d\phi}{dr} - \frac{2\phi}{r^2}$$

$$\nabla^2 u = \frac{\partial}{\partial x} \frac{\partial u}{\partial x} + \frac{\partial}{\partial y} \frac{\partial u}{\partial y} + \frac{\partial}{\partial z} \frac{\partial u}{\partial z}$$

$$= \frac{d}{dr} \left(\frac{d\phi}{dr} - \frac{\phi}{r} \right) \sin^3 \theta \sin^2 \varphi + \frac{d}{dr} \left(\frac{\phi}{r} \right) 2\theta \sin \varphi$$

$$+ \dots \sin^3 \theta \sin^2 \varphi \sin \theta \sin^2 \varphi$$

$$= 2\theta \sin \varphi \left[\frac{d}{dr} \left(\frac{d\phi}{dr} - \frac{\phi}{r} \right) + \frac{d}{dr} \left(\frac{\phi}{r} \right) \right]$$

$$= 2\theta \sin \varphi \frac{d\phi}{dr}$$

~~ds = r dr~~

$$= \frac{d}{dx} \left[-\frac{2}{3} \mu \left(\frac{d\phi}{dr} + \frac{2\phi}{r} \right) \right] + 2 \left[\frac{d}{dx} \left(\mu \frac{d\phi}{dr} \right) + \frac{d}{dy} \left(\mu \frac{d\phi}{dr} \right) + \dots \frac{d}{dz} \left(\mu \frac{d\phi}{dr} \right) \right]$$

$$+ 2\mu \frac{\phi}{r}$$

$$\frac{d}{dr} \left[\mu \left(\frac{d\phi}{dr} - \frac{\phi}{r} \right) \right] \sin^3 \theta \sin^2 \varphi + \mu \left(\frac{d\phi}{dr} - \frac{\phi}{r} \right) \frac{2\sin^2 \theta \sin^2 \varphi + 2\sin \theta \sin \varphi \sin^2 \varphi}{r}$$

$$\frac{\sin^3 \theta \sin^2 \varphi}{\sin^3 \theta \sin^2 \varphi}$$

$$2\sin \theta \sin^2 \varphi \sin^2 \varphi \sin \varphi + \sin^3 \theta \sin^2 \varphi - 2\sin \theta \sin^2 \varphi$$

$$- \sin \theta \sin \varphi (\sin^2 \theta - \sin^2 \theta)$$

$$= 2\sin \theta \left[2\sin^2 \varphi + \sin \varphi \sin^2 \theta \sin^2 \varphi + \sin^3 \theta \sin^2 \varphi \right]$$

$$= 2\sin \theta \sin \varphi \sin^2 \varphi$$

$$6 \frac{d\delta}{dr} = -\frac{g a^2}{r^2} - \alpha 6 r^2 \frac{d}{dr} \left(\frac{\theta}{6 r^2} \right) + \frac{4 \mu \theta}{3 b} 6 r^2 \left[\frac{d}{dr} \left(\frac{d\delta}{dr} + \frac{2\delta}{r} \right) + \right. \\ \left. + \frac{4 \mu}{3 b} 6 r^2 \left[\frac{d\delta}{dr} - \frac{\delta}{r} \right] \frac{d\theta}{dr} \right]$$

$$\frac{c}{A} \frac{d\theta}{dr} + \frac{\alpha \theta}{6} \left[\frac{d\delta}{dr} + \frac{2\delta}{r} \right] = \frac{4 \mu \theta}{3 b} r^2 \left[\frac{d\delta}{dr} - \frac{\delta}{r} \right]^2$$

$$\frac{d\delta}{dr} \theta = -\frac{g a^2}{r^2} - \alpha \frac{d\theta}{dr} + \frac{\alpha \theta}{6} \left[\frac{d\delta}{dr} + \frac{2\delta}{r} \right] + \frac{4 \mu \theta}{3 b} \dots = \frac{d}{dr} \left(\frac{\delta}{r} - \frac{\delta}{r} \right) + \frac{3}{r} \left(\frac{d\delta}{dr} - \frac{\delta}{r} \right)$$

$$6 \frac{d\delta}{dr} = -\frac{g a^2}{r^2} - \left(\alpha + \frac{c}{A} \right) \frac{d\theta}{dr} + \frac{4 \mu}{3 b} \left\{ \theta 6 r^2 \frac{d}{dr} \left[\frac{d\delta}{dr} + \frac{2\delta}{r} \right] + 6 \frac{d\theta}{dr} r^2 \left[\frac{d\delta}{dr} - \frac{\delta}{r} \right] \right. \\ \left. + r^2 \theta \left[\frac{d\delta}{dr} - \frac{\delta}{r} \right]^2 \right\}$$

$$\theta \left[r^2 6 \frac{d\delta}{dr} + 2 r \delta \frac{d\theta}{dr} - 2 \delta^2 + r^2 \left(\frac{d\delta}{dr} \right)^2 + 6^2 - 2 6 r \frac{d\delta}{dr} \right] \\ = \theta \left[r^2 6 \frac{d\delta}{dr} + r^2 \left(\frac{d\delta}{dr} \right)^2 - 6^2 \right]$$

$$= \frac{d}{dr} \left[6 r^2 \left(\frac{d\delta}{dr} - \frac{\delta}{r} \right) \right] = \left(\frac{d\delta}{dr} \right)^2 r^2 - 6 r \frac{d\delta}{dr} + 2 r \delta \frac{d\theta}{dr} - 2 \delta^2 + 6 r^2 \frac{d\delta}{dr} - 6 r \frac{d\delta}{dr} + 6^2$$

$$\begin{cases} 6 \frac{d\delta}{dr} = -\frac{g a^2}{r^2} - \left(\alpha + \frac{c}{A} \right) \frac{d\theta}{dr} + \frac{4 \mu}{3 b} \frac{d}{dr} \left[\theta 6 r^2 \left(\frac{d\delta}{dr} - \frac{\delta}{r} \right) \right] & \text{Ia} \\ \frac{c}{A} \frac{d\theta}{dr} + \frac{\alpha \theta}{6} \left[\frac{d\delta}{dr} + \frac{2\delta}{r} \right] = \frac{4 \mu}{3 b} \theta r^2 \left[\frac{d\delta}{dr} - \frac{\delta}{r} \right]^2 & \text{IIa} \end{cases}$$

$$\frac{d\delta}{dr} - \frac{\delta}{r} = r \frac{d}{dr} \left(\frac{\delta}{r} \right) = r \frac{d}{dr} \left(\frac{\delta r^2}{r^3} \right)$$

$$\frac{d\delta}{dr} + \frac{2\delta}{r} = \frac{1}{r^2} \frac{d}{dr} (6 r^2)$$

$6r^2 = 2r$

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$$\frac{\sigma^2}{2} = \frac{ga^2}{r} + m - \left(\alpha + \frac{c}{A}\right) \theta + \frac{4\mu}{3b} \theta \sigma r^2 \left(\frac{d\sigma}{dr} - \frac{\sigma}{r}\right) \quad I_b$$

$$\frac{c}{A} \frac{d\theta}{dr} + \frac{\alpha \theta}{\sigma} \left[\frac{d\sigma}{dr} + \frac{2\sigma}{r} \right] = \frac{4\mu}{3b} \theta r^2 \left(\frac{d\sigma}{dr} - \frac{\sigma}{r} \right)^2 \quad II_b$$

$$6r^2 = 2 = \frac{b}{\rho}$$

$$\frac{1}{2} \frac{r^2}{r^4} = \frac{ga^2}{r} + m - \left(\alpha + \frac{c}{A}\right) \theta + \frac{4\mu}{3b} \theta r^2 \frac{d}{dr} \left(\frac{2}{r^3} \right) \quad I_c$$

$$\frac{c}{A} \frac{d\theta}{dr} + \frac{\alpha \theta}{2} \frac{dr}{dr} = \frac{4\mu}{3b} \theta r^4 \left[\frac{d}{dr} \left(\frac{2}{r^3} \right) \right]^2 \quad II_c$$

$$\frac{\sigma}{r} = u$$

$$\frac{u^2 r^2}{2} = \frac{ga^2}{r} + m - \left(\alpha + \frac{c}{A}\right) \theta + \frac{4\mu}{3b} \theta r^4 u \frac{du}{dr} \quad I_d$$

$$\frac{c}{A} \frac{d\theta}{dr} + \frac{\alpha \theta}{u r^3} \frac{d}{dr} (u r^3) = \frac{4\mu}{3b} \theta r^4 \left(\frac{du}{dr} \right)^2 \quad II_d$$

tedy $\frac{d\theta}{dr} > 0$ musí být:

$$\frac{3\alpha\theta}{u r} + \frac{\alpha\theta}{u} \frac{du}{dr} \geq \frac{4\mu}{3b} \theta r^4 \left(\frac{du}{dr} \right)^2$$

$$\frac{4\mu\alpha}{3b} \frac{u^2}{r} + \frac{4\mu\alpha}{3b} u \frac{du}{dr} \geq \left(\frac{4\mu}{3b} \right)^2 r^4 u^2 \left(\frac{du}{dr} \right)^2$$

$$\left(\frac{4\mu}{3b} \right)^2 r^4 u \frac{du}{dr} \geq \frac{\alpha}{2} + \sqrt{\frac{\alpha^2}{4} + \frac{4\mu\alpha}{b} u^2 r^3}$$

$$\left. \begin{aligned} \frac{ga^2}{r^2} + \frac{m}{r} - \left(\alpha + \frac{c}{A}\right) \frac{\theta}{r} + \frac{4\mu}{3b} \theta r^2 \left(\frac{d\sigma}{dr} - \frac{\sigma}{r} \right) \frac{\sigma}{r} &= 0 \\ \left[\frac{ga^2}{r^2} + \frac{m}{r} - \left(\alpha + \frac{c}{A}\right) \frac{\theta}{r} \right] \frac{d\sigma}{dr} + \frac{4\mu}{3b} \theta r^2 \left(\frac{d\sigma}{dr} - \frac{\sigma}{r} \right) \frac{\sigma}{r} &= 0 \end{aligned} \right\}$$

$$\frac{4}{3} \frac{1}{b} \theta r^2 \left(\frac{d\theta}{dr} - \frac{\theta}{r} \right) = \frac{d\theta}{dr} \left[\frac{g a^2}{r^2} + \frac{m}{\theta} - \left(\alpha + \frac{c}{A} \right) \frac{\theta}{\delta} \right] - \frac{g a^2}{r^2} - \frac{m}{\theta} + \left(\alpha + \frac{c}{A} \right) \frac{\theta}{r}$$

$$= \frac{c}{A} \frac{d\theta}{dr} + \frac{\alpha \theta}{\delta} \left(\frac{d\delta}{dr} + \frac{2\delta}{r} \right)$$

$$\frac{d\theta}{dr} \left[\frac{g a^2}{r^2} + \frac{m}{\theta} \right] - \left[\frac{g a^2}{r^2} + \frac{m}{\theta} \right] + \left(\frac{c}{A} - \alpha \right) \frac{\theta}{r} - \left(\frac{c}{A} + 2\alpha \right) \frac{\theta}{\delta} \frac{d\delta}{dr} = \frac{c}{A} \frac{d\theta}{dr}$$

$$\frac{1}{\theta} \left(\frac{g a^2}{r^2} + m \right) \left(\frac{d\delta}{dr} - \frac{\delta}{r} \right) - \frac{\theta}{\delta} \left(\frac{c}{A} + 2\alpha \right) \left(\frac{d\delta}{dr} - \frac{\delta}{r} \right) - \frac{3\alpha \theta}{r}$$

$$\frac{1}{\theta} \left(\frac{d\delta}{dr} - \frac{\delta}{r} \right) \left[\frac{g a^2}{r^2} + m - \left(\frac{c}{A} + 2\alpha \right) \theta \right] = \frac{3\alpha \theta}{r} + \frac{c}{A} \frac{d\theta}{dr}$$

$$\left[\frac{g a^2}{r^2} - g a^2 + \left(\alpha + \frac{c}{A} \right) \theta - \left(\alpha + \frac{c}{A} \right) \theta - \alpha \theta \right] = \left[g a^2 \left(\frac{a}{r} - 1 \right) + \left(\alpha + \frac{c}{A} \right) (\theta - \theta) - \alpha \theta \right]$$

$$I.b): \quad \frac{\delta^2}{2} = g a + m \theta - \left(\alpha + \frac{c}{A} \right) \theta + \frac{4}{3} \frac{1}{b} \theta \cdot \delta \cdot a^2 \left(\frac{d\delta}{dr} - \frac{\delta}{r} \right)$$

$$\frac{\delta^2 - \delta_0^2}{2} = g a \underbrace{\left(\frac{a}{r} - 1 \right)}_{<0} - \underbrace{\left(\alpha + \frac{c}{A} \right) (\theta - \theta_0)}_{>0} + \underbrace{\frac{4}{3} \frac{1}{b} \theta \delta a^2 \left(\frac{d\delta}{dr} - \frac{\delta}{r} \right)}_{\varepsilon}$$

$$\frac{4}{3} \frac{1}{b} \left\{ \frac{c}{A} \frac{d\theta}{dr} \frac{1}{\theta} + \frac{\alpha}{\delta} \left[\frac{d\delta}{dr} + \frac{2\delta}{r} \right] \right\} = \left[\frac{4}{3} \frac{1}{b} r \left(\frac{d\delta}{dr} - \frac{\delta}{r} \right) \right]^2$$

$$= \frac{1}{(\theta \delta r)^2} \left[\frac{g a^2}{r^2} + m - \left(\alpha + \frac{c}{A} \right) \theta \right]^2$$

$$\frac{4}{3} \frac{1}{b} \left\{ \frac{c}{A} \frac{d\theta}{dr} \frac{1}{\theta} + \frac{\alpha}{\delta} \frac{d\delta}{dr} + \frac{2\alpha}{r} \right\} = \uparrow$$

$$\frac{4}{3} \frac{1}{b} \frac{d\delta}{dr} = \frac{4}{3} \frac{1}{b} \frac{\delta}{r} - \frac{1}{\theta \delta r^2} \left[\frac{g a^2}{r^2} + m - \left(\alpha + \frac{c}{A} \right) \theta \right]$$

$$\frac{4}{3} \frac{1}{b} \left\{ \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dr} + \frac{\alpha}{r} + \frac{2\alpha}{r} \right\} = \frac{\alpha}{\theta \delta r^2} \left[\quad \right] + \frac{1}{(\theta \delta r)^2} \left[\quad \right]^2$$

Jaka będzie wartość $\left(\frac{d\phi}{dr} - \frac{c}{r}\right)_{r=a}$?

W przybliżeniu:

$$\frac{c}{A} \log \theta + \alpha (\log b + \log r) = \text{const}$$

$$\theta^{\frac{c}{A}} (br)^{\alpha} = \text{const} = \theta_0^{\frac{c}{A}} \left(\frac{b}{r_0}\right)^{\alpha}$$

$$\frac{g r^2}{r} + m = \left(\alpha + \frac{c}{A}\right) \theta$$

$$\underline{g a + m = \left(\alpha + \frac{c}{A}\right) \theta_0}$$

$$\left(\frac{d\theta}{dr}\right)_0 = - \frac{g}{\left(\alpha + \frac{c}{A}\right) \theta_0}$$

$$\underline{g a \left(\frac{a}{r} - 1\right) = \left(\alpha + \frac{c}{A}\right) (\theta - \theta_0)}$$

$$\frac{2\alpha\theta}{r} + \frac{\alpha\theta}{b} \frac{db}{dr} - \frac{\frac{c}{A} g}{\alpha + \frac{c}{A}} = 0$$

$$\frac{\alpha\theta_0}{b} \frac{db}{dr} = \frac{g}{1 + \frac{\alpha A}{c}} - \frac{2\alpha\theta_0}{a}$$

$$\begin{aligned} \left(\frac{db}{dr} - \frac{b}{r}\right)_0 &= \frac{b}{\alpha\theta_0} \left[\frac{g}{1 + \frac{\alpha A}{c}} - \frac{2\alpha\theta_0}{a} - \frac{\alpha\theta_0}{a} \right] \\ &= b \left[\frac{g}{\underbrace{\alpha\theta_0 \left(1 + \frac{\alpha A}{c}\right)}_{=r}} - \frac{3}{a} \right] \end{aligned}$$

$$\frac{9.8}{1.4 \cdot 270 \cdot 290} - \frac{3}{6,366 \cdot 200} \gg 0$$

$$\left(\frac{db}{dr}\right)_0 > \left(\frac{b}{r}\right)_0$$

$$\left(\frac{1}{b} \frac{db}{dr}\right)_0 > \left(\frac{1}{r}\right)_0$$

$$\left(\frac{d \log b}{dr}\right)_0 > \left(\frac{1}{r}\right)_0$$

Opowiadanie zmienia się z czasem

Jednak $\frac{d\theta}{dr}$ stanie się $= \frac{6}{r}$ to:

$$\frac{ga^2}{r} + m - (\alpha + \frac{\epsilon}{A})\theta = 0$$

$$ga(\frac{a}{r} - 1) - (\alpha + \frac{\epsilon}{A})(\theta - \theta_0) = 0$$

$$\frac{\epsilon}{A} \frac{d\theta}{dr} + \frac{3\alpha}{r} = 0$$

$$ga(1 - \frac{a}{r}) = (\alpha + \frac{\epsilon}{A})(\theta - \theta_0)$$

Wszystko ok, a musi być by' wreszcie zmieniła się wartość $\frac{d\theta}{dr}$ i stanie się $= 0$ to musi istnieć punkt gdzie:

$$\frac{\alpha}{\theta} \left(\frac{d\theta}{dr} + \frac{2\theta}{r} \right) = \frac{4\mu}{3b} r^2 \left(\frac{d\theta}{dr} - \frac{6}{r} \right)^2$$

Tam gdzie $\frac{d\theta}{dr} = 0$!

Czy ten punkt będzie osiągnięty?

$$\frac{d\theta}{dr} > \frac{6}{r}$$

$$\frac{\alpha}{\theta} \frac{d\theta}{dr} + \frac{2\alpha}{r} \geq \frac{4\mu}{3b} r^2 \left(\frac{d\theta}{dr} - \frac{6}{r} \right)^2$$

$$\theta^2 = s$$

$$\frac{\alpha}{2} \frac{ds}{dr} + \frac{2\alpha s}{r} \geq \frac{4\mu}{3b} r^2 \left[\frac{1}{2} \left(\frac{ds}{dr} \right) - \frac{6}{r} \right]^2$$

$$\frac{\alpha}{2} s \frac{ds}{dr} + \frac{2\alpha s^2}{r} \geq \frac{4\mu}{3b} \left[\frac{1}{4} r^2 \left(\frac{ds}{dr} \right)^2 - r s \frac{ds}{dr} + s^2 \right]$$

$$0 \geq \frac{4\mu}{3b} \left[\frac{r^2}{4} \left(\frac{ds}{dr} \right)^2 \right] - s \frac{ds}{dr} \left[\frac{4\mu r}{3b} + \frac{\alpha}{2} \right] + s^2 \left[\frac{4\mu}{3b} - \frac{2\alpha}{r} \right]$$

$$0 \geq \frac{4\mu}{3b} \frac{1}{4} \left(r \frac{ds}{dr} \right)^2 - r \frac{ds}{dr} s \left[\frac{4\mu}{3b} + \frac{\alpha}{2r} \right] + s^2 \left[\frac{4\mu}{3b} - \frac{2\alpha}{r} \right]$$

$$0 \geq \left(\frac{r}{2} \frac{ds}{dr} \right)^2 - 2 \left(\frac{r}{2} \frac{ds}{dr} \right) s \left(1 + \frac{3b}{4\mu} \frac{\alpha}{2r} \right) + s^2 \left(1 - \frac{3b}{4\mu} \frac{2\alpha}{r} \right)$$

$$\left[\frac{r}{2} \frac{ds}{dr} - s \left(1 + \frac{3b}{4f} \frac{\alpha}{2r} \right) \right]^2 \leq s^2 \left[\left(\frac{3b}{4f} \frac{\alpha}{2r} + \left(\frac{3b}{4f} \frac{\alpha}{2r} \right)^2 + \frac{3b}{4f} \frac{2\alpha}{r} \right) \right]$$

$$s^2 \frac{3b}{4f} \frac{\alpha}{r} \left(3 + \frac{3b}{4f} \frac{\alpha}{4r} \right)$$

$$2 \frac{\alpha}{r} \left[\left[s + \frac{1}{8} \frac{ds}{dr} \right]^2 - \frac{1}{64} \left(\frac{ds}{dr} \right)^2 \right] \geq \frac{4f}{3b} \left[\frac{r}{2} \frac{ds}{dr} - s \right]^2$$

Jeżeli $\frac{ds}{dr}$ może być dowolnie małe, wtedy w trójkącie musi być punkt osiągnięty

W przeciwnym przypadku (?) $\frac{d\theta}{dr}$ może być < 0

$$\frac{ds}{dr} > \frac{6}{r}$$

~~zatem mógłby być punkt gdzie $\theta = 0$~~

$$(\theta_0 - \theta) \left(\alpha + \frac{c}{r} \right) = + g^2 \left(1 - \frac{a}{r} \right) - \frac{4f}{3b} \theta b r^2 \left(\frac{1}{r} - \frac{1}{r_0} \right)$$

Wzrost mógłby być punktem gdzie $\theta = 0$ jeżeli 1) b i $\frac{ds}{dr}$ stałymi a $\frac{d\theta}{dr} = 0$
2).

1) wymagaloby więcej danych: $b \frac{ds}{dr} = -g \frac{a^2}{r^2}$! co nie ma sensu bo

właściwie rozwiązanie było że $\frac{ds}{dr} > \frac{6}{r}$

$$-\frac{2a}{r}$$

$$-\frac{2a}{r}$$

$$-\frac{2a}{r}$$

$$\frac{c}{A} \frac{d\theta}{dr} + \frac{3\alpha}{r} + \frac{\alpha}{\theta} \left[\frac{d\theta}{dr} - \frac{\theta}{r} \right] = \frac{4\mu}{3b} r^2 \left[\frac{d\theta}{dr} - \frac{\theta}{r} \right]^2$$

$$\frac{4\mu}{3b} r^2 \left[\frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dr} + \frac{3\alpha}{r} \right] = \frac{1}{\theta^2} \left[\frac{g a^2}{r} + m - \left(\alpha + \frac{c}{A} \right) \theta \right] + \left\{ \frac{1}{\theta^2} \left[\frac{g a^2}{r} + m - \left(\alpha + \frac{c}{A} \right) \theta \right] \right\}^2$$

$$\frac{4\mu}{3b} \theta^2 = \frac{\frac{1}{\theta} \left[\frac{g a^2}{r} + m - \left(\alpha + \frac{c}{A} \right) \theta \right] + \frac{1}{\theta^2} \left[\frac{g a^2}{r} + m - \left(\alpha + \frac{c}{A} \right) \theta \right]^2}{\frac{4\mu}{3b} r^2 \left[\frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dr} + \frac{3\alpha}{r} \right]}$$

$$\left[\underbrace{\frac{g a^2}{r} + m - \left(\alpha + \frac{c}{A} \right) \theta}_v + r^2 \theta \left[\frac{1}{2} \frac{d}{dr} \left\{ \frac{\frac{\alpha}{\theta} \left[\frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dr} + \frac{3\alpha}{r} \right]^2}{r^2 \left[\frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dr} + \frac{3\alpha}{r} \right]} \right\} - \frac{1}{r} \frac{\frac{\alpha}{\theta} \left[\frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dr} + \frac{3\alpha}{r} \right]^2}{r^2 \left[\frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dr} + \frac{3\alpha}{r} \right]} \right] \right]$$

$$0 = v + \frac{r^2 \theta}{2} \frac{d}{dr} \left\{ \frac{\frac{1}{2} v + \frac{1}{\theta} v^2}{r^2 \left[\frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dr} + \frac{3\alpha}{r} \right]} \right\} - \frac{\theta \cdot \frac{1}{2} v + \frac{1}{\theta} v^2}{r^2 \left(\frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dr} + \frac{3\alpha}{r} \right)}$$

$$Id: \quad 0 = \frac{g a^2}{r} + m - \left(\alpha + \frac{c}{A} \right) \theta + \frac{4\mu}{3b} \theta r^4 u \frac{du}{dr} \quad \left| \frac{du}{dr} \right.$$

$$\frac{c}{A} \frac{d\theta}{dr} + \frac{3\alpha\theta}{r} + \frac{\alpha\theta}{u} \frac{du}{dr} = \frac{4\mu}{3b} \theta r^4 \left(\frac{du}{dr} \right)^2 \quad \left| u \right.$$

$$\frac{c}{A} \frac{d\theta}{dr} + \frac{3\alpha\theta}{r} = \frac{c}{A r} \left[r \frac{d\theta}{dr} + \frac{3\alpha}{\theta} \theta \right]$$

$$= \frac{c}{A} \frac{d}{dr} \left(\theta r^{\frac{3\alpha}{A}} \right) \cdot \frac{1}{r^{\frac{3\alpha}{A}}}$$

$$\frac{c}{A} u \frac{d\theta}{dr} + \frac{3\alpha\theta u}{r} = + \frac{c}{A} \theta \frac{du}{dr} - m \frac{du}{dr} - \frac{g a^2}{r} \frac{du}{dr}$$

$$\frac{c}{A} \frac{d}{dr} \left(\frac{\theta}{u} \right) + \frac{3\alpha}{r} \frac{\theta}{u} = - \frac{1}{u} \frac{d\theta}{dr} (m + \frac{g a^2}{r}) \frac{d(u)}{dr} = 0$$

$$0 = v + \frac{4\gamma}{3b} \theta \frac{r^4}{2} \frac{dv}{dr}$$

$$\frac{4\gamma}{3b} \frac{r^2}{2} \frac{dv}{dr} = - \frac{v}{\theta r^2}$$

$$u^2 \left[\frac{\epsilon}{A} \frac{d\theta}{dr} + \frac{3\alpha\theta}{2} \right] + \frac{\alpha\theta}{2} \frac{d(u^2)}{dr} = \frac{4\gamma}{3b} \frac{\theta r^4}{4} \left[\frac{d(u^2)}{dr} \right]^2$$

$$\frac{4\gamma}{3b} u^2 = \frac{1}{\frac{\epsilon}{A} \frac{d\theta}{dr} + \frac{3\alpha\theta}{2}} \left(+ \frac{v^2}{\theta r^4} + \frac{\alpha v}{r^4} \right)$$

$$0 = v + \frac{\theta r^4}{2} \frac{d}{dr} \left\{ \frac{\frac{v^2}{\theta} + \alpha v}{r^4 \left[\frac{\epsilon}{A} \frac{d\theta}{dr} + \frac{3\alpha}{2} \right]} \right\} \quad \text{to same factor}$$

$$\underbrace{\frac{g a^2}{r\theta} + \frac{m}{\theta} - (\alpha + \frac{\epsilon}{A})}_{w} + \frac{r^4}{2} \frac{d}{dr} \left\{ \frac{\left[\frac{g a^2}{r\theta} + \frac{m}{\theta} - (\alpha + \frac{\epsilon}{A}) \right]^2 + \alpha \left[\right]}{r^4 \left[\frac{\epsilon}{A} \frac{1}{\theta} \frac{d\theta}{dr} + \frac{3\alpha}{2} \right]} \right\}$$

$$\frac{1}{r^3} = z$$

$$-\frac{3}{2} dz = dz$$

$$\frac{d\theta}{dr} = -\frac{3}{r^3} \frac{d\theta}{dz}$$

$$2w = \frac{3}{2} \frac{d}{dz} \left\{ \frac{w^2 + w\alpha}{-3\frac{\epsilon}{A} \frac{1}{\theta} \frac{d\theta}{dz} + \frac{3\alpha}{2}} \right\} = \frac{d}{dz} \left\{ \frac{w^2 + w\alpha}{\frac{\alpha}{2} - \frac{\epsilon}{A} \frac{1}{\theta} \frac{d\theta}{dz}} \right\}$$

$$= \frac{d}{dz} \log \left(\frac{\alpha}{2} \theta \frac{\tilde{A}}{\tilde{A}} \right)$$

$$\frac{1}{2} = t \quad \frac{g a^2 t + m}{a} = y \quad \frac{dt}{dz} = -dt$$

$$\frac{y}{\theta} - \frac{k}{k-1} t - \frac{1}{2t^2} \frac{d}{dt} \left\{ \frac{\left(\frac{y}{\theta} - \frac{k}{k-1} \right)^2 + \left(\frac{y}{\theta} - \frac{k}{k-1} \right)}{\frac{3}{t^3} - \frac{1}{k-1} \frac{1}{\theta t^2} \frac{d\theta}{dt}} \right\}$$

$$\frac{1}{\theta} \left(\frac{g a^2}{r^2} + m \right) = w + \alpha + \frac{\epsilon}{A} \quad \frac{1}{\theta} \frac{d\theta}{dz} = \frac{-\frac{g a^2}{r^2} \frac{dz}{dz}}{\frac{g a^2}{r^2} + m} - \frac{\frac{d\epsilon}{dz}}{w + \alpha + \frac{\epsilon}{A}}$$

$$\log \left(\frac{g a^2}{r^2} + m \right) - \log \theta = \log \left(w + \alpha + \frac{\epsilon}{A} \right)$$

Uwzględnając warunki trybu 5 I:

$$\frac{c}{A} \frac{dA}{dr} + \frac{\alpha}{b} \frac{db}{dr} + \frac{2\alpha}{r} = 0$$

$$\log \left(\theta \frac{c}{A} b^{\alpha} r^{2\alpha} \right) = \text{const}$$

$$\left[\frac{\theta}{\theta_0} \right]^{\frac{c}{A\alpha}} \left(\frac{b}{b_0} \right) \left(\frac{r}{a} \right)^2 = 1$$

$$0 = -\frac{ga^2}{r^2} - \underbrace{\frac{a}{b} \frac{db}{dr} + \frac{2a}{r} + \frac{\alpha}{b} \frac{db}{dr}}_{-(\alpha + \frac{c}{A}) \frac{db}{dr}} + \frac{4\mu}{3b} 6r^2 \left[\theta \frac{d}{dr} \left(\frac{db}{dr} + \frac{2b}{r} \right) + \frac{d\theta}{dr} \left(\frac{db}{dr} - \frac{b}{r} \right) \right]$$

$$\frac{c}{A\alpha} = \frac{1}{k-1}$$

$$\frac{\theta}{\theta_0} \left(\frac{6r^2}{b_0 a^2} \right)^{\frac{1}{k-1}} = 1$$

$$\frac{\theta}{\theta_0} = \left(\frac{6r^2}{b_0 a^2} \right)^{1-k}$$

$$\frac{d\theta}{dr} = \frac{2(1-k)\theta}{\left(\frac{6r^2}{b_0 a^2} \right)^{1-k}} \frac{d}{dr} \left(\frac{6r^2}{b_0 a^2} \right)$$

$$= \frac{2(1-k)\theta}{\frac{6r^2}{b_0 a^2}} \frac{d}{dr} (6r^2)$$

$$1 + 30\alpha = \frac{0.00367}{1.110.14} \cdot \frac{184}{184}$$

$$\begin{array}{r} 288081 \\ 844 \\ \hline 20368 \end{array}$$

$$10885$$

$$\begin{array}{r} 1.414 \\ 14 \\ \hline 1554 : 184 = 0.844 \\ \hline 828 \end{array}$$

$$\begin{array}{r} 760 \\ 690 \\ \hline 70 \\ \hline 1.110.14 \\ \hline 0.844 \\ \hline 2.8385 \end{array}$$

~~Problemlösung:~~

I $0 = \frac{g \alpha}{2} m - (\alpha + \frac{c}{\lambda}) \theta$

$g = -\frac{\alpha k}{k-1} \frac{d\theta}{dx} \parallel \theta = \theta_0 - g x \frac{k-1}{\alpha k}$

$g \alpha (\frac{\alpha}{2} - 1) = \alpha \frac{k}{k-1} \theta$

$\frac{\theta}{\theta_0} = (\frac{\sigma}{\sigma_0})^{1-k} = (\frac{\rho}{\rho_0})^{1-k} = (\frac{\rho}{\rho_0})^{k-1}$

$\frac{k}{k_0} = \frac{\theta}{\theta_0} \frac{\rho}{\rho_0} = (\frac{\theta}{\theta_0})^{1+\frac{1}{k-1}} = (\frac{\theta}{\theta_0})^{\frac{k}{k-1}}$

$g x + m = -(\alpha + \frac{c}{\lambda}) \theta$

$\sigma = \sigma_0 (\frac{\theta}{\theta_0})^{\frac{1}{1-k}}$

$m = -(\alpha + \frac{c}{\lambda}) \theta_0$

$\frac{d\sigma}{d\lambda} = \frac{\sigma_0}{1-k} \frac{\theta^{\frac{k}{1-k}}}{\theta_0^{\frac{k}{1-k}}} \frac{d\theta}{d\lambda}$

$g x = (\alpha + \frac{c}{\lambda}) (\theta_0 - \theta)$

$g x = \alpha \frac{k}{k-1} (\theta_0 - \theta) = \alpha \frac{k}{k-1} \theta_0 (1 - \frac{\theta}{\theta_0})$

$\frac{d\sigma}{d\lambda} = \frac{\sigma_0}{1-k} \frac{1}{\theta_0^{\frac{k}{1-k}}} g \frac{k-1}{\alpha k} (\theta_0 - g x \frac{k-1}{\alpha k})^{\frac{k}{1-k}}$

$= \frac{\sigma_0}{\alpha k \theta_0^{\frac{1}{1-k}}} (\theta_0 - g x \frac{k-1}{\alpha k})^{\frac{k}{1-k}}$

$\frac{d\sigma}{d\lambda} = \frac{\sigma_0}{\alpha k \theta_0} (1 - \frac{g x (k-1)}{\theta_0 \alpha k})^{\frac{k}{1-k}}$

$\frac{\theta}{\theta_0} = \frac{1}{5}$

$(\frac{k}{k_0}) = (\frac{1}{5})^{\frac{1.4}{0.4}} = (\frac{1}{5})^{\frac{7}{2}}$

$\theta = 56^\circ \text{ ab.}$

$\approx 217^\circ$

$\lg(\frac{k}{k_0}) = -\frac{7}{2} \lg 5$

$\begin{array}{r} 0.69897 \\ 489279 \\ -244680 \\ \hline = 0.55360 - 3 \end{array}$

$\frac{k}{k_0} = 0.003578260$

$\mu = \text{ca } 2.5 \text{ mm}$

Nun aber nach Hermann, Hypothesen.

in ca 14000 m : $-65^\circ = 208^\circ$

$\Delta = 80^\circ$

während nach obigen Formel man sollte 140°

$\Delta = 140^\circ$

$\frac{7}{2} : x = \frac{7}{14} : 8$

$x = \frac{14}{7} = 2 = \frac{k}{k-1}$

$\frac{56}{208} = \frac{7}{26}$
 $(\frac{k}{k_0}) = (\frac{208}{280})^2 (\frac{7}{26})^2$

$\begin{array}{r} 41497 \\ 54407 \\ \hline 95904 \\ 004096 \end{array}$

$\begin{array}{r} 84510 \\ 41497 \\ \hline 43013 \\ 056987 \\ \hline 398909 \end{array}$

$\begin{array}{r} 1.99955 \\ 0.68192 \\ \hline 2.08647 \end{array}$

7 mm

Krytyczny punkt linii nie wykończ 27 km wzdł. tam g. o m. w. m. 1%,
 = 79 H.

zmniejszone a b o tyle przekasane

wz. zupełnie wystarczające są w równaniu przybliżone.

$$I.) \theta \frac{d\theta}{dx} = -g - (\alpha + \frac{c}{A}) \frac{d\theta}{dx} + \frac{4}{3} \theta \left[\theta \frac{d\theta}{dx} + \theta \left(\frac{d\theta}{dx} \right)^2 \right]$$

$$II.) \frac{\theta^2}{2} = -gx + m - (\alpha + \frac{c}{A}) \theta + \frac{4}{3} \theta \left[\theta \frac{d\theta}{dx} \right] = \left[\theta \frac{d\theta}{dx} + \left(\frac{d\theta}{dx} \right)^2 \right] \theta + \theta \frac{d\theta}{dx} \frac{d\theta}{dx}$$

$$III.) \frac{c}{A} \frac{d\theta}{dx} \frac{1}{\theta} + \frac{\alpha}{\theta} \frac{d\theta}{dx} = \frac{4}{3} \theta \left(\frac{d\theta}{dx} \right)^2$$

$$\theta \frac{d\theta}{dx} + g - \frac{4}{3} \theta \left[\theta \frac{d\theta}{dx} + \left(\frac{d\theta}{dx} \right)^2 \right] \theta = \left[-(\alpha + \frac{c}{A}) + \frac{4}{3} \theta \frac{d\theta}{dx} \right] \frac{d\theta}{dx}$$

$$\frac{1}{\theta} \left[\theta \frac{d\theta}{dx} + g \right] - \frac{4}{3} \theta \left[\theta \frac{d\theta}{dx} + \left(\frac{d\theta}{dx} \right)^2 \right] = \left[-(\alpha + \frac{c}{A}) + \frac{4}{3} \theta \frac{d\theta}{dx} \right] \frac{1}{\theta} \frac{d\theta}{dx}$$

$$= \frac{-(\alpha + \frac{c}{A}) + \frac{4}{3} \theta \frac{d\theta}{dx}}{\frac{\theta^2}{2} + gx - m} = \frac{A}{c} \left[\frac{4}{3} \theta \left(\frac{d\theta}{dx} \right)^2 - \frac{\alpha}{\theta} \frac{d\theta}{dx} \right]$$

$$\left[-(\alpha + \frac{c}{A}) + \frac{4}{3} \theta \frac{d\theta}{dx} \right] \left[\theta \frac{d\theta}{dx} + g \right] - \left[\frac{\theta^2}{2} + gx - m \right] \left[\theta \frac{d\theta}{dx} + \left(\frac{d\theta}{dx} \right)^2 \right] \frac{4}{3} \theta =$$

$$= \left[\frac{\theta^2}{2} + gx - m \right] \left[\frac{4}{3} \theta \left(\frac{d\theta}{dx} \right)^2 - \frac{\alpha}{\theta} \frac{d\theta}{dx} \right] \left[-(\alpha + \frac{c}{A}) + \frac{4}{3} \theta \frac{d\theta}{dx} \right] \frac{A}{c}$$

$$(p^2 + \frac{a}{2} p q + \frac{b}{3} q^2 = 0)$$

$$\frac{c}{A} \frac{d\theta}{dx} + \frac{\alpha}{\theta} \frac{d\theta}{dx} = \frac{4}{3} \theta \left(\frac{d\theta}{dx} \right)^2$$

$$\frac{c}{A} \left(\frac{dx}{d\theta} \right)^2 + \frac{\alpha}{\theta} \frac{dx}{d\theta} \frac{d\theta}{dx} = \frac{4}{3} \theta \frac{dx}{d\theta} \left| \frac{c}{A} p^2 + \frac{\alpha}{x} p q = \frac{4}{3} \theta q \right|$$

Answer:

$$\frac{c}{A} \theta \frac{d\theta}{dx} + \alpha \theta \frac{d\theta}{dx} = \frac{4}{3} \theta \frac{d\theta}{dx}$$

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$$\frac{c}{A} \theta \frac{d\theta}{dx} + \frac{d\theta}{dx} \frac{d\theta}{dx} + \alpha \theta \frac{d\theta}{dx}$$

$$\frac{c}{A} \theta \frac{d\theta}{dx} + \frac{c}{A} \frac{d\theta}{dx} \frac{d\theta}{dx} + \alpha \frac{d\theta}{dx} \frac{d\theta}{dx} + \alpha \theta \frac{d\theta}{dx} = \frac{4}{3} \theta \left[\frac{d\theta}{dx} \theta \left(\frac{d\theta}{dx} \right)^2 + \theta \left(\frac{d\theta}{dx} \right)^3 + 2 \theta \frac{d\theta}{dx} \frac{d\theta}{dx} \right]$$

$$I + III: \theta \frac{d\theta}{dx} = -g - \alpha \frac{d\theta}{dx} + \frac{c}{\theta} \frac{d\theta}{dx} + \frac{4}{3} \theta \left[\theta \frac{d\theta}{dx} + \theta \frac{d\theta}{dx} \frac{d\theta}{dx} \right]$$

$$\frac{1}{\theta} \frac{d\theta}{dx} = \frac{(m-gx)}{\theta} \frac{d\theta}{dx} - \left(\alpha + \frac{c}{A} \right) \frac{d\theta}{dx} + \frac{4}{3} \theta \frac{d\theta}{dx} \frac{d\theta}{dx}$$

$$\theta \frac{d\theta}{dx} - \frac{d\theta}{dx} \frac{d\theta}{dx} = - \frac{(m-gx)}{\theta} \frac{d\theta}{dx} + \frac{c}{A} \frac{d\theta}{dx} - g + \frac{c}{\theta} \frac{d\theta}{dx} + \frac{4}{3} \theta \frac{d\theta}{dx} \frac{d\theta}{dx}$$

$$-\frac{c}{A} \frac{1}{\theta^2} \left(\frac{d\theta}{dx} \right)^2 + \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dx} - \frac{\alpha}{\theta^2} \left(\frac{d\theta}{dx} \right)^2 + \frac{\alpha}{\theta} \frac{d\theta}{dx} = 2 \frac{4}{3} \theta \frac{d\theta}{dx} \frac{d\theta}{dx}$$

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$$\frac{dy}{dx} + X_1 y + X_2 = 0$$

$$y \frac{dy}{dx} + X_1 y^2 + X_2 y + X_3 = 0$$

$$y = e^{-\int X_1 dx} \left[C - \int X_2 e^{\int X_1 dx} dx \right]$$

$$e^{-\int X_1 dx} \left[C - \int X_2 e^{\int X_1 dx} dx \right] \left[-X_1 e^{-\int X_1 dx} \left(C - \int X_2 e^{\int X_1 dx} dx \right) - X_2 e^{-\int X_1 dx} + \frac{dC}{dx} e^{-\int X_1 dx} \right] + X_1 e^{-\int X_1 dx} \left(C - \int X_2 e^{\int X_1 dx} dx \right) + X_2$$

$$+ X_3 = 0$$

$$\left[C - \int X_2 e^{\int X_1 dx} dx \right] \frac{dC}{dx} + X_3 e^{2\int X_1 dx} = 0$$

$$c \frac{dc}{dx} + f_1(x) \frac{dc}{dx} + f_2(x) = 0$$

$$(c + f_1(x)) = y$$

$$\frac{dc}{dx} + f_1'(x) = \frac{dy}{dx}$$

$$\epsilon = -\frac{f_2}{(1+f_1') \frac{dy}{dx}} = \frac{-f_2 - f_1 \frac{dc}{dx}}{\frac{dc}{dx}} = -f_1 - \frac{f_2}{\frac{dc}{dx}}$$

$$\frac{dc}{dx} = -\frac{df_1}{dx} - \frac{df_2}{dx} + \frac{f_2}{\left(\frac{dc}{dx}\right)} \frac{d^2c}{dx^2}$$

$$\frac{dc}{dx} = p$$

$$f_2 \frac{dp}{dx} = p^3 + \frac{df_1}{dx} p^2 + \frac{df_2}{dx} p$$

$$\begin{aligned} \frac{d\theta}{dx} &= \frac{60}{\theta_0} \frac{1}{1-x} \frac{g}{ak} \left[\theta_0 - \frac{p x (k-1)}{ak} \right]^{\frac{k}{1-k}} \\ &= \frac{60 g}{ak \theta_0} \left[1 - \frac{p x (k-1)}{ak \theta_0} \right]^{\frac{k}{1-k}} \end{aligned}$$

(area tensor product) =

$$y \frac{dy}{dx} + y^2 X_1 + y X_2 + X_3 = 0$$

$$y + u = v$$

$$(y+u) \left(\frac{dy}{dx} + u' \right) + (y+u)^2 X_1 + X = 0$$

$$v \frac{dv}{dx} + v^2 X_1 + X = 0$$

for

$$y \frac{dy}{dx} + u \frac{dy}{dx} + y^2 X_1 + y \underbrace{(u' + 2u X_1)}_{= X_2} + u u' + u^2 X_1 + X = 0$$

zadání jako plošný prvek:

$$g_x = \alpha \frac{L}{k-1} (\theta_0 - \theta) \quad \frac{d\theta}{dx} = - \frac{g_x}{\alpha k} \frac{1}{\theta_0 - \theta}$$

$$\delta = \delta_0 \left(\frac{\theta}{\theta_0} \right)^{\frac{1}{1-k}}$$

$$\frac{d\delta}{dx} = \frac{g \delta_0}{\alpha k \theta_0} \left(1 - \frac{g_x (k-1)}{\theta_0 \alpha k} \right)^{\frac{k}{1-k}}$$

$$= \frac{g L}{k \theta_0} \left[1 - \frac{g_x (k-1)}{\theta_0 \alpha k} \right]^{\frac{k}{1-k}}$$

$$= \frac{4}{3} \mu \left(\frac{d\delta}{dx} \right)^L = \left(\frac{g L}{k \theta_0} \right)^2 \left[1 - \frac{g_x (k-1)}{\theta_0 \alpha k} \right]^{\frac{2k}{1-k}} \frac{4}{3} \mu$$

$$\int_0^x \left[1 - \frac{g_x (k-1)}{\theta_0 \alpha k} \right]^{\frac{2k}{1-k}} dx = \frac{\theta}{\theta_0}$$

$$= - \int_{\theta_0}^{\theta} \left(\frac{\theta}{\theta_0} \right)^{\frac{2k}{1-k}} \frac{\alpha k}{g(k-1)} d\theta = - \frac{\alpha k}{g(k-1) \theta_0^{\frac{2k}{1-k}}} \frac{1}{\frac{2k}{1-k} + 1} \theta^{\frac{2k}{1-k} + 1}$$

$$= + \frac{\alpha k}{g(k-1)} \left(\frac{\theta}{\theta_0} \right)^{\frac{2k}{1-k}} \theta - \theta_0 \left(\frac{\theta}{\theta_0} \right)^{\frac{2k}{1-k}} \frac{4}{3} \mu \left(\frac{g L}{k \theta_0} \right)^2$$

$$= \frac{4}{3} \mu \frac{\alpha}{1+k} \frac{g L}{k \theta_0^2} \theta_0 \left[\left(\frac{\theta}{\theta_0} \right)^{\frac{1+k}{1-k}} - 1 \right] = \frac{4}{3} \frac{\mu L g}{k (1+k)} \frac{1}{\theta_0 \theta_0} \left[\left(\frac{\theta}{\theta_0} \right)^{\frac{1+k}{1-k}} - 1 \right]$$

$$g_{\theta_0} = 0.00018 \text{ (gram)}$$

$$g = 980$$

$$\rho_0 = 0.0013$$

$$\rho_0 = 980.76 \cdot 13.6$$

$$\frac{g L}{\rho_0} = \frac{0.00018 \cdot 980}{980.76 \cdot 13.6 \cdot 0.0013} \frac{1}{1.4 \cdot 2.4} = 4.4$$

$$\frac{24}{336} = \frac{1008}{427}$$

$$m. L = 10 \text{ cm}$$

$$\frac{0.0006}{200}$$

$$m. \frac{\theta}{\theta_0} = \frac{1}{5} \quad \left(\frac{1}{5} \right)^6 = \frac{(125)^2}{250} = \frac{15000}{250}$$

$$\frac{0.0003}{150} = 0.0045$$

$$\log 2^{0.0045} = \frac{0.42426 \cdot 0.0045}{2.1713 \cdot 9}$$

$$0.0195397$$

$$2^{0.0045} = 1.046$$

$$\frac{6^2}{2} = -g + m - \left(\alpha + \frac{\epsilon}{A}\right)\theta + \frac{4}{3}\theta^2 \left(6 \frac{d\theta}{dx}\right) \quad \left| 2\theta \frac{d\theta}{dx} = \frac{4}{3}\theta^2 \left(\alpha + \frac{\epsilon}{A}\right) \frac{d\theta}{dx} + \frac{4}{3}\theta^2 \frac{d}{dx} \left(\theta \frac{d\theta}{dx}\right) \right.$$

$$\frac{\epsilon}{A} 6^2 \frac{d\theta}{dx} + \alpha \theta 6 \frac{d\theta}{dx} = \frac{4}{3}\theta^2 \left(6 \frac{d\theta}{dx}\right)^2$$

$$\left(\alpha + \frac{\epsilon}{A}\right) = \alpha \left(1 + \frac{1}{k-1}\right) = \frac{\alpha k}{k-1}$$

$$m = \left(\alpha + \frac{\epsilon}{A}\right)\theta_0 + \frac{6_0^2}{2} - \frac{4}{3}\theta_0^2 \left(6 \frac{d\theta}{dx}\right)_0$$

$$6^2 = a_0 + a_1 x + a_2 x^2 + a_3 x^3 + \dots$$

$$\frac{\theta}{\theta_0} = b_0 + b_1 x + b_2 x^2 + b_3 x^3 + \dots$$

$$2\theta \frac{d\theta}{dx} = a_1 + 2a_2 x + 3a_3 x^2 + 4a_4 x^3 + 5a_5 x^4 + \dots$$

$$\frac{2\theta}{\theta_0} \frac{d\theta}{dx} =$$

$$a_1 b_0$$

$$+ (a_1 b_1 + 2a_2 b_0)x$$

$$+ (a_1 b_2 + 2a_2 b_1 + 3a_3 b_0)x^2$$

$$+ (a_1 b_3 + 2a_2 b_2 + 3a_3 b_1 + 4a_4 b_0)x^3$$

$$+ (a_1 b_4 + 2a_2 b_3 + 3a_3 b_2 + 4a_4 b_1 + 5a_5 b_0)x^4$$

$$+ \dots$$

$$26 \frac{df}{dx} + 2g + \frac{2\alpha k}{k-1} \frac{d\theta}{dx} + \frac{4}{3} \frac{f}{\theta} \frac{d}{dx} \left(\theta 26 \frac{df}{dx} \right)$$

$$\left. \begin{aligned} a_1 + 2g + \frac{2\alpha k}{k-1} \theta_0 b_1 + \left(\frac{4}{3} \frac{f}{\theta} \right) (a_1 b_1 + 2a_2 b_0) \theta_0 &= 0 \\ x \quad f a_2 + \frac{2\alpha k}{k-1} \theta_0^2 b_2 + \frac{4}{3} \frac{f}{\theta} (a_1 b_2 + 2a_2 b_1 + 3a_3 b_0) \theta_0 &= 0 \\ x^2 \quad f a_3 + \frac{2\alpha k}{k-1} \theta_0^3 b_3 + \frac{4}{3} \frac{f}{\theta} (a_1 b_3 + 2a_2 b_2 + 3a_3 b_1 + 4a_4 b_0) \theta_0 &= 0 \\ x^3 \quad f a_4 + \frac{2\alpha k}{k-1} \theta_0^4 b_4 + \frac{4}{3} \frac{f}{\theta} (a_1 b_4 + 2a_2 b_3 + 3a_3 b_2 + 4a_4 b_1 + 5a_5 b_0) \theta_0 &= 0 \end{aligned} \right\}$$

$$\frac{\alpha}{k-1} a_0 b_1 + \frac{\alpha}{2} a_1 b_0 = \frac{4}{3} \frac{f}{\theta} \frac{b_0 a_1^2}{4}$$

$$\frac{\alpha}{k-1} (2a_0 b_2 + a_1 b_1) + \frac{\alpha}{2} (2a_2 b_0 + a_1 b_1) = \frac{4}{3} \frac{f}{\theta} \frac{1}{4} [b_0 (4a_1 a_2) + b_1 a_1^2]$$

$$\frac{\alpha}{k-1} (3a_0 b_3 + 2a_1 b_2 + a_2 b_1) + \frac{\alpha}{2} (3a_3 b_0 + 2a_2 b_1 + a_1 b_2) = \frac{4}{3} \frac{f}{\theta} \frac{1}{4} [b_0 (6a_1 a_3 + 4a_2^2) + b_1 (4a_1 a_2 + b_2 a_1^2)]$$

$$\begin{aligned} \frac{\alpha}{k-1} (4a_0 b_4 + 3a_1 b_3 + 2a_2 b_2 + a_3 b_1) + \frac{\alpha}{2} (4a_4 b_0 + 3a_3 b_1 + 2a_2 b_2 + a_1 b_3) &= \\ = \frac{4}{3} \frac{f}{\theta} \frac{1}{4} [b_0 (8a_1 a_4 + 12a_2 a_3) + b_1 (6a_1 a_3 + 4a_2^2) + b_2 (4a_1 a_2 + b_3 a_1^2)] \end{aligned}$$

John just $\frac{d^2\theta}{dx^2}$ is hydrodynamic pressure?

$\frac{dI}{dx^2}$:

$$\frac{d}{dx} \left(6 \frac{d\delta}{dx} \right) = \left(\frac{d\delta}{dx} \right)' + 6 \frac{d^2\delta}{dx^2} = - \left(\alpha + \frac{c}{A} \right) \frac{d^2\theta}{dx^2} + \frac{4}{3} \theta \left[\frac{6 \frac{d^2\delta}{dx^2} + \left(\frac{d\delta}{dx} \right)'}{\frac{d\delta}{dx}} + \theta \frac{d}{dx} \left[\frac{6 \frac{d^2\delta}{dx^2} + \left(\frac{d\delta}{dx} \right)'}{\frac{d\delta}{dx}} \right] \right]$$

$$0 = \frac{6 \frac{d^2\delta}{dx^2}}{\frac{d\delta}{dx}} \frac{d^2\theta}{dx^2} + \frac{d}{dx} \left(\frac{6 \frac{d\delta}{dx}}{\frac{d\delta}{dx}} \right) \frac{d\theta}{dx}$$

$$\frac{4}{3} \theta \frac{6 \frac{d\delta}{dx}}{\frac{d\delta}{dx}} = \alpha$$

$$\frac{c}{A} \frac{d^2\theta}{dx^2} = \frac{4}{3} \theta \frac{d}{dx} \left[\frac{6 \frac{d^2\delta}{dx^2} + \left(\frac{d\delta}{dx} \right)'}{\frac{d\delta}{dx}} \right]$$

$$g = \frac{4}{3} \theta \left[\frac{6 \frac{d^2\delta}{dx^2}}{\frac{d\delta}{dx}} + 6 \frac{d^2\delta}{dx^2} \right]$$

$$\frac{4}{3} \theta g \delta^2 = \frac{\alpha^2 \theta}{\frac{d\delta}{dx}} + \left(\frac{4}{3} \theta \right) \theta \frac{6^3 \frac{d\delta}{dx}}{\frac{d\delta}{dx}} \quad \text{II} \quad 2(I)$$

$$\times \left(\frac{4}{3} \theta \right)^2 \delta^3$$

$$\frac{c}{A} \frac{6 \frac{d^2\theta}{dx^2}}{\frac{d\delta}{dx}} + \frac{c}{A} \frac{d\delta}{dx} \frac{d\theta}{dx} + \alpha \frac{d\delta}{dx} \frac{d\theta}{dx} + \alpha \theta \frac{d^2\delta}{dx^2} = \frac{4}{3} \theta \left[\frac{d\theta}{dx} \frac{6 \left(\frac{d\delta}{dx} \right)'}{\frac{d\delta}{dx}} + \theta \left(\frac{d\delta}{dx} \right)' + 2 \theta \frac{d\delta}{dx} \frac{d^2\delta}{dx^2} \right]$$

$$\frac{c}{A} \frac{6 \frac{d^2\theta}{dx^2}}{\frac{d\delta}{dx}} \frac{4}{3} \theta \delta^3 + \left[\frac{4}{3} \theta \right] g \delta^2 = \theta \frac{\alpha^3}{\frac{d\delta}{dx}} + \theta \alpha \left(\frac{4}{3} \theta g \delta^2 - \alpha^2 \theta \right)$$

$$\frac{4}{3} \theta \frac{c}{A} \frac{6^4 \frac{d^2\theta}{dx^2}}{\frac{d\delta}{dx}} = \frac{4}{3} \theta g \delta^2$$

$$\left[\frac{d^2\theta}{dx^2} = \frac{g \alpha}{\frac{c}{A} \delta^2} \right]$$

> 0

Findy spöt vöringde k ring:

$$p = \frac{1}{s} = \frac{1}{u} \frac{du}{dz}$$

$$dz = \frac{1}{u} du$$

$$y = \frac{e^2}{k-1}$$

$$\theta = \frac{e^2}{\alpha u} = \frac{k-1}{\alpha} \frac{y}{u}$$

$$\frac{dp}{du} = -\frac{1}{s^2} \frac{ds}{du}$$

$$-(k+u)(1+u)u \frac{1}{s^3} \frac{ds}{du} - \frac{1}{s^2} [4u^2 - u(1+k) - 2k] + \frac{1}{s} [u^2 + 4u + 3k] + u^2 + ku - u - k \stackrel{=0}{\approx}$$

$$(k+u)(1+u)u \frac{ds}{du} + [4u^2 - u(1+k) - 2k]s - [u^2 + 4u + 3k]s^2 - [u^2 + ku - u - k]s^3 \stackrel{=0}{\approx}$$

$$s = a_0 + a_1 u + a_2 u^2 + a_3 u^3 + a_4 u^4 + \dots$$

$$-2ka_0 - 3ka_0^2 + ka_0^3 = 0$$

$$ka_0 [2 + 3a_0 - a_0^2] = 0$$

1st Roster

$$-g = \frac{1}{\rho} \frac{d\rho}{dz} \quad \boxed{D = \alpha \rho \theta}$$

$$\rho = \rho_l \text{ Vol. } \sim \quad \left. \begin{array}{l} 1 \text{ kg } 10/10 \text{ } 12 \text{ } \sim \frac{1}{\rho} \text{ Vol. } (e\gamma + 10) \\ \text{" " " } x \text{ kg } e\gamma \text{ } (1-x) \text{ kg } 10 \end{array} \right\}$$

$$= \cancel{g_d \text{ Vol. } 2 \rho_{\text{par}} v_0}$$

$$e\gamma \text{ spec. Vol. } \omega \text{ } \sim \rho_d = \frac{1}{\omega}$$

$$10 \text{ spec. Vol. } v=1 \text{ } \sim \rho_{\text{par}} = 1$$

$$1 \text{ kg } 10/10 \text{ } \sim \text{Vol. } \omega \frac{x}{\omega} + 1-x$$

$$\therefore \rho = \frac{1}{\omega \frac{x}{\omega} + 1-x} \neq \frac{\rho_d}{x}$$

$$\frac{1}{\rho} = \frac{x}{\rho_d}$$

$$\frac{x r}{T} \sim - \frac{x_0 r_0}{T_0} = c \ln \frac{T_0}{T}$$

$$\frac{r}{T} = A \omega \frac{d\rho}{dT}$$

$$A \omega x \frac{d\rho}{dT} = \frac{x_0 r_0}{T_0} + c \ln \frac{T_0}{T} = A \frac{x}{\rho_d} \frac{d\rho}{dT} = A \frac{1}{\rho} \frac{d\rho}{dT} = -A g \frac{dz}{dT}$$

$$-A g z = \frac{x_0 r_0}{T_0} T + c \ln T_0 - c \ln T + c \left. \ln T \right|_{T_0}^T$$

$$+ A g H = \cancel{\frac{x_0 r_0}{T_0} T} r_0 + c T_0$$

Dabei vorausgesetzt dass c ~~unverändert~~ von Temp. $\sim N^1$

II	regdn	regdn	θ	ρ	ρ	θ
I	"	regdn	θ	ρ	θ	ρ
I	"		θ	ρ	θ	ρ

$$p = \alpha \rho \theta = \frac{\alpha \theta b}{\phi} \quad \parallel \quad \frac{dp}{dx} = \alpha b \left[\frac{1}{\phi} \frac{d\theta}{dx} - \frac{\theta}{\phi^2} \frac{d\phi}{dx} \right]$$

$$= \alpha b \frac{1}{\sqrt{v}} \left[\frac{d\theta}{dx} - \frac{\theta}{2} \frac{dv}{dx} \right]$$

$$\log p = \log \alpha b + \log \theta - \log \phi$$

$$\frac{1}{p} \frac{dp}{dx} = \frac{1}{\theta} \frac{d\theta}{dx} - \frac{1}{2\phi} \frac{d\phi}{dx}$$

$$v = a_0 + a_1 x + a_2 x^2 + a_3 x^3 + \dots$$

$$\frac{1}{\sqrt{v}} = v^{-\frac{1}{2}} =$$

$$\log p = A \log \frac{\theta}{\phi}$$

$$p - p_0 = \int_0^\theta \alpha b \left[\frac{1}{\sqrt{v}} \frac{d\theta}{dx} - \frac{\theta}{2} \frac{dv}{dx} \right] = f_1(\theta, v_0, b, m)$$

$$p_0 + \int_0^\theta = \frac{\alpha \theta b}{\phi}$$

$$\frac{p_0}{\alpha b} + \underbrace{\int_0^\theta \left[\frac{1}{\sqrt{v}} \frac{d\theta}{dx} - \frac{\theta}{2} \frac{dv}{dx} \right]}_{\frac{\theta}{\phi} - \frac{\theta_0}{\phi_0}} = \frac{\theta}{\phi}$$

$$\frac{p_0}{\alpha b} = \frac{\theta_0}{\phi_0}$$

Terminierung notiert:

$$\rho = \frac{b}{\sigma}$$

$$0 = -g + \alpha \theta \frac{1}{\sigma} \frac{db}{dx} + \frac{4}{3} \frac{\mu}{b} \theta \frac{dx}{dx}$$

$$\frac{1}{\rho} \frac{d\rho}{dx} + \frac{1}{\sigma} \frac{db}{dx} = 0$$

by mix systemy polarnie i'wenty u
druck m'ig'sch 2

treboly podan' b, b_2, ρ_1

$$\mu = \alpha \theta \rho$$

$$\frac{dp_1}{dx} + \rho_1 g + \alpha \rho_1 \rho_2 (u_1 - u_2) = 0$$

$$\frac{dp_2}{dx} + \rho_2 g + \alpha \rho_1 \rho_2 (u_2 - u_1) = 0$$

$$\alpha_1 \theta \frac{1}{\rho_1} \frac{d\rho_1}{dx} + g + \alpha \rho_2 (u_1 - u_2) = 0$$

$$\alpha_2 \theta \frac{1}{\rho_2} \frac{d\rho_2}{dx} + g + \alpha \rho_1 (u_2 - u_1) = 0$$

$$\rho_1 = \alpha_1 \rho_1 \theta \quad \frac{d\rho_1}{dx} = \alpha_1 \theta \frac{d\rho_1}{dx} \text{ (jindli out)}$$

$$\rho_2 = \alpha_2 \rho_2 \theta$$

$$\frac{d}{dx} (\rho_1 + \rho_2) + (\rho_1 + \rho_2) g = 0$$

$$\left[\alpha_1 \theta \frac{d\rho_1}{dx} + \rho_1 g \right] = - \left[\alpha_2 \theta \frac{d\rho_2}{dx} + \rho_2 g \right]$$

$$\frac{d}{dx} (\rho_1 u_1) = 0$$

$$u = u + \mu$$

$$\frac{d}{dx} (\rho_2 u_2) = 0$$

$$u = u + \mu$$

$$\rho_1 u_1 = c_1$$

$$\rho_2 u_2 = c_2$$

$$\text{Für } z=0: u_1 = u_2 = u_0$$

$$\frac{\rho_{10}}{\rho_{20}} = \frac{c_1}{c_2}$$

$$\frac{\rho_1}{\rho_2} = \frac{c_1}{c_2} \frac{u_2}{u_1}$$

$$\alpha_1 \theta \frac{1}{\rho_1} \frac{d\rho_1}{dx} + g + \alpha \left(\frac{\rho_2 c_1}{\rho_1} - c_2 \right) = 0$$

$$\alpha_1 \theta \frac{d\rho_1}{dx} + \rho_1 g + \alpha (c_1 \rho_2 - c_2 \rho_1) = 0$$

$$\alpha_2 \theta \frac{d\rho_2}{dx} + \rho_2 g + \alpha (c_2 \rho_1 - c_1 \rho_2) = 0$$

$$\rho_1 \rho_2 (u_1 - u_2) = c_1 \rho_2 - c_2 \rho_1 = \rho_2 c_1 \left[1 - \frac{c_2}{c_1} \frac{\rho_1}{\rho_2} \right]$$

$$c_1 = \rho_{10} u$$

$$c_2 = \rho_{20} u$$

$$= \rho_2 c_1 \left[1 - \frac{\rho_{20}}{\rho_{10}} \frac{\rho_1}{\rho_2} \right]$$

$$= \rho_1 c_1 \left[\frac{\rho_2}{\rho_1} - \frac{\rho_{20}}{\rho_{10}} \right]$$

$$\alpha_1 \theta \frac{d\rho_1}{dr} + (g + ac_1) \frac{d\rho_1}{dr} + a - r = 0$$

$$d_2 \theta \frac{d\rho_2}{dr} = -(g + ac_1) \rho_2 - ac_2 \rho_1$$

$$= \left(\frac{g + ac_1}{ac_1} \right) \left[\rho_1 (g + ac_1) - \alpha_1 \theta \frac{d\rho_1}{dr} \right] - ac_2 \rho_1$$

$$\alpha_1 \alpha_2 \theta^2 \frac{d^2 \rho_1}{dr^2} + \alpha_2 \theta (g + ac_1) \frac{d\rho_1}{dr} + (g + ac_1) \left[\rho_1 (g + ac_1) - \alpha_1 \theta \frac{d\rho_1}{dr} \right] - a^2 c_1 c_2 \rho_1 = 0$$

$$\alpha_1 \alpha_2 \theta^2 \frac{d^2 \rho_1}{dr^2} + [\alpha_2 (g + ac_1) + \alpha_1 (g + ac_1)] \theta \frac{d\rho_1}{dr} + [(g + ac_1)(g + ac_1) - a^2 c_1 c_2] \rho_1 = 0$$

$$\rho_1 = \frac{A_1 e^{-\beta r}}{r} + B e^{\gamma r}$$

$$\alpha_1 \alpha_2 \theta^2 \beta^2 - [\alpha_2 (g + ac_1) + \alpha_1 (g + ac_1)] \theta \beta + (g + ac_1)(g + ac_1) - a^2 c_1 c_2 = 0$$

$$[\alpha_1 \theta \beta - (g + ac_1)] [\alpha_2 \theta \beta - (g + ac_1)] = a^2 c_1 c_2 = \frac{a^2 c_1 c_2 - (g - ac_1)(g - ac_1)}{\alpha_1 \alpha_2}$$

$$(\theta \beta)^2 - \left[\frac{g + ac_1}{\alpha_1} + \frac{g + ac_1}{\alpha_2} \right] \theta \beta + \frac{g^2 + g(g + ac_1)}{\alpha_1 \alpha_2} = 0$$

$$\theta \beta = + \frac{g + ac_1}{2\alpha_1} + \frac{g + ac_1}{2\alpha_2} \pm \sqrt{\left(\frac{g + ac_1}{2\alpha_1} \right)^2 + \left(\frac{g + ac_1}{2\alpha_2} \right)^2 + \frac{a^2 c_1 c_2}{\alpha_1 \alpha_2}}$$

$$\alpha_1 \alpha_2 \theta^2 \beta^2 - g(\alpha_1 + \alpha_2) \theta \beta + g^2 = 0 \quad \theta \beta = \frac{g}{\alpha_1} \quad \frac{(g + ac_1)^2}{4\alpha_1^2} + \frac{(g + ac_1)^2}{4\alpha_2^2} + \frac{g^2}{4\alpha_1 \alpha_2}$$

$$(\alpha_1 \theta \beta - g)(\alpha_2 \theta \beta - g) = 0 \quad \theta \beta = \frac{g}{\alpha_2}$$

$$- \frac{1}{2} \alpha_1 \alpha_2 (g + ac_1)(g + ac_1) + \frac{1}{2} a^2 c_1 c_2 \alpha_1 \alpha_2 + \alpha_1^2 (g + ac_1)^2 + \alpha_2^2 (g + ac_1)^2$$

$$- 2\alpha_1 \alpha_2 g^2 + 2\alpha_1 \alpha_2 g(ac_1 + ac_2) + 2\alpha_1 \alpha_2 a^2 c_1 c_2 + \alpha_1^2 g^2 + 2\alpha_1^2 g ac_1 + \alpha_1^2 a^2 c_1^2 + \alpha_2^2 g^2 + 2\alpha_2^2 g ac_2 + \alpha_2^2 a^2 c_2^2$$

$$= \frac{g^2 (\alpha_1 - \alpha_2)^2 + 2ga(\alpha_1^2 c_1 + \alpha_2^2 c_2 - 2\alpha_1 \alpha_2 c_1 - 2\alpha_1 \alpha_2 c_2) + a^2 (\alpha_1^2 c_1^2 + \alpha_2^2 c_2^2)}{2\alpha_1}$$

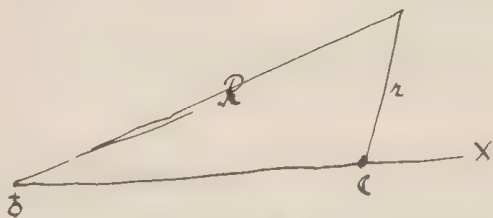
Isotermisem töltés döntő részét ^{u.p.} magy. energiát; közegum.

$$u = u_1 = 0$$

$$\left. \begin{aligned} \frac{\partial p_1}{\partial x} &= p_1 X_1 & \frac{\partial p_2}{\partial x} &= p_2 X_2 \\ \frac{\partial p_1}{\partial y} &= p_1 Y_1 & \frac{\partial p_2}{\partial y} &= p_2 Y_2 \\ \frac{\partial p_1}{\partial z} &= p_1 Z_1 & \frac{\partial p_2}{\partial z} &= p_2 Z_2 \end{aligned} \right\} \frac{\partial p_1}{\partial x} = p_1 \frac{F_1}{F_2} \rightarrow \frac{\partial p_2}{\partial x} = p_2 \frac{F_2}{F_1}$$

$$X_1 = X_2 = \frac{k M}{R} \frac{\partial u}{\partial x}$$

etc.



$$\int \frac{1}{p_1} dp_1 = u = \int \frac{1}{p_2} dp_2$$

$$u = \frac{k M}{R} + \frac{k m}{z}$$

$$p_1 = \alpha_1 p_1 \theta$$

$$p_2 = \alpha_2 p_2 \theta$$

$$\log p_1 = \log \alpha_1 \theta + \log p_1$$

$$u = \alpha_1 \theta \log p_1 + \text{const} = \alpha_2 \theta \log p_2 + \text{const} = \frac{k M}{R} + \frac{k m}{z}$$

$$\alpha_1 \theta \log p_1 + \text{const} = \alpha_2 \theta \log p_2 + \text{const} -$$

$$\alpha_1 \theta \log p_{10} + \text{const} = \frac{k M}{A}$$

$$\alpha_1 \theta \log \frac{p_1}{p_{10}} = \left[\frac{k M}{R} + \frac{k m}{z} - \frac{k M}{A} \right] \quad \left| \quad \alpha_2 \theta \log \frac{p_2}{p_{20}} = \left[\dots \right] \right.$$

$$\alpha_1 \lg \frac{p_1}{p_{10}} = \alpha_2 \lg \frac{p_2}{p_{20}}$$

$$\left(\frac{p_1}{p_{10}} \right)^{\alpha_1} = \left(\frac{p_2}{p_{20}} \right)^{\alpha_2}$$

$$\frac{p_1}{p_{10}} = \left(\frac{p_2}{p_{20}} \right)^{\frac{\alpha_2}{\alpha_1}}$$

$$\frac{p_1}{p_2} = \frac{p_{10}}{p_{20}^{\frac{\alpha_2}{\alpha_1}}} p_2^{\left(\frac{\alpha_2}{\alpha_1} - 1 \right)}$$

Wzr. ichy stromkowa jeston

czym jezto byto niezmienne, $\frac{\alpha_2}{\alpha_1} - 1$ musiatobybyc < 0 , wzr. $\alpha_1 = \alpha_2$

Inaczej je jezto ma wzrasc a n.p. $\alpha_2 > \alpha_1$

bycie moze stromkowa ~~wzrasc~~ ^{zmniejsz} co'wosci parabolicznej tam jezto p jest

wzrasc n.p. wodzie ^{zmniejsz} ~~wzrasc~~ o tluszczu

$$f(x) = \frac{1}{2}x^2 - \frac{1}{2}x + \frac{1}{2}$$

$$f'(x) = x - \frac{1}{2}$$

$$f''(x) = 1$$

$$f(x) = \frac{1}{2}x^2 - \frac{1}{2}x + \frac{1}{2}$$

$$f'(x) = x - \frac{1}{2}$$

$$f''(x) = 1$$

$$f(x) = \frac{1}{2}x^2 - \frac{1}{2}x + \frac{1}{2}$$

$$f'(x) = x - \frac{1}{2}$$

$$f''(x) = 1$$

$$f(x) = \frac{1}{2}x^2 - \frac{1}{2}x + \frac{1}{2}$$

$$f'(x) = x - \frac{1}{2}$$

$$f''(x) = 1$$

$$f(x) = \frac{1}{2}x^2 - \frac{1}{2}x + \frac{1}{2}$$

Bestimmung eines aus drei Punkten: untern

$$r = \alpha \rho \theta \quad \theta = \text{const}$$

$$\rho = f(\alpha, \theta)$$

$$R = -\frac{1}{\alpha} \int_{\alpha}^{\infty} \rho^2 d\alpha = -\frac{1}{\alpha} \int_{\alpha}^{\infty} f(\alpha) d\alpha$$

$$R = \frac{1}{\rho} \frac{d\rho}{d\alpha}$$

$$-\frac{1}{\alpha} \int_{\alpha}^{\infty} \rho^2 d\alpha = \frac{1}{\alpha} \alpha \theta \frac{d\rho}{d\alpha}$$

$$-k \rho^2 = \alpha \theta \frac{d}{d\alpha} \left(\alpha^2 \frac{d\rho}{d\alpha} \right)$$

$$-\frac{k}{\alpha} \alpha^2 \rho = 2\alpha \frac{d\rho}{d\alpha} - \frac{\rho^2}{\alpha^2} \left(\frac{d\alpha}{d\alpha} \right)^2 + \frac{\rho}{\alpha^2} \frac{d\rho}{d\alpha}$$

$$E_{gr} = \int_0^{\infty} \rho U d\alpha \quad U = \frac{k}{2} \int_{\alpha}^{\infty} \rho^2 d\alpha$$

$$= \int_0^{\infty} k \alpha \int_{\alpha}^{\infty} \rho^2 d\alpha d\alpha = k \int_0^{\infty} \rho^2 d\alpha \int_{\alpha}^{\infty} \alpha d\alpha$$



$$Z = \int \left[u \frac{\partial u}{\partial t} + v \frac{\partial v}{\partial t} - (uX + vY + wZ) + c \frac{\partial \tau}{\partial t} \right] du +$$

$$\int_{\Sigma} \left\{ \begin{aligned} & (q_{xx} \cos nx + q_{xy} \cos ny + q_{xz} \cos nz) u + \\ & (q_{yx} \cos nx + q_{yy} \cos ny + q_{yz} \cos nz) v + \\ & (q_{zx} \cos nx + q_{zy} \cos ny + q_{zz} \cos nz) w \end{aligned} \right\} dS =$$

$$\int_{\Sigma} \frac{i}{2} \left[\frac{\partial}{\partial x} (q_{xx} u) + (q_{xy} v) + (q_{xz} w) \right] + \frac{\partial}{\partial y} (q_{xy} u + q_{yy} v + q_{yz} w) + \frac{\partial}{\partial z} (q_{xz} u +$$

$$= \iiint \left[u \left(\frac{\partial q_{xx}}{\partial x} + \frac{\partial q_{xy}}{\partial y} + \frac{\partial q_{xz}}{\partial z} \right) + v \left(\frac{\partial q_{xy}}{\partial x} + \frac{\partial q_{yy}}{\partial y} + \frac{\partial q_{yz}}{\partial z} \right) + w \left(\frac{\partial q_{xz}}{\partial x} + \frac{\partial q_{yz}}{\partial y} + \frac{\partial q_{zz}}{\partial z} \right) \right]$$

$$+ q_{xx} \frac{\partial u}{\partial x} + q_{xy} \frac{\partial u}{\partial y} + q_{xz} \frac{\partial u}{\partial z} + q_{xy} \frac{\partial v}{\partial x} + q_{yy} \frac{\partial v}{\partial y} + q_{yz} \frac{\partial v}{\partial z} + q_{xz} \frac{\partial w}{\partial x} + q_{yz} \frac{\partial w}{\partial y} + q_{zz} \frac{\partial w}{\partial z} +$$

$$+ v \left[\frac{\partial q_{xy}}{\partial x} + \frac{\partial q_{yy}}{\partial y} + \frac{\partial q_{yz}}{\partial z} \right]$$

$$+ w \left[\frac{\partial q_{xz}}{\partial x} + \frac{\partial q_{yz}}{\partial y} + \frac{\partial q_{zz}}{\partial z} \right]$$

$$- (uX + vY + wZ) + c \frac{\partial \tau}{\partial t} \Big] d\tau = 0$$

$$= \iiint \frac{\partial}{\partial t} \left[u \frac{\partial u}{\partial t} + v \frac{\partial v}{\partial t} - (uX + vY + wZ) + c \frac{\partial \tau}{\partial t} \right] d\tau +$$

$$c \frac{\partial}{\partial t} \left[\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right] + \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = - \frac{1}{2} \left[\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right]^2 + \frac{1}{2} \left[\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right]^2$$

$$\frac{\partial}{\partial \theta} + \alpha \frac{\partial}{\partial \phi} = \frac{\partial}{\partial \theta} + \frac{\partial}{\partial \phi}$$

$$\frac{\partial}{\partial \theta} + \frac{\partial}{\partial \phi} = \frac{\partial}{\partial \theta} + \frac{\partial}{\partial \phi}$$

$$\frac{\partial}{\partial \theta} + \frac{\partial}{\partial \phi} = \frac{\partial}{\partial \theta} + \frac{\partial}{\partial \phi}$$

$$\frac{\partial}{\partial \theta} = \frac{\partial}{\partial \theta}$$

$$\frac{\partial}{\partial \theta} = \frac{\partial}{\partial \theta}$$

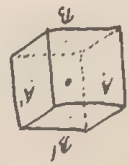
$$\frac{\partial}{\partial \theta} + \frac{\partial}{\partial \phi} = \frac{\partial}{\partial \theta} + \frac{\partial}{\partial \phi}$$

$$\frac{\partial}{\partial \theta} + \frac{\partial}{\partial \phi} = \frac{\partial}{\partial \theta} + \frac{\partial}{\partial \phi}$$

$$\frac{\partial}{\partial \theta} + \frac{\partial}{\partial \phi} = \frac{\partial}{\partial \theta} + \frac{\partial}{\partial \phi}$$

$$\frac{\partial}{\partial \theta} + \frac{\partial}{\partial \phi} = \frac{\partial}{\partial \theta} + \frac{\partial}{\partial \phi}$$

Direct method:



path of the centre: $u \Delta t, v \Delta t, w \Delta t$

path of point A: $u(x - \frac{\Delta t}{2}), v(x - \frac{\Delta t}{2}), w(x - \frac{\Delta t}{2})$

A': $u(x + \frac{\Delta t}{2}, y, z), v(x + \frac{\Delta t}{2}, y, z), w(x + \frac{\Delta t}{2}, y, z)$

but the force on Δt is Δt during the whole time.

let's carry on from Δt to $\Delta t + \Delta t$ $\left[\frac{\partial^2}{\partial t^2} \Delta t \right]$

$$u(x + \frac{\Delta t}{2}, y, z) \Delta t \cdot \rho_{xx}(x + \frac{\Delta t}{2}, y, z) \Delta t - u(x - \frac{\Delta t}{2}, y, z) \Delta t \cdot \rho_{xx}(x - \frac{\Delta t}{2}, y, z) \Delta t$$

$$+ u(x, y + \frac{\Delta t}{2}, z) \Delta t \cdot \rho_{xy}(x, y + \frac{\Delta t}{2}, z) \Delta t$$

$$A_{xx} = \int - \left(\rho_{xx} + \frac{\partial}{\partial x} \left[u \left(\frac{\partial u}{\partial x} + v \frac{\partial v}{\partial x} + w \frac{\partial w}{\partial x} \right) \right] + \rho_{xy} \left[v \frac{\partial v}{\partial y} + w \frac{\partial w}{\partial y} \right] + \rho_{xz} \left[w \frac{\partial w}{\partial z} + v \frac{\partial v}{\partial z} + u \frac{\partial u}{\partial z} \right] \right) \Delta x \Delta y \Delta z$$

$$\int \left[\rho_{xx} \left(\frac{\partial u}{\partial x} \right) + \rho_{xy} \left(\frac{\partial v}{\partial y} \right) + \rho_{xz} \left(\frac{\partial w}{\partial z} \right) \right] \Delta x \Delta y \Delta z + \rho_{xy} \left[v \frac{\partial v}{\partial y} + w \frac{\partial w}{\partial y} \right] \Delta x \Delta z + \rho_{xz} \left[w \frac{\partial w}{\partial z} + v \frac{\partial v}{\partial z} + u \frac{\partial u}{\partial z} \right] \Delta x \Delta y$$

$$+ \rho_{xy} \left(\frac{\partial v}{\partial x} + \frac{\partial v}{\partial y} \right) + \rho_{xz} \left(\frac{\partial w}{\partial x} + \frac{\partial w}{\partial y} \right) + \rho_{yz} \left(\frac{\partial w}{\partial y} + \frac{\partial w}{\partial z} \right) + \rho_{xx} \left(\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} \right) + \rho_{yy} \left(\frac{\partial v}{\partial y} + \frac{\partial v}{\partial z} \right) + \rho_{zz} \left(\frac{\partial w}{\partial z} + \frac{\partial w}{\partial x} \right)$$

$$-\left[\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right] = \frac{\partial}{\partial t} \left[u \frac{\partial x}{\partial t} + v \frac{\partial y}{\partial t} + w \frac{\partial z}{\partial t} \right]$$

$$\int \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) dx dy dz$$

$$A_{\text{tot}} = \int \left[\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) u + \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) v + \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) w \right] dx dy dz$$

$$\int u \Delta v dx = - \int \left(u \frac{\partial^2 v}{\partial x^2} + u \frac{\partial^2 v}{\partial y^2} + u \frac{\partial^2 v}{\partial z^2} \right) dx dy dz + \int u \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} \right) dx dy dz$$

$$A_{\text{tot}} = \int \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) \left(u \frac{\partial^2 v}{\partial x^2} + v \frac{\partial^2 v}{\partial y^2} + w \frac{\partial^2 v}{\partial z^2} \right) dx dy dz + \int \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) \left(u \frac{\partial^2 v}{\partial x^2} + v \frac{\partial^2 v}{\partial y^2} + w \frac{\partial^2 v}{\partial z^2} \right) dx dy dz$$

$$\begin{aligned} & \left[2 \frac{\partial^2 u}{\partial x^2} v + \frac{\partial^2 u}{\partial x \partial y} v + \frac{\partial^2 u}{\partial y^2} v + \frac{\partial^2 u}{\partial x \partial z} v + \frac{\partial^2 u}{\partial y \partial z} v + \frac{\partial^2 u}{\partial z^2} v \right] dx dy dz \\ & + \left[2 \frac{\partial^2 v}{\partial x^2} u + \frac{\partial^2 v}{\partial x \partial y} u + \frac{\partial^2 v}{\partial y^2} u + \frac{\partial^2 v}{\partial x \partial z} u + \frac{\partial^2 v}{\partial y \partial z} u + \frac{\partial^2 v}{\partial z^2} u \right] dx dy dz \\ & + \left[2 \frac{\partial^2 w}{\partial x^2} u + \frac{\partial^2 w}{\partial x \partial y} u + \frac{\partial^2 w}{\partial y^2} u + \frac{\partial^2 w}{\partial x \partial z} u + \frac{\partial^2 w}{\partial y \partial z} u + \frac{\partial^2 w}{\partial z^2} u \right] dx dy dz \end{aligned}$$

$$X = -\frac{\partial \psi}{\partial x}$$

$$\rho \frac{\partial u}{\partial t} = \rho X - \frac{\partial p}{\partial x} + \mu \nabla^2 u$$

$$\rho \frac{\partial v}{\partial t} = \rho Y - \frac{\partial p}{\partial y} + \mu \nabla^2 v$$

$$\rho \frac{\partial w}{\partial t} = \rho Z - \frac{\partial p}{\partial z} + \mu \nabla^2 w$$

$$\frac{\partial}{\partial t} \int_V \rho (u^2 + v^2 + w^2) dV + \rho \iint_S (u^2 + v^2 + w^2) dS = 0$$

$$\rho dx = dm$$

$$\frac{\partial}{\partial t} \left[\int_V \rho (u^2 + v^2 + w^2) dV + \rho \iint_S (u^2 + v^2 + w^2) dS \right] = 0$$

$$\left[\rho \frac{\partial u}{\partial t} + \rho u \frac{\partial u}{\partial x} + \rho v \frac{\partial u}{\partial y} + \rho w \frac{\partial u}{\partial z} + \frac{\partial \rho}{\partial t} u + \frac{\partial \rho}{\partial x} u^2 + \frac{\partial \rho}{\partial y} uv + \frac{\partial \rho}{\partial z} uw \right] dm = 0$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = - (uX + vY + wZ)$$

$$u \frac{\partial u}{\partial t} = 0$$

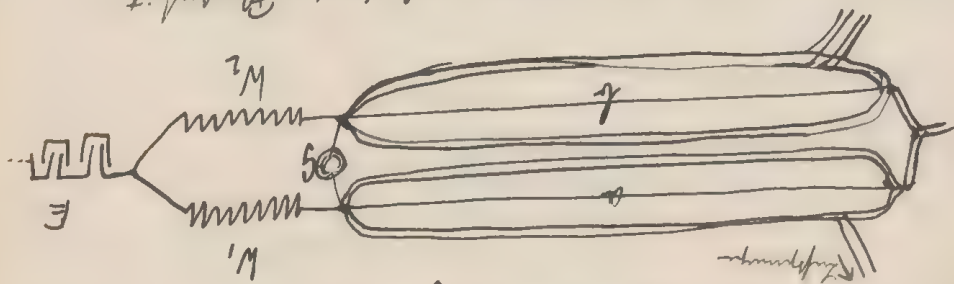
$$\left[\rho \frac{\partial u}{\partial t} + \rho u \frac{\partial u}{\partial x} + \rho v \frac{\partial u}{\partial y} + \rho w \frac{\partial u}{\partial z} + \frac{\partial \rho}{\partial t} u + \frac{\partial \rho}{\partial x} u^2 + \frac{\partial \rho}{\partial y} uv + \frac{\partial \rho}{\partial z} uw \right] dm = 0$$

$$\left[- \left[u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right] + \frac{\mu}{\rho} \left(u \frac{\partial^2 u}{\partial x^2} + v \frac{\partial^2 u}{\partial x \partial y} + w \frac{\partial^2 u}{\partial x \partial z} \right) + \frac{\partial u}{\partial t} \right] dm = 0$$

$$\left[\rho \frac{\partial u}{\partial t} + \rho u \frac{\partial u}{\partial x} + \rho v \frac{\partial u}{\partial y} + \rho w \frac{\partial u}{\partial z} + \frac{\partial \rho}{\partial t} u + \frac{\partial \rho}{\partial x} u^2 + \frac{\partial \rho}{\partial y} uv + \frac{\partial \rho}{\partial z} uw \right] dm = 0$$

[illegible]

Verfahren zur Abgrenzung der Zithelorgane, Impunctur etc.
darstellen mit Impuncturformung von 5000.
(Abbildung nach von Schleiermacher gemacht)



2. und mit 100 g. gelblich, & mit gut leuchtender Phosphoreszenz

di Wiskondah & Henry van a, ^{twint} alle Amery in 5 ~~honderd~~!

erhöhen diesen mehr od. - Nullum Theod., Compensierung durch
Änderung von W_1 , oder Abnahme in α Ätzung und zu messende
Veränderung; Abmessung ~~unter~~^{in Test} in W_1 -Kette durch Dornen
oder Kessel in W_1 und W_2 (oder auch im primären Kreis) durch
Gitterverhältnisse. Wiederkommen von a, b, c möglichst; E. d. dno.

Längs
 des Gang vor Brücken und anderen Bänke (gleiche Art) und
 veränderten Material; bei diesen Gestein ist die Vermehrung
 gewachsen, bei ~~denen~~ oder drinnen (Näheren $\frac{1}{2}$ m) Temperatur-

15 7-8. 6. 108
15

KARL LUZANSKY
WIEN
IV. Wiedner-Hauptstrasse 21
No. 231 80 Blatt
~23

ony i
naciski.

jeszcze za
by motyw
wałe z 28

s tego sztanda-
iactw,

e.
li.

prze-
sz wi-

egłej
czad-

k długo jeszcze

Ale idęm byłoby

aprawiałem, gdyby naród

nasz nie ciążył na decyzjach w każdej
fazie, jaką przynosią zawikłania orężne

i dyplomatyczne. Dlatego oczekiwac

dziemy w tej chwili głosu G

su nie tylko odczuć to, ale po-

go, który powinien odezwać się z

łą przekonania, że przyszłość na-

wymaga złączenia Galicyi z powstającą
niepodległą Polską. Mamy nadzieję

że odezwie, i że w rozważaniu bez

padnie z takim naciskiem, jaki go

magają obecne stosunki i dobro Oj-

czyzny.

na 8.
wze. żądań un
innych grup narodu

„Zwłaszcza
przez g. i. y. i.

cze
br. i. i. i.

WYSTAWA

5. maja.

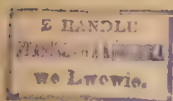
wystaw
prze. P. w. a. l. y. s. e. i. i.

9408

II

112
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130

Thermal effect of effluvia:

N. Sturgeson Weir Am 37 p. 341 (1889)

right addition no sign

~~KB~~

$$\int_V \frac{\partial}{\partial t} \frac{dF}{dt} = \int_V k \frac{\partial \theta}{\partial t} dv = \int_V \left[\frac{c}{A} \frac{\partial \rho}{\partial t} + \rho \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) + f \operatorname{div} - \Phi \right] dv$$

$$0 = \frac{\partial f_{xx}}{\partial x} + \frac{\partial f_{xy}}{\partial y} + \frac{\partial f_{xz}}{\partial z} = -\frac{\partial f}{\partial x} + \frac{\mu}{3} \frac{\partial \text{div}}{\partial x} + \mu V_u^x$$

132

$$f = -\frac{\partial f}{\partial x}$$

$$\frac{\partial f}{\partial x} = \mu \left(\frac{1}{3} \frac{\partial \text{div}}{\partial x} + V_u^x \right)$$

$$r = R \rho \theta$$

$$\frac{\partial f}{\partial y} = \mu \left(\frac{1}{3} \frac{\partial \text{div}}{\partial y} + V_v^y \right)$$

$$\frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} = 0$$

$$\frac{\partial f}{\partial z} = \mu \left(\frac{1}{3} \frac{\partial \text{div}}{\partial z} + V_w^z \right)$$

$$\frac{c}{A} \rho \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) + f \text{div} = \Phi$$

Princ. equations

$$\bar{W}_I = - \iint f (u l + v m + w n) dS = - \iiint \left[\frac{\partial}{\partial x} (\rho u) + \frac{\partial}{\partial y} (\rho v) + \frac{\partial}{\partial z} (\rho w) \right] dv$$

$$\bar{W}_I = \iiint \Phi dv$$

$$\bar{W}_I = -R \iiint \theta \left[\frac{\partial}{\partial x} (\rho u) + \dots \right] + \rho \left[\frac{\partial}{\partial x} (\theta u) + \dots \right]$$

$$= - \iiint R \rho \left[u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + \dots \right] + \rho \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)$$

$$-\bar{W}_I = \iiint \Phi + (R - \frac{c}{A}) \iiint \rho \left(u \frac{\partial \theta}{\partial x} + \dots \right)$$

$$= \underbrace{\iiint \rho (u l + v m + w n) dS}_{= (1 - \frac{c}{AR}) \iiint f (u l + v m + w n) dS}$$

$$-\bar{W}_I = (k-1) \bar{W}_I$$

$$-W_I = \iiint \left(u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + w \frac{\partial f}{\partial z} \right) + f \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) dV$$

2. term:

$$\iiint R \rho \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) dV = \iiint \left(u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + w \frac{\partial f}{\partial z} \right) dV$$

$$\underbrace{\iiint \underbrace{R \rho \theta (u l + v m + w n)}_f}_{= -W_I} dV = -W_I$$

2. term 2 : $\iiint f \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) dV = 0$

$$-W_I = \iiint \left(u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + w \frac{\partial f}{\partial z} \right) dV =$$

$$= \mu \iiint \left(u \nabla^2 u + v \nabla^2 v + w \nabla^2 w \right) dV + \frac{1}{3} \left(u \frac{\partial \operatorname{div}}{\partial x} + v \frac{\partial \operatorname{div}}{\partial y} + w \frac{\partial \operatorname{div}}{\partial z} \right) dV$$

$$= \mu \iiint u \left(\frac{\partial u}{\partial x} l + \frac{\partial u}{\partial y} m + \frac{\partial u}{\partial z} n \right) + v \left(\frac{\partial v}{\partial x} l + \dots \right) + \dots dV +$$

$$+ \frac{1}{3} \iiint \operatorname{div} (u l + v m + w n) dV$$

$$- \iiint \left[\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial y} \right)^2 + \left(\frac{\partial u}{\partial z} \right)^2 + \dots \right. \right.$$

$$\left. + \frac{1}{3} (\operatorname{div})^2 \right] dV$$

$$= \mu \iiint \frac{\partial}{\partial n} \left(\frac{u^2 + v^2 + w^2}{2} \right) dS + \frac{1}{3} \iiint \operatorname{div} dV - \mu \iiint \uparrow$$

2 drugi strony $\bar{W}_{II} = \iiint \Phi dv =$

133

$$\mu \iiint \left(\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial y} \right)^2 + \left(\frac{\partial u}{\partial z} \right)^2 + \dots + \frac{1}{3} (\text{div})^2 \right. \\ \left. + 2 \left[\frac{\partial w}{\partial y} \frac{\partial v}{\partial z} + \frac{\partial u}{\partial z} \frac{\partial v}{\partial x} + \frac{\partial v}{\partial x} \frac{\partial u}{\partial y} - \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} - \frac{\partial v}{\partial y} \frac{\partial u}{\partial z} - \frac{\partial w}{\partial z} \frac{\partial u}{\partial x} \right] dv \right.$$

$$\iiint \left[\frac{\partial u}{\partial y} \frac{\partial v}{\partial z} - \frac{\partial v}{\partial y} \frac{\partial u}{\partial z} \right] dv = \iiint u \left(m \frac{\partial v}{\partial z} - n \frac{\partial v}{\partial y} \right) dV - \iiint u \frac{\partial v}{\partial y \partial z} - \frac{\partial v}{\partial y \partial z} dv$$

$$\iiint \dots = \iiint v \left(n \frac{\partial u}{\partial y} - m \frac{\partial u}{\partial z} \right) dV$$

$$\bar{W}_{II} = \mu \iiint \left(\frac{\partial u}{\partial x} \right)^2 + \frac{1}{3} (\text{div})^2 + \mu \iiint \left\{ u \left(n \frac{\partial w}{\partial x} - l \frac{\partial w}{\partial z} \right) + w \left(l \frac{\partial u}{\partial z} - n \frac{\partial u}{\partial x} \right) + \right. \\ \left. \pm l u \frac{\partial w}{\partial x} \pm m v \frac{\partial w}{\partial y} \pm n w \frac{\partial w}{\partial z} + v \left(l \frac{\partial u}{\partial y} - m \frac{\partial u}{\partial x} \right) + u \left(m \frac{\partial v}{\partial x} - l \frac{\partial v}{\partial y} \right) + w \left(m \frac{\partial v}{\partial z} - n \frac{\partial v}{\partial y} \right) + v \left(n \frac{\partial w}{\partial y} - m \frac{\partial w}{\partial z} \right) \right\} dV$$

zatem jeżeli można zamieścić w tej postaci chrzostu to będzie

$\bar{W}_{II} = \bar{W}_I$ co 2 tamtych warunków tylko study są zgodne' więc

jeżeli $\bar{W}_{II} = \bar{W}_I = 0$

Albo też: natomiast $\iiint f dV = 0$ w

$$\iiint \Phi dv = \frac{c}{A} \iiint \rho \left(u \frac{\partial \theta}{\partial x} + \dots \right) = - \frac{c}{AR} \bar{W}_I \quad \text{to samo co poprzednie}$$

$$\bar{W}_{II} = \mu \iiint \left(\frac{\partial u}{\partial x} \right)^2 + \dots + \frac{1}{3} \text{div}^2 + \mu \iiint \left[u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \left(\frac{\partial u}{\partial x} \right) - \frac{\partial u}{\partial x} \text{div} \right] dV$$

=

$$+ 2 \mu \iiint \left[l v \frac{\partial u}{\partial y} - n \frac{\partial u}{\partial z} + m \frac{\partial u}{\partial x} \right] dV$$

patrz Lamba p. 519

leg motive transform form $\theta = f(\varphi)$

$$\rho = \varphi(\varphi) = \frac{1}{2f(\varphi)}$$

$$\frac{\partial \rho}{\partial x} = \rho \left(V_h + \frac{\partial \ln}{\partial x} \right)$$

$$\frac{\partial \rho}{\partial y} =$$

$$\frac{\partial \rho}{\partial z} =$$

$$\frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} = 0$$

$$II). \frac{c}{A} \rho \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) + \rho \left(\frac{\partial \rho}{\partial x} + \dots \right) = \Phi$$

$$\left[\rho \left(u \frac{\partial u}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial w}{\partial z} \right) = - \left[u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} \right] + \rho \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) \right]$$

$$\frac{c}{A} \rho \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) = \Phi + \left[u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} \right]$$

$$\frac{\partial \theta}{\partial x} = f' \frac{\partial f}{\partial x}$$

$$\frac{c}{AR} \frac{\rho f'}{f} \left(u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + w \frac{\partial f}{\partial z} \right) = \Phi + [\dots]$$

$$\frac{c}{AR} = \frac{k}{k-1}$$

jiel' s'iz izda ismanis adibot yungo: $\rho = c \rho^k$

$$\rho = c' \rho^{\frac{1}{k}} = \frac{1}{k} \rho^{\frac{1}{k}}$$

$$f = \rho^{\frac{1}{k-1}}$$

$$f \sim \rho^{\frac{k-1}{k}}$$

$$\frac{f f'}{f} = \frac{k-1}{k}$$

$$f' \sim \frac{k-1}{k} \rho^{-\frac{1}{k}}$$

$$\text{eater redukcijs} \quad \frac{c}{AR} \frac{f f'}{f} = 1$$

Wise tykko motive jiel' $\Phi = 0$

~~Hydrodynamic~~

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Initial $v = u = 0$:

$$\frac{\partial p}{\partial x} = \mu \left[\frac{1}{3} \frac{\partial^2 u}{\partial x^2} + \nabla^2 u \right]$$

$$\frac{\partial p}{\partial y} = \mu \frac{1}{3} \frac{\partial^2 u}{\partial x \partial y}$$

$$\frac{\partial p}{\partial z} = \mu \frac{1}{3} \frac{\partial^2 u}{\partial x \partial z}$$

$$\frac{\partial(\rho u)}{\partial x} = 0$$

$$\frac{c}{A} \rho u \frac{\partial \theta}{\partial x} + \rho \frac{\partial u}{\partial x} = \Phi_u$$

Hydrodynamic condition:

$$x=0: p_0, p_0$$

$$x=l: p_1$$

$$\frac{\partial p}{\partial x} = \frac{4}{3} \mu \frac{\partial^2 u}{\partial x^2} \quad \left| \frac{u}{u_0} \right. \quad \rho u = \rho_0 u_0$$

$$\frac{c}{A} \rho u \frac{\partial \theta}{\partial x} + \rho \frac{\partial u}{\partial x} = \frac{4}{3} \mu \left(\frac{\partial u}{\partial x} \right)^2$$

$$\frac{c}{A} \frac{\partial \theta}{\partial x} = \frac{1}{k-1} p$$

$$\frac{c}{A} \rho u \frac{\partial \theta}{\partial x} + \frac{\partial(\rho u)}{\partial x} = \frac{4}{3} \mu \left[u \frac{\partial^2 u}{\partial x^2} + \left(\frac{\partial u}{\partial x} \right)^2 \right] = \frac{4}{3} \mu \frac{\partial}{\partial x} \left(u \frac{\partial u}{\partial x} \right)$$

$$p = 2 \rho \theta$$

$$\frac{c}{A} \rho u \theta + \rho u = \frac{4}{3} \mu \frac{\partial u}{\partial x}$$

$$p = \frac{4}{3} \mu \frac{\partial u}{\partial x} + p_0 \quad \uparrow \quad \left\| \frac{c}{A} \rho u \frac{\partial \theta}{\partial x} + \frac{4}{3} \mu \left(\frac{\partial u}{\partial x} \right)^2 + p_0 \frac{\partial u}{\partial x} = \frac{4}{3} \mu \left(\frac{\partial u}{\partial x} \right)^2 \right.$$

$$\frac{c}{A} \rho u \theta + p_0 u = \text{const} = a$$

$$\frac{c}{A R} \rho u + p_0 u = \left(\frac{c}{A R} + 1 \right) p_0 u + \frac{4}{3} \mu \frac{c}{A R} u \frac{\partial u}{\partial x} = a$$

$$\frac{4}{3} \mu u \frac{\partial u}{\partial x} + k p_0 u = (k-1) a$$

$$\frac{4}{3}\mu u \frac{du}{dx} + k p_0 u = (k-1) a \quad \parallel \quad \frac{\frac{4}{3}\mu u du}{(k-1)a - k p_0 u} = dx$$

Substitution: $u = \alpha + z$

$$\frac{4}{3}\mu \alpha \frac{dz}{dx} + \frac{4}{3}\mu z \frac{dz}{dx} + k p_0 \alpha + k p_0 z = (k-1) a$$

$$\alpha = \frac{(k-1)a}{k p_0}$$

$$\frac{4}{3}\mu z \frac{dz}{dx} + \frac{4}{3}\mu \alpha \frac{dz}{dx} + k p_0 z = 0$$

$$\frac{4}{3}\mu \frac{dz}{dx} + \frac{4}{3}\mu \alpha \frac{d \log z}{dx} + k p_0 = 0$$

$$\frac{4}{3}\mu z + \frac{4}{3}\mu \alpha \log z + k p_0 x = b$$

$$\frac{4}{3}\mu (u - \alpha) + \frac{4}{3}\mu \alpha \log(u - \alpha) + k p_0 x = b \quad \text{erset } \alpha \text{ durch seinen Wert}$$

$$\frac{4}{3}\mu \log \left[e^{u-\alpha} (u-\alpha)^\alpha \right] = b - k p_0 x$$

$$\frac{\mu u}{k-1} + p_0 u$$

$$= \frac{k p_0}{k-1} \alpha$$

$$p = p_0 + \frac{4}{3}\mu \frac{du}{dx}$$

$$e^{u-\alpha} (u-\alpha)^\alpha = e^{\frac{b - k p_0 x}{\frac{4}{3}\mu}}$$

$$e^u (u-\alpha)^\alpha = B e^{-\frac{3}{4} \frac{k p_0}{\mu} x}$$

~~$$e^u (u-\alpha)^\alpha = B e^{-\frac{3}{4} \frac{k p_0}{\mu} x}$$~~

$$e^{u + \frac{3}{4} \frac{k p_0}{\mu} x} (u-\alpha)^\alpha = B$$

Wzrost eliminacji: $\theta = \frac{\mu}{R\rho}$

$$\rho \frac{dn}{dx} + n \frac{d\rho}{dx} = 0 \quad 135$$

$$\frac{c}{AR} \rho n \left[\frac{1}{\rho} \frac{d\rho}{dx} - \frac{\rho}{\rho^2} \frac{d\rho}{dx} \right] + \rho \frac{dn}{dx} = \frac{4}{3} \mu \left(\frac{dn}{dx} \right)^2$$

$$-\frac{1}{\rho} \frac{d\rho}{dx} = + \frac{1}{n} \frac{dn}{dx}$$

$$\left. \begin{aligned} \frac{c}{AR} \left[n \frac{d\rho}{dx} + \rho \frac{dn}{dx} \right] + \rho \frac{dn}{dx} &= \frac{4}{3} \mu \left(\frac{dn}{dx} \right)^2 \\ \frac{d\rho}{dx} &= \frac{4}{3} \mu \frac{dn}{dx^2} \end{aligned} \right\}$$

Zatem ~~z~~ 3 stale do
opraczenia ρ, n
a jednocześnie do θ lub ρ

Stale masy i potencjału w tej postaci energii:

$$u = u_1 : x = 0$$

$$u = u_2 : x = l$$

$$b = \frac{4}{3} \mu \log e^{u_1 - \alpha} (u_1 - \alpha)^\alpha$$

$$\frac{4}{3} \mu \log \left[e^{u - u_1} \cdot \left(\frac{u - \alpha}{u_1 - \alpha} \right)^\alpha \right] = -k \rho_0 x$$

$$k \rho_0 x = \frac{4}{3} \mu \log \left[e^{u_1 - u} \left(\frac{u_1 - \alpha}{u - \alpha} \right)^\alpha \right]$$

$$k \rho_0 l = \frac{4}{3} \mu \log \left[e^{-u_1 - u_2} \left(\frac{u_1 - \alpha}{u_2 - \alpha} \right)^\alpha \right]$$

$$\frac{x}{l} = \frac{\log}{\log} = \frac{(u_1 - u) + \alpha \log(u_1 - \alpha) - \alpha \log(u - \alpha)}{(u_1 - u_2) + \alpha \log(u_1 - \alpha) - \alpha \log(u_2 - \alpha)}$$

$$\left[e^{(u_1 - u_2) + \alpha \log \left(\frac{u_1 - \alpha}{u_2 - \alpha} \right)} \right] = e^{(u_1 - u) + \alpha \log \left(\frac{u_1 - \alpha}{u - \alpha} \right)}$$

$$\left\| \begin{aligned} \alpha &= \text{prędkość dla } x \rightarrow \infty \\ \rho_0 \alpha + (k-1) \rho_0 \alpha &= k \rho_0 \alpha \\ \rho_0 \alpha &= \rho_0 \end{aligned} \right.$$

$$\left(\frac{dn}{dx} \right)_{\infty} = 0$$

$$p = p_{\infty} \frac{k\alpha - (k+1)u}{u} = p_{\infty} \left(k \frac{\alpha}{u} - k+1 \right) = p_{\infty} \left[1 + k \left(\frac{\alpha}{u} - 1 \right) \right]$$

$$u \leq \alpha$$

$$k p_{\infty} x = \frac{4}{3} \mu \log \left[e^{\frac{u_1 - u}{\alpha - u_1}} \left(\frac{\alpha - u_1}{\alpha - u} \right)^{\alpha} \right]$$

$$x=0 : u = u_1$$

$$x=\infty : u = \alpha$$

$$x=\infty : p = p_{\infty}$$

$$p u = \text{const}$$

$$\frac{p}{\theta} u = \text{const} = \frac{p_{\infty} \alpha}{\theta_{\infty}}$$

$$\theta = \frac{p u}{p_{\infty} \alpha} \theta_{\infty} = \theta_{\infty} \cdot \frac{u + k(\alpha - u)}{\alpha} = \theta_{\infty} \left[k - (k-1) \frac{u}{\alpha} \right]$$

$$\frac{4}{3} \mu \frac{du}{dx} = p - p_{\infty}$$

Więc istotnie: jeżeli $u_1 < u < \alpha$

$$\text{to: } 0 < x < \infty$$

$$p_{\infty} \left[1 + k \left(\frac{\alpha}{u} - 1 \right) \right] > p > p_{\infty}$$

$$> \frac{du}{dx} > 0$$

$$\theta_{\infty} \left[k - (k-1) \frac{u}{\alpha} \right] > \theta > \theta_{\infty}$$

$$\frac{2}{3} \frac{p_{\infty} \alpha}{\mu}$$

$$\log(1-x) = -x - \frac{x^2}{2} - \frac{x^3}{3}$$

$$\frac{p}{p_{\infty}} = \frac{u_0}{u}$$

$$x = \frac{\frac{2}{3} (u^2 - u_0^2)}{p_{\infty} u}$$

Więc dane muszą być 4 warunkami!

Wypiszmy wzorek p i θ :

$$\frac{1}{k} \frac{p - p_{\infty}}{p_{\infty}} = \left(\frac{\alpha}{u} - 1 \right)$$

$$\frac{u}{\alpha} = \frac{1}{1 + \frac{1}{k} \left(\frac{p}{p_{\infty}} - 1 \right)}$$

$$\frac{p u}{\theta} = \text{const} = \frac{p_{\infty} u_0}{\theta_{\infty}} \parallel \theta = \text{const}$$

$$x = \frac{2}{3} \frac{u_0}{p_{\infty}} \left[1 - \left(\frac{u_0}{u} \right)^2 \right]$$

$$= \frac{2}{3} \frac{u_0}{p_{\infty}} \left[1 - \left(\frac{u_0}{u} \right)^2 \right] = \frac{2}{3} \frac{u_0}{p_{\infty}} \left[1 - \left(\frac{p_{\infty}}{p} \right)^2 \right]$$

$$= \frac{2}{3} \frac{u_0}{p_{\infty}} \left[\frac{p}{p_{\infty}} - \frac{p_{\infty}}{p} \right]$$

$$\theta = \theta_{\infty} \left[k - \frac{k-1}{1 + \frac{1}{k} \left(\frac{k}{p_{\infty}} - 1 \right)} \right] = \theta_{\infty} \frac{k + \frac{k}{p_{\infty}} - 1 - k + 1}{1 - \frac{1}{k} + \frac{1}{k} \frac{k}{p_{\infty}}}$$

$$= \theta_{\infty} \frac{\frac{k}{p_{\infty}}}{k-1 + \frac{k}{p_{\infty}}}$$

Zudem: $p_{\infty} = p \frac{k}{k-1 + \frac{k}{p_{\infty}}}$

$$\rho = \rho_{\infty} \left[\frac{k-1}{k} + \frac{p}{k p_{\infty}} \right]$$

$$u_0 = 300.00 \quad p_0 = 1 \text{ atm} = 10^6$$

$$\frac{p}{p_0} = \frac{1}{2} \quad x = \frac{9}{4} \frac{3}{100} = \frac{27}{400} = 0.0675 \text{ cm}$$

$$\frac{p}{p_0} = \frac{1}{10} \quad x = \frac{9}{4} \frac{100}{100} = \frac{9}{4} = 0.225 \text{ cm}$$

Lambert's law: $p_{01} = p_{\infty} \left[1 + k \left(\frac{\alpha}{u_0} - 1 \right) \right]$

$$\frac{p_{\infty}}{p_0}$$

$$\frac{u_0}{u_1}$$

$$\frac{\theta_0}{\theta_1}$$

lim $p_{\infty} = 0$: $u_0 = \infty$ $\frac{\alpha}{u_0} = 0$

$$\frac{p_0}{p} = \lim_{\alpha \rightarrow \infty} \frac{1 + k \left(\frac{\alpha}{u_0} - 1 \right)}{1 + k \left(\frac{\alpha}{u_1} - 1 \right)} = \frac{u_1}{u_0} \quad \parallel \quad \lim_{\alpha \rightarrow \infty} \log \left(\frac{\alpha - u_1}{\alpha - u_0} \right)^{\alpha} = \log \left(\frac{1 - \frac{u_1}{\alpha}}{1 - \frac{u_0}{\alpha}} \right)^{\alpha}$$

$$= \log \left(1 + \frac{u_0 - u_1}{\alpha} \right)^{\alpha} = (u_0 - u_1)$$

$$k p_{\infty} x = \frac{4}{3} \left[\log \left(\frac{\alpha - u_1}{\alpha - u_0} \right) + \frac{u_0 - u_1}{\alpha} \right]$$

$$p_{\infty} = \frac{p_0}{1 + k \left(\frac{\alpha}{u_1} - 1 \right)} \quad \parallel \quad k p_{\infty} x = \frac{4}{3} p_0 \left[1 + k \left(\frac{\alpha}{u_1} - 1 \right) \right] \left\{ u_1 - u_0 + \alpha \left[\log \left(\frac{\alpha - u_1}{\alpha - u_0} \right) - \log \left(\frac{\alpha - u_1}{\alpha - u_0} \right) \right] \right\}$$

$$\log \frac{k p_{\infty} x}{\frac{4}{3} p_0} = \frac{u_1 - u_0 + \alpha \left[\log \frac{\alpha - u_1}{\alpha - u_0} - \log \frac{\alpha - u_1}{\alpha - u_0} \right]}{\frac{1}{1 + k \left(\frac{\alpha}{u_1} - 1 \right)}} = \frac{\log \frac{\alpha - u_1}{\alpha - u_0} + \frac{\alpha}{u_1} \left(\frac{1}{\alpha - u_1} - \frac{1}{\alpha - u_0} \right)}{1 + k \left(\frac{\alpha}{u_1} - 1 \right)}$$

$$= -\frac{u_1}{\alpha} + \frac{1}{2} \left(\frac{u_1}{\alpha} \right)^2 + \frac{4}{\alpha} - \frac{1}{2} \left(\frac{u_1}{\alpha} \right)^2 + x + \frac{4}{\alpha} + \left(\frac{u_1}{\alpha} \right)^2 - x - \frac{4}{\alpha} - \left(\frac{u_1}{\alpha} \right)^2 \quad \left(\frac{k}{u_1} \right)^2 \alpha^2$$

$$= -\frac{k}{u_1} \frac{2}{2} (u_1^2 - u_0^2)$$

$$\frac{k}{u_1}$$

Przykład

Ruchy parcia nieskompresyjnego, zmiennego: ρ, p, T .

$$\begin{array}{l} \rho \frac{\partial u}{\partial t} = -\frac{\partial p}{\partial x} + \frac{\mu}{3} \frac{\partial \text{div}}{\partial x} + \mu \nabla^2 u \\ \rho \frac{\partial v}{\partial t} = \\ \rho \frac{\partial w}{\partial t} = \end{array} \quad \left| \begin{array}{l} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{array} \right| \quad \left| \begin{array}{l} \frac{\partial}{\partial y} \\ -\frac{\partial}{\partial x} \\ \end{array} \right|$$

$$\frac{\mu}{3} \nabla^2 \text{div} v + \mu \nabla^2 \text{div} v = 0$$

$$\nabla^2 \text{div} v = 0$$

$$\nabla^2 \xi = \nabla^2 \eta = \nabla^2 \zeta = 0$$

$$\nabla^2 \text{curl} v = 0$$

$$\nabla^2 \text{curl} v = 0$$

$$v = \nabla \psi + \text{curl} v$$

$$\nabla^2 v = 0$$

Jżeli prędkość jest taka, że $\text{div} v = 0$ i $\text{curl} v = 0$ to v jest irrotacyjny i bezdivergencyjny, wtedy: ruch taki jak ciepły nieskompresyjny z potencjałem prędkości:

[nie ma zjawisk skrzyżowania!
ruch wzdłuż linii prędkości]

$$u = \frac{\partial \psi}{\partial x} \quad v = \frac{\partial \psi}{\partial y} \quad w = \frac{\partial \psi}{\partial z}$$

$$\text{div} v = \frac{\partial u}{\partial x} + \dots = \nabla^2 \psi = 0$$

$$\nabla^2 u = \frac{\partial^2}{\partial x^2} \nabla^2 \psi = 0$$

N. p. kula w prędkości

$$\varphi = \frac{a}{r} \quad u = -\frac{x}{r^3} a \quad v = -\frac{y}{r^3} a \quad w = -\frac{z}{r^3} a$$

$$\frac{\partial u}{\partial x} = \left(-\frac{1}{r^3} + \frac{3x^2}{r^5} \right) a = \frac{a}{r^5} \left(-1 + \frac{3x^2}{r^2} \right)$$

To byłoby niezgodne z nierównością bycia nieodwracalnego

ciągłego, ale to wynika z prędkości: bo $\text{curl} v$ nie będzie 0 na powierzchni $\text{div} v$ jest potencjałem

Równanie wypływu tutaj nie ma sensu, bo robimy linie $\rho=0$ tylko wtedy, gdy $\rho \neq 0$ a wtedy musimy mieć jakiś wykładnik potęgowa funkcji.

Równanie ~~to~~ ustawić się wskazać prowadzącego w tym tutaj dążyć do tego, żebyśmy w rachuby, to jest być:

$$\kappa \nabla^2 \theta = \Phi$$

linia skrajna
kierunek i nie są przeciwnymi!

~~Np. kółko o promieniu~~

$$\varphi = \frac{ca^2 x}{r^3} \quad \frac{\partial \varphi}{\partial x} = \frac{ca^2}{r^3} \left[1 - \frac{3x^2}{r^2} \right] = u$$

$$\frac{\partial \varphi}{\partial y} = \frac{3ca^2 xy}{r^5} = v$$

$$\operatorname{div} v = - \frac{1}{r^3} \frac{\partial}{\partial r} (r^3 v_r)$$

$$- \frac{1}{r^3} \frac{\partial}{\partial r} (r^3 v_r)$$

$$\frac{\partial \varphi}{\partial z} = \frac{3ca^2 xz}{r^5} = v$$

$$v = \nabla \varphi + \nabla \int \frac{\operatorname{div} v}{r} dr + \operatorname{curl} \int \frac{\operatorname{curl} v}{r} dr$$

$$\nabla^2 \operatorname{div} v = \operatorname{div} \nabla^2 v \quad ? \quad \nabla \operatorname{curl} v = \operatorname{curl} \nabla^2 v$$

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) \Big| \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + \dots$$

$$\text{zatem Resultat: } \operatorname{div} \nabla^2 v = 0$$

$$\operatorname{curl} \nabla^2 v = 0$$

$$\therefore \nabla^2 v = \nabla u$$

fuzyjnie drzewa!

$$\nabla^2 v = -\frac{1}{3} \nabla \operatorname{div} v$$

$$\nabla \operatorname{div} v = \operatorname{curl}^2 v$$

$$\operatorname{curl}^2 v = \frac{4}{3} \nabla \operatorname{div} v$$

$$u = -\frac{1}{3} \operatorname{div} v$$

K₇. d'ok planiny

$$v = \omega = 0$$

$$dw = 0$$

$$\frac{1}{3} \frac{\partial^2 u}{\partial x^2} + \frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} = 0$$

$$\frac{1}{3} \frac{\partial u}{\partial x^2} = 0$$

$$\frac{1}{3} \frac{\partial u}{\partial y^2}$$

$$\neq 0$$

$$\left\{ \begin{array}{l} \frac{\partial u}{\partial x} = f(x) \\ \text{při } x=c \end{array} \right.$$

při planym $x=c$

$$\frac{\partial u}{\partial x} = 0$$

$$u = \frac{y}{\delta} c$$

$$\frac{\partial u}{\partial y} = \frac{c}{\delta}$$

$$\Phi = \mu \left(\frac{\partial u}{\partial y} \right)^2 = \mu \frac{c^2}{\delta^2}$$

$$-K \frac{\partial^2 \theta}{\partial y^2} = \mu \frac{c^2}{\delta^2}$$

$$\frac{d\theta}{dy} = -\frac{\mu}{K} \frac{c^2}{\delta^2} y + a$$

$$\theta = -\frac{\mu}{K} \frac{c^2}{\delta^2} \frac{y^2}{2} + ay + \theta_0$$

$$\theta_0 = -\frac{\mu}{K} \frac{c^2}{\delta^2} \frac{\delta^2}{2} + a\delta + \theta_0$$

$$\theta - \theta_0 = \frac{\mu}{K} \frac{c^2}{\delta^2} \frac{y^2 \delta^2}{2}$$

$$a = -\frac{\mu}{K} \frac{c^2}{\delta^2} \frac{\delta}{2}$$

$$\theta = \frac{\mu}{K} \frac{c^2}{\delta^2} \frac{y(\delta-y)}{2} + \theta_0$$

$$\text{Maximum: } y = \frac{\delta}{2} \quad \theta = \frac{\mu}{K} \frac{c^2}{8} + \theta_0$$

Nikolai 2 p'uboz vartoy K₇.

$$\mu = 0.00017$$

$$K = 42 \cdot 10^6 \cdot 0.000057$$

$$\frac{\mu}{8K} = \frac{1.7 \cdot 10^{-4}}{8 \cdot 42 \cdot 0.57 \cdot 10^2} = 10^{-8}$$

$$\text{Wize dop'ino jazy } \theta = 10^{-4} \frac{\mu}{K}$$

Wzrostle ~~z~~ przy terminowaniu białek bardzo nieznaczny, przy zwykłym 138
 przykroćcie

$$\frac{1}{3} \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} = 0$$

$$\frac{1}{3} \frac{\partial}{\partial y} (\quad) + \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} = 0$$

$$\frac{1}{3} \frac{\partial}{\partial z} (\quad) + \frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} = 0$$

$$\iint_S \frac{dS \cos \alpha}{r}$$



$$\frac{4\pi}{3} r^3 + \frac{4}{3} \frac{\partial}{\partial r} r^2$$

$$r \left(\frac{8\pi}{3} - 4 \right) = -\frac{4}{3} r$$

Stwierdza dodatkowo $\text{div } v = U = f(x, y, z)$ otrzymuje się

$$w = -\frac{1}{3} \int \frac{\partial U}{\partial z} dz + A_3$$

$$v = -\frac{1}{3} \int \frac{\partial U}{\partial y} dy + A_2$$

$$u = -\frac{1}{3} \int \frac{\partial U}{\partial x} dx + A_1$$

$$v = -\frac{1}{3} \int \frac{\partial U}{\partial y} dy + A_2$$

$$\nabla^2 U = 0$$

$$\text{div } U = 0$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = -\frac{1}{3} \int \frac{\nabla^2 U}{r} dz + \frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z}$$

$$\nabla^2 u = -\frac{1}{3} \int \frac{\partial (\nabla^2 U)}{\partial x} dz + \frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} = 0$$

$$\frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} = 0$$

2

Ad. -

wygodniej w notacji tensor:

dla notacji: $T_I = \iint u \frac{\partial}{\partial x} + \dots$

$$\begin{aligned} & \iint \rho u \left[u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right] + \\ & + v \left[u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right] + \\ & + w \left[u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} \right] dv = \iint \rho \left(u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) \cdot \frac{u^2 + v^2 + w^2}{2} dv \end{aligned}$$

$$= - \iint \frac{u^2 + v^2 + w^2}{2} \rho (u l + v m + w n) dV + \iint \frac{u^2 + v^2 + w^2}{2} \rho \left[\frac{\partial}{\partial x} (p u) + \frac{\partial}{\partial y} (p v) + \frac{\partial}{\partial z} (p w) \right]$$

Wzrost się stądże tak samo

Całki podane są

$$\begin{aligned} & \iint u \left(n \frac{\partial w}{\partial x} - l \frac{\partial w}{\partial z} + m \frac{\partial v}{\partial x} - l \frac{\partial v}{\partial y} \right) + \dots \\ & \pm l \frac{\partial u}{\partial x} \end{aligned}$$

$$\begin{aligned} & = \iint u \frac{\partial}{\partial x} (l u + m v + n w) - l u \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) \\ & + v \frac{\partial}{\partial y} \quad - m v (\quad) \\ & + w \frac{\partial}{\partial z} \quad - n w (\quad) \end{aligned}$$

$$= \iint \left[\left(u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) v_n - v_n \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) \right] dV$$

rotur u coloni:

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$$W_{II} = W_I + \mu \int \left[\frac{\partial}{\partial n} \left(\frac{u^2 + v^2 + w^2}{2} \right) + \frac{1}{3} v_n \operatorname{div} v + \left(u \frac{\partial}{\partial x} + \dots \right) v_n - v_n \operatorname{div} v \right] dS$$

$$W_{II} = W_I + \mu \int \left[\frac{\partial}{\partial n} \left(\frac{v^2}{2} \right) + (\nabla v) \cdot \nabla v - \frac{2}{3} \operatorname{div} v \nabla v \cdot n \right] dS$$

$$W_{II} = -W_I$$

$$0 = W_I \left(1 + \frac{1}{k-1} \right) + \mu \int$$

$$W_I = -\frac{k-1}{k} \mu \int$$

$$W_{II} = \frac{1}{k} \mu \int \left[u \frac{\partial u}{\partial x} + v \frac{\partial v}{\partial x} + w \frac{\partial w}{\partial x} + u \frac{\partial u}{\partial y} + v \frac{\partial v}{\partial y} + w \frac{\partial w}{\partial y} - \frac{2}{3} u \left[\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right] \right]$$

$$= \frac{\mu}{k} \int \left[\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial x} \right)^2 + \left(\frac{\partial w}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial y} \right)^2 + \left(\frac{\partial v}{\partial y} \right)^2 + \left(\frac{\partial w}{\partial y} \right)^2 + \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + \frac{\partial v}{\partial x} \frac{\partial u}{\partial y} - \frac{2}{3} \frac{\partial u}{\partial x} \left[\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right] \right]$$

$$+ u \frac{\partial^2 u}{\partial x^2} + v \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 u}{\partial x \partial y} \right) + w \left(\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 u}{\partial x \partial z} \right) - \frac{2}{3} u \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial x \partial y} + \frac{\partial^2 w}{\partial x \partial z} \right)$$

$$u \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) + \frac{1}{3} \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} + \frac{\partial u}{\partial z} \right) = \frac{2}{3} u \frac{\partial}{\partial x} \left(\dots \right)$$

$$u \frac{\partial u}{\partial x}$$

$$\frac{1}{k} \left[\Phi + u \frac{\partial \Phi}{\partial x} + v \frac{\partial \Phi}{\partial y} + w \frac{\partial \Phi}{\partial z} \right] = \Phi$$

$$u \frac{\partial \Phi}{\partial x} + v \frac{\partial \Phi}{\partial y} + w \frac{\partial \Phi}{\partial z} = (k-1) \Phi$$

by the adjoint result?

Two dimensional prob.

$$\begin{aligned} u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} &= - \frac{\partial \phi}{\partial x} + \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) \\ u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} &= - \frac{\partial \phi}{\partial y} + \mu \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) \end{aligned} \quad \left| \begin{array}{l} \frac{\partial}{\partial y} \\ \frac{\partial}{\partial x} \end{array} \right.$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} = f$$

$$u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} = \mu \left(\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} \right)$$

$$\frac{\partial u}{\partial x} \frac{\partial f}{\partial x} + \frac{\partial v}{\partial x} \frac{\partial f}{\partial y} + u \frac{\partial f}{\partial x^2} + v \frac{\partial f}{\partial x \partial y} = \mu \frac{\partial^2 f}{\partial x^2}$$

$$\frac{\partial u}{\partial y} \frac{\partial f}{\partial x} + \frac{\partial v}{\partial y} \frac{\partial f}{\partial y} + u \frac{\partial f}{\partial x \partial y} + v \frac{\partial f}{\partial y^2} = \mu \frac{\partial^2 f}{\partial y^2}$$

$$\frac{\partial u}{\partial x} \frac{\partial f}{\partial y} - \frac{\partial v}{\partial y} \frac{\partial f}{\partial x} + u \frac{\partial f}{\partial x^2} + v \frac{\partial f}{\partial x \partial y} = \mu \frac{\partial^2 f}{\partial x^2}$$

$$\frac{\partial u}{\partial x} \frac{\partial f}{\partial x} + \frac{\partial u}{\partial y} \frac{\partial f}{\partial y} + \frac{\partial v}{\partial x} \frac{\partial f}{\partial y} + \frac{\partial v}{\partial y} \frac{\partial f}{\partial x} + u \frac{\partial^2 f}{\partial x^2} + v \frac{\partial^2 f}{\partial x \partial y} =$$

$$\frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} - u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} = - \frac{\partial \phi}{\partial x} + \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} - u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} = - \frac{\partial \phi}{\partial y} + \mu \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right)$$

By continuity:

$$u = \frac{\partial \psi}{\partial y}$$

$$v = - \frac{\partial \psi}{\partial x}$$

$$\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} = 0$$

$$f = - \left(\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} \right)$$

$$\frac{\partial \psi}{\partial y} \frac{\partial}{\partial x} \left(\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} \right) - \frac{\partial \psi}{\partial x} \frac{\partial}{\partial y} \left(\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} \right) = \mu \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \left(\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} \right)$$

$$v = \nabla \cdot + \text{curl}$$

$$\begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F & G & H \end{vmatrix}$$

$$u = \frac{\partial H}{\partial x} + \frac{\partial G}{\partial y}$$

$$v = \frac{\partial H}{\partial y} - \frac{\partial G}{\partial x}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0 \Rightarrow \nabla \cdot u + \frac{\partial}{\partial y} (H - G) = 0$$

$$f = - \left(\frac{\partial^2 G}{\partial x^2} + \frac{\partial^2 H}{\partial y^2} \right)$$

Do p. badno natf. lwa stwa hydric mari = 0

$$\text{zatem } \frac{\delta \varphi}{\delta x} + \frac{\delta \varphi}{\delta y} = f(\varphi)$$

zatem prava stwa:

$$\left(\frac{\delta}{\delta x} + \frac{\delta}{\delta y} \right) f(\varphi) = 0 \quad \text{Myślenie! dowód!}$$

Ata moim sposobem rozwinięci:

$$\varphi = \varphi_0 + \mu \left(\frac{\partial \varphi}{\partial \mu} \right)_0 \quad \varphi = f(x, y, \mu)$$

$$\varphi(x, y, \mu) = \varphi(x, y, \mu=0) + \mu \left[\frac{\partial \varphi(x, y, \mu)}{\partial \mu} \right]_{\mu=0}$$

$$v = 4.70$$

$$\frac{\partial f}{\partial x} = \mu \left[\frac{1}{3} \frac{\partial^2 u}{\partial x^2} + V u \right]$$

$$\frac{\partial f}{\partial y} = \mu \frac{1}{3} \frac{\partial^2 u}{\partial x \partial y}$$

$$\frac{\partial f}{\partial z} = \mu \frac{1}{3} \frac{\partial^2 u}{\partial x \partial z}$$

$$\frac{\partial}{\partial x}(\rho u) = 0$$

$$\rho u = f(y, z)$$

$$u \frac{\partial \rho}{\partial x} + \rho \frac{\partial u}{\partial x} = 0$$

$$\frac{c}{A} \rho u \frac{\partial \theta}{\partial x} + f \frac{\partial u}{\partial x} = \Phi$$

$$\frac{\partial f}{\partial x \partial y}$$

$$\frac{\partial}{\partial y}(\nabla^2 u) = 0$$

$$\frac{\partial}{\partial z}(\nabla^2 u) = 0$$

$$\nabla^2 u = f(x)$$

$$\mu = \frac{1}{3} \theta$$

$$\theta = \frac{\mu}{R_e}$$

$$\frac{1}{3} \mu$$

$$\nabla^2 f = \frac{4}{3} \mu \frac{\partial}{\partial x}(\nabla^2 u)$$

$$\nabla^2 f = \frac{4}{3} \mu \frac{\partial^2 u}{\partial x^2}$$

$$\frac{c}{AR} \rho u \left[\frac{1}{\rho} \frac{\partial f}{\partial x} - \frac{f}{\rho^2} \frac{\partial \rho}{\partial x} \right] + f \frac{\partial u}{\partial x} = \Phi$$

$$\frac{c}{AR} \left[u \frac{\partial f}{\partial x} - \frac{f u}{\rho} \frac{\partial \rho}{\partial x} \right] + f \frac{\partial u}{\partial x} = \Phi$$

$$\frac{c}{AR} u \frac{\partial f}{\partial x} + \left[\frac{c}{AR} + 1 \right] f \frac{\partial u}{\partial x} = \Phi$$

$$u \frac{\partial f}{\partial x} + k f \frac{\partial u}{\partial x} = (k-1) \Phi$$

$$f = \frac{\mu}{3} \frac{\partial u}{\partial x} + \varphi(x)$$

$$\frac{\mu}{3} \frac{\partial^2 u}{\partial x^2} + \frac{\partial \varphi}{\partial x} = \frac{\mu}{3} \frac{\partial^2 u}{\partial x^2} + \mu \nabla^2 u$$

$$\nabla^2 f = \frac{\mu}{3} \frac{\partial}{\partial x}(\nabla^2 u) + \nabla^2 \varphi = \frac{4}{3} \mu \frac{\partial}{\partial x}(\nabla^2 u)$$

$$\nabla^2 \varphi = \frac{\partial^2 \varphi}{\partial x^2} = \mu \frac{\partial}{\partial x}(\nabla^2 u)$$

$$\frac{\partial \varphi}{\partial x} = \mu \nabla^2 u + \text{const}$$

$$\varphi(x) = \mu \int \nabla^2 u dx$$

symplectic geometry
 $\mu = \frac{4}{3} \mu \frac{\partial^2 u}{\partial x^2} + c$

$$\frac{4}{3}\mu u \frac{\partial u}{\partial x^2} + k \frac{4}{3}\mu \left(\frac{\partial u}{\partial x}\right)^2 + kc \frac{\partial u}{\partial x} = (k-1) \left[\frac{4}{3} \left(\frac{\partial u}{\partial x}\right)^2 + \left(\frac{\partial u}{\partial y}\right)^2 + \left(\frac{\partial u}{\partial z}\right)^2 \right]$$

$$\left. \frac{4}{3}\mu \left(\frac{\partial u}{\partial x^2} + \frac{\partial u}{\partial y^2} + \frac{\partial u}{\partial z^2}\right) = f(x) \right\}$$

$$u = a_0 + a_1 x + a_2 x^2 + b_1 y + \frac{c_1 y^2}{2} + \frac{c_2 z^2}{2}$$

$$v = w = 0 \quad \text{hydrodynamic}$$

$$\rho u \frac{\partial u}{\partial x} = - \frac{\partial p}{\partial x} + \dots$$

$$\rho u = \text{const}$$

$$\frac{c}{A} \rho u \frac{\partial \theta}{\partial x} + \mu \frac{\partial u}{\partial x} = 0$$

$$p = R \rho \theta$$

$$\frac{c}{A} \rho_0 u_0 \frac{d\theta}{dx} + (\rho_0 - u \rho_0 u_0) \frac{du}{dx} = 0$$

$$\frac{c}{A} \rho_0 u_0 \theta + \rho_0 u - \rho_0 u_0 \frac{u^2}{2} = a$$

$$\frac{c}{AR} u \mu$$

$$= \frac{c}{AR} u (\rho_0 - \rho_0 u_0 u)$$

$$u^2 \left[\frac{c}{AR} + \frac{1}{2} \right] \rho_0 u_0 - u \left[\frac{c}{AR} + 1 \right] \rho_0 = a$$

$$\frac{1}{k-1}$$

$$u^2 (k+1) \rho_0 u_0 - 2u k \rho_0 = A$$

$$\mu \frac{\partial u}{\partial x} = \frac{c}{A} \frac{\partial p}{\partial x}$$

$$\rho_0 u_0 \frac{\partial u}{\partial x} = - \frac{\partial p}{\partial x}$$

$$\rho_0 u_0 u + p = p_0$$

$$\frac{c}{A} \rho_0 u_0 \theta + R \rho_0 \theta = 0$$

$$\frac{c}{AR} \frac{d\theta}{dx} + \frac{d}{dx} = 0$$

$$\frac{p}{p_0} = \left(\frac{u_0}{u} \right)^k$$

$$p = p_0 \left(\frac{u_0}{u} \right)^k$$

$$\rho_0 u_0 \cdot u + p_0 \left(\frac{u_0}{u} \right)^k = p_0$$

$$?$$

$$u = \text{const.}!$$

$$\frac{dp}{dx} = \frac{4}{3} \mu \frac{d^2 u}{dx^2}$$

$$\frac{d}{dx}(\rho u) = 0$$

$$\frac{c}{A} \rho u \frac{d\theta}{dx} + \rho \frac{du}{dx} = \frac{4}{3} \mu \left(\frac{du}{dx} \right)^2$$

$$u = \mu \theta$$

Wytyczne kulisty

$$u = 1 \cdot \frac{x}{r} \quad v = 1 \cdot \frac{y}{r} \quad w = 1 \cdot \frac{z}{r}$$

$$= x \varphi \quad = y \varphi \quad = z \varphi$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 3\varphi + \varphi' r$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} = 4\varphi' \frac{x}{r} + \varphi'' x$$

$$\frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \dots \right) = 4\varphi' \frac{x}{r} + \varphi'' x$$

$$\frac{d\varphi}{dx} = \frac{d\varphi}{dr} \frac{x}{r} = \frac{4}{3} \mu \left[4\varphi' \frac{x}{r} + \varphi'' x \right]$$

$$= \frac{4}{3} \mu \frac{d}{dr} [3\varphi + r\varphi'] \cdot \frac{x}{r}$$

$$I). \quad p = \frac{4}{3} \mu [3\varphi + r\varphi'] + p_0$$

$$II). \quad 4\pi r^2 \varphi r \rho = \text{const}$$

$$\varphi \rho r^3 = \text{const}$$

$$\rho d(\varphi r^3) + \varphi r^3 d\rho = 0$$

$$\rho (\varphi' r^3 + 3r^2 \varphi) + \varphi r^3 \frac{d\rho}{dr} = 0$$

$$(3\varphi + \varphi' r) + \varphi r \frac{1}{\rho} \frac{d\rho}{dr} = 0$$

$$III). \quad \frac{4}{A} \rho \left[x\varphi \frac{x}{r} \frac{d\varphi}{dr} + y\varphi \frac{y}{r} \frac{d\varphi}{dr} + \dots \right] + \mu [3\varphi + \varphi' r] = \Phi$$

$$\Phi =$$

$$\frac{\partial u}{\partial x} = \varphi + \varphi' \frac{x^2}{r}$$

$$\frac{\partial^2 u}{\partial x^2} = \frac{3x}{r} \varphi' - \varphi' \frac{x^3}{r^3} + \varphi'' \frac{x^3}{r^3}$$

$$\frac{\partial u}{\partial y} = \varphi' \frac{xy}{r}$$

$$\frac{\partial^2 u}{\partial y^2} = \varphi' \left(\frac{x}{r} - \frac{xy^2}{r^3} \right) + \varphi'' \frac{xy^2}{r^3}$$

$$\frac{\partial^2 u}{\partial z^2} = \varphi' \left(\frac{x}{r} - \frac{xz^2}{r^3} \right) + \varphi'' \frac{xz^2}{r^3}$$

$\frac{\partial u}{\partial x} = \varphi + \varphi' \frac{x^2}{r^2}$	$\frac{\partial v}{\partial x} = \varphi' \frac{xy}{r^2}$	$\frac{\partial u}{\partial x} = \varphi' \frac{x^2}{r^2}$
$\frac{\partial u}{\partial y} = \varphi' \frac{xy}{r^2}$	$\frac{\partial v}{\partial y} = \varphi + \varphi' \frac{y^2}{r^2}$	$\frac{\partial u}{\partial y} = \varphi' \frac{y^2}{r^2}$
$\frac{\partial u}{\partial z} = \varphi' \frac{x^2}{r^2}$	$\frac{\partial v}{\partial z} = \varphi' \frac{yz}{r^2}$	$\frac{\partial u}{\partial z} = \varphi + \varphi' \frac{z^2}{r^2}$

$$\frac{\Phi}{r} = -\frac{2}{3} [3\varphi + r\varphi']^2 + 2 \left[\left(\varphi + \frac{x^2}{r^2} \varphi' \right)^2 + \left(\varphi + \frac{y^2}{r^2} \varphi' \right)^2 + \left(\varphi + \frac{z^2}{r^2} \varphi' \right)^2 \right] +$$

$$+ 4 \varphi'^2 \left[\frac{y^2 z^2}{r^2} + \frac{z^2 x^2}{r^2} + \frac{x^2 y^2}{r^2} \right]$$

$$= -\frac{2}{3} [3\varphi + r\varphi']^2 + 2 \left[3\varphi^2 + 2\varphi\varphi' r + \varphi'^2 \frac{x^4 + y^4 + z^4 + 2x^2 y^2 + \dots}{r^2} \right]$$

$$= -\frac{2}{3} [3\varphi + r\varphi']^2 + 2 [3\varphi^2 + 2r\varphi\varphi' + r^2 \varphi'^2]$$

$$= -\frac{2}{3} r^2 \varphi'^2 + 2 r^2 \varphi'^2 = \frac{4}{3} r^2 \varphi'^2$$

$$\text{III). } \frac{c}{A} \rho \varphi r \frac{d\theta}{dr} + \mu [3\varphi + r\varphi'] = \frac{4}{3} \mu r^2 \varphi'^2$$

$$\theta = \frac{\mu}{R\rho}$$

$$\frac{c}{AR} \left(\varphi r \frac{d\mu}{dr} - \frac{\varphi r \mu}{\rho} \frac{d\rho}{dr} \right) = \frac{c}{AR} \left[\varphi r \frac{4}{3} \mu (r\varphi' + r\varphi') + \left[\frac{4}{3} \mu (3\varphi + r\varphi') + \mu_0 \right] [3\varphi + r\varphi'] \right] +$$

$$+ \left[\frac{4}{3} \mu (3\varphi + r\varphi') + \mu_0 \right] [3\varphi + r\varphi'] = \Phi$$

$$\frac{c}{AR} (4\varphi' + r\varphi'') \varphi r + \left(1 + \frac{c}{AR}\right) (3\varphi + r\varphi') (3\varphi + r\varphi' + P_0) = r^2 \varphi'^2$$

$$P_0 = \frac{\mu_0}{\frac{1}{2} \frac{r}{r_0}}$$

$$(4\varphi' + r\varphi'') \varphi r - (k-1) r^2 \varphi'^2 + k (3\varphi + r\varphi') (3\varphi + r\varphi' + P_0) = 0$$

$$r^2 \varphi \varphi'' + \varphi'^2 [r^2(1-k) + k r^2] + \varphi' [4 r \varphi + 6 k r \varphi + P_0 k r] + 9 k \varphi^2 + 3 k \varphi P_0 = 0$$

$$r^2 (\varphi \varphi'' + \varphi'^2) + \varphi' [2 r \varphi (2+3k) + k r P_0] + 3 k \varphi [3\varphi + P_0] = 0$$

$$\frac{d}{dr} (\varphi \varphi')$$

$$\underbrace{r^4 \frac{d}{dr} (\varphi \varphi') + \varphi \varphi' \cdot 4 r^3}_{\frac{d}{dr} (\varphi \varphi' r^4)} + k (6 \varphi \varphi' r^3 + 9 \varphi^2 r^2) + 3 k [2 r^3 \varphi \varphi' + 3 r^2 \varphi^2] + k P_0 (\varphi' r^3 + 3 \varphi^2 r) = 0$$

$$\frac{d}{dr} (r^3 \varphi^2) \quad \frac{d}{dr} (\varphi r^2)$$

$$\varphi \varphi' r^4 + 3 k \varphi^2 r^3 + k P_0 \varphi r^3 = a$$

$$\varphi \varphi' + 3 k \frac{\varphi^2}{r} + k P_0 \frac{\varphi}{r} = \frac{a}{r^4}$$

$$\frac{d\varphi}{dr} + 6 k \frac{\varphi}{r} + k P_0 \frac{1}{r} = \frac{a}{r^5}$$

$$\varphi^2 = 2r$$

$$\varphi \varphi' = \frac{dr}{dr}$$

$$r\varphi = y$$

$$r\varphi' + \varphi = \frac{dy}{dr}$$

$$r^2 \varphi' = r \frac{dy}{dr} - y$$

$$r y (r \frac{dy}{dr} - y) + 3 k r y^2 + k P_0 r^2 y = a$$

$$r^2 y \frac{dy}{dr} + (3k-1) r y^2 + k P_0 r^2 y = a$$

$$y \frac{dy}{dr} + (3k-1) \frac{y^2}{r} + k P_0 y = \frac{a}{r^2}$$

$$\frac{dy}{dr} + (3k-1) \frac{y}{r} + k P_0 y = 0$$

$$y = uv$$

$$\frac{dy}{dr} = u \frac{dv}{dr} + v \frac{du}{dr}$$

$$u^2 v \frac{dv}{dr} + u v^2 \frac{du}{dr} + (3k-1) \frac{u^2 v^2}{r} + k P_0 u v = \frac{a}{r^2}$$

$$u^2 \left[v \frac{dv}{dr} + (3k-1) \frac{v^2}{r} \right] + u \frac{du}{dr} \cdot v^2 + k P_0 u v = \frac{a}{r^2}$$

$$\underbrace{\hspace{10em}}_{=0}$$

$$\log v = -(3k-1) \log r$$

$$v = r^{1-3k}$$

$$u \frac{du}{dr} + u R_1 = R_2$$

$$\begin{aligned} & \parallel \quad u = x + y \\ & \cancel{x \frac{dx}{dr} + x \frac{dy}{dr} + y \frac{dx}{dr} + y \frac{dy}{dr} + x R_1 + y R_1 = R_2} \end{aligned}$$

$$\begin{aligned} & \cancel{u = x + y} \\ & \cancel{y x^2 \frac{dx}{dr} + x y^2 \frac{dx}{dr} + x y R_1 = R_2} \end{aligned}$$

$$\text{Since } a=0:$$

$$u = -k P_0 \int \frac{dr}{r} = -\frac{k P_0}{b} \int \frac{dr}{r^{1-3k}} = -\frac{k P_0}{b} \int (r^{3k-1}) dr$$

$$u = -\frac{k P_0}{b} \frac{r^{3k}}{3k} + c$$

$$y = c r^{1-3k} - \frac{P_0}{3} r = r \varphi = s$$

$$\varphi = c r^{-3k} - \frac{P_0}{3}$$

$$\varphi' = -3k c r^{-3k-1}$$

$$I). \quad \rho = \frac{4}{3} \mu \left[3c r^{-3k} - P_0 - 3k c r^{-3k} + P_0 \right] = 4\mu c (1-k) r^{-3k}$$

$$II). \quad \rho \left[c r^{3(1-k)} - \frac{P_0}{3} r^3 \right] = \text{const} \quad \text{not the numerator!}$$

$$\varphi r^3 = \frac{c}{\rho}$$

$$\varphi = \frac{c}{\rho r^3}$$

$$\varphi' = -\frac{3c}{\rho r^4} - \frac{c}{\rho^2 r^3} \frac{d\rho}{dr}$$

$$\left[-\frac{3c^2}{\rho^2 r^7} - \frac{c^2}{\rho^3 r^6} \frac{d\rho}{dr} \right] r^4 + 3k \frac{c^2}{\rho^2 r^6} r^3 + k P_0 \frac{c}{\rho} = a$$

$$\frac{c^2}{r^2} \frac{1}{\rho^3} \frac{d\rho}{dr} + \frac{3c^2}{\rho^2 r^3} + \frac{3k c^2}{\rho^2 r^3} + k P_0 \frac{c}{\rho} = a$$

$$\frac{d\rho}{dr} + \rho \cdot \frac{3(k+1)}{r} + \frac{k P_0}{c} \frac{\rho^2}{r^2} = \frac{a}{c^2} \rho^3 r^2$$

$$\rho = u v^3$$

$$u \left[\frac{dv}{dr} + v \frac{3k+1}{r} + \frac{k P_0}{c} \frac{u v^2}{r^2} \right] + v \frac{du}{dr} = \frac{a}{c^2} u^3 v^3 r^2$$

$$\frac{u}{r} \frac{dv}{dr} + (3k+1) \frac{u^2}{r^2} + k P_0 \frac{u}{r^2} = \frac{a}{r^3}$$

hidrodinamiske denoormirane, povelje:

$$I. \left\{ \begin{aligned} \frac{\partial f}{\partial x} &= \frac{\mu}{3} \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) \\ \frac{\partial f}{\partial y} &= \frac{\mu}{3} \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \mu \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) \end{aligned} \right. \quad \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right) = 0$$

$$II. \frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} = 0$$

$$II. \frac{c}{A} \rho \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} \right) + \mu \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = \Phi$$

$$\theta = \frac{f}{\rho p}$$

$$\frac{c}{AR} \rho \left[\frac{1}{\rho} \frac{\partial f}{\partial x} - \frac{f}{\rho} \frac{\partial \rho}{\partial x} \right]$$

$$III. \frac{c}{AR} \rho \left[u \frac{1}{\rho} \frac{\partial f}{\partial x} + v \frac{1}{\rho} \frac{\partial f}{\partial y} \right] - u \frac{f}{\rho} \frac{\partial \rho}{\partial x} - v \frac{f}{\rho} \frac{\partial \rho}{\partial y} + \dots$$

$$\frac{1}{k-1} \left[u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} - \frac{f}{\rho} \left(u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} \right) \right] + \mu \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = \Phi$$

$$\frac{\partial f}{\partial t} + \rho \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} = 0$$

$$III. u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + \mu \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + (k-1) \mu \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = (k-1) \Phi$$

$$III. u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + k \mu \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = (k-1) \Phi$$

zad. vrtelji pota got podeliti!

$$u = \frac{\partial p}{\partial x}$$

$$v = \frac{\partial p}{\partial y}$$

$$f = \frac{\mu}{3} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) \int u dx + v dy + \dots$$

$$\nabla^2 \varphi = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial x^2}$$

Eliminating ρ | $p = R\rho\theta$

$$\cancel{R\theta \left(\frac{\partial \rho}{\partial x} + \rho \frac{\partial \theta}{\partial x} \right) = \frac{\mu}{3} \frac{\partial}{\partial x}}$$

$$\text{Wtedy: } \frac{\partial p}{\partial x} = \frac{\mu}{3} \frac{\partial}{\partial x} \left(\frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} \right) + \mu \frac{\partial}{\partial x} \left(\frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right) = \frac{4\mu}{3} \frac{\partial}{\partial x} \left(\frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right) \varphi$$

$$\frac{\partial p}{\partial y} = \frac{4\mu}{3} \frac{\partial}{\partial y} () \varphi$$

$$\text{I. } p = p_0 + \frac{4\mu}{3} \left(\frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right)$$

$$\text{II. } \frac{\partial \varphi}{\partial x} \frac{\partial p}{\partial x} + \frac{\partial \varphi}{\partial y} \frac{\partial p}{\partial y} + k p \nabla^2 \varphi = (k-1) \Phi$$

$$\Phi = -\frac{2}{3} \mu (\nabla^2 \varphi)^2 + 2 \left[\left(\frac{\partial^2 \varphi}{\partial x^2} \right)^2 + \left(\frac{\partial^2 \varphi}{\partial y^2} \right)^2 \right] + 4 \left(\frac{\partial^2 \varphi}{\partial x \partial y} \right)^2$$

$$\left[\left(\frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right) \left(\frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right) \right]^2$$

$$\cancel{k p \nabla^2 \varphi} = \frac{4\mu}{3} \left[\left(\frac{\partial \varphi}{\partial x} \right)^2 + \left(\frac{\partial \varphi}{\partial y} \right)^2 - \frac{\partial^2 \varphi}{\partial x^2} \frac{\partial^2 \varphi}{\partial y^2} + 3 \left(\frac{\partial^2 \varphi}{\partial x \partial y} \right)^2 \right]$$

$$\text{I. } \nabla^2 p = \frac{\mu}{3} \nabla^2 \left(\frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right) + \mu \nabla^2 \left(\frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right) = \frac{4\mu}{3} \nabla^2 \left(\frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right)$$

$$p = \frac{4\mu}{3} \left(\frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right) + A \quad \parallel \nabla^2 A = 0 \quad \left. \vphantom{\frac{4\mu}{3}} \right\} \text{Jedyną możliwość}$$

Wobec tego $A = p_0 = \text{const}$:

$$\frac{4}{3} \mu \left(\frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} \right) + \frac{4\mu}{3} \left(\frac{\partial^2 \varphi}{\partial x \partial y} + \frac{\partial^2 \varphi}{\partial y \partial x} \right) + \cancel{\frac{4\mu}{3} \left(\frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right)^2} =$$

$$(k-1) \left[-\frac{2}{3} \left(\frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right)^2 + 2 \left(\frac{\partial^2 \varphi}{\partial x^2} \right)^2 + 2 \left(\frac{\partial^2 \varphi}{\partial y^2} \right)^2 + \left(\frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right)^2 \right] - \frac{4}{3} \mu \left(\frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right)^2 - A \left(\frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right)$$

$$u \left[\frac{4}{3} \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial x \partial y} \right] + v \left[\frac{4}{3} \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 u}{\partial x \partial y} \right] =$$

$$k \left[-2 \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)^2 + 2 \left(\frac{\partial u}{\partial x} \right)^2 + 2 \left(\frac{\partial v}{\partial y} \right)^2 + \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)^2 \right] +$$

$$+ \left[\frac{2}{3} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)^2 - 2 \left(\frac{\partial u}{\partial x} \right)^2 - 2 \left(\frac{\partial v}{\partial y} \right)^2 - \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)^2 \right]$$

$$= k \left[-7 \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)^2 \right] + \left[\frac{2}{3} (\quad) - \right]$$

zadanie: sprządnij równanie ruchu potencjału strumienia: $\frac{\partial \psi}{\partial x} + \frac{\partial \psi}{\partial y} = 0$

$$\frac{\partial u}{\partial x} = \frac{\partial \psi}{\partial x^2} \quad \frac{\partial u}{\partial y} = \frac{\partial \psi}{\partial x \partial y} = \frac{\partial v}{\partial x}$$

$$\frac{\partial \psi}{\partial x} \left[\frac{4}{3} \frac{\partial}{\partial x} \left(\frac{\partial \psi}{\partial x} + \frac{\partial \psi}{\partial y} \right) + \frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial x \partial y} \right] + \frac{\partial \psi}{\partial y} \left[\frac{4}{3} \frac{\partial}{\partial y} \left(\frac{\partial \psi}{\partial x} + \frac{\partial \psi}{\partial y} \right) + \frac{\partial^2 \psi}{\partial y^2} + \frac{\partial^2 \psi}{\partial x \partial y} \right] =$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$\frac{\partial \psi}{\partial x} \left[\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial x \partial y} \right]$$

$$0 = (k) \left[2 \left(\frac{\partial \psi}{\partial x^2} \right)^2 + 2 \left(\frac{\partial \psi}{\partial y^2} \right)^2 + 4 \left(\frac{\partial^2 \psi}{\partial x \partial y} \right)^2 \right]$$

$$0 = \left(\frac{\partial \psi}{\partial x^2} \right)^2 + 2 \left(\frac{\partial \psi}{\partial x \partial y} \right)^2 + \left(\frac{\partial \psi}{\partial y^2} \right)^2$$

$$\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial y} \right)^2$$

Można też to zrobić z użyciem

$$\frac{\partial u}{\partial x} - \frac{\partial u}{\partial y} = \frac{\partial v}{\partial x} - \frac{\partial v}{\partial y} = 0$$

$$v = \varphi \cdot u$$

Na površini musí být rovnováha $u > 0$
 $v < 0$

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t.z. tem musí

Postup:

$$\frac{\partial v}{\partial n} = u \frac{\partial \varphi}{\partial x} + \varphi \frac{\partial u}{\partial x}$$

$$v = u(2-u) = 2u - u^2$$

\oint

$$d \left[\left(1 - \frac{1}{3} \right) \left(\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} + \frac{\partial u}{\partial z} \right) \right] = \frac{\partial \varphi}{\partial x} dx + \frac{\partial \varphi}{\partial y} dy + \frac{\partial \varphi}{\partial z} dz$$

$$= \mu (\nabla_u^2 dx + \nabla_v^2 dy + \nabla_w^2 dz)$$

$$= \mu S(\nabla_v^2 \cdot d\mathbf{b})$$

málokdy v drog

Nad krycí zankostí:

$$\int_{\sigma} d\varphi = 0$$

$$\int_{\sigma} S(\nabla_v^2 \cdot d\mathbf{b}) = 0$$

$$\text{Integrovaní Stokesa: } \int_{\sigma} S(\nabla \cdot \text{curl}(\mathbf{v})) dS = \int_{\sigma} S(\mathbf{v} \cdot d\mathbf{b})$$

$$\int_{\sigma} S(\nabla \cdot \text{curl}(\nabla_v^2)) dS = 0$$

$$\text{curl} \nabla_v^2 = \nabla \text{curl} \mathbf{v}$$

$$\text{curl}^2 \mathbf{v} = \nabla \text{div} \mathbf{v} - \nabla^2 \mathbf{v}$$

$$\text{curl} \nabla_v^2 = -\text{curl}^3 \mathbf{v} - \text{curl} \nabla \text{div} \mathbf{v}$$

$$= \nabla \text{curl} \mathbf{v} - \nabla \text{div} \text{curl} \mathbf{v}$$

$$\text{tedy } \nabla_v^2 = \nabla^2 \mathbf{v} = \nabla \text{div} \mathbf{v} - \text{curl}^2 \mathbf{v}$$

$$\int (\nabla_u^2 dx + \nabla_v^2 dy + \nabla_w^2 dz) = \nabla^2 \int u dx + v dy + w dz$$

Spiegamy rodzaj: $\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y}, \frac{\partial v}{\partial x} = 0$

$$\begin{cases} \frac{\partial f}{\partial x} = \mu \nabla^2 u \\ \text{---} \end{cases}$$

$$f = A \quad \parallel \nabla^2 A = 0$$

$$u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} = (k-1) \left[2 \left(\frac{\partial u}{\partial x} \right)^2 + 2 \left(\frac{\partial v}{\partial y} \right)^2 + 2 \left(\frac{\partial v}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial y} + \frac{\partial u}{\partial x} \right)^2 - \right]$$

k

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

k

$$u \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) + v \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) = (k-1) \left[2 \left(\frac{\partial u}{\partial x} \right)^2 + 2 \left(\frac{\partial v}{\partial y} \right)^2 + \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)^2 \right]$$

$$\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} = \frac{\partial u}{\partial x} \frac{\partial v}{\partial y}$$

$$u \frac{\partial^2 u}{\partial x^2} + \left(\frac{\partial u}{\partial x} \right)^2 + \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + u \frac{\partial^2 v}{\partial x^2} = 0$$

$$u \frac{\partial^2 u}{\partial x \partial y} + \frac{\partial u}{\partial x} \frac{\partial u}{\partial y} + \frac{\partial u}{\partial y} \frac{\partial v}{\partial y} + u \frac{\partial^2 v}{\partial y^2} = 0$$

$$v \frac{\partial^2 v}{\partial y^2} + \left(\frac{\partial v}{\partial y} \right)^2 + \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + v \frac{\partial^2 u}{\partial x \partial y} = 0$$

~~Rozdział 3~~

Główny punkt: dla każdej powierzchni jest $u=v=0$
 otrzymujemy z III: Składowe u i v w kierunku strumienia
 normalnego

$$\frac{\partial u}{\partial x} = 0$$

[co dozwolone ponieważ tylko pierwsze potęgę]

$$k \mu \frac{\partial v}{\partial y} = (k-1) \mu \left[-\frac{2}{3} \left(\frac{\partial v}{\partial y} \right)^2 + 2 \left(\frac{\partial v}{\partial y} \right)^2 + \left(\frac{\partial u}{\partial y} \right)^2 \right] + (k-1) \mu \nabla^2 v$$

$$\underbrace{\frac{4}{3} \left(\frac{\partial v}{\partial y} \right)^2}$$

z II wytycznej wartości: $\frac{\partial u}{\partial y} = 0$

z regu wytycznej $\frac{\partial u}{\partial y} = 0$ ¹⁴¹⁸

Co prawda: ciepła zostani wyrażane długości $\frac{\partial u}{\partial y} \geq 0$, podnoszących nie do
my parabolicznej, zatem umożliwia wytopić grzewie - gdyż że $\frac{\partial u}{\partial y} = 0$

lub tu: uwzględnienie przewodzenia ciepła!

wszyscy n.p. dla przyjęcia jest już niski

uwzględnienie przewodzenia ciepła nie będzie

wszyscy tutej
dla przyjęcia jest już niski

Zatem adrobny i ten jest bardzo niemały w n.p. dla niski ~~skorzystaj~~

Ponieważ się ciepła składowa ciepła przewodnictwa ciepła wewnątrz niski

na przed form! Co prawda, że znaczenie może być tylko n.p. dla

nowy waty w dośw. Kuchino

zły przewodnik będzie przez ciepła znaczenie niż dobry

$$\begin{aligned} u &= u_0 + a\rho + b\rho^2 \\ \frac{\partial u}{\partial \rho} &= a + 2b\rho = 0 \\ \text{lub } u_0 + a\delta + b\delta^2 &= 0 \end{aligned}$$

$$u_0 + \delta(a + 2b\delta) - b\delta^2 = 0$$

$$b = \frac{u_0}{\delta^2}$$

$$a = -\frac{2u_0}{\delta}$$

Oblicz zatem więcej przyjęcia determinacji: adrobny!

$$\rho \left(\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} \right) + u \frac{\partial \rho}{\partial x} + u \frac{\partial \rho}{\partial y} = 0$$

$$\left(\frac{\partial u}{\partial y} \right)^2 = -\frac{\kappa}{\mu} \left(\frac{\partial^2 \theta}{\partial x^2} + \frac{\partial^2 \theta}{\partial y^2} + \frac{\partial^2 \theta}{\partial z^2} \right)$$

Robiąc założenie że $\frac{\partial \theta}{\partial x} = \frac{\partial \theta}{\partial z} = 0$

$$\left(\frac{\partial u}{\partial y} \right)^2 = -\frac{\kappa}{\mu} \frac{\partial^2 \theta}{\partial y^2}$$

Prüfung

Vorgehensweise: 1. Bestimmung der Randwerte 2. Bestimmung der Randwerte

$$\frac{\partial f}{\partial y} = \frac{\partial f}{\partial z} = 0$$

$$\frac{\partial f}{\partial x} = \mu \left(\frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right)$$

$$\frac{\partial(\rho u)}{\partial x} = 0$$

$$\text{II. } u \frac{\partial f}{\partial x} + k \mu \frac{\partial u}{\partial x} = (k-1) \left[\left(\frac{\partial u}{\partial y} \right)^2 + \left(\frac{\partial u}{\partial z} \right)^2 \right] \mu + \kappa \Delta^2 \theta$$

$$u = f(x, r)$$

$$\left(\frac{\partial u}{\partial y} \right)^2 + \left(\frac{\partial u}{\partial z} \right)^2 = (f')^2$$

$$\frac{\partial u}{\partial y} = f' \frac{y}{r}$$

$$\left. \begin{aligned} \frac{\partial^2 u}{\partial y^2} &= f'' \frac{y^2}{r^2} + f' \left(\frac{1}{r} - \frac{y^2}{r^3} \right) \\ \frac{\partial^2 u}{\partial z^2} &= f'' \frac{z^2}{r^2} + f' \left(\frac{1}{r} - \frac{z^2}{r^3} \right) \end{aligned} \right\} \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} = f'' + f' \frac{1}{r} = \frac{1}{r} d(r f')$$

$$\frac{\partial f}{\partial x} = \mu \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right) = \mu \left[\frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} \right]$$

$$\rho u = f(r)$$

$$\begin{aligned} u \frac{\partial f}{\partial x} + k \mu \frac{\partial u}{\partial x} &= (k-1) \mu \left(\frac{\partial u}{\partial r} \right)^2 + \underbrace{\frac{\kappa}{r} \frac{1}{r} \frac{\partial}{\partial r} \left[r \frac{\partial}{\partial r} \left(\frac{f}{\rho} \right) \right]}_{= -\frac{\kappa}{r} \frac{1}{r} \frac{\partial}{\partial r} \left[\frac{r}{\rho^2} \frac{\partial \rho}{\partial r} \right]} \end{aligned}$$

~~III. Bestimmung der Randwerte~~

$$u = \frac{r^2}{4} \varphi(x) + \psi(x) \log(r) + \chi(x)$$

$$\frac{\partial}{\partial r} \left(\frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} \right) = 0$$

$$\frac{\partial u}{\partial r} = \frac{r}{2} \varphi(x) + \frac{1}{r} \psi(x)$$

$$\mu \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right) = \mu \varphi(x) = \frac{d\varphi}{dx}$$

$$\mu = \int \rho(x) dx$$

$$\frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right) = r \varphi(x)$$

$$r \frac{\partial u}{\partial r} = \frac{r^2}{2} \varphi(x) + \psi(x)$$

Standardize $k=0$:

$$\frac{n^2}{4} [\varphi(x)]^2 + 2 \int \lambda \varphi(x) \varphi(x) + \chi(x) \varphi(x) + k \left[\frac{n^2}{4} \varphi(x) \int \varphi(x) dx + 2 \int \lambda \varphi(x) \int \varphi(x) dx + \chi'(x) \int \varphi(x) dx \right] =$$

$$= (k-1) \left[\frac{n^2}{4} [\varphi(x)]^2 + \varphi(x) \varphi(x) + \frac{1}{n^2} [\chi(x)]^2 \right]$$

kuris bagi persamaan dlo derivate 2, φ x

$$[\varphi(x)]^2 + k \varphi'(x) \int \varphi(x) dx = (k-1) [\varphi(x)]^2$$

$$\varphi(x) \varphi(x) + k \varphi'(x) \int \varphi(x) dx = 0$$

$$\chi(x) \varphi(x) + k \chi'(x) \int \varphi(x) dx = (k-1) \varphi(x) \varphi(x)$$

$$0 = \frac{k-1}{n^2} [\varphi(x)]^2 \quad \varphi(x) = 0$$

$$\cancel{\chi} \varphi \pm k \chi' \int \varphi \quad \text{atau}$$

$$\frac{\chi}{\chi'} \varphi = -k \int \varphi$$

$$\varphi - \frac{\chi \chi''}{\chi'^2} \varphi + \frac{\chi}{\chi'} \varphi' = -k \varphi$$

$$\varphi \left[1 + k \frac{\chi}{\chi'} - \frac{\chi \chi''}{\chi'^2} \right] = -\frac{\chi}{\chi'} \varphi'$$

$$(1+k) \frac{\chi'}{\chi} - \frac{\chi''}{\chi'} = a \frac{4-k}{2-k}$$

$$(1+k) \frac{\chi'}{\chi} - \frac{\chi''}{\chi'} = a \frac{4-k}{2-k} x +$$

$$\frac{\chi'}{\chi^{1+k}} = e \quad e^{a \frac{k-4}{k-2} x}$$

$$\chi^{-k} = \frac{-ek}{k-2} \int e^{a \frac{k-4}{k-2} x} dx$$

$$\cancel{\chi} \int \varphi = \frac{(k-2)}{k} \frac{\varphi^2}{\varphi'}$$

$$k \varphi = \frac{k-2}{k} \left[2\varphi - \frac{\varphi^2 \varphi'}{\varphi'^2} \right]$$

$$k-4 = (k-2) \frac{\varphi \varphi''}{\varphi'^2}$$

$$\frac{k-4}{k-2} \frac{\varphi'}{\varphi} = \frac{\varphi''}{\varphi'}$$

$$a \frac{k-4}{k-2} \varphi = \varphi'$$

$$\frac{\varphi'}{\varphi} = a \frac{k-4}{k-2}$$

$$\varphi = b e^{a \frac{k-4}{k-2} x}$$

Należy pamiętać, że na pewnym przedziale musi być stała u (niezmienna dla r):

$$\frac{\delta^2}{4} \varphi(x) + \chi(x) = 0$$

$$\chi(x) = -\frac{\delta^2}{4} \varphi(x) \quad \varphi = 0$$

Jeśli więc:

$$\varphi^2 + k \varphi' \int \varphi = 0$$

to musi zachodzić, że z równania dla φ jest stała u (niezmienna dla r) i musi być stała u dla $r=0$ i musi zachodzić także przy $r \rightarrow \infty$.

Spójrzmy na $\kappa \geq 0$:

$$u = \frac{r^2 - \delta^2}{4} \varphi(x)$$

$$\rho u = f(r):$$

$$\frac{\partial u}{\partial r} = \frac{\kappa}{2} \varphi(x)$$

$$\frac{r^2}{4} \rho \varphi(x) - \frac{\delta^2}{4} \rho \varphi(x) = \rho u = f(r)$$

$$\frac{\partial}{\partial r} = 0:$$

$$\frac{r^2 - \delta^2}{4} \frac{\partial}{\partial x} (\rho \varphi) = 0$$

$$\frac{\partial \varphi}{\partial x} \varphi + \rho \frac{\partial \varphi}{\partial x} = 0$$

$$\rho \varphi = f(r)$$

$$\frac{1}{\rho} = \frac{\varphi(x)}{f(r)}$$

$$\frac{1}{r} \frac{\partial}{\partial r} \left[r \frac{\partial}{\partial r} \frac{1}{f(r)} \right] = F(r)$$

$$\frac{d\varphi}{dx} = \mu \varphi \quad \mu = \mu \int \varphi dx$$

$$\frac{r^2 - \delta^2}{4} \mu \varphi^2 + k \mu \frac{r^2 - \delta^2}{4} \varphi' \int \varphi = \mu (k-1) \frac{r^2}{4} \varphi^2 + \frac{\kappa \varphi(x)}{2} F(r)$$

Musi być pewnym warunkiem dla δ i κ i x .

$$(r^2 - \delta^2) [\varphi^2(x) + k \varphi'(x) \int \varphi dx] = (k-1) r^2 \varphi^2(x) + \frac{4k}{\mu R} \varphi(x) F(r)$$

$$r^2 [(2-k) \varphi^2(x) + k \varphi'(x) \int \varphi dx] - \delta^2 [\varphi^2(x) + k \varphi'(x) \int \varphi dx] = \frac{4k}{R\mu} \varphi(x) F(r)$$

$$2r \left[\right] = \frac{4k}{R\mu} \varphi(x) F'(r)$$

$$2 \left[\right] = \frac{4k}{R\mu} \varphi(x) F'(r)$$

$$\frac{F''}{F'} = \frac{1}{r}$$

$$\log F' = \log r + \dots$$

$$F' = \text{const} = \frac{dF}{dr}$$

$$F = a r^2 + b$$

$$(2-k) \varphi^2 + k \varphi' \int \varphi = \frac{2ak}{R\mu} \varphi \quad \parallel \quad -\delta^2 [\varphi^2 + k \varphi' \int \varphi] = \frac{4bk}{R\mu} \varphi$$

$$2(2-k) \varphi \varphi' + k \varphi'^2 + k \varphi' \varphi = \frac{2ak}{R\mu} \varphi'$$

$$[2-k] [\varphi^2 \varphi'' - 2\varphi \varphi'^2] = k \varphi'^3 - \frac{2ak}{R\mu} [\varphi \varphi'' - \varphi'^2]$$

$$[2-k] \left[\frac{\varphi''}{\varphi'} - 2 \frac{\varphi'}{\varphi} \right] - k \frac{\varphi'}{\varphi} = \frac{2ak}{R\mu} \left[\frac{\varphi''}{\varphi'} - \frac{\varphi'}{\varphi} \right]$$

$$(4-k) \varphi'' = \left[\frac{2ak}{R\mu} + \frac{4bk}{\delta^2 R\mu} \right] \varphi'$$

$f = \text{const}$

$$\text{Wichtig: } \theta = \frac{\mu}{R\rho} = \frac{\mu u}{R\mu} = \frac{\mu(x) \frac{r^2}{4} \varphi(x)}{R}$$

$$\frac{1}{2} \frac{\partial}{\partial r} \left(r \frac{\partial \theta}{\partial r} \right) = \frac{\mu \varphi}{2} F(r) = \frac{\mu \varphi}{2} \left(\frac{a r^2}{2} + b \right)$$

$$\frac{\partial}{\partial r} \left(r \frac{\partial \theta}{\partial r} \right) = \frac{\mu \varphi}{R} \left[\frac{a r^3}{2} + b r \right]$$

$$r \frac{\partial \theta}{\partial r} = \frac{\mu \varphi}{R} \left[\frac{a r^4}{8} + \frac{b r^2}{2} \right] + \text{const}$$

$$\theta = \frac{\mu \varphi}{R} \left[\frac{a r^4}{32} + \frac{b r^2}{4} \right] + \text{const} \cdot \ln r + \text{const}$$

$$r = r_1 + (r_2 - r_1) \frac{x}{l} \quad \parallel \quad \frac{dr}{dx} = \frac{r_2 - r_1}{l} = \mu \varphi$$

$$\varphi = \frac{r_2 - r_1}{l \mu} = \frac{2 a \kappa}{(2-k) R \mu} = \frac{-4 b \kappa}{\delta^2 R \mu}$$

$$a = - \frac{2 b}{(2-k) \delta^2}$$

$$a = \frac{2-k}{2} \frac{(r_2 - r_1) R}{\delta^2 l \kappa}$$

$$b = - \frac{(2-k) \delta^2}{2} a$$

$$\theta = \frac{r_2 - r_1}{R l \mu} \left[r_1 + (r_2 - r_1) \frac{x}{l} \right] \left[\frac{r^4}{32} - \frac{(2-k) \delta^2 r^2}{8} \right] \frac{2-k}{2} \frac{r_2 - r_1}{l \kappa} R \frac{1}{\delta^2} \left[- \frac{\delta^4}{32} + \frac{(2-k) \delta^4}{8} \right]$$

$$\theta - \theta_0 = \left(\frac{r_2 - r_1}{l} \right)^2 \frac{2-k}{46} \frac{1}{\kappa \mu} \left[r_1 + (r_2 - r_1) \frac{x}{l} \right] \left[\frac{r^4 - \delta^4}{4} - (2-k) \delta^2 \left(\frac{r^2 - \delta^2}{4} \right) \right]$$

$$= \frac{1}{4} (r^2 - \delta^2) \left[\frac{r^2 + \delta^2}{4} - (2-k) \delta^2 \right]$$

$$= \frac{1}{4} (r^2 - \delta^2) \left[r^2 + (4k-7) \delta^2 \right]$$

$$\rho = \frac{\mu}{R\theta}$$

$$\rho u = \mu \frac{r^2 - \delta^2}{4} \varphi$$

$$R \left[\theta_0 + \frac{\mu}{R} \cdot \frac{2-k}{64} \frac{\mu^2 \cdot R}{\ell k} R (r^2 - \delta^2 - 4(2-k)\delta^2) \right]$$

$$M = 2\pi \int_0^{\delta} r \rho u dr = \frac{\pi \mu \varphi}{2R} \int_0^{\delta} (r^3 - r\delta^2) dr$$

↓
Nur max. wert
 $\rho u = \mu(r)$

Is same dimensionale:

$$\frac{\partial \mu}{\partial t} = 0 \quad r = \text{max}$$

$$\left\{ \begin{array}{l} \frac{\partial \mu}{\partial x} = \mu \frac{\partial^2 u}{\partial y^2} \\ \frac{\partial \rho u}{\partial x} = 0 \\ u \frac{\partial \mu}{\partial x} + k \mu \frac{\partial u}{\partial x} = (k-1) \mu \left(\frac{\partial u}{\partial y} \right)^2 + k \frac{\partial^2 \theta}{\partial y^2} \left(\frac{\partial \mu}{\partial x} \right) \end{array} \right. \longrightarrow$$

$$\frac{\partial^3 u}{\partial y^3} = 0$$

$$\theta = \frac{\mu}{2R} \quad \frac{\partial^2 \theta}{\partial y^2} = \frac{\mu}{R} \frac{\partial^2}{\partial y^2} \left(\frac{1}{\rho} \right)$$

$$u = \frac{y^2}{2} \varphi(x) + y \psi(x) + \chi(x)$$

$$\rho u = f(y)$$

$$\left. \begin{array}{l} y=0 \\ y=\delta \end{array} \right\} u=0 \quad \chi=0$$

$$y = -\frac{\delta}{2} \quad \varphi(x)$$

$$\frac{\partial \mu}{\partial x} = \mu \varphi(x)$$

$$\mu = \mu \int \varphi(x) dx + \mu_0$$

$$u = \frac{y^2}{2} \frac{1}{\mu} \frac{d\mu}{dx} + y \varphi(x) + \chi(x)$$

$$\frac{\partial u}{\partial y} = \frac{y}{\mu} \frac{d\mu}{dx} + \varphi(x)$$

$$u = \frac{y(y-\delta)}{2} \frac{1}{\mu} \frac{d\mu}{dx}$$

$$\frac{\partial u}{\partial y} = \frac{2y-\delta}{2\mu} \frac{d\mu}{dx}$$

$$\rho u = \frac{y(y-\delta)}{2\mu} \frac{d\mu}{dx} = f(y)$$

$$\rho = \frac{f(y)}{\frac{d\mu}{dx}} \quad \left| \frac{1}{\rho} = \frac{d\mu}{f(y) dx} \right.$$

$$\frac{\partial^2 \theta}{\partial y^2} = \frac{1}{R} \frac{d\mu}{dx} \frac{\partial}{\partial y} \left[\frac{1}{f(y)} \right]$$

$$\frac{y^2 - y\delta}{2} \left(\frac{dy}{dx} \right)^2 + k \rho \frac{d^2 y}{dx^2} \frac{y^2 - y\delta}{2} = (k-1) \left(\frac{2y - \delta}{2} \right)^2 \left(\frac{dy}{dx} \right)^2 + \rho \frac{dy}{dx} \frac{k}{2} F(y)$$

$$\cancel{\left(\frac{y - \delta}{2} \right)^2 \left(\frac{dy}{dx} \right)^2}$$

$$\left(\frac{dy}{dx} \right)^2 \left[\frac{y^2 - y\delta}{2} - (k-1) \left(\frac{2y - \delta}{2} \right)^2 \right] + k \rho \frac{d^2 y}{dx^2} \frac{y^2 - y\delta}{2} = \rho \frac{dy}{dx} \frac{k}{2} F(y)$$

$$\left(\frac{dy}{dx} \right)^2 \left[y - \frac{\delta}{2} - (k-1)(2y - \delta) \right] + k \rho \frac{d^2 y}{dx^2} \left(y - \frac{\delta}{2} \right) = \rho \frac{dy}{dx} \frac{k}{2} F(y)$$

$$y^2 \left[\left(\frac{3}{2} - k \right) \left(\frac{dy}{dx} \right)^2 + \frac{k}{2} \rho \frac{d^2 y}{dx^2} \right] + y\delta \left[\left(k - \frac{3}{2} \right) \left(\frac{dy}{dx} \right)^2 - \frac{k}{2} \rho \frac{d^2 y}{dx^2} \right]$$

$$\left(-\frac{(k-1)\delta^2}{4} \left(\frac{dy}{dx} \right)^2 \right) = \rho \frac{dy}{dx} \frac{k}{2} F(y)$$

$$(y^2 - y\delta) \left[\left(\frac{3}{2} - k \right) \left(\frac{dy}{dx} \right)^2 + \frac{k}{2} \rho \frac{d^2 y}{dx^2} \right]$$

$$(2y - \delta) \left[\quad \right] = \rho \frac{dy}{dx} \frac{k}{2} F'(y)$$

$$2 \left[\quad \right] = \quad F''(y)$$

$$y - \frac{\delta}{2} = \frac{F'}{F''}$$

$$\frac{F''}{F'} = \frac{1}{y - \frac{\delta}{2}}$$

$$\ln F' = \ln \left(y - \frac{\delta}{2} \right) + \dots$$

$$F' = a \left(y - \frac{\delta}{2} \right)$$

$$F = a \left(\frac{y^2}{2} - y \frac{\delta}{2} \right) + b = \frac{a}{2} y (y - \delta) + b$$

$$(y^2 - y\delta) \left[\right] - \frac{(k-1)\delta^2}{4} \left(\frac{dy}{dx} \right)^2 = \mu \frac{dy}{dx} \frac{k}{R} \left[\frac{a}{2} (y^2 - y\delta) + b \right]$$

$$\left. \begin{aligned} \left(\frac{3}{2} - k \right) \left(\frac{dy}{dx} \right)^2 + \frac{k}{2} \mu \frac{d^2 y}{dx^2} &= \frac{a}{2} \frac{k}{R} \mu \frac{dy}{dx} \\ \frac{(k-1)\delta^2}{4} \left(\frac{dy}{dx} \right)^2 &= -b \frac{k}{R} \mu \frac{dy}{dx} \end{aligned} \right\}$$

$$\frac{1}{\mu} \frac{dy}{dx} = - \frac{4bk}{(k-1)\delta^2 R}$$

$$\mu = A e^{\frac{-4bk y x}{(k-1)\delta^2 R}}$$

$$\left(\frac{3}{2} - k \right) \left[\frac{4bk}{(k-1)\delta^2 R \mu} \right]^{\frac{3-k}{2}} \left[\frac{3}{2} - k + \frac{k}{2} \right] = - \frac{a}{2} \frac{k}{R}$$

$$a = - \frac{4(3-k)b}{(k-1)\delta^2}$$

$$\frac{\partial^2 \theta}{\partial y^2} = \mu \frac{dy}{dx} F = \mu \frac{dy}{dx} \left[\frac{a}{2} (y^2 - y\delta) + b \right]$$

$$\frac{\partial \theta}{\partial y} = \mu \frac{dy}{dx} \left[\frac{a}{2} \left(\frac{y^3}{3} - y^2 \frac{\delta}{2} \right) + by \right] + v(x)$$

$$\theta = \mu \frac{dy}{dx} \left[\frac{a}{2} \left(\frac{y^4}{12} - \frac{y^3 \delta}{6} \right) + b \frac{y^2}{2} \right] + y v(x) + \gamma(x)$$

$$y=0 : \theta_0 = \gamma(x)$$

$$y=\delta : \theta_0 = \mu \frac{dy}{dx} \left[-\frac{a}{2} \frac{\delta^3 y}{12} + b \frac{\delta^2 y}{2} \right] + \delta v(x) + \gamma$$

$$\theta = \theta_0 + \mu \frac{dy}{dx} \left[\frac{a}{2} \left(\frac{y^4 + \delta^3 y}{12} - \frac{y^2 \delta}{6} \right) + b \frac{y^2 - y\delta}{2} \right] = \frac{\mu u}{R \rho u}$$

$$R\theta = \frac{f}{\rho}$$

$$R\theta = \frac{f(x)}{f(y)} \cdot \frac{y(y-\delta)}{2\mu} \frac{dy}{dx} = F(y) \mu \frac{dy}{dx} = \frac{c}{2} F(y)$$

Numeratoren des Nenners, ohne $\frac{dy}{dx}$ zu berücksichtigen

$$f \frac{dy}{dx} = \text{const}$$

$$f^2 = cx + a \quad \left| f \frac{dy}{dx} = \frac{c}{2} \right|$$

$$u\rho = f = \frac{y(y-\delta)}{2\mu} \cdot \frac{1}{F(y)}$$

~~$$f \frac{dy}{dx} = \frac{c}{2}$$~~

$$f \frac{dy}{dx} = \frac{c}{2} \quad \left| f \frac{d^2y}{dx^2} + \left(\frac{dy}{dx}\right)^2 = 0 \right|$$

$$u = \frac{y(y-\delta)}{2} \cdot \frac{1}{\mu} \frac{dy}{dx}$$

$$\frac{\partial^2 \theta}{\partial y^2} = \frac{c}{2R} F''$$

$$\frac{y^2 - y\delta}{2\mu} \left(\frac{dy}{dx}\right)^2 + k \frac{y^2 - y\delta}{2\mu} \mu \frac{d^2y}{dx^2} = (k-1) \mu \left(\frac{2y-\delta}{2\mu}\right)^2 \left(\frac{dy}{dx}\right)^2 + \frac{kc}{2R} F''(y)$$

$$f = \sqrt{cx+a}$$

$$f \frac{d^2y}{dx^2} = -\frac{c^2}{4(cx+a)}$$

$$\frac{dy}{dx} = \frac{c}{2\sqrt{cx+a}}$$

$$\left(\frac{dy}{dx}\right)^2 = \frac{c^2}{4(cx+a)}$$

$$\frac{d^2y}{dx^2} = \frac{-c^2}{4\sqrt{(cx+a)^3}}$$

$$\left[(1-k)(y^2 - y\delta) - (k-1) \frac{(2y-\delta)^2}{2} \right] \frac{c^2}{4(cx+a)}$$

$$(1-k) y^2 - y\delta - 2y^2 + 2y\delta$$

Wie die optische invariant II

($x = f(x)$ etc.)
Zurück zur ursprünglichen Form:

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$$\frac{\rho}{\rho_0} = \left(\frac{p}{p_0}\right)^k$$

$$\rho = h(x)$$

$$\frac{\partial(\rho u)}{\partial x} = 0$$

$$\mu^{\frac{1}{K}} \sim \rho$$

$$\rho u = f_c(r)$$

for minimization of 2 cost : $\frac{\partial}{\partial z} \left[\frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} \right] = 0$

$$\frac{dy}{dx} = \mu \varphi(x)$$

$$u = \frac{z^2}{4} (x + y + 2z + j)$$

$$u = \frac{a^2 - \delta^2}{4} \varphi(x)$$

$$u = \frac{r^2 - \dot{r}^2}{4\mu} \frac{d\mu}{dx}$$

$$\frac{1}{\rho_0} \frac{d\rho}{dx} = \frac{k}{\rho_0^k} \rho^{k-1} \frac{d\rho}{dx}$$

$$\frac{\partial}{\partial x} \left[\frac{r^2 \sqrt{2}}{4\mu} \frac{k p_0}{\rho_0} \rho \frac{dx}{dx} \right] = \text{Answer 0}$$

$$\frac{r^2 - s^2}{4\mu} \frac{k\rho_0}{\rho_0 k} \cdot \frac{\rho^{k+1}}{k+1} = Xf(z) + Y(z)$$

~~$p^{k+1} = ax + b$~~

$$r^{\frac{k+1}{k}} = ax + b$$

$$p_2 \frac{k+1}{2} - p_1 \frac{k+1}{n} = a$$

$$\mu_{\frac{k+1}{K}} - \mu_1 = \frac{x}{\ell} (\mu_2 - \mu_1)$$

未。

Podobnie jak przy
izotermicznym wychodni tyko

is $\frac{1+k}{s}$ we have $\frac{1}{s} = \frac{1}{1+k} + \frac{k}{s(1+k)}$

Terminiene 2 ungleichbar $\frac{\partial u}{\partial x^2}$

$$\frac{dp}{dx} = \mu \frac{\partial u}{\partial y^2} + \frac{4}{3} \mu \frac{\partial u}{\partial x^2}$$

$$\frac{\partial(pu)}{\partial x} = 0 = \frac{\partial(pu)}{\partial x} = 0$$

$$\mu u = \varphi(y)$$

$$u = \frac{\varphi(y)}{f(x)}$$

$$\mu = f(x)$$

$$\frac{\varphi^{(4)}}{\varphi^{(3)}} = \frac{\varphi''}{\varphi'}$$

Notionum tyko jeli: ~~Notionum tyko jeli~~

$$f(x) f'(x) = a$$

$$\frac{1}{2} \frac{d}{dx} f^2$$

$$f^2 = 2ax + b$$

$$f^2 = \sqrt{2ax + b}$$

$$f' = \frac{a}{\sqrt{\quad}}$$

$$f'' = -\frac{a^2}{\sqrt{\quad}}$$

$$f(x) \frac{d^2}{dx^2} \left[\frac{1}{f(x)} \right] = c$$

$$\frac{1}{f^2} - \frac{f''}{f^3}$$

$$-\frac{f''}{f^3} + 2 \frac{f'^2}{f^4} =$$

$$+ \frac{a^2}{(2ax+b)^2} + \frac{2a^2}{(\quad)^2} = c$$

Nimmalsen opore jeli $a=0$

A. zu $f = \text{const}$

Drei matricen: $\varphi'(y) = a$ $\varphi(y) = b$ nimmalsen bo dyta $a =$

Zaten to wofel nie moie di puytostowam do wamh' poytostowyl

Jedyn matric: $f = \text{const}$ lub $\mu u = \text{const}$

Determinare le componenti minime p , q , v , u $\neq 0$

$$\frac{\partial f}{\partial x} = \mu \frac{\partial u}{\partial y} + \frac{1}{3} \mu \frac{\partial u}{\partial x^2}$$

$$\frac{\partial f}{\partial y} =$$

$$\frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} = 0$$

$$\rho u = \frac{\partial \psi}{\partial y}$$

$$\rho v = -\frac{\partial \psi}{\partial x}$$

$$\frac{\Delta \psi}{\rho} = R\theta$$

$$\frac{v}{u} = -\frac{\frac{\partial \psi}{\partial x}}{\frac{\partial \psi}{\partial y}}$$

$$u = \frac{1}{\rho} \frac{\partial \psi}{\partial y} = \frac{R\theta}{\rho} \frac{\partial \psi}{\partial y}$$

$$v = -\frac{1}{\rho} \frac{\partial \psi}{\partial x} = -\frac{R\theta}{\rho} \frac{\partial \psi}{\partial x}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = -\frac{1}{\rho} \left(u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} \right)$$

$$= -\frac{1}{\rho^2} \left(\frac{\partial \psi}{\partial y} \frac{\partial \rho}{\partial x} - \frac{\partial \psi}{\partial x} \frac{\partial \rho}{\partial y} \right)$$

$$\frac{\partial u}{\partial x} = \frac{1}{\rho} \frac{\partial^2 \psi}{\partial x \partial y} - \frac{1}{\rho^2} \frac{\partial \rho}{\partial x} \frac{\partial \psi}{\partial y}$$

$$\frac{\partial v}{\partial y} = -\frac{1}{\rho} \frac{\partial^2 \psi}{\partial x \partial y} + \frac{1}{\rho^2} \frac{\partial \rho}{\partial y} \frac{\partial \psi}{\partial x}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = -\frac{1}{\rho^2} \left(\frac{\partial \rho}{\partial y} \frac{\partial \psi}{\partial y} - \frac{\partial \rho}{\partial x} \frac{\partial \psi}{\partial x} \right) + \frac{1}{\rho} \left(\frac{\partial^2 \psi}{\partial y^2} - \frac{\partial^2 \psi}{\partial x^2} \right)$$

$$\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} = +\frac{1}{\rho^2} \left(\frac{\partial \rho}{\partial y} \frac{\partial \psi}{\partial y} + \frac{\partial \rho}{\partial x} \frac{\partial \psi}{\partial x} \right)$$

$$+ \frac{1}{\rho} \left(\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} \right)$$

$$\Phi = \frac{1}{3} \mu \left[\left(\frac{\partial u}{\partial x} \right)^2 - 2 \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + \left(\frac{\partial v}{\partial y} \right)^2 \right] + \mu \left[\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right]^2$$

$$= \frac{1}{\rho^4} \left[\left(\frac{\partial \psi}{\partial y} \frac{\partial \rho}{\partial x} \right)^2 + \left(\frac{\partial \psi}{\partial x} \frac{\partial \rho}{\partial y} \right)^2 \right] + \frac{1}{\rho^2} \left(\frac{\partial^2 \psi}{\partial x \partial y} \right)^2 - \frac{1}{\rho^3} \frac{\partial \psi}{\partial x \partial y} \left[\frac{\partial \rho}{\partial x} \frac{\partial \psi}{\partial y} + \frac{\partial \rho}{\partial y} \frac{\partial \psi}{\partial x} \right]$$

$$- \frac{1}{\rho^4} \frac{\partial \rho}{\partial x} \frac{\partial \rho}{\partial y} \frac{\partial \psi}{\partial x} \frac{\partial \psi}{\partial y}$$

$$- \frac{1}{\rho^2} \left(\frac{\partial^2 \psi}{\partial x \partial y} \right)^2 + \frac{1}{\rho^3} \frac{\partial \psi}{\partial x \partial y} \left[\frac{\partial \rho}{\partial x} \frac{\partial \psi}{\partial y} + \frac{\partial \rho}{\partial y} \frac{\partial \psi}{\partial x} \right]$$

III)

$$k \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = \frac{4\mu}{3} \left[\left(\frac{\partial u}{\partial x} \right)^2 - \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + \left(\frac{\partial v}{\partial y} \right)^2 \right] + \mu \left[\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right]^2$$

$$- \frac{\mu}{3} \left[u \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + v \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \right] - \mu \left[u \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) + v \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) \right]$$

$$= \frac{4}{3} \mu \left[\left(\frac{\partial u}{\partial x} \right)^2 - u \frac{\partial^2 u}{\partial x^2} + \left(\frac{\partial v}{\partial y} \right)^2 - v \left(\frac{\partial^2 v}{\partial y^2} \right) \right] - \frac{4}{3} \mu \left[\frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + u \frac{\partial^2 v}{\partial x \partial y} + v \frac{\partial^2 u}{\partial x \partial y} \right]$$

$$u^2 \left[\frac{1}{u^2} \left(\frac{\partial u}{\partial x} \right)^2 - \frac{1}{u} \frac{\partial^2 u}{\partial x^2} \right] + v^2 \left[\dots \right]$$

$$= - u^2 \frac{\partial}{\partial x} \left(\frac{1}{u} \frac{\partial u}{\partial x} \right) + \mu \left[\left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)^2 - u \frac{\partial^2 u}{\partial y^2} - v \frac{\partial^2 v}{\partial x^2} \right]$$

$$= - \left[u^2 \frac{\partial}{\partial x} (\log u) + v^2 \frac{\partial}{\partial y} (\log v) \right] \frac{4}{3} - \left[u^2 \frac{\partial}{\partial y} (\log u) + v^2 \frac{\partial}{\partial x} (\log v) \right]$$

~~Handwritten scribbles~~

$$[a_1 x^3 + a_2 x y^2 + a_3] [8a_1 + 2a_2] x + \frac{2}{3} b_2 y + \left[-\frac{b_2}{3} x^3 + b_2 y^2 x + b_3 \right] \left[\frac{8}{3} b_2 + 6b_3 \right] x + \frac{2}{3} a_2 y$$

$$+ k \left[\frac{\mu}{3} + \mu (4a_1 + a_2) x^2 + \frac{2}{3} a_2 y^2 + \frac{2}{3} b_2 x y \right] [3a_1 x^2 + a_2 y^2 + 2b_2 x y] =$$

		stopy		równania $\frac{\partial^2 \Phi}{\partial x^2}$		równania	
funkcje	u	1	3 + 3	$\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial x \partial y} = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2}$	$x^{n-3} y^3$	0	0
	v	2	6 + 6				
	f	3	10 + 10				
		4	15 + 15				
		5	21 + 21				
		6	28				

Wstawiamy do równania dla Φ :

stopień:	$2(n-1)$	0	1	2	3	4	5	6	7	8
		0	6	15	28	45				

przetwórz rotacje dowolnych:

1	6
2	6
3	5
4	2
5	-3

$$u = e^{ax+y}$$

$$v = e^{bx+y}$$

$$p = e^{cx+y}$$

$$\frac{\partial u}{\partial x} = \frac{\partial}{\partial x} e^{ax+y} = a e^{ax+y}$$

$$\frac{\partial v}{\partial y} = \frac{\partial}{\partial y} e^{bx+y} = e^{bx+y}$$

$$\frac{\partial^2 u}{\partial x^2} = \frac{\partial}{\partial x} (a e^{ax+y}) = a^2 e^{ax+y}$$

$$\frac{\partial^2 v}{\partial x \partial y} = \frac{\partial}{\partial x} (e^{bx+y}) = b e^{bx+y}$$

$$e^{\lambda} \frac{\partial p}{\partial x} = \left\{ \frac{4\mu}{3} \left[\frac{\partial^2 p}{\partial x^2} + \left(\frac{\partial p}{\partial x} \right)^2 \right] + \mu \left[\frac{\partial^2 p}{\partial y^2} + \left(\frac{\partial p}{\partial y} \right)^2 \right] \right\} e^{\lambda} + \frac{1}{3} \left[\frac{\partial^2 p}{\partial x \partial y} + \frac{\partial p}{\partial x} \frac{\partial p}{\partial y} \right] e^{\lambda}$$

$$u = x(2ax - y^2) \phi$$

$$v = x(2bx - y^2) \psi$$

$$\frac{\partial u}{\partial x} =$$

$$u = x(a_1 x^2 + a_2 y^2) + a_3$$

$$v = x(b_1 x^2 + b_2 y^2) + b_3$$

$$\frac{\partial u}{\partial x} = 3a_1 x^2 + 2a_2 xy$$

$$\frac{\partial v}{\partial y} = 2b_2 xy$$

$$\frac{\partial v}{\partial x} = 3b_1 x^2 + b_2 y^2$$

$$\frac{\partial^2 u}{\partial x^2} = 6a_1 x$$

$$\frac{\partial^2 u}{\partial y^2} = 2a_2 x$$

$$\frac{\partial^2 v}{\partial y^2} = 2b_2 x$$

$$\frac{\partial^2 v}{\partial x^2} = 6b_1 x$$

$$\frac{\partial^2 u}{\partial x \partial y} = 2a_2 y$$

$$\frac{\partial^2 v}{\partial x \partial y} = 2b_2 y$$

$$\frac{\partial p}{\partial x} = \frac{4\mu}{3} 6a_1 x + \frac{1}{3} 2b_2 y + \mu 2a_2 x = \mu(8a_1 + 2a_2)x + \frac{2\mu}{3} b_2 y$$

$$\frac{\partial p}{\partial y} = \frac{4\mu}{3} 2b_2 x + \frac{1}{3} 2a_2 y + \mu 6b_1 x = \mu\left(\frac{8}{3}b_2 + 6b_1\right)x + \frac{2\mu}{3} a_2 y$$

$$p = p_0 + \mu(4a_1 + a_2)x^2 + \frac{1}{3} a_2 y^2 + \frac{2\mu}{3} b_2 xy$$

$$\frac{\partial^2}{\partial x \partial y} \log u = \frac{\partial}{\partial y} \left(\frac{1}{u} \frac{\partial u}{\partial x} \right) = -\frac{1}{u^2} \frac{\partial u}{\partial x} \frac{\partial u}{\partial y} + \frac{1}{u} \frac{\partial^2 u}{\partial x \partial y}$$

$$\frac{2\mu}{3} b_2 = \frac{8}{3} b_2 + 6b_1$$

$$b_2 = -3b_1$$

$$u = a_0 + a_1 x + a_2 y + a_3 x^2 + a_4 xy + a_5 y^2 \quad \left| \quad \frac{\partial u}{\partial x} = a_1 + 2a_3 x + a_4 y \right.$$

$$v = b_0 + b_1 x + b_2 y + b_3 x^2 + b_4 xy + b_5 y^2 \quad \left| \quad \frac{\partial u}{\partial x^2} = 2a_3 \quad \frac{\partial u}{\partial x \partial y} = a_4 \quad \frac{\partial u}{\partial y^2} = 2a_5 \right.$$

$$\frac{\partial^2 v}{\partial x^2} = 2b_3$$

$$\frac{\partial^2 v}{\partial x \partial y} = b_4 \quad \frac{\partial^2 v}{\partial y^2} = 2b_5$$

$$\frac{\partial f}{\partial x} = \frac{4}{3} \mu (2a_3 + b_4) + \mu (2a_3 + 2a_5)$$

$$\frac{\partial v}{\partial y} = b_2 + b_4 x + 2b_5 y$$

$$\frac{\partial f}{\partial x} = \mu \left(\frac{8}{3} a_3 + \frac{b_4}{3} + 2a_5 \right)$$

$$\frac{\partial v}{\partial x} = b_1 + 2b_3 x + b_4 y$$

$$\frac{\partial u}{\partial y} = a_2 + a_4 x + 2a_5 y$$

$$\frac{\partial f}{\partial y} = \mu \left(\frac{8}{3} b_3 + \frac{a_4}{3} + 2b_5 \right)$$

$$f = f_0 + \mu \left(\frac{8}{3} a_3 + \frac{1}{3} b_4 + 2a_5 \right) x + \mu \left(\frac{8}{3} b_3 + \frac{1}{3} a_4 + 2b_5 \right) y$$

$$\mu \left(\frac{8}{3} a_3 + \frac{1}{3} b_4 + 2a_5 \right) (a_0 + a_1 x + a_2 y + a_3 x^2 + a_4 xy + a_5 y^2) +$$

$$\left(\frac{8}{3} b_3 + \frac{1}{3} a_4 + 2b_5 \right) (b_0 + b_1 x + b_2 y + b_3 x^2 + b_4 xy + b_5 y^2) +$$

$$k \left[f_0 + \mu \left(\frac{8}{3} a_3 + \frac{1}{3} b_4 + 2a_5 \right) x + \mu \left(\frac{8}{3} b_3 + \frac{1}{3} a_4 + 2b_5 \right) y \right] \left[a_1 + b_1 + (2a_3 + b_4)x + (2b_5 + a_4)y \right]$$

$$= (k-1) \left\{ \left[\frac{4}{3} \mu \{ (a_1 + 2a_3 x + a_4 y)^2 + (b_1 + b_4 x + 2b_5 y)^2 - (a_1 + 2a_3 x + a_4 y)(b_1 + b_4 x + 2b_5 y) \} \right. \right. \\ \left. \left. + \mu [a_2 + b_1 + (a_4 + 2b_3)x + (2a_5 + b_4)y]^2 \right\} \right.$$

$$\left(\frac{8}{3} a_3 + \frac{1}{3} b_4 + 2a_5 \right) a_0 + \left(\frac{8}{3} b_3 + \frac{1}{3} a_4 + 2b_5 \right) b_0 + \cancel{4a_0 b_0} k(a_1 + b_1) \frac{\mu}{\mu} =$$

$$= (k-1) \left[\frac{4}{3} (a_1^2 + b_1^2 - a_1 b_1) + (a_2 + b_1)^2 \right]$$

$$A a_5 + B b_5 + k B (2b_5 + a_4) = (k-1) \left[\frac{4}{3} (a_4^2 + 4b_5^2 - 2a_4 b_5) + (2a_5 + b_4)^2 \right]$$

$$\text{Spróbować } a_0 = b_0 = a_1 = b_1 = a_5 = b_5 = 0$$

$$\text{tzn. że } u = v = 0 \text{ na osi } X$$

$$\begin{aligned} & \left(\frac{8}{3} a_3 + \frac{1}{3} b_4 \right) (a_1 x + a_3 x^2 + a_4 x y) + \left(\frac{8}{3} b_3 + \frac{1}{3} a_4 \right) (b_1 x + b_3 x^2 + b_4 x y) + \\ & + k \left[\frac{4}{3} + \left(\frac{8}{3} a_3 + \frac{1}{3} b_4 \right) x + \left(\frac{8}{3} b_3 + \frac{1}{3} a_4 \right) y \right] [a_1 + b_1 + (2a_3 + b_4)x + (2b_3 + a_4)y] \\ & = (k-1) \left[\frac{4}{3} \left\{ (a_1 + 2a_3 x + a_4 y)^2 + (b_1 x)^2 - (a_1 + 2a_3 x + a_4 y) b_4 x \right\} + \right. \\ & \quad \left. [b_1 + (a_4 + 2b_3)x + b_4 y]^2 \right] \end{aligned}$$

6. Porównać na płaszczyźnie $y^2, x^2, xy, x, y, 0$

$$u = x(a_1 + a_3 x + a_4 y)$$

$$v = x(b_1 + b_3 x + b_4 y)$$

zrobić równocześnie między a_i i b_i by $= 0$
na drugiej stronie tej strony także
 $a_1 : b_1 = a_3 : b_3 = a_4 : b_4$

$$\begin{aligned} & \left(\frac{8}{3} a_3 + \frac{1}{3} b_4 \right) a_4 x + \left(\frac{8}{3} b_3 + \frac{1}{3} a_4 \right) b_4 x + k \left(\frac{8}{3} b_3 + \frac{1}{3} a_4 \right) [a_1 + b_1 + (2a_3 + b_4)x + (2b_3 + a_4)y] + \\ & + a_4 \left[\frac{4}{3} + \left(\frac{8}{3} a_3 + \frac{1}{3} b_4 \right) x + \left(\frac{8}{3} b_3 + \frac{1}{3} a_4 \right) y \right] = \end{aligned}$$

$$= (k-1) \left[\frac{8}{3} a_4 (a_1 + 2a_3 x + a_4 y) - a_4 b_4 x + 2 [b_1 + (a_4 + 2b_3)x + b_4 y]^2 \right]$$

$$k \left\{ \left(\frac{8}{3} b_3 + \frac{1}{3} a_4 \right) a_4 + a_4 \left(\frac{8}{3} b_3 + \frac{1}{3} a_4 \right) \right\} = (k-1) \left(\frac{8}{3} a_4^2 + 2 b_4^2 \right)$$

$$k a_4 \left(\frac{8}{3} b_3 + \frac{1}{3} a_4 \right) =$$

Czy możliwe są następujące formy

$$u = a + e^{\alpha_1 x + \alpha_2 y}$$

$$\frac{\partial u}{\partial x} = \alpha_1 e^{\alpha_1 x + \alpha_2 y}$$

$$\frac{\partial u}{\partial y} = \alpha_2 e^{\alpha_1 x + \alpha_2 y}$$

$$v = b + e^{\beta_1 x + \beta_2 y}$$

$$\frac{\partial v}{\partial x} = \beta_1 e^{\beta_1 x + \beta_2 y}$$

$$\frac{\partial v}{\partial y} = \beta_2 e^{\beta_1 x + \beta_2 y}$$

Znając teki u i v należy złożyć równanie $u=0$ oraz $v=0$ przy $x=0$ $y=$

$$r = R \rho \theta$$

$$\rho \frac{\partial \theta}{\partial x} + \theta \frac{\partial \rho}{\partial x} = \frac{\mu}{3R} \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \frac{\mu}{2} \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right)$$

$$\rho \left[\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} \right] = - \frac{\partial p}{\partial x} + \frac{4\mu}{3} \frac{\partial^2 u}{\partial x^2}$$

$$\frac{\partial p}{\partial t} + \frac{\partial(\rho u)}{\partial x} = 0$$

| u

$$\frac{\partial^2 p}{\partial t^2} = - \frac{\partial^2(\rho u)}{\partial x \partial t}$$

$$\frac{\partial(\rho u)}{\partial t} + \frac{\partial(\rho u^2)}{\partial x} = - \frac{\partial p}{\partial x} + \frac{4\mu}{3} \frac{\partial^2 u}{\partial x^2}$$

$$\frac{\partial^2 p}{\partial t^2} = \frac{\partial^2(\rho u^2)}{\partial x^2} + \frac{\partial^2 p}{\partial x^2} - \frac{4\mu}{3} \frac{\partial^3 u}{\partial x^3}$$

$$\frac{\partial^2 p}{\partial t^2} = \frac{\partial^2}{\partial x^2} \left[p + \rho u^2 - \frac{4\mu}{3} \frac{\partial u}{\partial x} \right]$$

$$= \frac{\partial^2}{\partial x^2} \left[\rho(R\theta + u^2) - \frac{4\mu}{3} \frac{\partial u}{\partial x} \right]$$

Zamieńmy teraz u i u^2

$$\frac{c}{A} \rho \left(\frac{\partial \theta}{\partial t} + u \frac{\partial \theta}{\partial x} \right) + \rho \frac{\partial u}{\partial x} = \bar{F} + k \nabla^2 \theta$$

$$\frac{\partial p}{\partial t} + u \frac{\partial p}{\partial x} + k \rho \frac{\partial u}{\partial x} = (k-1) \bar{\Phi} + (k-1) k \frac{\partial^2 \theta}{\partial x^2}$$

$$\frac{\partial^2 \rho}{\partial t^2} = R \frac{\partial^2}{\partial t^2}(\rho \theta) = R \left[\rho \frac{\partial^2 \theta}{\partial t^2} + 2 \frac{\partial \rho}{\partial t} \frac{\partial \theta}{\partial t} + \theta \frac{\partial^2 \rho}{\partial t^2} \right]$$

zamiast tego: $\rho \theta$ i wyżej pójść:

$$\frac{\partial^2 \rho}{\partial t^2} = \frac{\partial^2}{\partial x^2} [R \rho \theta]$$

\downarrow

$$\frac{R}{k-1} \rho \left(\frac{\partial \theta}{\partial t} + u \frac{\partial \theta}{\partial x} \right) + \frac{\partial u}{\partial x} = k \frac{\partial \theta}{\partial x}$$

$$\frac{R}{k-1} \rho \frac{\partial \theta}{\partial t} - R \theta \frac{\partial \rho}{\partial t} = k \frac{\partial \theta}{\partial x}$$

$$\frac{\partial \rho}{\partial t} + \rho_0 \frac{\partial u}{\partial x} + u \frac{\partial \rho}{\partial x} = 0$$

Przybliżone rozwiązanie:

$$\text{wynikowo: } u = a \sin(\alpha x - \beta t)$$

$$\rho = -\rho_0 \frac{\alpha}{\beta} \sin(\alpha x - \beta t)$$

W jednowymiarowym zadaniu: upływa k

$$\left\{ \begin{array}{l} \frac{d\rho}{dx} = \frac{4}{3}\mu \frac{d^2 u}{dx^2} \quad \rho u = \rho_0 u_0 \\ u \frac{d\rho}{dx} + k \rho \frac{du}{dx} = (k-1) \frac{4}{3}\mu \left(\frac{du}{dx} \right)^2 + (k-1) k \frac{d^2 \theta}{dx^2} \end{array} \right. \quad \theta = \frac{4\mu}{R \rho_0 u_0}$$

$$\frac{d\theta}{dx} = \frac{1}{R \rho_0 u_0} \left[\rho_0 \frac{du}{dx} + \frac{4}{3}\mu \left(\frac{du}{dx} \right)^2 + \frac{4}{3}\mu u \frac{d^2 u}{dx^2} \right]$$

$$\rho = \rho_0 + \frac{4}{3}\mu \frac{du}{dx}$$

$$\frac{4}{3}\mu u \frac{d^2 u}{dx^2} + k \rho_0 \frac{du}{dx} + \frac{4}{3}\mu k \left(\frac{du}{dx} \right)^2 = \frac{4}{3}\mu k \left(\frac{du}{dx} \right)^2 - \frac{4}{3}\mu \left(\frac{du}{dx} \right)^2 + (k-1) k \frac{d^2 \theta}{dx^2}$$

$$\frac{4}{3}\mu \left[u \frac{d^2 u}{dx^2} + \left(\frac{du}{dx} \right)^2 \right] + k \rho_0 \frac{du}{dx} = (k-1) k \frac{d^2 \theta}{dx^2}$$

$$\frac{4}{3}\mu u \frac{du}{dx} + k \rho_0 u = (k-1) k \frac{d\theta}{dx} + (k-1) a$$

$$= (k-1) a + \frac{(k-1) k}{R \rho_0 u_0} \left[\rho_0 \frac{du}{dx} + \frac{4}{3}\mu \frac{d}{dx} \left(u \frac{du}{dx} \right) \right]$$

$$\frac{(k-1)\kappa}{R\rho_0 u_0} \left[\frac{4}{3}\mu \frac{d}{dx} \left(u \frac{du}{dx} \right) + p_0 \frac{du}{dx} \right] - \frac{4}{3}\mu u \frac{du}{dx} = k p_0 x - a(k-1)$$

Z približením podstatného jeho prvému približeniu:

$$R \frac{dp}{dx} = - \frac{(k-1)p_0}{\rho_0 u_0} \frac{du}{dx}$$

$$\frac{\frac{4}{3}\mu u - \frac{(k-1)\kappa}{R\rho_0 u_0} p_0}{k p_0 u - a(k-1)} du = dx$$

$$\int \frac{\frac{4}{3}\mu u - \frac{(k-1)\kappa}{u_0 \theta_0}}{u - \alpha} du = k p_0 x - b$$

$$= \frac{4}{3}\mu + \frac{\frac{4}{3}\mu \alpha - \frac{(k-1)\kappa}{u_0 \theta_0}}{u - \alpha}$$

$$\frac{4}{3}\mu(u-\alpha) + \left[\frac{4}{3}\mu \alpha - \frac{(k-1)\kappa}{u_0 \theta_0} \right] \log(u-\alpha) = k p_0 x - b$$

$$\frac{\partial^2 \rho}{\partial t^2} = R \left[\rho_0 \frac{\partial^2 \theta}{\partial x^2} + 2 \frac{\partial \rho}{\partial x} \frac{\partial \theta}{\partial x} + \theta_0 \frac{\partial^2 \rho}{\partial x^2} \right]$$

$$\rho_0 \frac{\partial \theta}{\partial t} - (k-1) \theta_0 \frac{\partial \rho}{\partial t} = \frac{(k-1) \kappa}{R} \frac{\partial^2 \theta}{\partial x^2} \quad 158$$

$$\frac{\partial^3 \rho}{\partial t^3} = R \theta_0 \frac{\partial^3 \rho}{\partial t \partial x^2} + \kappa (k-1) \frac{\partial^3 \theta}{\partial x^3}$$

↓
przybliżeni

$$\rho_0 \frac{\partial^3 \theta}{\partial t \partial x^2} = (k-1) \theta_0 \frac{\partial^3 \rho}{\partial t \partial x^2} + (k-1) \frac{\kappa}{R} \frac{\partial^3 \theta}{\partial x^3}$$

$$\rho \sim \rho^k \sim \rho^\theta$$

$$\theta \sim \rho^{k-1}$$

$$\frac{\partial \theta}{\partial x} = \frac{\partial}{\partial x} \rho^{k-1} = (k-1) \rho^{k-2} \frac{\partial \rho}{\partial x}$$

$$\frac{\partial^3 \theta}{\partial x^3} = (k-1) \frac{\partial^3 \rho}{\partial x^3} \frac{1}{\rho}$$

$$\frac{\partial^3 \rho}{\partial t^3} = R \theta_0 \kappa \frac{\partial^3 \rho}{\partial t \partial x^2} + \kappa \frac{(k-1)^2 \theta_0}{\rho_0} \frac{\partial^3 \rho}{\partial x^3}$$

$$\rho = a \sin(\alpha x - \beta t)$$

$$\alpha^3 = R \theta_0 \kappa \alpha^2 \beta - \frac{\kappa (k-1)^2 \theta_0}{\rho_0} \alpha^3$$

$$\alpha^3 = R \theta_0 \kappa \alpha - \frac{\kappa (k-1)^2 \theta_0}{\rho_0}$$

$$\frac{\beta}{\alpha} = a$$

$$a = \sqrt{\kappa R \theta_0} \quad \text{gdy } I \text{ przybliżeni}$$

$$\left[\alpha^2 - R \theta_0 \right] = - \frac{\kappa (k-1)^2 \theta_0}{\rho_0 \sqrt{\kappa R \theta_0}}$$

$$a = \sqrt{\kappa R \theta_0 - \frac{\kappa (k-1)^2 \theta_0}{\rho_0 a}}$$

$$a = \sqrt{a_0^2 - \frac{\kappa (k-1)^2 \theta_0}{\rho_0 a_0^3}}$$

$$= a_0 \left[1 - \frac{1}{2} \frac{\kappa (k-1)^2 \theta_0}{\rho_0 a_0^3} \right]$$

$$\frac{1}{2} \frac{(0.4)^2 \cdot 300 \cdot 0.000 \dots}{0.0013 \cdot (33000)^3} !$$

$$\begin{aligned}
& -\frac{2}{3} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)^2 + 2 \left(\frac{\partial u}{\partial x} \right)^2 + 2 \left(\frac{\partial v}{\partial y} \right)^2 + \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)^2 \\
& - u \frac{\partial}{\partial x} \left[-\frac{2}{3} \mu \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + 2 \mu \frac{\partial u}{\partial x} \right] - v \frac{\partial}{\partial y} \left[-\frac{2}{3} \mu \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + 2 \mu \frac{\partial v}{\partial y} \right] \\
& - u \frac{\partial}{\partial y} \left[\mu \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right] - v \frac{\partial}{\partial x} \left[\mu \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right]
\end{aligned}$$

$$\begin{aligned}
k \rho \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) &= \frac{2}{3} \left[u \frac{\partial}{\partial x} \rho \text{div} + v \frac{\partial}{\partial y} \rho \text{div} - \rho [\text{div}]^2 \right] \\
& - 2 \left[u \frac{\partial}{\partial x} \left(\mu \frac{\partial u}{\partial x} \right) + v \frac{\partial}{\partial y} \left(\mu \frac{\partial v}{\partial y} \right) \right] - \mu \left(\frac{\partial u}{\partial x} \right)^2 - \mu \left(\frac{\partial v}{\partial y} \right)^2 \\
& - \left[u \frac{\partial}{\partial y} \left(\mu \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right) + v \frac{\partial}{\partial x} \left(\mu \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right) - \mu \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)^2 \right] \\
&= \frac{2}{3} \left\{ u^2 \left[\frac{1}{u} \frac{\partial}{\partial x} \left(\mu \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \right) - \frac{1}{u^2} \frac{\partial u}{\partial x} \cdot \mu \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \right] + v^2 \left[\frac{1}{v} \frac{\partial}{\partial y} \left(\mu \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right) - \frac{1}{v^2} \frac{\partial v}{\partial y} \cdot \mu \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right] \right\}
\end{aligned}$$

~~1~~ + -

$$\begin{aligned}
&= \frac{2}{3} \left[u^2 \frac{\partial}{\partial x} \left(\mu \frac{\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)}{u} \right) + v^2 \frac{\partial}{\partial y} \left(\mu \frac{\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)}{v} \right) \right] \\
& - 2 \left[u^2 \frac{\partial}{\partial x} \left(\mu \frac{\frac{\partial u}{\partial x}}{u} \right) + v^2 \frac{\partial}{\partial y} \left(\mu \frac{\frac{\partial v}{\partial y}}{v} \right) \right] - \left[u^2 \frac{\partial}{\partial y} \left(\mu \frac{\left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)}{u} \right) + v^2 \frac{\partial}{\partial x} \left(\mu \frac{\left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)}{v} \right) \right] \\
& 2(k-1) \rho \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)
\end{aligned}$$

Przykładem uogólnienia podstawić: $\rho = \sqrt{cx+a} + \varphi$

$$u = \frac{y(y-\delta)}{2\mu} \frac{d\varphi}{dx} + \varphi$$

$$\begin{cases} \frac{\partial \rho}{\partial x} = \mu \frac{\partial^2 u}{\partial y^2} \\ \frac{\partial \rho}{\partial y} = \frac{\mu}{3} \frac{\partial^2 u}{\partial x \partial y} \end{cases}$$

$$\frac{\partial(\rho u)}{\partial x} = 0$$

$$u \frac{\partial \rho}{\partial x} + \rho \frac{\partial u}{\partial x} = (k-1)\mu \left(\frac{\partial u}{\partial y}\right)^2 + k(k-1) \frac{\partial^2 \theta}{\partial y^2}$$

$$u = \frac{y(y-\delta)}{4\mu} \cdot \frac{-c}{\sqrt{cx+a}} + \varphi \quad \parallel \quad \frac{\partial u}{\partial y} = \frac{2y-\delta}{4\mu} \cdot \frac{c}{\sqrt{cx+a}} + \frac{\partial \varphi}{\partial y} \quad \left\| \quad \frac{\partial^2 u}{\partial y^2} = \frac{c}{2\mu \sqrt{cx+a}} + \frac{\partial^2 \varphi}{\partial y^2} \right.$$

$$\frac{\partial u}{\partial x} = \frac{y(y-\delta)}{8\mu (\sqrt{cx+a})^3} \frac{c^2}{\partial x} + \frac{\partial \varphi}{\partial x} \quad \frac{\partial^2 u}{\partial x \partial y} = \frac{-(2y-\delta)c^2}{8\mu (\sqrt{cx+a})^3} + \frac{\partial^2 \varphi}{\partial x \partial y}$$

$$\frac{c}{2\sqrt{cx+a}} + \frac{\partial \rho}{\partial x} = \mu \frac{c}{2\mu \sqrt{cx+a}} + \mu \frac{\partial^2 \varphi}{\partial y^2} \quad \left. \begin{aligned} \frac{\partial \varphi}{\partial y} &= \frac{\mu}{3} \left[\frac{-(2y-\delta)c^2}{8\mu (\sqrt{cx+a})^3} + \frac{\partial^2 \varphi}{\partial x \partial y} \right] \end{aligned} \right\} \text{Transform!}$$

$$k(k-1) \frac{\partial^2 \theta}{\partial y^2} = \frac{y(y-\delta)}{4\mu} \frac{-c}{\sqrt{cx+a}} \frac{-c}{2\sqrt{cx+a}} + k\sqrt{cx+a} \frac{y(y-\delta)c^2}{8\mu (\sqrt{cx+a})^3}$$

$$- (k-1)\mu \frac{(2y-\delta)^2}{16\mu^2} \frac{c^2}{(cx+a)}$$

$$\begin{aligned} k \frac{\partial^2 \theta}{\partial y^2} &= \frac{-2y(y-\delta) - (2y-\delta)^2}{16\mu^2} \frac{c^2}{(a-cx)} = \frac{-\delta^2 + 4y\delta - 4y^2 + 2y\delta - 2y^2}{16\mu^2} \frac{c^2}{a-cx} \\ &= \frac{-(\delta^2 - 6y\delta + 6y^2)}{16\mu^2} \frac{c^2}{a-cx} \end{aligned}$$

$$\text{N.p. } y = \frac{\delta}{2} \quad \delta^2 - 3\delta^2 + \frac{6}{1} = -\frac{\delta^2}{2} \quad \left| \quad y^2 - y\delta + \frac{\delta^2}{4} = 0 \quad y = \frac{\delta}{2} \pm \sqrt{\frac{\delta^2}{4} - \frac{\delta^2}{4}} = \frac{\delta}{2} \pm \frac{\delta}{\sqrt{12}} \right.$$

$$k \frac{d\theta}{dy} = - \frac{(\delta^2 y - 3\delta y^2 + 2y^3)}{16\mu} \frac{c^2}{a-cx} + \cancel{\frac{1}{10}}$$

$$y = \frac{\delta}{2}$$

$$\frac{d\theta}{dy} = 0$$

$$\frac{1}{2} - \frac{2}{4} + \frac{1}{4}$$

$$k \theta = - \frac{(\delta^2 y^2 - 2\delta y^3 + \frac{y^4}{2})}{32\mu} \frac{c^2}{a-cx} + b$$

$$\theta = \theta_0 + \frac{\delta^2 (y - \frac{\delta}{2})^2}{32\mu k} \frac{c^2}{a-cx}$$

$$\text{Maximum } y = \frac{\delta}{2}$$

$$\theta = \theta_0 - \frac{\delta^4}{128\mu k} \frac{c^2}{a-cx}$$

$$= \theta_0 - \frac{\delta^4}{128\mu k} \frac{c^2}{r^2}$$

$$\frac{15 \cdot 8}{16 \cdot 7}$$

$$\frac{1}{3}$$

Podobnie przy symetrycznej waloracji:

$$u = \frac{r^2 - \delta^2}{8\mu} \frac{-c}{\sqrt{a-cx}} \quad || \quad \lambda = \sqrt{a-cx}$$

$$\frac{dy}{dx} = \mu \frac{1}{2} \frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right)$$

$$u \frac{dy}{dx} + k r \frac{du}{dx} = (k-1) \mu \left(\frac{\partial u}{\partial r} \right)^2 + (k-1) k \cdot \frac{1}{2} \frac{\partial}{\partial r} \left(r \frac{\partial \theta}{\partial r} \right)$$

$$\frac{dy}{dx} = \frac{-c}{2\sqrt{}}$$

$$\frac{\partial u}{\partial x} = \frac{r^2 - \delta^2}{8\mu} \frac{-c^2}{\sqrt{()^3}}$$

$$\frac{\partial u}{\partial r} = \frac{r}{4\mu} \frac{-c}{\sqrt{}}$$

$$\frac{c^2}{2} \frac{r^2 - \delta^2}{8\mu} \frac{1}{()} - k \frac{r^2 - \delta^2}{8\mu} \frac{c^2}{2} - (k-1) \mu \frac{r^2}{16\mu^2} \frac{c^2}{()} = (k-1) k \frac{1}{2} \frac{\partial}{\partial r} \left(r \frac{\partial \theta}{\partial r} \right)$$

$$\frac{\partial \theta}{\partial r} = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \theta}{\partial r} \right) = \frac{r^2 - \delta^2}{4\mu} \frac{c^2}{r^2}$$

$$\frac{1}{x} \frac{\partial}{\partial x} \left(x \frac{\partial \theta}{\partial x} \right) = \frac{1}{k\mu} \frac{-(x^2 - \delta^2) c^2 - x^2 c^2}{16(a - cx)} = \frac{c^2}{16k\mu} \frac{\delta^2 - 2x^2}{a - cx}$$

$$\frac{\partial}{\partial x} () = \frac{c^2}{16k\mu} \frac{\delta^2 - 2x^2}{a - cx}$$

$$x \frac{\partial \theta}{\partial x} = \frac{c^2}{16k\mu} \frac{\frac{\delta^2 x^2}{2} - \frac{x^4}{2}}{a - cx} + b$$

$$\frac{\partial \theta}{\partial x} = \frac{c^2}{32k\mu} \frac{2\delta^2 x - x^3}{a - cx} + \frac{b}{x}$$

$$\begin{cases} \theta = \frac{c^2}{32k\mu} \frac{\frac{\delta^2 x^2}{2} - \frac{x^4}{4}}{a - cx} + \frac{b}{2} \ln x + m \\ \theta_0 = \frac{\frac{\delta^2}{4}}{a - cx} + n \end{cases}$$



$$\theta = \theta_0 - \frac{c^2}{128k\mu} \frac{(\delta^2 - x^2)^2}{a - cx} = \theta_0 - \frac{(\delta^2 - x^2)^2}{128k\mu} \left[\frac{\mu_1^2 - \mu_2^2}{\ell_f} \right]^2$$

$$\left. \begin{aligned} \mu_1^2 &= \mu^2 \\ \mu_2^2 &= a - c\ell \end{aligned} \right\} \frac{\mu_1^2 - \mu_2^2}{\ell} = c \quad x = \frac{\delta}{2}$$

$$\text{Minimum: } \theta = \theta_0 - \frac{\delta^4}{k\mu} \frac{9}{16 \cdot 128} \left[\frac{\mu_1^2 - \mu_2^2}{\ell_f} \right]^2$$

$$\begin{aligned} N.p. \quad \delta &= 0.01 \\ \mu_1 &= 10^6 \parallel \mu_2 = \frac{3}{4} \cdot 10^6 \\ \ell &= 10 \\ \kappa &= 0.00006 \\ \mu &= 0.00017 \end{aligned}$$

$$\begin{aligned} & \frac{1}{240} \left[\frac{1}{2} \frac{10^6}{10} \right]^2 \cdot \frac{10^{-8}}{1.7 \cdot 6 \cdot 10^9 \cdot 42 \cdot 10^6} \\ &= \frac{10^5}{240 \cdot 4 \cdot 10 \cdot 42} = \frac{10^3}{96 \cdot 42} \\ &= \frac{10}{40} = \frac{1}{4} ^\circ \text{C} \end{aligned}$$

$$\left. \begin{aligned} \text{Izračunati vrijednosti n.p.} \quad \delta &= 0.02 \\ \ell &= 5 \text{ cm} \\ \mu_2 &= \frac{1}{2} \mu_1 \end{aligned} \right\} \text{bednja u mli}$$

$$\Delta \theta = \frac{1}{4} \cdot 16 \cdot 4 \cdot 3 = 48^\circ !!$$

II pythion:

$$\frac{\partial}{\partial x}(\rho u) + \frac{\partial}{\partial y}(\rho v) - \underbrace{R \rho \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} \right)}_{= R \rho \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} \right)} = 0$$

Integrally: by unalike $\theta = \text{const}$ // while $k=0$

$$\begin{aligned} \frac{\partial}{\partial x}(\rho u) + \frac{\partial}{\partial y}(\rho v) &= 0 = u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + \rho \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \\ \rho \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) &= -\frac{\mu}{3} \left[u \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + v \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \right] \\ &\quad - \mu \left[u \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) + v \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) \right] \end{aligned} \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} \text{I+II}$$

2 drugij stromy

$$\rho \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = \Phi \quad \text{zatem dyba mognetych byt:}$$

$$\begin{aligned} & \frac{1}{3} \left[u \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + v \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \right] + u \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) + v \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) + \\ & - \frac{2}{3} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)^2 + 2 \left(\frac{\partial u}{\partial x} \right)^2 + 2 \left(\frac{\partial v}{\partial y} \right)^2 + \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)^2 \end{aligned}$$

Najprostszj dawa i gubie nennatn pythody zidnanyu...

Podobienstwo dynamiczne

$$\frac{\partial \rho}{\partial x} = \frac{\mu}{3} \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \rho \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$$

$$\frac{\partial}{\partial x}(\rho u) + \frac{\partial}{\partial y}(\rho v) = 0$$

$$u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + k \rho \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = (k - \frac{1}{3}) \left[\left(\frac{\partial u}{\partial x} \right)^2 + \dots \right] + k \left[\frac{\partial^2 \theta}{\partial x^2} + \dots \right]$$

Mając rozwiązanie $p = p(x, y, z)$

$$\theta = \varphi(x, y, z)$$

$$\left. \begin{matrix} u \\ v \\ w \end{matrix} \right\} = \psi(x, y, z)$$

z danym rozwiązaniem o stałych (miernotomach)

I).

Otrzymamy inne rozwiązanie dla nazywa o rozmiarach n razy większych
podstawiając wykładnie $n x, n y, n z$ na miejsce x, y, z

$$\text{czyli } p = \frac{1}{n} p$$

II).

$\left. \begin{matrix} u \\ v \\ w \end{matrix} \right\}$ powiększyć n razy k n razy n razy n razy

III). n razy nazywa n razy większe

podstawia $n x, y, z$

k, μ, \dots n razy

IV).

n razy nazywa n razy $\left\{ \begin{matrix} x & y & z \\ u & v & w \end{matrix} \right\}$ p miernotom.
k (n) razy

Opisujemy więc podstawienie: $\begin{matrix} n & x \\ n & y \\ n & z \end{matrix}$ $\begin{matrix} k \\ \mu \\ \nu \end{matrix}$

$$a, \mu \dots \mu$$

$$p, k \dots k$$

$$\begin{matrix} m & u \\ m & v \\ m & w \end{matrix} \quad \begin{matrix} u \\ v \\ w \end{matrix}$$

$$b, p \dots p$$

$$n, \theta \dots \theta$$

$$\frac{1}{2\theta} \left[h \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right] + \frac{\partial \lambda}{\partial x} = \frac{1}{3} \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \mu \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)$$

I

II

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III

$$\frac{\partial}{\partial x} \Phi(x) + \frac{\partial}{\partial y} \Phi(y) = 0$$

$$u \frac{\partial \Phi}{\partial x} + v \frac{\partial \Phi}{\partial y} + w \frac{\partial \Phi}{\partial z} + k \mu \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = (k-1) \mu \Phi + k \nabla^2 \Phi$$

$$I). \quad \frac{b}{n} \frac{m^2}{n} \pm \frac{b}{n} \equiv \alpha \frac{m}{n^2}$$

$$III). \quad m \frac{b}{n} \equiv \alpha \frac{m^2}{n^2} \pm \beta \frac{n}{n^2}$$

$$I). \quad b \left(\frac{m^2}{n} + 1 \right) \equiv \alpha \frac{m}{n}$$

$$III). \quad b m \equiv \alpha \frac{m^2}{n} + \beta \frac{n}{n}$$

$$I). \quad \text{Kleinmengen} \quad \alpha = 1 \quad \beta = 1$$

$$b \left(\frac{m^2}{n} + 1 \right) \equiv \frac{m}{n}$$

$$b m \equiv \frac{m^2}{n} + \frac{n}{n}$$

1). Kleinmengen

$$\alpha = 1 \quad \beta = 1$$

$$b \left(\frac{m^2}{n} + 1 \right) \equiv \frac{m}{n}$$

$$b m \equiv \frac{m^2}{n} + \frac{1}{n m}$$

$$\left. \begin{aligned} b \left(\frac{m^2}{n} + 1 \right) &\equiv \frac{m}{n} \\ b m &\equiv \frac{m^2}{n} + \frac{1}{n m} \end{aligned} \right\} \text{Kleinmengen}$$

~~Kleinmengen~~

$$(m^2 + 1) \left(m + \frac{1}{m} \right) \equiv m$$

$$(m^2 + 1)^2 \equiv m$$

Kleinmengen

$$\text{Rohre rote} \quad r = -m^2$$

$$\frac{m}{n} + \frac{n}{n m} \left(\frac{m^2}{n} + 1 \right) \equiv \frac{1}{n}$$

$$m^2 + (m^2 + 1) \equiv m^2$$

Kleinmengen

Zaniedbyła produkt masy i kint.

~~II. $b = \alpha \frac{m}{n}$~~

~~III. $b \frac{m}{n} = \alpha \frac{m^2}{n^2} + \rho \frac{r}{n^2}$~~

~~$\alpha \frac{m^2}{n^2} = \alpha \frac{m^2}{n^2} + \rho \frac{r}{n^2}$~~

Nimniej!

II. $\frac{b}{n} m^2 = b = \alpha \frac{m}{n}$

III. $mb = \alpha \frac{m^2}{n} = \rho \frac{r}{n}$

~~3 równania~~ 3 równania masy 6 wielkości.

3 dozwolone

IV. ~~$m^2 = r$~~

$m^2 = r$

$\alpha \frac{m^2}{n} = \rho \frac{r}{n}$

$\alpha = \rho$

$\alpha m^2 = \rho r$

$\alpha r = \rho r$

zatem punkt jest tyko 2 dozwolone

$b = \alpha \frac{m}{n} = b \frac{m^2}{r}$

$mb = \alpha \frac{r}{n}$ } $m^2 = r$
 $b = \alpha \frac{m}{n}$

już, tak jest

punkt jest 2 równania:

$b = \alpha \frac{m}{n} = b \frac{m^2}{r}$ } $\left\{ \begin{array}{l} b = \alpha \frac{m}{n} \\ r = m^2 \end{array} \right\}$

$$b = 2 \frac{m}{n}$$

$$r = m^2$$

5 wielkości z których 3 dowolne

1. α i β :
określone i tworzące ostatnią

$$1). \text{ Niezmienność } \left\{ \begin{array}{l} \kappa \mu : \alpha = 1 \\ \theta : r = 1 \end{array} \right.$$

$$\mu = 1 \quad b = \frac{1}{n}$$

Uwaga: co do
ilosci ciał przemianowych

Tj. Rozmiary w rozrządzie, α i β zmieniają się w ten sposób, że masa przetrwała nie zmienia się.

$$2). \text{ Niezmienność } \kappa \mu : \alpha = 1$$

$$\text{warunek: } n = 1$$

$$b = m \quad r = m^2$$

to same jak dla
rodzaju 2 i 3
mianem

Przekształcenie przetrwania w rozrząd: α i β zmieniają się w ten sposób, że masa przetrwała nie zmienia się.

Różnica między przetrwaniem a rozrządem: α i β zmieniają się w ten sposób, że masa przetrwała nie zmienia się.

Uwaga: α i β zmieniają się w ten sposób, że masa przetrwała nie zmienia się.

$$I). \quad \frac{b}{n} m^2 = b = r \frac{m}{n} \quad \left\{ \begin{array}{l} r = m^2 \\ b = \frac{m^3}{n} \end{array} \right.$$

$$II). \quad m b = \frac{r^2}{n} \quad \left\{ \begin{array}{l} \frac{m^4}{n} = \frac{m^4}{n} \text{ same jak w poprzednim} \end{array} \right.$$

$$\text{Przekształcenie: } r = m^2 \quad b = \frac{m^3}{n}$$

1). Przekształcenie takie same

$$2). \quad n = 1 \quad \text{~~Przekształcenie~~ } r = m^2 \quad b = m^3$$

III.
a

$$a=1$$

~~III. a~~

$$m = \frac{1}{n}$$

$$b = \frac{1}{n^2}$$

$$r = \frac{1}{n^2}$$

Wz. ~~Wz.~~ porównajmy wartości w rozg. i zmniejszmy je o $\frac{1}{n}$
 aby od razu i tam zmniejszyć $\frac{1}{n^2}$ (porówn. Helmholtz)

IV.

$$a=1$$

$$m=n$$

$$b=1$$

$$r=n^2$$

[Ogólnie stajemy wobec nierówności, którą należy analizować w sposób inny]

$$\cancel{r^2 \varphi'' \varphi + 2r \varphi \varphi' - r^2 \varphi'^2} + b(2\varphi + r\varphi')(r_0 + 2r\varphi + r\varphi') = 0 \quad \Rightarrow 0$$

$$r^2 \varphi'' \varphi + 3r \varphi \varphi' + \varphi^2 + r \varphi \varphi' + r^2 \varphi'^2 + k[r\varphi + r\varphi'](r_0 + 2r\varphi + r\varphi') - \varphi^2 - r \varphi \varphi' - r^2 \varphi'^2$$

$$r^2(\varphi'' \varphi + \varphi'^2) + \varphi^2 + 4r \varphi \varphi'$$

$$\underbrace{r^2 d(\varphi \varphi') + 2r \varphi \varphi' + d(r \varphi^2)}_{d(r^2 \varphi \varphi')} \left. \vphantom{\frac{d(r^2 \varphi \varphi')}{d(r^2 \varphi \varphi')}}} \right\} = \frac{d[r \varphi \varphi' + r \varphi^2]}{d(r^2 \varphi \varphi')} = \frac{1}{2} d^2(r^2 \varphi^2)$$

$$r^2 \varphi'' \varphi + 4r \varphi \varphi' + r \varphi^2 + r^2 \varphi'^2$$

$$r^2 d(\varphi \varphi') + 3r \varphi \varphi' + \frac{1}{2} d(r^2 \varphi^2)$$

$$d(r^2 \varphi \varphi') + \frac{1}{2} d(r^2 \varphi^2) + k[r_0 d(r^2 \varphi) + 3\varphi r^2 + 3\varphi \varphi' r^2] = 0$$

$$r^2 \varphi \varphi' + \frac{r^2 \varphi^2}{2} + k r_0 r^2 \varphi + \frac{3}{2} k r^2 \varphi^2 = a$$

$$\cancel{r^2 \varphi \varphi'} + r^2 \varphi \varphi' + \frac{r^2 \varphi^2}{2} (1+3k) + k r_0 r^2 \varphi = a$$

Wzrosty kotowy dowodzenia:

$$u = x \frac{x}{n} \quad \parallel \quad v = 2 \frac{y}{n}$$

$$= \varphi x \quad = \varphi y$$

$$\frac{\partial u}{\partial x} = \varphi + \varphi' \frac{x^2}{n}$$

$$\frac{\partial u}{\partial y} = \varphi' \frac{xy}{n}$$

$$\frac{\partial^2 u}{\partial x^2} = \varphi' \frac{3x}{n} - \varphi' \frac{x^3}{n^3} + \varphi'' \frac{x^3}{n^2}$$

$$\frac{\partial^2 u}{\partial y^2} = \varphi' \frac{x}{n} - \varphi' \frac{xy^2}{n^3} + \varphi'' \frac{xy^2}{n^2}$$

$$\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} = \varphi' \frac{3x}{n} + \varphi'' x$$

$$\left(\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} \right) = 2\varphi + \varphi' x$$

$$\frac{\partial}{\partial x} = 3\varphi' \frac{x}{n} + \varphi'' x =$$

$$\frac{d}{dx} \cdot \frac{x}{n} = \frac{4}{3} (\varphi'' x + 3\varphi' \frac{x}{n})$$

$$I). \frac{d}{dx} = \frac{4}{3} (\varphi'' x + 3\varphi')$$

$$II). \varphi x \frac{x}{n} + \varphi x \frac{4}{3} (\varphi'' x + 3\varphi') + k p (2\varphi + x\varphi') =$$

$$= \frac{(k-1)^2}{3} \varphi^2 + \frac{4}{3} x \varphi \varphi' + \frac{4}{3} x^2 \varphi'^2 = \frac{(k-1)}{3} [\varphi^2 + x \varphi \varphi' + x^2 \varphi'^2]$$

$$I). \frac{d}{dx} = \frac{4}{3} \frac{d}{dx} [\varphi' x + 2\varphi]$$

$$p = \frac{4}{3} [\varphi' x + 2\varphi] + p_0 \frac{4}{3}$$

$$\Phi = -\frac{1}{3} (2\varphi + x\varphi')^2 + 4\varphi^2 + 2\varphi'^2 \frac{x^4 + y^4}{n^2}$$

$$+ 4\varphi \varphi' x + 4\varphi'^2 \frac{x^2 y^2}{n^2}$$

$$= -\frac{2}{3} (2\varphi + x\varphi')^2 + 4\varphi^2 + 4\varphi \varphi' x + 2x^2 \varphi'^2$$

$$r^3 \varphi' + \frac{r^2 \varphi^2}{2} (1+3k) + k p_0 r^2 \varphi = a$$

$$r \varphi = z$$

$$r d\varphi + \varphi dr = dz$$

$$r \varphi' = \frac{dz}{dr} - \frac{z}{r}$$

$$z \left(\frac{dz}{dr} - \frac{z}{r} \right) + \frac{z^2}{2} (1+3k) + k p_0 z z = a$$

$$\frac{z dz}{dr} + \frac{z^2}{2} \left(\frac{3k-1}{2} \right)$$

$$z \frac{dz}{dr} + \frac{z^2}{2} \frac{3k-1}{2} + k p_0 z = \frac{a}{r}$$

$$r^2 \varphi = z$$

$$\varphi = \frac{z}{r^2}$$

$$\varphi' = \frac{1}{r^2} \frac{dz}{dr} - \frac{2z}{r^3}$$

$$r z \left(\frac{1}{r^2} \frac{dz}{dr} - \frac{2z}{r^3} \right) + \frac{z^2}{r^2} \frac{1+3k}{2} + k p_0 z = a$$

$$z \frac{dz}{dr} - \frac{2z^2}{r^2} + \frac{z^2}{r^2} \left(\frac{1+3k}{2} \right) + k p_0 z = a$$

$$z \frac{dz}{dr} + \frac{z^2}{r^2} \frac{3(k-1)}{2} + k p_0 z = a$$

$$r \varphi^2 = z$$

$$\varphi \varphi' = \frac{1}{2r} \frac{dz}{dr} - \frac{z}{r^2}$$

$$\frac{1}{2} \left(r^2 \frac{dz}{dr} - rz \right) + rz \left(\frac{1+3k}{2} \right) + k p_0 r^2 z = a$$

$$r^2 \varphi^2 = y^2$$

$$2 + r \frac{dz}{dr} = 2y \frac{dy}{dr}$$

$$\frac{1}{2} y \frac{dy}{dr} - \frac{1}{2} y^2 + \frac{y^2}{2} \left(\frac{1+3k}{2} \right) + k p_0 r^2 y = a$$

$$y \frac{dy}{dr} + \frac{y^2}{2r} \frac{3k-1}{2} + k p_0 y = \frac{a}{r}$$

$$z \frac{dz}{dr} + \frac{z^2}{2} \frac{3k+1}{2} + k p_0 \frac{z}{r} = \frac{a}{r^3}$$

$$z \frac{dz}{dr} \frac{dr}{dr} + z^k \varphi \frac{3k-1}{2} + k p_0 z = \frac{a \varphi}{z}$$

~~$$z \frac{dz}{dr} \frac{dr}{dr} + z^k \varphi \frac{3k-1}{2} + k p_0 z = \frac{a \varphi}{z}$$~~

$$z + \varphi \frac{dz}{dr} = \frac{dz}{dr}$$

$$\frac{dr}{dz} = \frac{\varphi^2}{\varphi \frac{dz}{dr} - z}$$

$$\varphi^2 \frac{dr}{dz} = \varphi \frac{dz}{dr} - z$$

$$z \varphi^2 \frac{dz}{dr} + \left(z \varphi \frac{3k-1}{2} + k p_0 z - \frac{a \varphi}{z} \right) \left(\varphi \frac{dz}{dr} - z \right) = 0$$

$$z^2 \varphi = z$$

$$\frac{dr}{dz} = \frac{\varphi \frac{dz}{dr} - z}{2 \varphi \sqrt{\varphi z}}$$

$$\varphi z^2 + 2z \frac{dz}{dr} \varphi^2 = \frac{dz}{dr} \varphi$$

$$z \frac{dz}{dr} 2 \varphi \sqrt{\varphi z} + \left(\varphi \frac{dz}{dr} - z \right) \left[z^k \varphi \frac{3k-1}{2} + k p_0 z - \frac{a}{z} \right] = 0$$

$$\rightarrow z = u \cdot v$$

$$u v \left(u \frac{dv}{dr} + v \frac{du}{dr} \right) + \frac{u^2 v^2}{r^2} \frac{3k-1}{2} + k p_0 u v = \frac{a}{2}$$

$$u^2 \left[v \frac{dv}{dr} + \frac{v^2}{r^2} \frac{3k-1}{2} \right] + u \left[v^2 \frac{du}{dr} + k p_0 v \right] = \frac{a}{2}$$

$$\frac{du}{dr} = - \frac{k p_0}{v}$$

$$+ u^2 k p_0 \left[- \frac{1}{\left(\frac{dr}{du} \right)^2} \frac{d^2 u}{dr^2} \right] + \frac{u^2}{2 r^2} \frac{k^2 p_0^2}{\left(\frac{du}{dr} \right)^2} = \frac{a}{2}$$

$$v = - \frac{k p_0}{\frac{du}{dr}}$$

$$\frac{1}{v} \frac{dv}{dr} + \frac{3k-1}{2} \frac{1}{r} = 0$$

$$\gamma v = - \frac{3k-1}{2} \gamma r$$

$$v = A r^{-\frac{3k-1}{2}}$$

~~$$u \left(\frac{du}{dr} + k p_0 \frac{1}{v} \right) = \frac{a}{2}$$~~

$$u \frac{du}{dr} + k p_0 u A r^{\frac{3k-1}{2}} = \frac{a}{A^2} r^{-\frac{1-3k}{2}} = \frac{a}{A^2} r^{-3k}$$

~~$$\frac{du}{dr} = - \frac{k p_0}{v}$$~~

$$\varphi = 2r \quad \varphi = 2 + r \frac{dz}{dr}$$

60 -

20
20

$$2r^4(2+r \frac{dz}{dr}) + \frac{2^2 r^4}{2} \frac{3k+1}{2} + k_p r r^3 = 0$$

3 km

$$2r^5 \frac{dz}{dr} + 2^2 r^4 \frac{3k+1}{2} + r r^3 k_p = 0$$

III).

$$\frac{\partial \Phi}{\partial x} + \frac{\partial \Phi}{\partial y} = \frac{1}{r} \left(\frac{\partial \Phi}{\partial x} + \frac{\partial \Phi}{\partial y} \right) + \frac{1}{r} \left(\frac{\partial \Phi}{\partial x} + \frac{\partial \Phi}{\partial y} \right)$$

$$\iint \Phi dv = \mu \iint \left(\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} \right) + \dots + \frac{1}{3} (div)^2 +$$

$$\mu \left\{ u \left[m \frac{\partial v}{\partial x} + n \frac{\partial v}{\partial y} + l \frac{\partial u}{\partial x} - l \frac{\partial v}{\partial y} - l \frac{\partial u}{\partial z} \right] + v \left[\dots \right] + w \left[\dots \right] \right\}$$

$$\int \left(u \frac{\partial}{\partial x} v_n + v \frac{\partial}{\partial y} v_n + w \frac{\partial}{\partial z} v_n - v_n \operatorname{div} v \right)$$

$$\int \Phi = \iint \left(\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} \right) + \frac{1}{3} \operatorname{div}^2 + \iint \left(u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) v_n - \iint v_n \operatorname{div} v d\sigma$$

$$\iint \left(u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) dv = \iint \left(u l + v m + w n \right) d\sigma$$

$$\iint \left(u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) dv = \iint \left(u l + v m + w n \right) - \iint \left(u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) v_n$$

Ho H₁

$$= \iint \frac{\partial}{\partial n} \left(\frac{u^2 + v^2 + w^2}{2} \right) d\sigma + \frac{1}{3} \iint v_n \operatorname{div} v d\sigma - \mu \iint \left(\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} \right) \frac{1}{3}$$

$$c_0 \quad c_1 = \frac{c_0}{\sqrt{M_1}}$$

$$\left(\frac{c}{A} + R\right) \iint \rho \theta (u^2 + v^2 + w^2) dS =$$

$$= \iint \left[\frac{\partial}{\partial n} \left(\frac{u^2 + v^2 + w^2}{2} \right) + \frac{1}{3} v_n \operatorname{div} + \left(u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) v_n - v_n \operatorname{div} \right] dS +$$

$$= \iint \left[\frac{\partial}{\partial n} \left(\frac{u^2 + v^2 + w^2}{2} \right) + \left(u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) v_n - \frac{2}{3} v_n \operatorname{div} \right] dS +$$

$$+ \iint \frac{u^2 + v^2 + w^2}{2} \rho \left(\frac{v_n}{r} \right) dS$$

$$R \left(1 + \frac{1}{k-1} \right) \iint \dots = \frac{Rk}{k-1} \iint \rho \theta v_n dS = \uparrow = \frac{k}{k-1} \iint \rho v_n dS$$

Jedli na to zastoje do ruzki prgda



$$g_1 p_1 v_1 = g_2 p_2 v_2$$

$$\frac{kR}{k-1} \left(p_2 \theta_2 v_2 g_2 - p_1 \theta_1 v_1 g_1 \right) = - \frac{p_2 v_2^3 g_2 - p_1 v_1^3 g_1}{2} + \left\{ \left[\frac{\partial}{\partial s} \left(\frac{v_2^2}{2} \right) g_2 - \left(\frac{\partial}{\partial s} \left(\frac{v_1^2}{2} \right) g_1 \right) \right] \right.$$

$$\left. + \left[v_2 \frac{\partial v_2}{\partial s} g_2 - v_1 \frac{\partial v_1}{\partial s} g_1 \right] - \frac{2}{3} \left[v_2 \frac{\partial v_2}{\partial s} g_2 - v_1 \frac{\partial v_1}{\partial s} g_1 \right] \right\}$$

$$\left\{ \right\} = \frac{4}{3} \left[v_2 \frac{\partial v_1}{\partial s} g_2 - v_1 \frac{\partial v_1}{\partial s} g_1 \right] + \iint \frac{\partial}{\partial s} + \iint \nabla^2 \frac{u^2 + v^2 + w^2}{2} \frac{dv}{g_1 ds}$$

$$\frac{kR}{k-1} g_1 p_1 v_1 (\theta_2 - \theta_1) = p_1 p_1 v_1 \frac{v_2^2 - v_1^2}{2} + \frac{4}{3} \left[\frac{1}{p_2} \frac{\partial v_2}{\partial s} - \frac{1}{p_1} \frac{\partial v_1}{\partial s} \right] p_1 g_1 v_1$$

$$\frac{kR}{k-1} (\theta_2 - \theta_1) = - \frac{v_2^2 - v_1^2}{2} + \frac{4}{3} \left[\frac{1}{p_2} \frac{\partial v_2}{\partial s} - \frac{1}{p_1} \frac{\partial v_1}{\partial s} \right] + \left[\nabla^2 \left(\frac{u^2 + v^2 + w^2}{2} \right) \right] \frac{ds}{p_1 v}$$

$$\left(\frac{\partial}{\partial n} (u^2 + v^2 + w^2) \right) dS = \iint_{\partial V} S \left(\nabla \left(\frac{u^2 + v^2 + w^2}{2} \right) \cdot \vec{n} \right) dS =$$

$$\iint_{\partial V} \operatorname{div} \nabla \left(\frac{u^2 + v^2 + w^2}{2} \right) dv = \iiint_V \nabla^2 \left(\frac{u^2 + v^2 + w^2}{2} \right) dv = \iiint_V (\nabla^2)^2 \rho dS$$

$$u^2 + v^2 + w^2 = r^2$$

$$dv = \rho d\vec{r}$$

$$= \iint \left[u \frac{\partial u}{\partial n} + v \frac{\partial v}{\partial n} + w \frac{\partial w}{\partial n} \right] dS = \iint S v$$

Das ist jetzt zu zeigen, dass es die Lösung ist, dass u, v, w die Laplace-Gleichung erfüllen.

$$\delta \cdot \frac{\partial u}{\partial n}$$

$$\delta \cdot \frac{\partial v}{\partial n}$$

$$\delta \cdot \frac{\partial w}{\partial n}$$

$$\frac{\partial u}{\partial n} = \delta \frac{\partial u}{\partial r}$$

$$= \frac{\partial u}{\partial r} + \frac{1}{r} \frac{\partial u}{\partial \theta}$$

zweiter:

$$\iint u \frac{\partial u}{\partial n} dS \dots \delta \left[\left(\frac{\partial u}{\partial n} \right)^2 + \left(\frac{\partial v}{\partial n} \right)^2 + \left(\frac{\partial w}{\partial n} \right)^2 \right] dS \cdot dt$$

$$= \iint \left[\left(\frac{\partial u}{\partial n} \right)^2 + \left(\frac{\partial v}{\partial n} \right)^2 + \left(\frac{\partial w}{\partial n} \right)^2 \right] dS \cdot \rho$$

$$\rho, v, \rho_i = \rho \cdot v_i \rho_i$$

$$\delta dt \delta \left(\frac{\partial u}{\partial n} \right) \dots \rho = \dots$$

$$= \dots \frac{\partial u}{\partial r} \dots$$

zweiter:

zweiter: $\nabla^2 (u^2 + v^2 + w^2) = 0$ ist die Laplace-Gleichung, $\rho, \frac{\partial u}{\partial r}, \rho, \frac{\partial v}{\partial r}, \rho, \frac{\partial w}{\partial r}$ ist die

$$\frac{\partial^2 u}{\partial r^2} \dots = - \frac{u^2 + v^2 + w^2}{r^2}$$

Prędkość ruchu cieży: odwracalny

energiczny ruch $\frac{p_1 - p_2}{\omega}$ i ruch $\frac{u}{\omega}$ otrzymujemy znowu tożsamość

Szybki ruch nie odwracalny! Trójkąt z promieni cieży.

U górn: tożsamość prędkość ruchu nie odwracalny [asymetry: wpływ na

Idealne góry $\gamma = 1.300$
Nierówny i dotychczasowy, beztermin i bezprzewod
 Adiacja $\frac{1}{\rho_0} = \left(\frac{\rho}{\rho_0}\right)^k$ $\rho = \rho_0 \left(\frac{\rho}{\rho_0}\right)^{\frac{1}{k}}$

$$-\int \frac{dp}{\rho} = \frac{u^2 + v^2 + w^2}{2}$$

$$\int \frac{dp}{\rho_0 \left(\frac{\rho}{\rho_0}\right)^{\frac{1}{k}}} = \frac{\rho_0}{\rho_0} \int \frac{dp}{\rho^{\frac{1}{k}}} = \frac{\rho_0}{\rho_0} \frac{\rho^{-\frac{1}{k}+1}}{-\frac{1}{k}+1}$$

$$\frac{u^2 + v^2 + w^2}{2} = -\left(\frac{\rho_0}{\rho}\right)^{\frac{1}{k}} \frac{\rho}{\rho_0} \cdot \frac{k}{k-1} \Big| = -\frac{\rho_0}{\rho} \frac{\rho}{\rho_0} \frac{k}{k-1} \Big| = \frac{k \rho_0}{k-1} \Big|_2$$

Wzrost, a, a, a, a: $\frac{p_2}{\rho_2} = \frac{k}{k-1} \frac{\rho_0}{\rho_0} \left(\frac{\rho_0}{\rho_2}\right)^{\frac{1}{k}} = +K \frac{\rho_2}{\rho_0} \left(\frac{\rho_0}{\rho_2}\right)^{\frac{1}{k}}$

$$= -2 \frac{k}{k-1} \left[\frac{\rho_2}{\rho_0} \left(\frac{\rho_0}{\rho_2}\right)^{\frac{1}{k}} - \frac{\rho_0}{\rho_0} \right]$$

$$\frac{\rho_2}{\rho_0} \left(\frac{\rho_0}{\rho_2}\right)^{\frac{1}{k}} \left(\frac{2}{k-1} + 1\right) = \frac{2}{k-1} \frac{\rho_0}{\rho_0}$$

$$\frac{\rho_2}{\rho_0} \left(\frac{\rho_0}{\rho_2}\right)^{\frac{1}{k}} = \frac{2}{k+1}$$

$$\left(\frac{\rho_0}{\rho_2}\right)^{\frac{1-k}{k}} = \frac{2}{1+k}$$

$$\frac{\rho_2}{\rho_0} = \left(\frac{2}{1+k}\right)^{\frac{k}{1-k}}$$



$$\sqrt{k} \frac{\rho_2}{\rho_2} \cdot \rho_2 = \sqrt{k} \frac{\rho_2}{\rho_2} \cdot \rho_2$$

$$= \sqrt{k} \sqrt{\rho_2 \rho_0 \left(\frac{\rho_2}{\rho_0}\right)^{\frac{1}{k}}}$$

$$= \sqrt{k} \sqrt{\frac{\rho_0}{\rho_0^{\frac{1}{k}}}} \sqrt{\rho_2^{\frac{k+1}{k}}}$$

$$= \sqrt{k} \sqrt{\frac{\rho_0}{\rho_0^{\frac{1}{k}}}} \rho_0^{\frac{k+1}{2k}} \left(\frac{2}{1+k}\right)^{\frac{k}{2(1+k)}}$$

$$= \sqrt{k} \sqrt{\rho_0 \rho_0} \left(\frac{2}{1+k}\right)^{\frac{k+1}{2(1+k)}}$$

zinde rātrime: $\nabla(u^2 + v^2) = 0$

N.p. dromygnicome: $\frac{\partial}{\partial x}(u \frac{\partial u}{\partial x})$

$$u \frac{\partial^2 u}{\partial x^2} + v \frac{\partial^2 v}{\partial x^2} + u \frac{\partial^2 u}{\partial y^2} + v \frac{\partial^2 v}{\partial y^2} + \left(\frac{\partial u}{\partial x}\right)^2 + \left(\frac{\partial u}{\partial y}\right)^2 + \left(\frac{\partial v}{\partial x}\right)^2 + \left(\frac{\partial v}{\partial y}\right)^2 = 0$$

$$\frac{4}{3} \left(u \frac{\partial^2 u}{\partial x^2} + v \frac{\partial^2 v}{\partial y^2} + u \frac{\partial^2 u}{\partial y^2} + v \frac{\partial^2 v}{\partial x^2} + \frac{1}{5} \left(u \frac{\partial^2 v}{\partial x \partial y} + v \frac{\partial^2 u}{\partial x \partial y} \right) \right) +$$

$$k \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)^2 + \kappa \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) p_0 = (k-1) \left[\frac{1}{5} \left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial y} \right)^2 \right] + \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \left[\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right] - \frac{4}{3} \frac{\partial u}{\partial x} \frac{\partial v}{\partial y}$$

$$\frac{kR}{k-1} (\theta_2 - \theta_1) = \frac{\mu}{3} \frac{1}{\rho} \frac{\partial \theta}{\partial s} \left(\frac{\partial v}{\partial x} \frac{dx}{ds} + \frac{\partial v}{\partial y} \frac{dy}{ds} - \frac{\mu}{\rho} \right)$$

$$= \frac{\mu}{3} \frac{1}{\rho} \frac{u \frac{\partial^2 u}{\partial x^2} + v \frac{\partial^2 v}{\partial y^2} + v \frac{\partial^2 u}{\partial x \partial y} + u \frac{\partial^2 v}{\partial x \partial y}}{\sqrt{u^2 + v^2}}$$

$$\frac{kR}{k-1} (\theta - \theta_0) = \frac{\mu}{3} \frac{1}{\rho} \left(u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} \right) \sqrt{u^2 + v^2}$$

Wzrostaj zinde cālka nad poci. vāry = 0

Aty to v kordy punkti: ~~styk~~ zinde dla kordy elementu poci. vāry

1 v cālka nad dōk hū $\nabla(u^2 + v^2) = 0$



$$ds \int \nabla(u^2 + v^2) \cdot \mathbf{T}_0 \cdot \mathbf{n} = ds \int \mathbf{T}_0 \cdot \mathbf{n} \cdot \mathbf{R}(u^2 + v^2) = 0$$

$$= \int \mathbf{T}_0 \cdot \mathbf{n} \cdot \mathbf{R}(u^2 + v^2) df$$

$$\left[\int \mathbf{T}_0 \cdot \mathbf{n} \cdot \mathbf{R}(u^2 + v^2) df \right] = 0$$

$$\nabla p = \frac{\mu}{3} \nabla \operatorname{div} v + \mu \nabla^2 v - \underbrace{\rho(v \nabla) v}_{= -\rho(\nabla \frac{v^2}{2} + v \operatorname{curl} v)}$$

First we derive $\operatorname{curl} v \perp v$

$$\nabla^2 v = \nabla \operatorname{div} v - \operatorname{curl}^2 v$$

$$\int v \operatorname{curl} v = 0$$

in $\xi + v, \eta, \rho \xi = 0$

$$\nabla p = \frac{4}{3} \mu \nabla \operatorname{div} v - \operatorname{curl}^2 v$$

$$\operatorname{curl}^2 v = \nabla p - \frac{4}{3} \mu \operatorname{div} v$$

$$\operatorname{curl}^3 v = 0$$

$$\nabla^2 (\nabla p - \frac{4}{3} \mu \operatorname{div} v) = 0$$

$$v = \operatorname{curl} \frac{\operatorname{curl} v}{2} dv + \nabla \frac{\operatorname{div} v}{2} dv$$

$$= \operatorname{curl} \frac{\nabla p - \frac{4}{3} \mu \operatorname{div} v}{2} dv + \nabla \frac{\operatorname{div} v}{2} dv$$

~~Imaginary ρ string in $\operatorname{div} v = \frac{1}{\rho}$~~

$$\operatorname{div}(\rho v) = 0$$

→ to ensure $\operatorname{curl} v \perp \nabla p$

$$\begin{vmatrix} \frac{u}{v} & \frac{v}{v} & \frac{w}{v} \\ \frac{\partial u}{\partial x} & \frac{\partial v}{\partial x} & \frac{\partial w}{\partial x} \end{vmatrix}$$

$$\int S \cdot \nabla v dv = \int \left(\frac{1}{2} \rho v \frac{dv}{dt} - \dots \right)$$

$$\int \nabla^2 v dv$$

$$\int \nabla^2 v dv$$

$$\frac{u}{v}$$

$$\frac{d}{dt} \left(\rho \frac{dv}{dt} \right) = \rho \frac{dv}{dt}$$

Ungleichungen können auch:

$$\begin{aligned} \frac{u^2 + v^2 + 1}{2} &= \frac{k}{k-1} \left[\frac{p_0}{\rho_0} - \frac{p_0}{\rho_0} \left(\frac{p_0}{p} \right)^{\frac{1}{k}} \right] \\ &= \frac{k}{k-1} \left[\frac{p_0}{\rho_0} - \frac{p_0}{\rho_0} p^{1-\frac{1}{k}} \right] \quad \frac{p}{p_0} = \left(\frac{\rho}{\rho_0} \right)^k \\ &\quad \underbrace{\left[\frac{p_0}{\rho_0} \left(\frac{\rho}{\rho_0} \right)^k \right]^{\frac{k-1}{k}}} \\ &= \frac{k}{k-1} \left[\frac{p_0}{\rho_0} - \frac{p_0}{\rho_0} \left(\frac{\rho}{\rho_0} \right)^{k-1} \right] = \frac{k}{k-1} \frac{p_0}{\rho_0} \left[1 - \left(\frac{\rho}{\rho_0} \right)^{k-1} \right] \end{aligned}$$

gives $\gamma: \xi = \eta = \xi = 0$

$$u = \frac{\partial p}{\partial x} \quad \frac{\partial(pu)}{\partial x} + \dots = 0$$

$$u \frac{\partial p}{\partial x} + v \frac{\partial p}{\partial y} + \rho \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = 0$$

$$\left\{ \begin{aligned} \frac{\partial p}{\partial x} \frac{\partial (\gamma p)}{\partial x} + \frac{\partial p}{\partial y} \frac{\partial (\gamma p)}{\partial y} + \left(\frac{\partial \tilde{p}}{\partial x} + \frac{\partial \tilde{p}}{\partial y} \right) &= 0 \\ \left(\frac{\partial p}{\partial x} \right)^2 + \left(\frac{\partial p}{\partial y} \right)^2 &= \frac{k}{k-1} \frac{p_0}{\rho_0} \left[1 - \left(\frac{\rho}{\rho_0} \right)^{k-1} \right] \end{aligned} \right.$$

$$\gamma \left\{ 1 - \left[\left(\frac{\partial p}{\partial x} \right)^2 + \left(\frac{\partial p}{\partial y} \right)^2 \right] \frac{k-1}{k} \frac{p_0}{\rho_0} \right\} = (k-1) [\gamma p - \gamma_0 p_0]$$

$$\begin{aligned} (k-1) \frac{\partial \gamma p}{\partial x} &= \frac{\partial}{\partial x} \gamma \left\{ 1 - a \left[\left(\frac{\partial p}{\partial x} \right)^2 + \left(\frac{\partial p}{\partial y} \right)^2 \right] \right\} \\ &= \frac{-2a \left(\frac{\partial p}{\partial x} \frac{\partial \tilde{p}}{\partial x} + \frac{\partial p}{\partial y} \frac{\partial \tilde{p}}{\partial y} \right)}{1 - a \left[\left(\frac{\partial p}{\partial x} \right)^2 + \left(\frac{\partial p}{\partial y} \right)^2 \right]} \end{aligned}$$

$$2a \left[\left(\frac{\partial p}{\partial x} \right)^2 \frac{\partial \tilde{p}}{\partial x} + 2 \frac{\partial p}{\partial y} \frac{\partial \tilde{p}}{\partial x} \frac{\partial \tilde{p}}{\partial y} + \left(\frac{\partial p}{\partial y} \right)^2 \frac{\partial \tilde{p}}{\partial y} \right] - (k-1) \left(\frac{\partial \tilde{p}}{\partial x} + \frac{\partial \tilde{p}}{\partial y} \right) \left[1 - a \left[\left(\frac{\partial p}{\partial x} \right)^2 + \left(\frac{\partial p}{\partial y} \right)^2 \right] \right] = 0$$

Próba dla sfery izotermicznej:

$$\frac{p_0}{\rho_0} = a$$

$$\frac{u^2 + v^2}{2} = -\frac{p_0}{\rho_0} \ln \frac{\rho}{\rho_0}$$

$$\frac{\partial \ln p}{\partial x} = a \frac{\partial}{\partial x} \left[\left(\frac{\partial \varphi}{\partial x} \right)^2 + \left(\frac{\partial \varphi}{\partial y} \right)^2 \right]$$

$$a \left[\left(\frac{\partial \varphi}{\partial x} \right)^2 \frac{\partial \rho}{\partial x} + 2 \frac{\partial \varphi}{\partial x} \frac{\partial \varphi}{\partial y} \frac{\partial \rho}{\partial y} + \left(\frac{\partial \varphi}{\partial y} \right)^2 \frac{\partial \rho}{\partial y} \right] + \frac{\partial \rho}{\partial x} u + \frac{\partial \rho}{\partial y} v = 0 \quad \text{czyż?}$$

$$\frac{p}{\rho_0} = \left(\frac{\rho}{\rho_0} \right)^k \quad \frac{\theta}{\theta_0} = \left(\frac{\rho}{\rho_0} \right)^{k-1} = \left(\frac{p}{p_0} \right)^{\frac{k-1}{k}}$$

$$\frac{u^2 + v^2}{2} = \frac{k}{k-1} \left[\frac{p}{\rho_0} - \frac{p_0}{\rho_0} \frac{\theta}{\theta_0} \right] = \frac{k}{k-1} R \theta_0 \left[1 - \frac{\theta}{\theta_0} \right] = \frac{k}{k-1} R (\theta_0 - \theta)$$

u i v będzie miało maximum na osi symetrii
zatem $\frac{\partial}{\partial n} (u^2 + v^2) = 0$ wzdłuż osi jak θ (jak
dla prądu θ będzie ρ^2 to samo wzdłuż osi)

→ jeżeli zadani jest symetryczny:

izotermiczne:

$$\rho u = \text{const}$$

$$u e^{-\frac{p_0}{\rho_0} \frac{u^2}{2}} = \text{const}$$

adiabatyczne:

Równanie to ~~nie~~ musi być spełnione również wzdłuż osi

przy prądzie niesymetrycznym, było:

$$\begin{cases} \frac{\partial \rho}{\partial t} + \frac{\partial (\rho u)}{\partial x} = 0 \\ \frac{\partial \varphi}{\partial t} + \frac{1}{2} \left(\frac{\partial \varphi}{\partial x} \right)^2 = -\frac{k}{k-1} \frac{p_0}{\rho_0} \left[1 - \left(\frac{\rho}{\rho_0} \right)^{k-1} \right] \end{cases}$$

$$\begin{cases} \frac{\partial \rho}{\partial t} + \frac{\partial (\rho u)}{\partial x} = 0 \\ \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = -k \frac{p_0}{\rho_0} \left(\frac{\rho}{\rho_0} \right)^{k-2} \frac{\partial \rho}{\partial x} \end{cases} \quad \left| \cdot \frac{u}{\rho} \right. \quad \begin{cases} \frac{\partial \rho u}{\partial t} + \frac{\partial (\rho u^2)}{\partial x} = -\frac{k p_0}{\rho_0} \left(\frac{\rho}{\rho_0} \right)^{k-2} \rho \frac{\partial \rho}{\partial x} \end{cases}$$

$$\Delta^2 \theta = \frac{0}{\alpha} \left[u \frac{\partial^2}{\partial x^2} + v \frac{\partial^2}{\partial y^2} + k \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) - (k-1) \Phi \right]$$

$$\alpha = \frac{1}{\lambda}$$

$$\theta = \theta_0 + \alpha \varphi + \frac{\alpha^2}{2} \psi + \dots$$

$$\theta = \theta_0 + \alpha \theta' + \frac{\alpha^2}{2} \theta'' + \dots$$

$$\Delta^2 \theta = \alpha \Delta^2 \varphi + \frac{\alpha^2}{2} \Delta^2 \psi + \dots$$

$$u = u_0 + \alpha u' + \frac{\alpha^2}{2} u'' + \dots$$

~~Dla danych u i v, k i p, możemy wyznaczyć~~

$$p = p_0 + \alpha p' + \frac{\alpha^2}{2} p'' + \dots$$

$\Delta^2 \varphi = u \frac{\partial^2}{\partial x^2} + v \frac{\partial^2}{\partial y^2} + \dots$ Wtedy w pierwszym przybliżeniu:

$$\frac{\partial(p_0 u_0)}{\partial x} + \frac{\partial(p_0 v_0)}{\partial y} = 0$$

$$\frac{\partial \varphi_0}{\partial x} = \frac{1}{3} \frac{\partial}{\partial x} \left(\frac{\partial u_0}{\partial x} + \dots \right) + \dots$$

$$\frac{\partial(p_0 u_0)}{\partial x} + \frac{\partial(p_0 v_0)}{\partial y} = 0$$

$$\frac{1}{\rho_0} = R \theta_0$$

$$\Delta^2 \theta' = \left[u_0 \frac{\partial^2}{\partial x^2} + \dots - (k-1) \Phi_0 \right]$$

2e porównajmy drugie przybliżenie:

$$\frac{p_0 + \alpha p'}{\rho_0 + \alpha \rho'_0} = R(\theta_0 + \alpha \theta')$$

$$\frac{p'}{p_0} = \frac{\theta'}{\theta_0} + \frac{\rho'}{\rho_0}$$

$$p_0 + \alpha p' = R(\theta_0 + \alpha \theta')(\rho_0 + \alpha \rho'_0)$$

$$\rho_0 \left(\frac{\partial u'}{\partial x} + \frac{\partial v'}{\partial y} \right) + u_0 \frac{\partial \rho'}{\partial x} + v_0 \frac{\partial \rho'}{\partial y} = 0$$

$$p' = R \left[\rho_0 \theta' + \rho' \theta_0 \right] = p_0 \left[\frac{\theta'}{\theta_0} + \frac{\rho'}{\rho_0} \right]$$

$$\frac{\partial p'}{\partial x} = \frac{p_0}{3} \frac{\partial^2 u'}{\partial x^2} + \dots$$

$$p' = p_0 \frac{\theta'}{\theta_0} + R \theta_0 \rho'$$

$$R \theta_0 \frac{\partial \rho'}{\partial x} = \frac{\partial p'}{\partial x} - \frac{\partial p_0}{\partial x} \frac{\theta'}{\theta_0} - \frac{p_0}{\theta_0} \frac{\partial \theta'}{\partial x}$$

$$\frac{\partial p'}{\partial x} = \frac{\frac{\partial p_0}{\partial x} \cdot \theta' + p_0 \frac{\partial \theta'}{\partial x}}{\theta_0} + R \theta_0 \frac{\partial \rho'}{\partial x}$$

$$R \theta_0 \rho_0 \left(\frac{\partial u'}{\partial x} + \frac{\partial v'}{\partial y} \right) + \dots$$

$$+ u_0 \frac{\partial \rho'}{\partial x} + v_0 \frac{\partial \rho'}{\partial y} - \frac{\theta'}{\theta_0} (u_0 \frac{\partial p_0}{\partial x} + v_0 \frac{\partial p_0}{\partial y}) -$$

$$- \frac{p_0}{\theta_0} (u_0 \frac{\partial \theta'}{\partial x} + v_0 \frac{\partial \theta'}{\partial y}) = 0$$

$$\nabla_i: \quad \frac{\partial f'}{\partial x} = \frac{\mu}{3} \frac{\partial}{\partial x} \left(\frac{\partial u'}{\partial x} + \frac{\partial v'}{\partial y} \right) + \dots$$

$$\frac{\partial f'}{\partial y} = \dots$$

$$\rho_0 \left(\frac{\partial u'}{\partial x} + \frac{\partial v'}{\partial y} \right) + \mu_0 \frac{\partial f'}{\partial x} + \nu_0 \frac{\partial f'}{\partial y} = \frac{\mu_0}{\theta_0} \left(u_0 \frac{\partial}{\partial x} + v_0 \frac{\partial}{\partial y} \right) (\rho_0 \theta')$$

first dummy streamlines $\frac{\partial f'}{\partial y} = 0$ [later written by the first $\frac{\partial u'}{\partial x}$, b. not a streamlines do $\frac{\partial u'}{\partial y}$]

$$\therefore v' = 0$$

$$\left\{ \begin{array}{l} \frac{\partial f'}{\partial x} = \mu \frac{\partial^2 u'}{\partial y^2} \\ \rho_0 \frac{\partial u'}{\partial x} + \mu_0 \frac{\partial f'}{\partial x} = \frac{1}{\theta_0} \mu_0 \frac{\partial (\rho_0 \theta')}{\partial x} \end{array} \right. \quad \Big| : \frac{\partial}{\partial y^2}$$

$$\frac{\partial^2 f'}{\partial x^2} = \mu \frac{\partial^3 u'}{\partial x \partial y^2}$$

$$\rho_0 \frac{\partial u'}{\partial x \partial y^2} + \frac{\partial \mu_0}{\partial y^2} \frac{\partial f'}{\partial x} = \frac{1}{\theta_0} \frac{\partial^2}{\partial y^2} \left(\mu_0 \frac{\partial}{\partial x} \right)$$

$$\rho_0 \frac{\partial^2 f'}{\partial x^2} + \mu \frac{\partial \mu_0}{\partial y^2} \frac{\partial f'}{\partial x} = \frac{\mu}{\theta_0} \frac{\partial^2}{\partial y^2} \left(\mu_0 \frac{\partial (\rho_0 \theta')}{\partial x} \right)$$

$$\int \frac{1}{R\theta} \mu \frac{\partial u}{\partial x} + \frac{\partial 1}{\partial x} = \mu \frac{\partial^2 u}{\partial x^2}$$

$$\mu \frac{\partial \Phi}{\partial x} + k r \frac{\partial u}{\partial x} = (k-1)\mu \Phi + \binom{k-1}{k} \nabla^2 \theta$$

Podobništro dla isinyh gorai 2

given value of $R = \frac{1}{\rho_0}$

2m m g x 2 m R n p R d k j k d a n i

$$\left. \begin{aligned} \frac{b m^2}{p r n} &\equiv \frac{b}{n} \equiv \alpha \frac{m}{n^2} \\ \frac{m b}{n} &\equiv \alpha \frac{m^2}{n^2} \equiv \beta \frac{n}{n^2} \end{aligned} \right\}$$

$$\frac{m^2}{\rho r} = 1$$

$$\frac{f}{n} = \alpha \frac{m}{n} = \beta \frac{r}{m n} \quad \left. \begin{array}{l} \text{no } f \text{ within} \\ 4 \text{ downslope} \end{array} \right\}$$

St. George's downtown P. A. R.

$$\frac{m^2}{r} \equiv \rho \equiv \frac{m^2}{r} \equiv \frac{\rho}{\alpha}$$

$$b \approx \alpha \frac{m}{n}$$

$$\rho \equiv \beta_{\alpha}$$

12 tyżek!
(Podobne mogą być tyżki w innych takich godzinach!)

przy których $\frac{x}{\mu R}$ ~~tolisane~~ ~~wzr~~ przy których

Table 1

$\frac{P_{O_2}}{P_{H_2}}$	O_2	N_2	CO_2	CH_4	C_2H_6	CO
$\frac{7}{0.5} = 14$	$\frac{16.1}{1}$	$\frac{14.1}{1}$	$\frac{22.071}{0.82} = 19$	$\frac{8.165}{0.63} = 21$	$\frac{14.589}{0.56} = 22$	$\frac{22.073}{0.82} = 20$

wie wohl nicht die Wissenschaften sind für Kinder zu erklären und zu erklären

Ustady redukuj się to no:

$$\frac{m^2}{n} = \rho$$

stwierdza dowolnie i wielkości

$$b = \alpha \frac{m}{n}$$

Wg. $\rho, \alpha, n=1,$

$$m^2 = \rho$$

$$b n = \alpha m = \alpha \sqrt{\rho}$$

$$\left. \begin{array}{l} m = \sqrt{\rho} \\ b n = \alpha \sqrt{\rho} \end{array} \right\}$$

I. robisz warunki niesumienne $n=1$ powyżej

$$\left\{ \begin{array}{l} m = \sqrt{\rho} = \sqrt{\frac{1}{\rho_0}} \\ b = \alpha \sqrt{\rho} = \frac{\alpha}{\sqrt{\rho_0}} \end{array} \right.$$

Wg. powyższych $\sim \frac{1}{\sqrt{\rho_0}}$
jakiś wymiar $\sim \frac{\alpha}{\sqrt{\rho_0}}$

ilosc przepływu $\sim \frac{u}{R\theta} \parallel \frac{b m}{\rho r} = \frac{3}{\rho} = \underline{\underline{\alpha}}$

~~zatem~~ zatem jakiś

ograniczenie się no ρ i ρ_0

$$\frac{m^2}{\rho n} = 1 \quad m = \sqrt{\rho n}$$

zatem $m = \sqrt{\rho}$
ponieważ ρ jest stałe
zatem dla powyższych n

II. dla warunków niesumienne $b=1$

$$m^2 = \rho$$

$$n = \alpha m = \alpha \sqrt{\rho}$$

$$m = \frac{1}{\sqrt{\rho_0}}$$

$$n = \frac{\alpha}{\sqrt{\rho_0}}$$

$$\rho = \frac{m^2}{n}$$

$$b = \alpha \frac{m}{n}$$

$$m = \sqrt{\rho}$$

$$n = 1$$

$$m = \sqrt{\rho}$$

$$b = \alpha \sqrt{\rho}$$

$$n = 1$$

$$m = \frac{1}{\alpha}$$

$$n = \frac{1}{\alpha \sqrt{\rho}}$$

$$\frac{\partial u}{\partial t} = 0$$

$$\left. \begin{array}{l} b=1 \\ n=1 \\ m = \sqrt{\rho} \\ b = \alpha \sqrt{\rho} \end{array} \right\}$$

$$\left. \begin{array}{l} b=1 \\ b=1 \\ \alpha = m \\ n = 3/\alpha \end{array} \right\}$$

zatem $\frac{m^2}{\rho n} = \alpha$
zatem dla powyższych $n \sim \frac{1}{m}$

Des taria ad laty uni:

$$\frac{b m^2}{\rho n} \equiv \frac{b}{n}$$

$$\frac{m b}{n} \equiv k \frac{b}{n} \quad k=1$$

Sylko takie będo podobne, które nęgo taria k

Testum smu, a taria uni:

$$\frac{b m^2}{\rho n} \equiv \frac{b}{n} \equiv \alpha \frac{m}{n^2}$$

$$m^2 = \rho$$

$$b n = \alpha m = \alpha \sqrt{\rho}$$

To jest tak samo jak z uwzględnieniem Φ i $\Delta \Phi$ jeżeli $k = \infty$!

$$m = \sqrt{\rho} = \frac{1}{\sqrt{\rho_0}}$$

$$b n = \frac{\alpha}{\sqrt{\rho_0}}$$

to jest równość niesamodzielna:
ciężar przyspieszenia $\propto \alpha$

$$\text{ciężar przyspieszenia} \propto \frac{\alpha}{\alpha} \sqrt{\rho_0} = \sqrt{\rho_0}$$

$$\text{ciężar} \frac{F}{R_0} = \frac{\alpha}{\sqrt{\rho_0}} \rho_0 = \alpha \sqrt{\rho_0} \quad \text{ciężar} \propto \frac{\sqrt{\rho_0}}{\alpha \sqrt{\rho_0}} = \frac{1}{\alpha}$$

to jest ciężarowi do dwojaka nadeknieć musi jeżeli $k = \infty$

i jeżeli powiemy że ciężar jest odpowiednio większy.

U prvom slučaju metoda transverzija:
 Objekti su mjerena pod istom udaljenošću $\frac{1}{2}(\rho_0 + \rho_1)$ ~~u istom~~ $\frac{1}{2}(\rho_0 + \rho_1)$

Stavljajući $u = u_0 + \mu u'$ itd.

$$\left. \begin{aligned} u_0 \frac{\partial u_0}{\partial x} + \dots &= -\frac{\partial \rho_0}{\partial x} \\ \frac{\partial \rho_0 u_0}{\partial x} + \dots &= 0 \\ u_0 \frac{\partial \rho_0}{\partial x} + \dots + k \rho_0 \left(\frac{\partial u_0}{\partial x} + \dots \right) &= \kappa \Delta^2 \theta_0 \end{aligned} \right\} \rho_0 = R \theta_0$$

$$\left\{ \begin{aligned} u_0 \frac{\partial u'}{\partial x} + \dots + u' \frac{\partial u_0}{\partial x} + \dots &= -\frac{\partial \rho'}{\partial x} + \frac{\mu}{3} \frac{\partial}{\partial x} \left(\frac{\partial u_0}{\partial x} + \frac{\partial u}{\partial y} \right) + \dots \\ \rho_0 \frac{\partial u'}{\partial x} + u_0 \frac{\partial \rho'}{\partial x} + \dots &= 0 \\ u_0 \frac{\partial \rho'}{\partial x} + \dots + u' \frac{\partial \rho_0}{\partial x} + \dots + k \rho_0 \left(\frac{\partial u'}{\partial x} + \dots \right) + k \rho' \left(\frac{\partial u_0}{\partial x} + \dots \right) &= (k-1) \rho_0 + \kappa(k-1) \Delta^2 \theta' \end{aligned} \right.$$

~~$\rho = R \theta$~~ $\rho' = R [\theta_0 \rho' + \theta' \rho_0]$

Drugi slučaj i poredak

~~$\frac{\partial \rho}{\partial x}$~~

$$u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} + k \rho \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = 0$$

$$u \frac{\partial \rho_0}{\partial x} + v \frac{\partial \rho_0}{\partial y} + w \frac{\partial \rho_0}{\partial z} + k \rho_0 \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = 0$$

$$u \frac{\partial \rho_0}{\partial x} + v \frac{\partial \rho_0}{\partial y} + \dots + \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = 0$$

$$-\rho \left[u \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + v \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + w \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) \right] + k \rho \left(\frac{\partial u}{\partial x} + \dots \right) = 0$$

$$\left(u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) \frac{u^2 + v^2 + w^2}{2} = \frac{k \rho}{\rho} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)$$

$$u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + w \frac{\partial f}{\partial z} + k \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = 0 \quad \text{III)}$$

zinde sie zuponyje $\frac{f}{p_0} = \left(\frac{p}{p_0} \right)^k :$ IV)

$$\therefore k u \frac{\partial p}{\partial x} \cdot p^{k-1} + \dots + k p^k \frac{\partial u}{\partial x} = 0$$

$$\text{II). } \frac{\partial(pu)}{\partial x} + \frac{\partial(pv)}{\partial y} + \dots = 0$$

steji sie stedy vz, vzke rovnost III moze
bude rovnost IV

III otrzymame sie vztahem IV do II

steje ste u tepe mi vyjika ze z III i II rovnice vyjde IV?

$$\left(u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) \log p + k \left(\frac{\partial u}{\partial x} + \dots \right) = 0$$

$$\left(u \frac{\partial}{\partial x} + \dots \right) \log p + \left(\frac{\partial u}{\partial x} + \dots \right) = 0 \quad | -k$$

$$\left(u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) \log \left(\frac{p}{p_0} \right) = 0$$

Is znazy ze kazda usteticka form mi umenia jednosmery byje $\log \left(\frac{p}{p_0} \right)$
zatem pravadiet.

Vynika stedy dla mchu mchovory z rovnice $\int \frac{dp}{p} = \frac{k}{k-1} = \frac{u^2 v^2 w^2}{2}$
to rovnice dla mchu ofebnyho vzty $\int \dots$:

$$\frac{k R (\theta_2 - \theta_1)}{k-1} + \left(\frac{u^2 v^2 w^2}{2} \right)_2 - \left(\frac{u^2 v^2 w^2}{2} \right)_1 = 0$$

~~steje puzijem dle rovnice mchovory~~

Zatem ~~ste~~ $\frac{k}{k-1} R \theta + \frac{u^2 v^2 w^2}{2} = \text{const} = \frac{k}{k-1} R \theta_0$ | jinde w rovnice u vztych

maksymalne vartni dle rychlosti ply $\theta = 0$

$$\frac{u^2 v^2 w^2}{2} = \frac{k}{k-1} R \theta_0 = \frac{k}{k-1} \frac{p_0}{\rho_0}$$

$$\sqrt{k^2 + k^2} = \sqrt{\frac{2}{k-1}} \sqrt{k \frac{k_0}{p_0}}$$

but the magnitude $a^2 = k \frac{k_0}{p} = k R \theta$

$\sqrt{\frac{2}{k-1}}$ is the magnitude of the vector $= \sqrt{\frac{2}{k-1}}$ or the magnitude of the vector

$$\sqrt{\frac{2}{0.4}} = \sqrt{5} = 2.4$$

which is the magnitude of the vector (0° ab.)

Since we are given the vector & the magnitude

$$\sqrt{a^2} = a$$

$$\frac{k}{k-1} \theta + \frac{k \theta}{2} = \frac{k}{k-1} \theta_0$$

$$(2+k-1)\theta = 2\theta_0$$

$$\theta = \frac{2\theta_0}{k+1}$$

$$\theta_0 - \theta = \theta_0 \frac{k-1}{k+1}$$

$$h_f. \theta_0 = 300$$

$$\theta_0 - \theta = \frac{0.4}{2.4} \cdot 300 = 50^\circ$$

$$+ 27^\circ$$

$$- 23^\circ$$

ni nie wyprawa myśli

Ten sam knottet lings prode
i rokkende gredmon:

N. f. kula s ciezary ponozajezzi

rise. Atkinson's problem
principle)

wie steht
um die 1000

Ny. cythrae near *rupi* Tokoro

Neodwarczy: $\frac{-u}{v}$ mi będzie wygodniej jest $\frac{+u}{v}$ jest wygodnie

[her response was energy!
~~that~~ they do do the degree

nie zmienia się znak d p

Convolv. taraiensis

Nispravilne, bo opisa da uholi tehni so pač ~~1-200~~ ¹⁻²⁰⁰ ~~2~~ brezuplošno ustroji:

$$\frac{\delta p}{\delta x} = \mu \frac{\delta^2 u}{\delta y^2}$$

$$\frac{\partial \phi(x)}{\partial x} = 0$$

$$p \frac{\partial u}{\partial x} + u \frac{\partial p}{\partial x}$$

} just 22 syllables pure p. 12 to 144 taken syllables pure
 -u. -p de ignem ~~de~~ p. nominative: do nothing remarkable!

Wykazywanie własności stanów mieszanin

Entropia = $S = k_B \ln \Omega + R \ln v + \text{const}$

$R \ln \frac{1}{\rho} - 2k_B \ln \frac{1}{\rho} = c_v (\ln \theta + (k-1) \ln v)$

$= c_v \ln \frac{\theta}{\rho^{k-1}} + \text{const} = c_v \ln \frac{p}{\rho^k} + \text{const}'$

$\frac{\partial f}{\partial x} = \mu \frac{\partial u}{\partial x}$

$p = p_1 + p_2$
 $u = u_1 + u_2$

$\frac{\partial p u}{\partial x} + \dots = 0$

$(p_1 + p_2) \left(\frac{\partial u_1}{\partial x} + \frac{\partial u_2}{\partial x} \right) + (u_1 + u_2) \left(\frac{\partial p_1}{\partial x} + \frac{\partial p_2}{\partial x} \right) + \dots = 0$

Obliczenie rozprawy alternatywnej uformułowania oparte dla bardzo małych $\frac{\partial p}{\partial x} \neq 0$

$p_1 \frac{\partial u_1}{\partial x} + p_2 \frac{\partial u_2}{\partial x} + u_1 \frac{\partial p_1}{\partial x} + u_2 \frac{\partial p_2}{\partial x} + \dots = 0$

$\frac{\partial p}{\partial x} = \frac{1}{2} \left(\frac{\partial p_1}{\partial x} + \frac{\partial p_2}{\partial x} \right) + \mu \frac{\partial u}{\partial x}$

$p = p_1 + p_2$

$u = u_1 + u_2$

$\frac{\partial p_2}{\partial x} = \frac{1}{2} \left(\frac{\partial p_1}{\partial x} + \frac{\partial p_2}{\partial x} \right) + \mu \frac{\partial u_2}{\partial x}$

$p \frac{\partial u}{\partial x} + u \frac{\partial p}{\partial x} = 0$

$p_1 \left(\frac{\partial u_1}{\partial x} + \dots \right) = 0$

$p \left(\frac{\partial u_2}{\partial x} + \dots \right) + u \frac{\partial p}{\partial x} = 0$

$(u_1 + u_2) \left(\frac{\partial p_1}{\partial x} + \frac{\partial p_2}{\partial x} \right) = 0$

Ugibione oblique dla kute i jone

Resonans: isturimione: ediotopane

$$\left\{ \begin{aligned} \frac{\partial \epsilon}{\partial x} &= \frac{\mu}{3} \frac{\partial}{\partial x} \text{div} + \mu \Delta^2 u \quad \left\| \begin{aligned} k p \text{div} + u \frac{\partial \epsilon}{\partial x} + v \frac{\partial \epsilon}{\partial y} + w \frac{\partial \epsilon}{\partial z} &= 0 \end{aligned} \right. \\ \end{aligned} \right.$$

Suponijmo p jako bodno drue, podrespt $\frac{\partial \epsilon}{\partial x}$ nako, stigne is $\text{div} = 0$
 nize maky tokin jak u cewy $p \approx P + p$ $P = \text{const}$

$$\text{div} = \cancel{\frac{\partial}{\partial x} (u \frac{\partial \epsilon}{\partial x} + v \frac{\partial \epsilon}{\partial y} + w \frac{\partial \epsilon}{\partial z})} = - \frac{1}{P+p} \left(u \frac{\partial \epsilon}{\partial x} \right)$$

$$= - \frac{1}{P} \left(u \frac{\partial \epsilon}{\partial x} \right) + \frac{p}{P^2} \left(u \frac{\partial \epsilon}{\partial x} \right)$$

$$p = p_0 + \frac{1}{P} p' + \frac{1}{2} \left(\frac{p'}{P} \right)^2 p'' + \dots$$

$$\left\{ \begin{aligned} \frac{\partial p_0}{\partial x} + \frac{1}{P} \frac{\partial p'}{\partial x} + \dots &= \frac{\mu}{3} \frac{\partial}{\partial x} \left(\cancel{\text{div}} + \frac{1}{P} \text{div}' + \right) + \mu \left[\Delta^2 u_0 + \frac{1}{P} \Delta^2 u' + \right] \\ \left(\frac{\partial p_0}{\partial x} + \frac{1}{P} \frac{\partial p'}{\partial x} + \right) \left(\cancel{\text{div}} + \frac{1}{P} \text{div}' + \right) &+ \mu \left(u_0 + \frac{1}{P} u' \right) \left(\frac{\partial p_0}{\partial x} + \frac{1}{P} \frac{\partial p'}{\partial x} \right) + \dots = 0 \end{aligned} \right.$$

Wznowy wzorje za $\frac{1}{P}$:

$$\frac{\partial p_0}{\partial x} + \dots = 0 \quad \frac{\partial p_0}{\partial x} + \dots = 0 \quad p = p_0 + \frac{1}{P} p'$$

$$\frac{\partial p_0}{\partial x} = \mu \Delta^2 u_0 \quad \frac{\partial p_0}{\partial x} = \mu \Delta^2 u_0 \quad \frac{\partial p_0}{\partial x} = \mu \Delta^2 u_0$$

$$\frac{\partial p_0}{\partial x} = \mu \Delta^2 u_0 \quad \frac{\partial p_0}{\partial x} = \mu \Delta^2 u_0 \quad \frac{\partial p_0}{\partial x} = \mu \Delta^2 u_0$$

$$\frac{\partial p_0}{\partial x} = \mu \Delta^2 u_0 \quad \frac{\partial p_0}{\partial x} = \mu \Delta^2 u_0 \quad \frac{\partial p_0}{\partial x} = \mu \Delta^2 u_0$$

$$p' = K \frac{\partial p_0}{\partial x} + \dots$$

$$\frac{\partial}{\partial x} \left(\text{div}' + \dots \right) \left(1 + \frac{\rho_0}{\rho} + \frac{1}{\rho} \rho' + \dots \right) + \left(\rho_0 + \frac{1}{\rho} \rho' \right) \left(\frac{\partial \rho_0}{\partial x} + \frac{1}{\rho} \frac{\partial \rho'}{\partial x} \right) + \dots = 0$$

$$k \text{div}' + u_0 \frac{\partial \rho_0}{\partial x} + v_0 \frac{\partial \rho_0}{\partial y} + w_0 \frac{\partial \rho_0}{\partial z} = 0$$

$$\left. \begin{aligned} \frac{\partial \rho'}{\partial x} &= \frac{\mu}{3} \frac{\partial \text{div}'}{\partial x} + \mu \Delta^2 u' \\ \frac{\partial \rho'}{\partial y} &= \frac{\mu}{3} \frac{\partial \text{div}'}{\partial y} + \mu \Delta^2 v' \\ \frac{\partial \rho'}{\partial z} &= \frac{\mu}{3} \frac{\partial \text{div}'}{\partial z} + \mu \Delta^2 w' \end{aligned} \right\} \begin{aligned} \Delta^2 \rho' &= \frac{4\mu}{3} \Delta^2 \text{div}' \\ \rho' &= \frac{4\mu}{3} \text{div}' + \varphi \end{aligned} \quad \Delta^2 \varphi = 0$$

$$\begin{aligned} \mu \frac{\partial \text{div}'}{\partial x} + \frac{\partial \rho}{\partial x} &= \mu \Delta^2 u' = \frac{\partial}{\partial x} (\mu \text{div}' + \varphi) \\ \mu \Delta^2 v' &= \frac{\partial}{\partial y} (\quad) \\ \mu \Delta^2 w' &= \frac{\partial}{\partial z} (\quad) \end{aligned}$$

$$\frac{\partial}{\partial x} \left(\text{div}' + \dots \right) \frac{\partial \rho_0}{\partial x} + \dots = k \text{div}'$$

$$\rho = \rho_0 - \frac{3}{2} \mu c a \frac{x}{r^3}$$

$$\left. \begin{aligned} \frac{\partial \rho}{\partial x} &= -\frac{3}{2} \mu c a \left(\frac{1}{r^3} - \frac{3x^2}{r^5} \right) \\ \frac{\partial \rho}{\partial y} &= \frac{3}{2} \mu c a \frac{xy}{r^5} \\ \frac{\partial \rho}{\partial z} &= \frac{3}{2} \mu c a \frac{xz}{r^5} \end{aligned} \right| \begin{aligned} u &= -\frac{3}{4} \frac{c a}{r^4} \left(1 - \frac{a^2}{r^2} \right) \frac{x^2}{r^3} + c \left(1 - \frac{3}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3} \right) \\ v &= -\frac{3}{4} c a \left(1 - \frac{a^2}{r^2} \right) \frac{xy}{r^3} \\ w &= -\frac{3}{4} c a \left(1 - \frac{a^2}{r^2} \right) \frac{xz}{r^3} \end{aligned}$$

$$u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} = -\frac{27}{8} \mu c^2 a^2 \frac{x^2}{r^6} + \frac{9}{8} \mu c^2 a^2 \left(1 - \frac{a^2}{r^2} \right) \frac{x^2}{r^6} - \frac{3}{2} \mu c^2 a \frac{1}{r^3} \left(1 - \frac{3}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3} \right)$$

$$+ \frac{9}{2} \mu c^2 a \frac{x^2}{r^5} \left(1 - \frac{3}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3} \right)$$

$$\begin{aligned}
 -k \operatorname{div}' &= -\frac{3}{2} \mu a c^2 \frac{1}{r^3} \left(1 - \frac{2}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3} \right) + \frac{9}{2} \mu c^2 a \frac{x^2}{r^5} \left(1 - \frac{2}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3} \right) \\
 &\quad - \frac{18}{8} \mu c^2 a \frac{x^2}{r^5} \left(\frac{a}{r} - \frac{a^3}{r^3} \right) \\
 &\quad + \frac{9}{2} \mu c^2 a \frac{x^2}{r^5} \left(1 - \frac{5}{4} \frac{a}{r} + \frac{1}{4} \frac{a^3}{r^3} \right)
 \end{aligned}$$

symetry axis $dx \pm x$

dla $r=a, r=\infty$

$\operatorname{div}' \geq 0$

dla $x=0: r>a \quad \operatorname{div}' < 0$

dla $x=r: (0' \chi) \quad \operatorname{div}' = \mu c^2 a \frac{1}{r^3} \left[3 - \frac{9}{2} \frac{a}{r} + \frac{3}{2} \frac{a^3}{r^3} \right] = 3 \mu c^2 a \frac{1}{r^3} \left[1 - \frac{3}{2} \frac{a}{r} + \frac{1}{2} \frac{a^3}{r^3} \right]$

$\frac{a}{r} = 1 - \delta \quad 1 - \frac{3}{2}(1-\delta) + \frac{1}{2}(1-\delta)^3 = \frac{3}{2}\delta - \frac{3}{2}\delta^2 + \frac{3}{2}\delta^3 - \frac{\delta^3}{2} > 0$

$\operatorname{div}' > 0$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial x \partial y} + \frac{\partial^2 u}{\partial x \partial z} = \frac{\partial \operatorname{div}'}{\partial x} = \Delta^2 u + \underbrace{\frac{\partial \xi}{\partial y} - \frac{\partial \eta}{\partial z}}_{= -\frac{\partial \varphi}{\partial x}}$$

$$\frac{\partial}{\partial y} \left(\frac{\partial u}{\partial z} - \frac{\partial u}{\partial y} \right) + \frac{\partial u}{\partial y} \left(\frac{\partial}{\partial z} \left(\frac{\partial u}{\partial x} - \frac{\partial u}{\partial z} \right) \right) + \frac{\partial^2 u}{\partial z^2}$$

$$\frac{\partial \operatorname{div}'}{\partial y} = \Delta^2 u + \underbrace{\frac{\partial \xi}{\partial z} - \frac{\partial \xi}{\partial x}}_{= -\frac{\partial \varphi}{\partial y}}$$

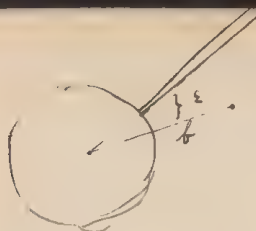
$$\frac{\partial \operatorname{div}'}{\partial z} = \Delta^2 u + \underbrace{\frac{\partial \eta}{\partial x} - \frac{\partial \eta}{\partial y}}_{= -\frac{\partial \varphi}{\partial z}}$$

$\xi=0 \quad \frac{\partial u}{\partial y} - \frac{\partial u}{\partial z} = 0$

~~$\frac{\partial \xi}{\partial x} = \frac{\partial \varphi}{\partial y} \quad \frac{\partial \eta}{\partial x} = -\frac{\partial \varphi}{\partial z}$~~

~~$\frac{\partial^2 \xi}{\partial x \partial z} + \frac{\partial^2 \eta}{\partial x \partial y} = 0$~~

~~$\frac{\partial \xi}{\partial x} + \frac{\partial \eta}{\partial y} = f(y, z)$~~



$$\int_a^\infty \frac{1}{r^3} \left(1 - \frac{5}{4} \frac{a}{r} + \frac{1}{4} \frac{a^3}{r^3} \right) \frac{r^2 \sin \theta}{\sqrt{b^2 + r^2 - 2br \cos \epsilon}} dr$$

$$\frac{\partial}{\partial x} \left(\frac{x^m}{r^n} \right) = m \frac{x^{m-1}}{r^n} - n \frac{x^{m+1}}{r^{n+2}}$$

$$\frac{\partial^2}{\partial x^2} \left(\frac{x^m}{r^n} \right) = m(m-1) \frac{x^{m-2}}{r^n} - \cancel{2m} n(2m+1) \frac{x^m}{r^{n+2}} + n(n+2) \frac{x^{m+2}}{r^{n+4}}$$

$$\frac{\partial}{\partial y} \left(\frac{x^m}{r^n} \right) = -n \frac{x^m y}{r^{n+2}}$$

$$\frac{\partial^2}{\partial y^2} \left(\frac{x^m}{r^n} \right) = -n \frac{x^m}{r^{n+2}} + n(n+2) \frac{x^m y^2}{r^{n+4}}$$

$$\begin{aligned} \Delta^2 \left(\frac{x^m}{r^n} \right) &= m(m-1) \frac{x^{m-2}}{r^n} - \frac{x^m}{r^{n+2}} [n(2m+1) + 2n] + \frac{x^m}{r^{n+2}} n(n+2) \\ &= m(m-1) \frac{x^{m-2}}{r^n} + \frac{x^m}{r^{n+2}} \underbrace{[n^2 + 2n - 2mn - 3n]}_{n^2 - 2mn - n} \end{aligned}$$

$$m=4 \quad n=10$$

$$m=2$$

$$\Delta^2 \left(\frac{x^2}{r^n} \right) = \frac{2}{r^n} + (n^2 - 5n) \frac{x^2}{r^{n+2}}$$

$$n=3: \quad \Delta^2 \left(\frac{x^2}{r^3} \right) = \frac{2}{r^3} - 6 \frac{x^2}{r^5} = 2 \left(\frac{1}{r^3} - \frac{3x^2}{r^5} \right)$$

$$n=4: \quad \Delta^2 \left(\frac{x^2}{r^4} \right) = \frac{2}{r^4} - 4 \frac{x^2}{r^6} = 2 \left(\frac{1}{r^4} - \frac{2x^2}{r^6} \right)$$

$$n=5: \quad \Delta^2 \left(\frac{x^2}{r^5} \right) = \frac{2}{r^5}$$

$$n=6: \quad \Delta^2 \left(\frac{x^2}{r^6} \right) = \frac{2}{r^6} + 6 \frac{x^2}{r^8} = 2 \left(\frac{1}{r^6} + 3 \frac{x^2}{r^8} \right)$$

$$\frac{x^2}{r^5} = \frac{1}{3} \frac{1}{r^3} - \frac{1}{6} \Delta^2 \left(\frac{x^2}{r^3} \right) = \frac{2}{r^3} + \frac{1}{24} \frac{x^2}{r^5}$$

$$n=10: \quad \frac{x^2}{r^5} = \frac{2}{r^{10}} + 50 \frac{x^2}{r^{12}}$$

$$\begin{array}{r} 100 \\ - 80 \\ \hline 20 \end{array}$$

$$\begin{array}{r} 64 \\ - 8 \\ \hline 56 \end{array}$$

$$\frac{x^2}{2^5} = \frac{1}{3} \frac{1}{2^3} - \frac{1}{6} \Delta^2 \left(\frac{x^2}{2^3} \right)$$

$$\frac{x^2}{2^6} = \frac{1}{2} \frac{1}{2^4} - \frac{1}{4} \Delta^2 \left(\frac{x^2}{2^4} \right) \quad -\frac{5}{4} a$$

$$\frac{x^2}{2^8} = -\frac{1}{3} \frac{1}{2^6} + \frac{1}{6} \Delta^2 \left(\frac{x^2}{2^6} \right) \quad \frac{1}{4} a^3$$

$$\frac{x^2}{2^5} - \frac{5}{4} a \frac{x^2}{2^6} + \frac{1}{4} a^3 \frac{x^2}{2^8} = \frac{1}{3} \frac{1}{2^3} - \frac{5}{8} \frac{a}{2^4} - \frac{1}{12} \frac{a^3}{2^6}$$

$$- \Delta^2 \left\{ \frac{1}{6} \frac{x^2}{2^3} - \frac{5}{16} \frac{a x^2}{2^4} - \frac{1}{24} \frac{a^3 x^2}{2^6} \right\}$$

$$\frac{q}{2} \mu c^2 a \left\{ \left(\frac{x^2}{2^5} - \frac{5}{4} a \frac{x^2}{2^6} + \frac{1}{4} a^3 \frac{x^2}{2^8} \right) - \frac{1}{3} \left(\frac{1}{2^3} - \frac{5}{4} \frac{a}{2^4} - \frac{1}{4} \frac{a^3}{2^6} \right) \right\} = \frac{q}{2} \mu c^2 a$$

$$\left(-\frac{5}{8} + \frac{1}{4} \right) \frac{a}{2^4} - \Delta^2 \left\{ \frac{1}{6} \frac{x^2}{2^3} - \right\}$$

$$= -\frac{q}{2} \mu c^2 a \left[\frac{3}{8} \frac{a}{2^4} + \frac{1}{6} \Delta^2 \left(\frac{x^2}{2^3} - \frac{15}{8} \frac{a x^2}{2^4} - \frac{1}{4} \frac{a^3 x^2}{2^6} \right) \right]$$

$$\Delta^2 \left(\frac{x^2}{2^3} \right) = -\frac{\partial^2}{\partial x^2} \left(\frac{x^2}{2^3} \right) + \dots = 2 \left(-\frac{1}{2^4} + \frac{1}{2^6} \right) = \frac{2}{2^4}$$

$$= -\mu c^2 a \left[\frac{27}{32} \frac{a}{2^2} + \frac{3}{4} \left(\frac{x^2}{2^3} - \frac{15}{8} \frac{a x^2}{2^4} - \frac{1}{4} \frac{a^3 x^2}{2^6} \right) \right]$$

$$\text{Zatem } \Delta^2 \psi = \Delta^2 \psi$$

$$\Delta^2 u' = \Delta^2 \frac{\partial \psi}{\partial x} + \frac{1}{\mu} \frac{\partial^2 \psi}{\partial x^2}$$

$$\Delta^2 v' = \Delta^2 \frac{\partial \psi}{\partial y} + \frac{1}{\mu} \frac{\partial^2 \psi}{\partial y^2}$$

$$\Delta^2 w' = \Delta^2 \frac{\partial \psi}{\partial z} + \frac{1}{\mu} \frac{\partial^2 \psi}{\partial z^2}$$

$$\frac{\partial u'}{\partial x} + \frac{\partial v'}{\partial y} + \frac{\partial w'}{\partial z} = \Delta^2 \psi$$

$$\text{Rozwijemy typ: } u' = \frac{\partial \psi}{\partial x} + U$$

$$v' = \frac{\partial \psi}{\partial y} + V$$

$$w' = \frac{\partial \psi}{\partial z} + W$$

$$\Delta^2 U = \frac{1}{\mu} \frac{\partial^2 \psi}{\partial x^2}$$

$$\Delta^2 V =$$

$$\Delta^2 W =$$

$$\frac{\partial U}{\partial x} + \frac{\partial V}{\partial y} + \frac{\partial W}{\partial z} = 0$$

$$\Delta^2 \psi = 0 \quad \left. \begin{array}{l} \text{Zupełnie} \\ \text{to samo} \\ \text{jak dla} \\ u, v, w \end{array} \right\}$$

$$\left. \frac{\partial \psi}{\partial x} \right|_{x=a} = -\mu c^2 a^2 \left[-\frac{27}{8} \frac{a}{a^3} \frac{x}{2} + 3 \left(\frac{x}{a^3} - \frac{15ax}{8a^4} - \frac{a^3 x}{4a^6} \right) - \frac{3}{2} \left(\frac{3x^3}{a^5} - \frac{15}{2} \frac{ax^3}{a^6} - \frac{3}{2} \frac{a^3 x^3}{a^8} \right) \right] \quad 177$$

$$= -\mu c^2 a^2 \left[\frac{3x}{2a^3} \left[1 - 3 \frac{a}{x} - \frac{1}{4} \frac{a^3}{x^3} \right] - \frac{9}{4} \frac{x^3}{a^5} \left[1 - \frac{5}{2} \frac{a}{x} - \frac{1}{2} \frac{a^3}{x^3} \right] \right]$$

$$+ \left. \frac{\partial \psi}{\partial y} \right|_{y=a} = -\mu c^2 a^2 \left[-\frac{27}{8} \frac{a}{a^3} \frac{y}{2} - \frac{9}{4} \frac{x^2 y}{a^5} \left[1 - \frac{5}{2} \frac{a}{x} - \frac{1}{2} \frac{a^3}{x^3} \right] \right]$$

$$+ \left. \frac{\partial \psi}{\partial z} \right|_{z=a} = -\mu c^2 a^2 \left[\dots \right]$$

Sta $x=a$:

$$\left. -x \frac{\partial \psi}{\partial x} \right|_{x=a} = -\mu c^2 a^2 \left[\frac{3}{a^3} \frac{a}{a^3} \left(-\frac{9}{4} \right) - \frac{9}{2} \frac{x^3}{a^5} (-2) \right] = \frac{\mu c^2 a^2}{2a} \left[\frac{27}{4} \frac{x}{a} - 9 \frac{a^3}{a^3} \right]$$

$$= 9 \frac{\mu c^2}{2a} \left[\frac{3}{4} \frac{x}{a} - \frac{a^3}{a^3} \right]$$

$$+ \left. x \frac{\partial \psi}{\partial y} \right|_{x=a} = +\mu c^2 a^2 \left[\frac{27}{8} \frac{y}{a^3} + \frac{9}{2} \frac{x^2 y}{a^5} (-2) \right] = 9 \frac{\mu c^2}{2a} \left[\frac{3}{8} \frac{y}{a} - \frac{x^2 y}{a^3} \right]$$

$$+ \left. x \frac{\partial \psi}{\partial z} \right|_{x=a} = \dots = \frac{9 \mu c^2}{2a} \left[\frac{3}{8} \frac{z}{a} - \frac{x^2 z}{a^3} \right]$$

Wzika utworzeni $\Delta^2 \psi$:

$$3 \frac{1}{a^3} \left[1 - \frac{3a}{2} - \frac{1}{4} \frac{a^3}{a^3} \right] - 9 \frac{x^2}{a^5} \left[1 - \frac{3a}{2} - \frac{1}{4} \frac{a^3}{a^3} \right] + 3 \frac{x^2}{a^3} \left[\frac{3a}{a^3} + \frac{3}{4} \frac{a^3}{a^5} \right] -$$

$$- \frac{27}{2} \frac{x^2}{a^5} \left[1 - \frac{5}{2} \frac{a}{x} - \frac{1}{2} \frac{a^3}{a^3} \right] + \frac{45}{2} \frac{x^4}{a^7} \left[1 - \frac{5}{2} \frac{a}{x} - \frac{1}{2} \frac{a^3}{a^3} \right] - \frac{9}{2} \frac{x^4}{a^5} \left[\frac{5}{2} \frac{a}{a^3} + \frac{3}{2} \frac{a^3}{a^5} \right]$$

$$- \frac{27}{8} \frac{a}{a^4} - \frac{9}{2} \frac{x^2}{a^5} \left[1 - \frac{5}{2} \frac{a}{x} - \frac{1}{2} \frac{a^3}{a^3} \right] + \frac{27}{2} \frac{ay^2}{a^6} + \frac{45}{2} \frac{x^2 y^2}{a^7} \left[1 - \frac{5}{2} \frac{a}{x} - \frac{1}{2} \frac{a^3}{a^3} \right] -$$

$$- \frac{9}{2} \frac{x^2 y^2}{a^5} \left[\frac{5}{2} \frac{a}{a^3} + \frac{3}{2} \frac{a^3}{a^5} \right]$$

$$- \frac{27}{8} \frac{a}{a^4} - \frac{9}{2} \frac{x^2}{a^5} \left[1 - \frac{5}{2} \frac{a}{x} - \frac{1}{2} \frac{a^3}{a^3} \right] + \frac{27}{2} \frac{az^2}{a^6} + \frac{45}{2} \frac{x^2 z^2}{a^7} \left[1 - \frac{5}{2} \frac{a}{x} - \frac{1}{2} \frac{a^3}{a^3} \right] -$$

$$- \frac{9}{2} \frac{x^2 z^2}{a^5} \left[\frac{5}{2} \frac{a}{a^3} + \frac{3}{2} \frac{a^3}{a^5} \right]$$

$$\begin{aligned}
&= \frac{3}{2^3} \left[1 - \frac{3a}{2} - \frac{1}{4} \frac{a^3}{2^3} \right] - \frac{27}{4} \frac{a}{2^4} + \frac{27}{2} a \frac{(y^2 + z^2)}{2^6} - \frac{9x^2}{2^5} \left[1 - \frac{3a}{2} - \frac{1}{4} \frac{a^3}{2^3} \right] \\
&\quad + \frac{3x^2}{2^3} \left[\frac{3a}{2^3} + \frac{3}{4} \frac{a^3}{2^5} \right] - \frac{9}{2} \frac{x^2}{2^3} \left[\frac{5}{2} \frac{a}{2^3} + \frac{3}{2} \frac{a^3}{2^5} \right] \\
&= \frac{3}{2^3} \left[1 - \frac{3a}{2} - \frac{1}{4} \frac{a^3}{2^3} \right] - \frac{27}{4} \frac{a}{2^4} + \frac{27}{2} \frac{a}{2^4} \left[1 - \frac{x^2}{2^2} \right] - \frac{9x^2}{2^5} \left[1 - \frac{3a}{2} - \frac{1}{4} \frac{a^3}{2^3} \right] \\
&\quad + \frac{3x^2}{2^5} \left[3 \frac{a}{2} + \frac{3}{4} \frac{a^3}{2^3} \right] - \frac{9}{2} \frac{x^2}{2^5} \left[\frac{5}{2} \frac{a}{2^3} + \frac{3}{2} \frac{a^3}{2^5} \right] \\
&= \frac{3}{2^3} \left[1 - \frac{3a}{4^2} - \frac{1}{4} \frac{a^3}{2^3} \right] + \frac{x^2}{2^3} \left[\frac{9}{2} \left(-\frac{27}{2} + 27 + 9 - \frac{45}{4} \right) + \frac{a^3}{2^3} \left[\frac{9}{4} + \frac{9}{4} - \frac{27}{4} \right] \right] \\
&= \frac{3}{2^3} \left[1 - \frac{3a}{4^2} - \frac{1}{4} \frac{a^3}{2^3} \right] + \frac{9}{2^5} \frac{x^2}{2^5} \left[-1 + \frac{5}{4} \frac{a}{2} - \frac{1}{4} \frac{a^3}{2^3} \right] \quad \text{Zjedna cis}
\end{aligned}$$

Tieto hodnoty jsmu U V W tak upravim zeby na konciach ovi
vartovali byh nulovne:

$$U = - \frac{27 \mu c^2}{8a} \frac{x}{a} \left[1 - \frac{4}{3} \frac{x^2}{a^2} \right]$$

$$V = - \frac{27 \mu c^2}{8a} \frac{y}{a} \left[\frac{1}{2} - \frac{4}{3} \frac{x^2}{a^2} \right]$$

$$W = - \frac{27 \mu c^2}{8a} \frac{z}{a} \left[\frac{1}{2} - \frac{4}{3} \frac{x^2}{a^2} \right]$$

Opisom usporiadani:

$$U = \frac{1}{\mu} \sum \left\{ \frac{n^2}{2(2n+1)} \frac{d p_n}{dx} + \frac{n^2}{(n+1)(2n+1)(2n+3)} \frac{d}{dx} \left(\frac{p_n}{n^{2n+1}} \right) \right\} + \sum \frac{d p_n}{dx}$$

$$V = \frac{d}{dy} \quad \frac{d}{dy} \quad \frac{d p_n}{dy}$$

$$W =$$

$$\begin{aligned} \mu_0 &= \omega r^2 \\ \mu_1 &= x \\ \mu_2 &= r^2 \sin \theta \\ \mu &= r^2 \sin \theta \\ \mu_{-1} &= \\ \mu_{-2} &= \frac{1}{r^{n+1}} \sin \theta \end{aligned}$$

$$\frac{4x^2}{2^3}$$

$$\frac{2x}{2^4} - \frac{3x^3}{2^5}$$

$$\mu_2 =$$

$$x^4 + y^4 + z^4 = 0$$

$$\int_0 = 1$$

$$\int_1 = \omega$$

$$\int_2 = \frac{1}{2}(3\omega^2 - 1)$$

$$\int_3 = \frac{1}{2}(5\omega^3 - 3\omega)$$

$$x \quad \frac{x}{2^3}$$

$$\frac{1}{2} 3 \mu_0 = 1 \quad \mu_{-1} = \frac{1}{r}$$

$$\mu_1 = x \quad \mu_{-2} = \frac{x}{r^3}$$

$$\mu_2 = \frac{1}{2}(3x^2 - r^2) \quad \mu_{-3} = \frac{1}{2r^3}(3\frac{x^2}{r^2} - 1)$$

$$x^4 + y^4 + z^4 = 1 \quad \mu = \frac{1}{2(2n+3)} \quad \mu_n + \frac{1}{2} \sum_{n \leq 0} \mu_n = 0$$

$$\begin{aligned} \frac{\partial \mu_3}{\partial x} &= \frac{3x}{2r^5} - \frac{3x}{2r^5} \left(\frac{3x^2}{r^2} - 1 \right) + \frac{3x}{2r^5} - \frac{3x^3}{r^7} = \frac{3x}{r^5} \left[\frac{3}{2} - \frac{5}{2} \frac{x^2}{r^2} \right] \\ &= \frac{4x}{2r^5} \left[1 - \frac{5}{3} \frac{x^2}{r^2} \right] \end{aligned}$$

$$\frac{\partial \mu_{-3}}{\partial y} = -\frac{3y}{2r^5} \left(\frac{3x^2}{r^2} - 1 \right) - \frac{3y}{2r^5} = -\frac{3y}{2r^5} \left[\frac{3}{2} - \frac{5}{2} \frac{x^2}{r^2} \right] = -\frac{4y}{2r^5} \left[\frac{3}{2} - \frac{5}{2} \frac{x^2}{r^2} \right]$$

$$\frac{\partial}{\partial x} \left(\frac{\mu_{-3}}{r^5} \right) = \frac{\partial}{\partial x} \left[\frac{1}{2} \left(\frac{3x^2}{r^2} - 1 \right) \right] = \frac{1}{2} \frac{\partial}{\partial x} \left[\frac{3x^2}{r^2} - r^2 \right] = 3x - x = 2x$$

$$\frac{\partial}{\partial y} \left(\frac{\mu_{-3}}{r^5} \right) = \frac{1}{2} \frac{\partial}{\partial y} \left[3x^2 - r^2 \right] = -y$$

$$n = -3$$

$$U = \frac{-x^2}{2.5} \cdot \frac{3x^3}{x^5} \left[\frac{3}{2} - \frac{5}{2} \frac{x^4}{x^2} \right] + \frac{1}{2.5} \cdot \frac{1}{x^3} \cdot 2x = \frac{1}{10} \frac{x}{x^3} \left[-\frac{5}{2} + \frac{15}{2} \frac{x^4}{x^2} \right]$$

$$= -\frac{1}{4} \frac{x}{x^3} \left[1 - 3 \frac{x^4}{x^2} \right]$$

$$V = \frac{-x^2}{2.5} \cdot \frac{3x^3}{x^5} \left[\frac{1}{2} - \frac{5}{2} \frac{x^4}{x^2} \right] - \frac{1}{10} \cdot \frac{1}{x^3} \cdot 4 = \frac{1}{10} \frac{4}{x} \left[-\frac{5}{2} + \frac{15}{2} \frac{x^4}{x^2} \right]$$

$$= -\frac{1}{4} \frac{4}{x^3} \left[1 - 3 \frac{x^4}{x^2} \right]$$

$$U = A \frac{x}{x^3} \left[1 - 3 \frac{x^4}{x^2} \right] + B \frac{x}{x^3} + C \frac{x}{x^5} \left[\frac{3}{2} - \frac{5}{2} \frac{x^4}{x^2} \right]$$

$$V = A \frac{4}{x^3} \left[1 - 3 \frac{x^4}{x^2} \right] + B \frac{4}{x^3} + C \frac{4}{x^5} \left[\frac{1}{2} - \frac{5}{2} \frac{x^4}{x^2} \right]$$

$$A \left[\frac{1}{x^3} + B \frac{1}{x^3} + \frac{3}{2} C \frac{1}{x^5} \right] = \frac{1}{x^3}$$

$$\left[-3A \frac{1}{x^5} - \frac{5}{2} C \frac{1}{x^7} \right] \cdot x^3 = -\frac{4}{3} \frac{1}{x^3}$$

$$A \frac{1}{x^3} + B \frac{1}{x^3} + \frac{1}{2} C \frac{1}{x^5} = \frac{1}{2} \frac{1}{x^3}$$

$$-3A \frac{1}{x^5} - \frac{5}{2} C \frac{1}{x^7} = -\frac{4}{3} \frac{1}{x^3}$$

$$\frac{3A}{x^5} + \frac{5}{4} \frac{1}{x^3} = \frac{4}{3} \frac{1}{x^3}$$

$$\frac{3A}{x^5} = \left(\frac{4}{3} - \frac{5}{4} \right) \frac{1}{x^3} = \frac{1}{12} \frac{1}{x^3}$$

$$A = \frac{x^2}{36}$$

$$A + B + \frac{1}{2} C \frac{1}{a^2} = \frac{1}{2} a^2$$

$$B = \frac{1}{2} a^2 - \frac{a^2}{36} - \frac{1}{2} \frac{a^2}{2} = \frac{2}{9} a^2$$

$$U = -\frac{27 \mu e^2}{8a} \left[\frac{a^2}{36} \left\{ \frac{x}{2^3} \left[1 - 3 \frac{x^2}{2^2} \right] + 8 \frac{x}{2^3} \right\} + \frac{a^4}{2} \frac{x}{2^5} \left[\frac{3}{2} - 5 \frac{x^2}{2^2} \right] \right]$$

$$U = -\frac{27 \mu e^2}{8a} \left[-\frac{a^2}{12} \frac{x^3}{2^5} + \frac{a^4}{4} \frac{x}{2^5} \left[3 - 5 \frac{x^2}{2^2} \right] \right]$$

$$V = -\frac{27 \mu e^2}{8a} \left[-\frac{a^2}{12} \frac{x^2}{2^5} + \frac{a^4}{4} \frac{x}{2^5} \left[1 - 5 \frac{x^2}{2^2} \right] \right]$$

$$U = +\frac{27 \mu e^2 a^4}{32} \left[\frac{1}{3} \frac{x}{2^5} - \frac{a^2 x}{2^5} \left(3 - 5 \frac{x^2}{2^2} \right) \right]$$

$$V = \frac{27 \mu e^2 a^4}{32} \left[\frac{1}{3} \frac{x^2}{2^5} - \frac{a^2 x^2}{2^5} \left(1 - 5 \frac{x^2}{2^2} \right) \right]$$

Prova: $\frac{\partial U}{\partial x} + \frac{\partial V}{\partial y} + \frac{\partial W}{\partial z} \sim = \frac{x^2}{2^5} - \frac{5}{3} \frac{x^4}{2^7} - \left(\frac{3a^2}{2^5} + \frac{15a^2 x^2}{2^7} + \frac{15a^2 x^2}{2^7} - \frac{35x^4}{2^9} \right)$

$+ \frac{1}{2^3} - \frac{3x}{2^5} = 0$

$+ \frac{1}{2} \left\{ \frac{1}{3} \frac{x}{2^5} - \frac{5}{3} \frac{x^3}{2^7} - \frac{a^2}{2^5} + \frac{5a^2 x^2}{2^7} + \frac{5a^2 x^2}{2^7} - \frac{35x^4}{2^9} \right\}$

$= -\frac{5a^2}{2^7} (x^2 + y^2 + z^2) + \frac{5a^2 x^2}{2^7}$

$= \frac{1}{2^7} \left\{ 2^4 - \frac{5}{3} (x^4 + y^4 + z^4) - \frac{5a^2 x^2}{2^5} \right\} = 0$

$$\Delta^2 U \sim \frac{1}{3} \left(0 \frac{x}{2^5} - 10 \frac{x^3}{2^7} \right) - 3a^2 \left(10 \frac{x}{2^7} + 5a^2 \frac{x}{2^7} - 6 \frac{x}{2^7} \right) = \frac{2x}{2^5} - \frac{10}{3} \frac{x^3}{2^7}$$

$$\Delta^2 V \sim \frac{2}{3} \frac{x}{2^5} - \frac{10}{3} \frac{x^3}{2^7}$$

$$\Delta^2 W \sim \frac{2}{3} \frac{x}{2^5} - \frac{10}{3} \frac{x^3}{2^7}$$

$$\Delta^2 \left(\frac{\partial U}{\partial x} + \frac{\partial V}{\partial y} + \frac{\partial W}{\partial z} \right) = 0$$

ipotesis 2a

Curvature radius

in high water

top of

Δu

$$\theta = \frac{1}{2} \int \frac{1}{\Delta u} du$$

$$\Delta u \frac{du}{dx} = \Delta u \cdot \frac{du}{dx}$$

depth of water

depth of water

$$\frac{\mu_1 - \mu_2}{l} \frac{a^4 n}{g_n} = F$$

$$\mu_1 - \mu_2 = \frac{g_n}{a^4 n} F l$$

$$\frac{40000. \times 0.0015. \times 1000}{3.16} = 0.06 \text{ etc.}$$

$$-\frac{52}{27}$$

$$-\frac{5}{27} + \frac{352^2}{29}$$

$$-\frac{72}{29}$$

$$-\frac{7}{29} + 63 \frac{2^2}{291}$$

$$\frac{1}{3} \frac{yx^2}{n^5} - \frac{a^2y}{n^5} + \frac{-a^2xy}{n^7}$$

$$\frac{1}{3} \frac{2xy}{n^5} - \frac{5x^3}{n^7} + \frac{5a^2xy}{n^7} + \frac{15a^2xy}{n^7} - \frac{35a^2x^3}{n^9}$$

$$\frac{2}{3} \frac{4}{n^5} - \frac{10x^3}{n^7} - \frac{15x^4}{n^7} + \frac{35x^4}{n^7} + \frac{15a^2y}{n^7} - \frac{112.5.7}{n^9} \frac{a^2x^2}{n^7} - \frac{3.5.7}{n^9} \frac{a^2x^4}{n^7} + \frac{9.35}{n^9} \frac{a^2x^4}{n^7}$$

$$\frac{1}{3} \frac{x^2}{n^5} - \frac{15x^4}{n^7} - \frac{a^2}{n^5} + \frac{-a^2y}{n^7} + \frac{5a^2x^2}{n^7} - \frac{35a^2x^4}{n^9}$$

$$-\frac{5}{3} \frac{x^4}{n^7} - \frac{10x^4}{n^7} + \frac{15.7}{n^9} \frac{x^4y^3}{n^9} + \frac{15a^2y}{n^7} + \frac{15a^2y^3}{n^9} - \frac{105a^2xy}{n^9} + \frac{3.9}{n^9} \frac{a^2x^4y^3}{n^9}$$

$$\frac{1}{3} \frac{4x^2}{n^7} - \frac{2x^2}{n^7} + \frac{15a^2xy}{n^9}$$

$$-\frac{5}{3} \frac{yx^2}{n^7} + \left(\frac{35}{3} \frac{yx^2z^2}{n^9} + \frac{5a^2y}{n^7} \right) - \frac{35a^2yz^2}{n^9} - \frac{35a^2x^2}{n^9} + \frac{9.35}{n^9} \frac{a^2xy^2z^2}{n^9}$$

$$+\frac{35x^2y}{n^7} \quad -\frac{35a^2yz^2}{n^9} \quad +\frac{9.35}{n^9} \frac{a^2xy^2z^2}{n^9}$$

$$\frac{2}{3} \frac{4}{n^5} - \frac{10}{3} \frac{x^2y}{n^7}$$

=0

$$-\frac{35a^2y}{n^7}$$

$$-105$$

$$-210$$

$$-35$$

$$150$$

$$+ 3/5$$

$$= -35 \frac{a^2x^2}{n^9}$$

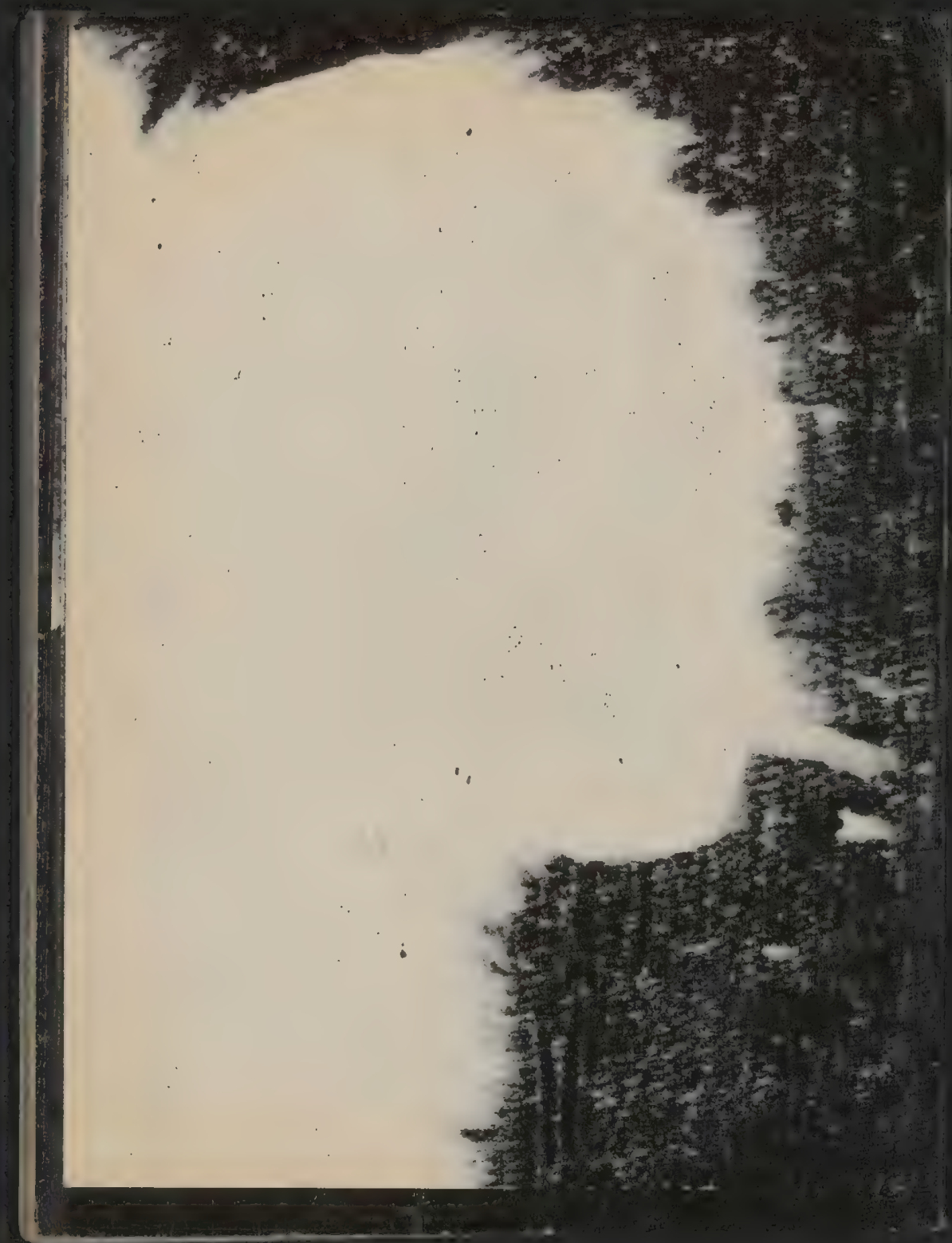
$$\frac{2}{n^5} - \frac{10x^2}{n^7} - \frac{10x^2}{n^7} + \frac{70x^2}{n^9}$$

$$\frac{10}{3} \frac{1}{n^5} - \frac{10}{3}$$

$$\frac{2}{3n^5} - \frac{10}{3} \frac{x^2}{n^7} - \frac{10x^2}{3n^7} + \frac{70x^2}{n^9}$$

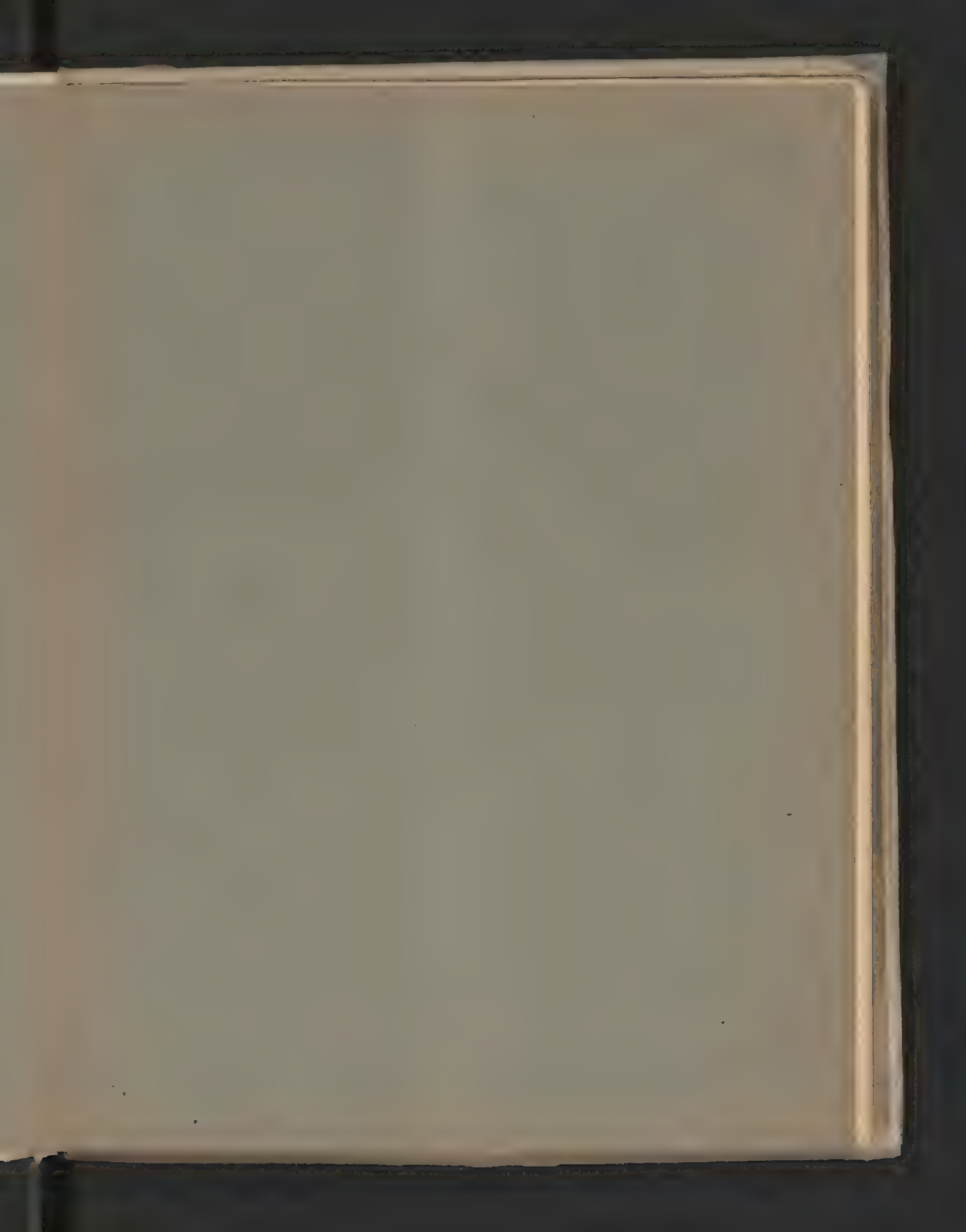
$$\frac{2}{3n^5} - \frac{10}{3} \frac{x^2}{n^7} - \frac{10x^2}{3n^7} + \frac{70x^2}{n^9}$$

$$\frac{70x^2}{3n^9}$$



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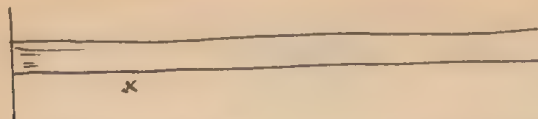
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$$\frac{\partial}{\partial x} \left[r \frac{\partial u}{\partial r} \right] = -r \frac{\partial p}{\partial x}$$

$$\frac{\partial^2}{\partial r^2} \left(r \frac{\partial u}{\partial r} \right) = -\frac{\partial p}{\partial x} + r \frac{\partial^2 p}{\partial x^2}$$

$$r \frac{\partial u}{\partial r} = \text{const} + C$$

$$r \frac{\partial^2}{\partial r^2} \left(r \frac{\partial u}{\partial r} \right) = + \frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right)$$

$$\frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right) = + \log(r) + \text{const}$$

$$\frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right) = \frac{r \frac{\partial p}{\partial x}}{r}$$

$$u = - \frac{r^2}{2} \frac{\partial p}{\partial x} + \text{const}$$

$$r \frac{\partial u}{\partial r} = \frac{r^2}{2} \varphi(x) + \psi(x)$$

$$\frac{\partial u}{\partial r} = r \varphi(x) + \frac{1}{r} \psi(x)$$

$$u = \frac{r^2}{2} \varphi(x) + \psi(x) \log r + \chi(x)$$

$$u = \frac{r^2 - R^2}{2} \varphi(x)$$

$$\frac{\partial}{\partial x} (p u) = \text{const}$$

$$p u = \text{const} + \Phi(x) = p \frac{r^2 - R^2}{2} \varphi(x)$$

$$p \varphi(x) = \text{const}$$

$$u = \frac{r^2 - R^2}{2} \frac{\text{const}}{p}$$

$$\frac{\partial p}{\partial r} = -r \frac{\partial p}{\partial x}$$

$$r=R \quad u=0$$

$$r=0 \quad u = \text{const}$$

$$\psi(x) = 0$$

$$0 = \frac{R^2}{2} \varphi(x) + \chi(x)$$

$$\varphi(x) = -\frac{2}{R^2} \chi(x)$$

$$\chi(x) = -\frac{R^2}{2} \varphi(x)$$

$$u = (a^2 - r^2) \frac{k}{r}$$

$$\frac{\partial u}{\partial r} = -2r \frac{k}{r^2}$$

$$-r \frac{\partial u}{\partial x} + \mu \left[2 \left(\frac{\partial u}{\partial r} \right)^2 \right] = 4 \mu \frac{\partial}{\partial r} \left(r \frac{\partial \theta}{\partial r} \right)$$

$$-8 \mu \left(\frac{k}{r} \right)^2 r^2 = \frac{\partial}{\partial r} ()$$

$$\frac{8}{3} \mu \left(\frac{k}{r} \right)^2 r^2 = \frac{\partial \theta}{\partial r} \left(\theta = \frac{8}{9} \mu \left(\frac{k}{r} \right)^2 r^3 + c \right)$$

$$\theta_0 = \frac{8}{9} \mu \left(\frac{k}{r} \right)^2 r^3$$

$$\theta - \theta_0 = \frac{8}{9} \mu \left(\frac{k}{r} \right)^2 (r^3 - a^3)$$

$$J_1 = \frac{A}{\lambda^5} e^{-\frac{\theta}{\lambda \theta}}$$

$$\frac{\partial J}{\partial \lambda} = -\frac{5}{\lambda} J + \frac{\partial}{\partial \theta} = 0$$

$$\lambda_m \theta = \frac{\partial}{\partial \theta}$$

$$\theta = 5 \lambda_m \theta$$

$$\begin{array}{r} 8.863.288.5 \\ 35452144 \\ \hline 3545 \end{array}$$

$$\theta = 1276.3$$

$$\frac{\partial}{\partial \theta} = 1443.15$$

$${}^{10} \log J_2 = {}^{10} \log A - 5 {}^{10} \log \lambda - \frac{\theta}{\lambda \theta} {}^{10} \log e$$

$$J = \frac{1440}{273} = 5.27$$

$$\frac{\partial}{\partial \theta} = 8863.04343$$

$$\lambda = 1: \log J = -3.8486$$

$$\begin{array}{r} 58531 \\ 23920 \\ \hline 0.34601 \end{array}$$

$$\begin{array}{r} 35452 \\ 2659 \\ 3545 \\ 205 \\ \hline 38486 \end{array}$$

$$\lambda = \frac{1}{2}$$

$$\begin{array}{r} + 0.30103.5 \\ 1.50515 \\ - 2.6972 \\ \hline 28080 \end{array}$$

$$\lambda_m = 1.735$$

$$\begin{array}{r} 0.23930 \\ - 1.1965 \\ - 2.2182 \\ \hline - 3.4147 \end{array}$$

$$\lambda = 2:$$

$$\begin{array}{r} 0.000 \\ - 1.50515 \\ - 1.9243 \\ \hline - 3.4295 \end{array}$$

$$58.5$$

$$\lambda = 3$$

$$\begin{array}{r} -1.2829 \\ \hline -2.3856 \\ \hline -3.6685 \end{array}$$

$$477.2$$

$$\lambda = 4$$

$$\begin{array}{r} 0.96215 \\ 3.0103 \\ \hline -3.97245 \\ \hline 3.2245 \end{array}$$

$$\theta = \begin{array}{r} 1.440 \\ 7.20 \\ \hline 2.160 \\ 2.73 \\ \hline 1.087 \end{array}$$

$$\frac{\sigma}{\theta} = \begin{array}{r} 1.28287 \\ 2.5657 \end{array}$$

$$\lambda = 1: \quad \begin{array}{r} \sigma \\ \hline \sigma \end{array} = \begin{array}{r} -2.5657 \\ -5.1314 \\ +1.5052 \\ \hline -3.0262 \end{array}$$

$$\lambda = 0.5$$

$$\lambda = 3$$

$$\begin{array}{r} 0.8552 \\ 2.3856 \\ \hline 3.2408 \end{array}$$

$$\lambda = 4 \quad \begin{array}{r} 0.6414 \\ 3.0103 \\ \hline 3.6517 \end{array}$$

$$\sigma = \begin{array}{r} 7.20 \\ 2.73 \\ \hline \end{array}$$

$$\frac{\sigma}{\theta} = 7.7572$$

$$\lambda_{max} = 3.47$$

$$\lambda = 3: \quad \begin{array}{r} -2.3856 \\ -2.5857 \\ \hline -4.9713 \end{array}$$

$$\lambda_{max} = 1.157$$

$$\begin{array}{r} 0.40929 \\ 0.16332 \\ \hline 0.74588 \\ 0.06333.5 \\ +0.31665 \\ \hline -2.2176 \\ -0.2166 \\ \hline -2.4342 \end{array}$$

$$\lambda = 2 \quad \begin{array}{r} \sigma \\ \hline \sigma \end{array} = \begin{array}{r} -1.28285 \\ 1.50515 \\ \hline -2.7880 \end{array}$$

$$3^4 = 81$$

$$\theta = 1440 \cdot \frac{5}{4}$$

$$\frac{3200}{1800}$$

$$\frac{273}{1527}$$

~~25657~~

$$38486 \cdot \frac{5}{5}$$

~~32~~

$$153944$$

$$\lambda = 1 \quad 307888$$

$$\lambda = 2$$

$$153944$$

$$150515$$

$$-30446$$

$$\lambda = \frac{1}{2}$$

$$-615776$$

$$+150515$$

$$-465261$$

$$\lambda = 1$$

$$1735 \cdot \frac{5}{5}$$

$$0347$$

$$1388$$

~~48820~~

$$014239$$

$$034601$$

$$221825$$

$$071195$$

$$29902$$

$$\lambda = 3$$

$$-102629$$

$$23856$$

$$-34119$$

$$\rho \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right) = \gamma \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) u + \frac{1}{3} \gamma \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) - \frac{\partial p}{\partial x}$$

$$u = f(r, \theta, \phi) = f(r, \theta, \phi)$$

$$v = f(r, \theta, \phi) \sin \theta = f(r, \theta, \phi) \sin \theta$$

$$w = f(r, \theta, \phi) \cos \theta = f(r, \theta, \phi) \cos \theta$$

$$x = r \sin \theta \cos \phi$$

$$u = f(r, \theta, \phi)$$

$$r, \theta = f(r, \theta)$$

$$y = r \sin \theta \sin \phi$$

$$v = f(r, \theta, \phi) \sin \theta$$

$$z = r \cos \theta$$

$$w = f(r, \theta, \phi) \cos \theta$$

$$\frac{\partial}{\partial x} = \frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial}{\partial \theta} + \frac{\partial \phi}{\partial x} \frac{\partial}{\partial \phi}$$

$$\frac{\partial r}{\partial x} = \frac{\partial}{\partial r} \cos \theta \cos \phi$$

$$\frac{\partial r}{\partial y} = \frac{\partial}{\partial r} \cos \theta \sin \phi$$

$$\frac{\partial r}{\partial z} = \frac{\partial}{\partial r} \cos \theta$$

$$\frac{\partial \theta}{\partial x} = \frac{\partial}{\partial \theta} \cos \theta \cos \phi$$

$$\frac{\partial \theta}{\partial y} = \frac{\partial}{\partial \theta} \cos \theta \sin \phi$$

$$\frac{\partial \theta}{\partial z} = \frac{\partial}{\partial \theta} \cos \theta$$

$$\frac{\partial \phi}{\partial x} = \frac{\partial}{\partial \phi} \cos \theta \cos \phi$$

$$\frac{\partial \phi}{\partial y} = \frac{\partial}{\partial \phi} \cos \theta \sin \phi$$

$$\frac{\partial \phi}{\partial z} = \frac{\partial}{\partial \phi} \cos \theta$$

$$\frac{\partial}{\partial x}$$

$$= \frac{\partial u}{\partial r^2} + \frac{\partial u}{\partial r} + \frac{1}{r} \frac{\partial u}{\partial \theta} + \frac{1}{r} \frac{\partial u}{\partial \phi}$$

$$\left[\frac{\partial^2}{\partial r^2} + \frac{\partial}{\partial r} + \frac{1}{r} \frac{\partial}{\partial \theta} - \frac{1}{r^2} \right] \cos \theta = \nabla^2 u$$

$$\nabla^2 u = \frac{\partial^2 u}{\partial r^2} + \frac{\partial u}{\partial r} + \frac{1}{r} \frac{\partial u}{\partial \theta}$$

$$\frac{\partial u}{\partial \theta} = \frac{\partial}{\partial \theta} \cos \theta + \frac{1}{r} \frac{\partial}{\partial \phi} + \frac{\partial u}{\partial \phi^2}$$

$$\rho \left[\frac{\partial \psi}{\partial t} + q \left(\frac{\partial \phi}{\partial r} \cos \psi + \frac{q}{r} \sin \psi \right) + q \sin \psi \left(\frac{\partial \phi}{\partial r} - \frac{q}{r} \right) \sin \psi + \omega \frac{\partial \psi}{\partial z} \right]$$

$$= \eta \left[\frac{\partial \psi}{\partial t} + \frac{4}{3} \left(\frac{\partial \psi}{\partial r} + \frac{1}{2} \frac{\partial \psi}{\partial r} - \frac{q}{r} \right) + \frac{1}{3} \frac{\partial \psi}{\partial r \partial z} \right] - \frac{\partial \psi}{\partial r}$$

$$\left[\frac{\partial \psi}{\partial t} + q \frac{\partial \psi}{\partial r} + \omega \frac{\partial \psi}{\partial z} \right] = \frac{\eta}{\rho} \left[\frac{4}{3} \frac{\partial \psi}{\partial r} + \frac{\partial \psi}{\partial r} + \frac{1}{2} \frac{\partial \psi}{\partial r} + \frac{1}{3} \left(\frac{\partial \psi}{\partial r \partial z} + \frac{1}{2} \frac{\partial \psi}{\partial r} \right) \right] - \frac{1}{\rho} \frac{\partial \psi}{\partial r}$$

$$\left[\frac{\partial \psi}{\partial t} + q \frac{\partial \psi}{\partial r} + \omega \frac{\partial \psi}{\partial z} \right] = \frac{\eta}{\rho} \left[\frac{\partial \psi}{\partial r} + \frac{4}{3} \left(\frac{\partial \psi}{\partial r} + \frac{1}{2} \frac{\partial \psi}{\partial r} - \frac{q}{r} \right) + \frac{1}{3} \frac{\partial \psi}{\partial r \partial z} \right] - \frac{1}{\rho} \frac{\partial \psi}{\partial r}$$

Equation of motion with ^{radial} ~~cylindrical~~ symmetry (independent of ψ)

$$\rho \frac{\partial \psi}{\partial t} = -\frac{2}{3} \mu \nabla^2 + \mu \left[2 \left(\frac{\partial u}{\partial r} \right)^2 + \left(\frac{\partial v}{\partial r} \right)^2 + \left(\frac{\partial w}{\partial r} \right)^2 + \left(\frac{\partial u}{\partial z} + \frac{\partial v}{\partial z} \right)^2 + \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)^2 \right]$$

$$- \mu \nabla^2 \psi$$

$$\rho \left[\frac{\partial \psi}{\partial t} + \omega \frac{\partial \psi}{\partial r} + \nu \frac{\partial \psi}{\partial y} + \nu \frac{\partial \psi}{\partial z} \right]$$

$$\rho \left[\frac{\partial \psi}{\partial t} + q \frac{\partial \psi}{\partial r} + \omega \frac{\partial \psi}{\partial z} \right] = -\mu \left[\frac{\partial \psi}{\partial r} + \frac{q}{r} + \frac{\partial \psi}{\partial z} \right] - \frac{2}{3} \mu \left[\frac{\partial \psi}{\partial r} + \frac{q}{r} + \frac{\partial \psi}{\partial z} \right]^2$$

$$+ \mu \left[2 \left(\frac{\partial \psi}{\partial r} \right)^2 \cos^2 \psi + 2 \frac{q}{r} \frac{\partial \psi}{\partial r} \cos \psi \sin \psi + \left(\frac{q}{r} \right)^2 \sin^2 \psi + \left(\frac{\partial \psi}{\partial z} \right)^2 \right]$$

$$+ \left(\frac{\partial \psi}{\partial r} + \frac{q}{r} \right)^2 \sin^2 \psi + \left(\frac{\partial \psi}{\partial r} + \frac{q}{r} \right)^2 \cos^2 \psi + 4 \left(\frac{\partial \psi}{\partial r} - \frac{q}{r} \right) \sin \psi \cos \psi$$

$$2 \left(\frac{\partial \psi}{\partial r} \right)^2 + 2 \left(\frac{q}{r} \right)^2 + 2 \left(\frac{\partial \psi}{\partial r} \right)^2 - 4 \sin \psi \cos \psi \left(\frac{\partial \psi}{\partial r} - \frac{q}{r} \right)^2 + \left(\frac{\partial \psi}{\partial r} \right)^2 + \left(\frac{\partial \psi}{\partial z} \right)^2 + 2 \frac{\partial \psi}{\partial r} \frac{\partial \psi}{\partial z}$$

$$\left[\frac{c_p}{A} \left(\frac{\partial \theta}{\partial t} + v \frac{\partial \theta}{\partial z} + w \frac{\partial \theta}{\partial r} \right) \right] = -\mu \left[\frac{\partial \theta}{\partial r} + \frac{v}{r} + \frac{\partial w}{\partial z} \right] + \mu \left[-\frac{2}{3} \left(\frac{\partial v}{\partial r} + \frac{v}{r} + \frac{\partial w}{\partial z} \right)^2 + 2 \left[\left(\frac{\partial w}{\partial z} \right)^2 + \left(\frac{v}{r} \right)^2 + \left(\frac{\partial v}{\partial z} \right)^2 \right] \right. \\ \left. + \left(\frac{\partial w}{\partial r} \right)^2 + \left(\frac{\partial v}{\partial z} \right)^2 + 2 \frac{\partial v}{\partial z} \frac{\partial w}{\partial r} \right] \\ = \left(\frac{\partial w}{\partial z} + \frac{\partial v}{\partial r} \right)^2$$

Thermal equation in respect to motion with radial symmetry

I.e. Stationary flow in tube:

$$q=0 \quad w = \frac{p_1^2 - p_2^2}{8\mu p l} (R^2 - r^2) \quad p^2 = p_1^2 - \left(\frac{p_1^2 - p_2^2}{l} \right) z = \alpha$$

With neglect of $\mu \frac{\partial w}{\partial z}$

$$w = \frac{\alpha (R^2 - r^2)}{8\mu p}$$

$$\frac{c_p}{A} w \frac{\partial \theta}{\partial z} = -\mu \frac{\partial w}{\partial z} + \mu \left(\frac{\partial w}{\partial z} \right)^2$$

$$\frac{\partial w}{\partial z} = -\frac{\alpha}{4\mu p}$$

$$\frac{c_p}{A} \frac{\partial \theta}{\partial z} \frac{\alpha (R^2 - r^2)}{8\mu p} = + \mu \frac{\alpha (R^2 - r^2)}{8\mu p^2} \frac{dp}{dz} + \mu \frac{\alpha^2 r^2}{16\mu^2 p^2}$$

$$= \frac{1}{8\mu p^2} \left[-\frac{\alpha^2 (R^2 - r^2)}{2} + \mu \frac{\alpha^2 r^2}{2\mu} \right]$$

$$= \frac{1}{8\mu p^2} \cdot \frac{\alpha^2 (2r^2 - R^2)}{2}$$

$$\frac{c_p}{A} \frac{\partial \theta}{\partial z} = \frac{\alpha (2r^2 - R^2)}{2\mu p (R^2 - r^2)} = \frac{\alpha (2r^2 - R^2)}{2(R^2 - r^2)}$$

$$= \frac{\alpha}{2} \frac{1}{\sqrt{p_1^2 - \alpha z}} \left[\frac{R^2}{R^2 - r^2} - 2 \right]$$

$$\frac{p}{\rho} = \alpha \theta$$

$$p = \frac{p}{\alpha \theta}$$

$$p = \frac{p^2}{\alpha \theta}$$

$$\frac{c_p}{A} \frac{\partial \theta}{\partial z} = \frac{\alpha (2r^2 - R^2)}{2\mu p (R^2 - r^2)} = \frac{\alpha}{2} \frac{1}{p_1^2 - \alpha z} \left[\frac{R^2}{R^2 - r^2} - 2 \right]$$

$$\frac{c}{R^2} \int 2\mu r w \theta dr = \frac{2\mu}{R^2} \int w \theta r dr$$

$$\frac{c}{A} \frac{\partial \theta}{\partial r} = -\frac{1}{2} \log(p_1^2 - az) \left[\frac{R^2}{R^2 - r^2} - 2 \right] + \text{const}$$

$$\frac{c}{A} \frac{\partial \theta}{\partial r} = -\frac{1}{2} \log p_1^2 \quad [\quad] + \text{---}$$

$$\frac{c}{A} [\theta^2 - \theta_0^2] = \log \frac{p_1^2}{p_1^2 - az} \left[\frac{R^2}{R^2 - r^2} - 2 \right]$$

$$\frac{c}{\alpha A} \log \frac{\theta}{\theta_0} = \frac{1}{2} \log \frac{p_1^2}{p_1^2 - az} \left[\frac{R^2}{R^2 - r^2} - 2 \right]$$

$$z = l:$$

$$\theta = \theta_0 \left[\frac{p_1}{p_2} \right]$$

$$\frac{2R^2 - R^2}{R^2 - r^2} \cdot \frac{\alpha A}{c}$$

$$\theta = \theta_0 \left[\frac{p_1^2}{p_1^2 - az} \right]^{\frac{1}{2} \frac{\alpha A}{c} \frac{2R^2 - R^2}{R^2 - r^2}}$$

$$= \theta_0 \left[1 - \frac{az}{p_1^2} \right]^{-\frac{\alpha A}{c} \frac{2R^2 - R^2}{R^2 - r^2}}$$

$$z = 0:$$

$$\theta = \theta_0 \left(\frac{p_1}{p_2} \right)^{-\frac{\alpha A}{c}}$$

$$\int \left(\frac{R^2}{R^2 - r^2} - 2 \right) r dr = R^2 \log(R^2 - r^2)$$

$$z = R:$$

$$\theta = \theta_0 \infty$$

With taking into account the condition of heat:

$$\frac{c\rho}{A} \frac{\partial \theta}{\partial z} \frac{a(R^2 - r^2)}{\rho_\mu r} = \frac{1}{\rho_\mu r^2} \frac{a^2(2R^2 - R^2)}{2} + \kappa \left[\frac{\partial \theta}{\partial r^2} + \frac{1}{r} \frac{\partial \theta}{\partial r} \right]$$

$$\frac{c}{\alpha A} \frac{1}{\theta} \frac{\partial \theta}{\partial z} \frac{a(R^2 - r^2)}{\rho_\mu} = \frac{1}{\rho_\mu (p_1^2 - az)} \frac{a^2(2R^2 - R^2)}{2} + \kappa \nearrow$$

$$\theta = b_0 + b_1 z + (\cancel{b_2} + b_3 z) r^2$$

$$\frac{\partial \theta}{\partial z} = b_1 + b_3 z \quad r \frac{\partial \theta}{\partial r} = 2 r^2 (b_2 + b_3 z)$$

$$\frac{1}{2} \frac{\partial}{\partial r} () = 4 \kappa (b_2 + b_3 z)$$

$$\frac{c}{\alpha A} \alpha (R^2 - r^2) (b_1 + b_3 z) (p_1^2 - a z) = a^2 \left(r^2 - \frac{R^2}{2} \right) (b_0 + b_1 z + b_2 r^2 + b_3 z r^2) + 4 \kappa (b_2 + b_3 z) (b_0 + b_1 z + b_2 r^2 + b_3 z r^2) (p_1^2 - a z)$$

$$\frac{c}{\alpha A} a R^2 b_1 p_1^2 = -a^2 \frac{R^2}{2} b_0 + 4 \kappa p_1^2 b_0 b_2$$

$$\frac{c}{\alpha A} a (R^2 b_3 - b_1) p_1^2 = a^2 \left(b_0 - \frac{R^2}{2} b_2 \right) + 4 \kappa b_2^2 p_1^2$$

$$-\frac{c}{\alpha A} a^2 R^2 b_1 = a^2 \left(\cancel{b_0} - \frac{R^2}{2} \right) b_0 + 4 \kappa \left[(b_0 b_3 + b_1 b_2) p_1^2 - a b_0 b_2 \right]$$

$$+\frac{c}{\alpha A} a^2 (b_1 - R^2 b_3) = a^2 \left(b_1 - \frac{R^2}{2} b_3 \right) + 4 \kappa \left[2 b_2 b_3 p_1^2 - a b_2^2 \right]$$

$$0 = a^2 \left[\cancel{b_0} - \frac{R^2}{2} (p_1^2 + a b_0) \right] + 4 \kappa p_1^2 (b_0 b_3 + b_1 b_2)$$

$$0 = a^2 \left[b_1 p_1^2 + b_0 - \frac{R^2}{2} (b_3 p_1^2 + b_2) \right] + 8 \kappa b_2 b_3 p_1^4$$

$$1 + \frac{\alpha A a}{2 c p_1^2} \frac{2 r^2 - R^2}{R^2 - r^2} z =$$

$$= \frac{R^2}{R^2 - r^2} - 2 = \frac{1}{1 - \frac{r^2}{R^2}} - 2 = 1 + \frac{r^2}{R^2} + \frac{r^4}{R^4} \dots - 2 = -1 + \frac{r^2}{R^2} + \frac{r^4}{R^4}$$

$$= 1 + \frac{\alpha A a}{2 c p_1^2} \frac{2 r^2 - R^2}{R^2 - r^2} z + \frac{\alpha A a}{2 c p_1^2} \frac{2 r^2 - R^2}{R^2 - r^2} \left[1 - \frac{a z}{p_1^2} \right]$$

$$\frac{\partial \theta}{\partial r} = \frac{\partial \theta}{\partial r} + \frac{\partial \theta}{\partial z} \left[1 - \frac{a z}{p_1^2} \right] = \frac{2 \kappa \alpha A a r}{2 c p_1^2} - \frac{2 \kappa \alpha A a r}{2 c p_1^2} \frac{a z}{p_1^2}$$

$$-\frac{a}{p_1^2 - a z} \frac{c}{\alpha A} \frac{\alpha (R^2 - r^2)}{2 c} = x$$

$$\gamma \left(\frac{\partial \tilde{w}}{\partial r^2} + \frac{1}{2} \frac{\partial w}{\partial r} \right) = \frac{\partial \mu}{\partial r}$$

$$\frac{\partial}{\partial r} (p w) \approx 0$$

$$+ b_{11} r^2$$

$$\theta = b_0 + b_1 r + b_2 r^2 + b_3 r^3 + b_4 r^4 + b_5 r^5 + \dots$$

$$\frac{2c}{\alpha A} a (R^2 - r^2) (r_1^2 - a^2) \frac{\partial \theta}{\partial r} = a^2 (2r^2 - R^2) \theta + \frac{16}{\mu k} (r_1^2 - a^2) \frac{\theta}{2} \frac{\partial}{\partial r} \left(r \frac{\partial \theta}{\partial r} \right)$$

$$r \frac{\partial \theta}{\partial r} = 2b_2 r^2 + 2b_3 r^3 + 4b_4 r^4 + 4b_5 r^5$$

$$\frac{\partial}{\partial r} () = 4b_2 r + 4b_3 r^2 + 16b_4 r^3 + 16b_5 r^4$$

$$\begin{aligned} & \frac{2c}{\alpha A} a (R^2 - r^2) (r_1^2 - a^2) (b_1 + b_2 r^2 + 2b_3 r^3 + b_4 r^4 + 2b_5 r^5) = \\ & = a^2 (2r^2 - R^2) (b_0 + b_1 r + b_2 r^2 + b_3 r^3 + b_4 r^4 + b_5 r^5) + \\ & + \frac{b_4}{\mu k} (r_1^2 - a^2) (b_0 + b_1 r + b_2 r^2 + b_3 r^3 + b_4 r^4 + b_5 r^5) (b_2 r + b_3 r^2 + 4b_4 r^3 + 4b_5 r^4) \end{aligned}$$

$$\beta R^2 r_1^2 b_1 = -a^2 R^2 b_0$$

$$-\beta R^2 a b_1 = -a^2 R^2 b_1 + \frac{b_4}{\mu k} r_1^2 b_0 b_2$$

$$-\beta r_1^2 b_1 + \beta R^2 r_1^2 b_2 = 2a^2 b_0$$

$$2r^2)$$

$$2\beta R^2 r_1^2 b_3 - \beta R^2 a b_2 + \beta \frac{b_4}{\mu k} a b_1 = -a^2 R^2 b_2 + 2a^2 b_1$$

$$\text{I II: } \beta R^2 \mu_i^2 h_2 = a^2 b_0 = -\mu_i^2 \rho h_1$$

$$h_1 = -\frac{a^2 b_0}{\rho \mu_i^2}$$

$$h_2 = \frac{a^2 b_0}{\rho \mu_i^2 R^2}$$

$$\text{II). } \frac{2}{3} \mu_i^2 h_{11} = \rho a h_1 - a^2 h_1 + 64 \mu_i^2 \frac{h_0 h_2}{R^2}$$

$$h_{11} = h_1 \left[\frac{a}{2 \mu_i^2} - \frac{a^2}{2 \rho \mu_i^2} \right]$$

$$= \frac{-a^3 b_0}{2 \mu_i^2 \rho \mu_i^2} \left(1 - \frac{a}{\rho} \right)$$

$$[1 - 2\alpha + \frac{17}{16}\alpha^2]^{-1} = 1 + 2\alpha - \frac{17}{16}\alpha^2 + 4\alpha^2 \dots$$

$$\frac{1}{1-x} = 1 + x + x^2 + \dots = 1 + 2\alpha + \frac{47}{16}\alpha^2$$

Distance - λ_p etc.

$$\frac{v_a}{v_i} = e^{\frac{h^2}{m v_i^2}} = e^{\frac{m v_i^2}{2}} = e^{\frac{m v_i^2}{2 RT}}$$

$$\frac{m v_i^2}{2} = \left[n \text{ sep } a \right] = LK \omega_f \text{ etc } \sqrt{1 - \dots}$$

$$\psi_f = \frac{2m a}{v_f}$$

$$\psi = \frac{RT}{2a} \log \frac{v_a}{v_i} = \frac{m h}{v_f}$$

$$\log \frac{v_a - b}{v_i - b} = \log \frac{v_a}{v_i} \cdot \frac{1 - \frac{b}{v_a}}{1 - \frac{b}{v_i}}$$

$$= \log \frac{v_a}{v_i} + \log \left(1 - \frac{b}{v_a}\right) - \log \left(1 - \frac{b}{v_i}\right)$$

$$= \log \frac{v_a}{v_i} - \frac{b}{v_a} + \frac{b}{v_i} - \frac{b^2}{v_a^2} + \frac{b^2}{v_i^2}$$

$$= \log \frac{v_a}{v_i} - b \left(\frac{1}{v_a} - \frac{1}{v_i} \right) - b^2 \left(\frac{1}{v_a^2} - \frac{1}{v_i^2} \right)$$

$$\begin{aligned} (178) \quad a \left(\frac{1}{v_f} - \frac{1}{v_i} \right) &= RT \left[\log \frac{v_f - b}{v_i - b} - \left(\frac{v_f}{v_f - b} - \frac{v_i}{v_i - b} \right) \right] \\ &= RT \left[\log \frac{v_f}{v_i} - b \left(\frac{1}{v_f} - \frac{1}{v_i} \right) - b^2 \left(\frac{1}{v_f^2} - \frac{1}{v_i^2} \right) \right. \\ &\quad \left. + b \left(\frac{1}{v_f} - \frac{1}{v_i} \right) - b^2 \left(\frac{1}{v_f^2} - \frac{1}{v_i^2} \right) \right] \\ &= RT (v_f - v_i) \end{aligned}$$

Odumans (978)

$$p(v_g - v_f) = nT \left[\gamma \frac{v_f - b}{v_f - b} + a \left(\frac{1}{v_g} - \frac{1}{v_f} \right) \right]$$

$$p = \frac{nT}{v - b} - \frac{a}{v^2}$$

$$nT \left[\underbrace{\frac{-v_f}{v_f - b} + \frac{nT}{v_f - b} + \gamma \frac{v_f - b}{v_f - b}}_{= L_i} = 2a \left(\frac{1}{v_g} - \frac{1}{v_f} \right) \right] = \text{identical with Helmholtz equation?}$$

$$\neq \gamma \frac{v_f}{v_f} - b \left(\frac{1}{v_g} - \frac{1}{v_f} \right) - b^2 \left(\frac{1}{v_g} - \frac{1}{v_f} \right)$$



$$4\pi \left[R^2 \sin \alpha - \frac{1}{3} \left(\sqrt{R^2 - r^2} \right)^2 \right]$$

$$= 4\pi R^2 \left[1 - \left(1 - \left(\frac{r}{R} \right)^2 \right)^{\frac{3}{2}} \right]$$

$$= 4\pi R^2 \left[1 - 1 + \frac{3}{2} \left(\frac{r}{R} \right)^2 \right]$$

$$= \frac{8\pi}{3} \frac{r^3}{R} = \frac{2\pi r^3}{3R}$$

m_1
 m_2
 m_3
 m_4
 m_5

$$\begin{aligned}
 W = & m_1 m_2 x_{12} + m_1 m_3 x_{13} + m_1 m_4 x_{14} + m_1 m_5 x_{15} \\
 & + m_2 m_3 x_{23} + m_2 m_4 x_{24} + m_2 m_5 x_{25} \\
 & + m_3 m_4 x_{34} + m_3 m_5 x_{35} \\
 & + m_4 m_5 x_{45}
 \end{aligned}$$

$$= \frac{1}{2} \sum_i \sum_k m_i m_k x_{ik}$$

$$= \frac{1}{2} \sum_i m_i \sum_k m_k x_{ik}$$

$$= \frac{1}{2} \int_0^{\infty} \frac{1}{M} \int_0^{\infty} \rho(r) \rho(r') x(r, r') dr dr' = 2 \pi M \rho \int_0^{\infty} f(r) r^2 dr$$

Σ , könnte also je e. p. allg. u. $n = \frac{nB}{2}$ da $B = \sqrt{2} \cdot 1$ ρ_{max}
 800. $\rho < f \sqrt{B} / \sqrt{e} \rho_{allg. u.}$, 1. D. l. oben; da B ist 1/4 p. allg. u.
 1. D. & l. D. $\sim \frac{1}{2} \rho_{max}$ 2. m. $\frac{W}{\frac{1}{2} \Sigma n U}$ p. 1). e. Summand fort
 2). U wird bei der betrachteten
 Teilchen klein und diese beiden Wdhgen ungefähr $\rho = B$
 also in Saure Arbeit $\frac{SW}{B}$
 Wenn man aber die entstehenden Teilchen wieder verschwindet so wird letzter
 Arbeit $= \frac{1}{2} B$ wieder gewonnen; also wirklich innere Verd. u. für 1 Teilchen $= \frac{B}{2}$!

$$dN = A e^{-h(U+L)} du dv dw \dots dx dy dz$$

$$= A e^{-h(U+L_a+L_i)} dw_a dw_i dv$$

$$N_u = A e^{-\frac{hU}{v}} \int e^{-L_a+L_i} dw_a dw_i = B e^{-\frac{hU}{v}} dv$$

$$= N_g e^{-\frac{hU}{v}} dv$$

$$\frac{p_f}{p_g} = e^{-\frac{hU}{v}} = e^{-h \int}$$

$$p = \frac{mc^2}{3n(d-2r)^3}$$

$$\cancel{b = \frac{3}{4}(d-2r)}$$

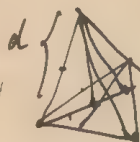
$$4 \frac{4}{3} \pi r^3 = b$$

$$2r = \sqrt[3]{\frac{3b}{2n}}$$

$$p = \frac{mc^2}{3n(\sqrt[3]{v} - \sqrt[3]{\frac{3b}{2n}})^3}$$

$$\cancel{d^3 = v}$$

$$\cancel{d = \sqrt[3]{v}}$$



$$h = \sqrt{d^2 - \left(\frac{3}{4} \frac{d}{\sqrt{3}}\right)^2}$$

$$= d \sqrt{1 - \frac{1}{4}} = d \sqrt{\frac{3}{4}}$$

$$d \frac{1}{2} \sqrt{3}$$

$$p = \frac{mc^2}{3n v \left(1 - \sqrt[3]{\frac{3b}{2n v}}\right)^3}$$

1/2 2/3

$$\frac{4}{3} \pi r^3 = b_1$$

$$r = \sqrt[3]{\frac{3b_1}{4n}}$$

$$p = \frac{mc^2}{3n(\sqrt[3]{v} - \sqrt[3]{\frac{6b_1}{n}})^3}$$

$$\cancel{\frac{d}{2} \cdot \frac{d}{2} \sqrt{3} \cdot d \sqrt{\frac{2}{3}}} = \frac{d^3}{\sqrt{2}} = v$$

$$d = \sqrt[3]{v \sqrt{2}}$$

$$\sqrt{2} = \frac{3b}{2n v}$$

$$\frac{b}{v} = \frac{n \sqrt{8}}{3}$$

$$p = \frac{mc^2}{3n \left(\sqrt[3]{v \sqrt{2}} - \sqrt[3]{\frac{6b_1}{n}} \right)^3} = \frac{mc^2}{\left(\sqrt[3]{3 \sqrt{2} n v} - \sqrt[3]{18 b_1} \right)^3} = \frac{mc^2}{3n \sqrt{2} \cdot v \left[1 - \sqrt[3]{\frac{b_1}{n \sqrt{2} v}} \right]^3}$$

$$\frac{6 b_1}{2 \sqrt{2}} = \beta$$

$$p = \frac{n m c}{3 n \sqrt{2} \cdot v \left(1 - \sqrt{\frac{\phi}{v}}\right)^3}$$

$$\left[\frac{\phi}{v}\right]^{\frac{1}{3}} \left[1 - \frac{v-\phi}{v}\right]^{\frac{1}{3}} = 1 - \frac{v-\phi}{3v}$$

$$p = \frac{n m c^2}{3 n \sqrt{2} \cdot v \left(\frac{v-\phi}{3v}\right)^3} = \frac{n m c^2}{3 n \sqrt{2}} \frac{9 v^2}{(v-\phi)^3} = n m c^2 \frac{3}{2} \frac{\beta}{4} \frac{v^2}{(v-\phi)^3}$$

$$p v = n m c^2 \cdot \frac{9}{2 \sqrt{2}} \frac{1}{\left(1 - \frac{\phi}{v}\right)^3} = \frac{9}{2 \sqrt{2}} \left[1 + 3 \frac{\phi}{v}\right]$$

$$\frac{1 + \frac{2}{3} x}{1 - \frac{x}{3}} = \left(1 + \frac{2}{3} x\right) \left(1 - \frac{x}{3}\right)^{-1} =$$

$$= \left(1 + \frac{2x}{3}\right) \left(1 + \frac{x}{3} + \frac{x^2}{9} + \frac{x^3}{27}\right)$$

$$= 1 + x + \frac{x^2}{3} + \frac{x^3}{9}$$

$$T = 22 \sqrt{10} = 1/2 \dots$$

$$= \dots$$

$$\dots$$

$$\dots$$

$$\dots$$

$$\dots$$

$$LE = 1, T = 2/2 = 1$$

$$\Sigma [1 + \frac{V}{3}] = 1 + \dots$$

$$\dots \left[\frac{V}{3} \right]$$

$$\frac{nm\bar{c}^2}{2}$$

$$\bar{c}^2 = 3nT$$

$$nT \left[1 + \frac{\sqrt{2}}{3} \frac{\delta}{\lambda} \right] = \rho v + \underbrace{\frac{1}{3} \frac{W_i''}{nm}}_{\frac{a}{v}}$$

$$\rho + \frac{a}{v} \rho = \frac{nT}{v} \left[1 + \frac{\sqrt{2}}{3} \frac{\delta}{\lambda} \right]$$

$$\frac{V}{nm} = v \parallel \frac{2\pi\delta^3}{3nm} = b$$

$$\frac{\delta}{v} = \frac{2\pi\delta^3 n}{3V}$$

$$W_i'' = 3\rho^2 V$$

Nach Jern für Plücker und nach Luthend für gute Körper

$$\lambda = d - b$$

Somit

$$\mu + \frac{a}{v} = \frac{rT}{v} \left[1 + \frac{\sqrt{2}}{3} \frac{b}{d-b} \right]$$

$$\frac{d}{b} = \sqrt[3]{\frac{v}{v_0}}$$

$$= \frac{rT}{v} \left[1 + \frac{\sqrt{2}}{3} \frac{1}{\sqrt[3]{\frac{v}{v_0}} - 1} \right]$$

$$\sqrt[3]{\frac{v}{v_0}} = \left[1 + \frac{v-v_0}{v_0} \right]^{\frac{1}{3}} = 1 + \frac{1}{3} \frac{v-v_0}{v_0}$$

$$= \frac{rT}{v} \left[1 + \frac{\sqrt{2}}{3} \frac{1}{\frac{1}{3} \frac{v-v_0}{v_0}} \right] = \frac{rT}{v} \left[\frac{v-v_0 + v_0 \sqrt{2}}{v-v_0} \right]$$

$$= \frac{rT}{v} \frac{v_0 \sqrt{2}}{v-v_0} = \frac{rT \sqrt{2}}{v-v_0}$$

$$\mu + \frac{a}{v} = \frac{rT}{v} \left[1 + \frac{\sqrt{2}}{3} \frac{b}{d-b} \right]$$

$$\frac{a}{v} - \frac{a v_0}{v^2} = rT \sqrt{2}$$

$$\frac{dv}{dt} \left[\frac{a}{v^2} + \frac{2 a v_0}{v^3} \right] = -rT \sqrt{2}$$

$$\text{mit } \mu: \quad \frac{a}{v_0} (v-v_0) = rT \sqrt{2}$$

$$\frac{a}{v_0} \frac{dv}{dt} = rT \sqrt{2}$$

$$\alpha = \frac{1}{3} \frac{1}{v} \frac{dv}{dt} = \frac{v_0}{3} \frac{(rT \sqrt{2})}{a T}$$

$$= \frac{v-v_0}{3 v_0 T} = \frac{rT \sqrt{2}}{3} \frac{v_0}{a} = \frac{rT \sqrt{2}}{3 a}$$

$$v-v_0 = \frac{a}{v_0} rT \sqrt{2} \frac{v_0}{a}$$

$$= \frac{a}{v_0} (v-v_0)$$

$$dp + \frac{2a}{v^3} dv = - \frac{\pi T \sqrt{2}}{(v-v_0)^2} dv$$

$$k = \frac{1}{v} \frac{dv}{dp} \quad k = v \frac{dp}{dv}$$

$$v \frac{dp}{dv} = \frac{2a}{v^2} - \frac{\pi T \sqrt{2}}{(v-v_0)^2} v = \frac{2a}{v^2} - \frac{a v}{v_0^2 (v-v_0)} = a \frac{2 v v_0^2 - 2 v_0^3 - v^3}{v_0^2 v^2 (v-v_0)}$$

$$= - \frac{a}{v_0 (v-v_0)} = \frac{a^2}{\pi \sqrt{2} v_0^3 T}$$

$$k = \frac{v_0 (v-v_0)}{a} = \pi T \sqrt{2} \frac{v_0^3}{a^2}$$

$$\frac{k}{a} = \frac{v-v_0}{\pi} \frac{3}{\sqrt{2}} \neq \frac{2(v-v_0)}{\pi} = \frac{3}{\sqrt{2}} T \sqrt{2} \frac{v_0^3}{a} = \frac{3}{\sqrt{2}} \frac{T \sqrt{2}}{\rho_0^2} \frac{1}{a}$$

$$a = \frac{\pi}{\rho} \frac{\sqrt{2}}{3} \frac{1}{a}$$

$$k = \frac{\pi T \sqrt{2}}{\rho^3} \frac{\rho^2}{\pi^2} \frac{1}{2} \alpha^2 = \frac{1}{2} \frac{\pi T \sqrt{2}}{\rho \pi^2} \alpha^2$$

$$k = \frac{2}{9} \frac{\rho \pi}{\sqrt{2} T \alpha^2} \left| \begin{aligned} &= \frac{\sqrt{2}}{9} \frac{\pi}{T} \cdot \frac{\rho}{\alpha^2} \\ &= \frac{\sqrt{2}}{9} \frac{R}{T} \frac{\rho}{\mu \alpha^2} \end{aligned} \right.$$

$$\alpha = \frac{R}{\mu}$$

$$= \frac{1}{\mu} \frac{\rho \pi}{T} = \frac{1}{\mu} \frac{\rho}{\rho T} = \frac{1}{\mu}$$

$$\frac{1000}{96 \cdot 13.6 \cdot 980} = \frac{1}{0.00129 \cdot 273}$$

$$\mu = \frac{\text{atmos.}}{14.5}$$

$$\frac{\sqrt{2} R}{\rho T} = \frac{\sqrt{2}}{9} \frac{980,000}{(273)^2 \cdot 0.00129}$$

$$\begin{array}{r} 2.4362 \\ 4.8724 \\ 0.1106 - 3 \\ 0.9542 \\ \hline 2.9372 \end{array}$$

$$\begin{array}{r} 0.20103 \\ 0.1505 \\ 5.9912 \\ \hline 6.1417 \\ 2.9372 \\ \hline 3.2045 \end{array}$$

$$G_{\text{m}} \frac{\rho}{\mu \alpha^2}$$

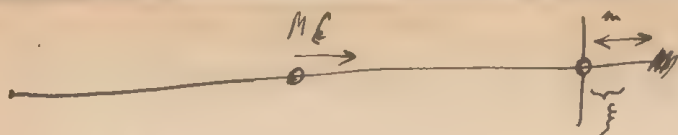
$$\frac{8.8 \cdot 145}{65.3 \cdot [168 \cdot 10^9]^2} = \frac{145}{\alpha \cdot \frac{\alpha A}{2}} = \frac{145 \cdot 10^{15}}{168 \cdot 10^9 \cdot 121 \cdot 10^9}$$

$$\begin{array}{r} 3.2045 \\ 1.1614 \\ \hline 4.3659 \end{array}$$

$$\begin{array}{r} 19.3659 \\ - 4.3081 \\ \hline 15.0578 \end{array}$$

$$\begin{array}{r} 2.2253 \\ 2.0828 \\ \hline 4.3081 \end{array}$$

$$1150 \cdot 10^{12}$$



$$\xi = A \sin \omega t$$

$$\xi|_0 = a \omega = v$$

$$\overline{M c^2} = \overline{m c^2}$$

$$\frac{\overline{M c^2} + \overline{m c^2} + \overline{V}}{2} = \frac{M c^2}{2}$$

$$\overline{V} = \frac{\overline{m c^2}}{2}$$

$$M = 2m$$

$$\frac{c^2}{h} = \frac{1}{3} C^2$$

$$\left. \begin{aligned} M v^2 + m v_0^2 &= M V_0^2 + m v_0^2 \\ M v + m v_0 &= M V_0 + m v_0 \end{aligned} \right\} \begin{aligned} M (V^2 - V_0^2) &= m (v_0^2 - v^2) \\ M (V - V_0) &= m (v_0 - v) \end{aligned}$$

$$\underline{V - v = -V_0 + v_0} \quad | \cdot m - M \quad \underline{V + V_0 = v + v_0}$$

$$V = \frac{M - m}{M + m} V_0 + \frac{2m}{M + m} v_0 = \frac{V_0 + 2v_0}{3}$$

$$v = \frac{\cancel{m} V_0 + \cancel{2M} V_0}{3} = \frac{-v_0 + 4V_0}{3}$$

$$\frac{v_0(m - M) + 2M V_0}{m + M}$$

$$f_0 = \frac{1}{2\pi} = \frac{1}{2\pi}$$

$$f_1 = \frac{1}{2\pi} = \frac{1}{2\pi}$$

$$f_2 = \frac{1}{2\pi} \left[-\frac{1}{2\pi} \right]$$

$$\frac{1}{2\pi} = \frac{1}{2\pi} + \frac{1}{2\pi} = \frac{1}{2\pi}$$

$$2.1) \frac{1}{2\pi} = \frac{1}{2\pi}$$

$$f_1 = \frac{1}{2\pi} = \frac{1}{2\pi}$$

$$1) \frac{1}{2\pi} = \frac{1}{2\pi} \left[-\frac{1}{2\pi} + \frac{1}{2\pi} \right]$$

$$f_1 = \frac{1}{2\pi} = \frac{1}{2\pi}$$

$$1.2) + \frac{1}{2\pi} = \frac{1}{2\pi} = \frac{1}{2\pi}$$

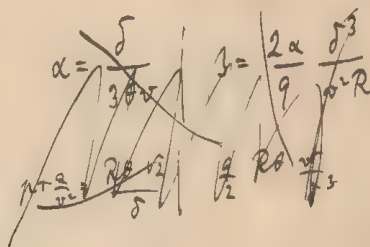
$$f_1 = \frac{1}{2\pi} = \frac{1}{2\pi}$$

$$f_1 = \frac{1}{2\pi} = \frac{1}{2\pi}$$

$$f_1 = \frac{1}{2\pi} = \frac{1}{2\pi}$$

Nach δ ges:

$$\left(p + \frac{a}{v}\right) \theta = \frac{q b^2 R \theta}{2(v-b)^3}$$



$$1 + \frac{2a}{v^3} \frac{dv}{d\theta} = -\frac{q b^2 R \theta}{2} \frac{3}{(v-b)^4} \frac{dv}{d\theta}$$

$$1 = \frac{dv}{d\theta} \left[\frac{2a}{v^3} - \frac{q \cdot 3 b^2 R \theta}{2 (v-b)^4} \right]$$

$$\left(p + \frac{a}{v}\right) \frac{3}{v-b} = \frac{dv}{d\theta} \frac{q}{v^2} \left[\frac{2}{v} - \frac{3}{v-b} \right]$$

$$\frac{v^2}{a} = \frac{2(v-b)^2}{q b^2 R \theta}$$

$$= \frac{dv}{d\theta} \frac{a [2v-2b-3v]}{v^3 (v-b)}$$

$$\frac{a}{v^2} (v-b)^3 = \frac{q}{2} b^2 R \theta$$

$$\frac{d\theta}{dv} = -\frac{a(v+2b)}{v^3(v-b)}$$

$$\left[-\frac{2a}{v^3} (v-b)^3 + \frac{3a}{v^2} (v-b)^2 \right] \frac{dv}{d\theta} = \frac{q}{2} R b^2 = \frac{dv}{d\theta} \frac{a(v-b)^2}{v^3} \left[-\frac{2(v-b)}{v} + 3 \right]$$

$$\left[-2a(v-b)^3 + 3av(v-b)^2 \right] \frac{dv}{d\theta} \frac{1}{v^3}$$

$$\left[-2av^3 + 6av^2b - 6avb^2 + 2ab^3 + 3av^3 - 6av^2b + 3avb^2 \right] \frac{1}{v^3} \frac{dv}{d\theta}$$

$$= \frac{a}{v^2} \left(\frac{v-b}{v} \right)^3$$

$$\frac{1}{v} \frac{dv}{d\theta} = \frac{v-b}{v+2b} \frac{1}{\theta} = \alpha$$

$$\frac{1}{v} \frac{dv}{d\theta} = \beta = \frac{v^2(v-b)}{a(v+2b)} = \frac{\theta a v^2}{a} = \frac{2a}{q} \frac{(v-b)^3}{b^2 R}$$

$$\alpha_{H_f} = \frac{1}{5500}$$

$$v-b = (v+2b) \theta \alpha$$

$$1 - \frac{b}{v} = (1 + \frac{2b}{v}) \theta \alpha \neq 3 \theta \alpha$$

~~280.3~~

$$\frac{300.3}{5500} = \frac{9}{55} = \frac{1}{6}$$

$$b = \frac{5}{6} v$$

$$\left[\begin{array}{l} \text{when } \alpha \rightarrow 0 \\ b \rightarrow 0 \end{array} \right]$$

$$RA = \frac{rv}{\theta} = \frac{nm\sigma}{\theta} = \frac{\rho c^2}{3\theta}$$

$$\frac{(1855)^2}{3.27} = \frac{(485)^2 \cdot 0.00129 \cdot 10^3}{3.27}$$

$$\underline{2.6857}$$

$$2.4362$$

$$5.3714$$

$$\underline{0.4771}$$

$$0.1106-3$$

$$2.9133$$

$$\underline{5.4820-3}$$

$$-2.9133$$

$$\underline{2.5687} = 370 \cdot 10^4$$

$$\rho = \frac{2}{9} \alpha \left(\frac{1}{6}\right)^3 \frac{1}{370 \cdot 10^4} = \frac{2}{9} \frac{1}{216} \frac{1}{5500} \frac{1}{370 \cdot 10^4}$$

$$0.9542$$

$$2.3345$$

$$3.7404$$

$$\underline{6.5682}$$

$$13.5973$$

$$\underline{2010}$$

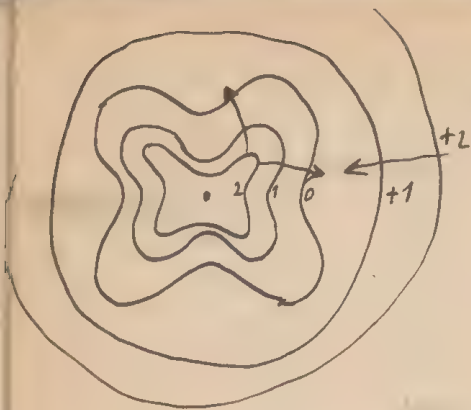
$$13.2963$$

$$= 2 \cdot 10^{-13} !$$

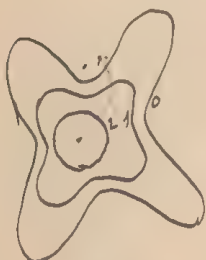
$$\rho_{H_f} = 0.000004 \cdot \frac{1}{13.6 \cdot 76 \cdot 980}$$

$$= 4 \cdot 10^{-12}$$

$$\text{also } 2037'$$



~~Handwritten scribbles~~



$$\varphi = \cancel{F_1} + F_2 + F_3 + \dots$$

$$= (x, y, z) + (x^2 + y^2, z) + \dots$$

$$X = -\frac{\partial \varphi}{\partial x} = -\left[\cancel{\frac{\partial F_1}{\partial x}} + \frac{\partial F_2}{\partial x} + \dots \right]$$

$$= -\left[(A_2 x + D_4 + \dots) - (A_3 x^2 + \dots) - \frac{\partial(F_3 + F_5 + \dots)}{\partial x} \right]$$

$$F_1 = 0$$

of the ~~Handwritten scribbles~~ x, y, z
 \hookrightarrow stabil

$$-\frac{1}{2}(Xx + Yy + Zz) = F_2 + \frac{3}{2}F_3 + 2F_4 + \dots = L$$

$$\varphi \text{ null } < 0 \text{ in } F_2 + F_3 + F_4 + \dots < 0$$

$$F_2 + \frac{1}{2}F_3 + 2F_4 + \dots > 0 > -\varphi$$

$$\underbrace{3F_3 + 5F_5 + \dots}_{>0} < \underbrace{2F_2 + 4F_4 + \dots}_{>0}$$

~~Handwritten scribbles~~ $F_2 + F_4$

Terminy z t.g. bez względu na

Nova t.g. przy uwzględnieniu

Elementy:

Mexv. ^{radii} ~~średnicy~~ ^{średnic} ~~średnic~~ ^{średnic}

Nova. - Poltem ~~wzrost~~ ^{wzrost} ~~prędkości~~

$$h = \frac{1}{\theta}$$

Classius-Virial

$$\bar{\varphi} = \int \varphi e^{-h\varphi} d\varphi$$

$$\nabla \bar{\varphi} = \int \nabla \varphi \cdot e^{-h\varphi} d\varphi - h \int \varphi \nabla \varphi \cdot e^{-h\varphi} d\varphi - \underbrace{\nabla h \int \varphi^2 e^{-h\varphi} d\varphi}_{>0}$$

$$\nabla(h\varphi) > 0$$

$$\nabla\left(\frac{\varphi}{h}\right) > 0$$

$$\int \nabla(\varphi e^{-h\varphi}) d\varphi < 0$$



$$\frac{2L}{3d^2(d-6)} - \rho - \frac{2}{d^3} \underbrace{A_m n \rho \lambda \frac{R}{2}}_{\rho} = 0$$

$$\rho + \frac{a}{v^2} = \frac{R\theta}{d^2(d-6)}$$

$$\cancel{\rho + \frac{a}{v^2}} = \frac{R\theta}{v^2} \underbrace{\frac{n}{1 - \frac{6}{2}}}_{\frac{1}{5} \frac{v-v_0}{v_0}}$$

$$= \frac{R\theta \cdot 3}{v-v_0}$$

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Zanim przejdę do właściwego przedmiotu chciałbym z firm ^{uzupełni} ~~o~~ dwa
zastrzeżenia 1) że w obec ^{stoski} ogromnej motylarni, który się zgromadził w
ostatnich latach, musimy zrezygnować z jednokrotnego traktowania całego przed-
miotu i opierać się na pewnym punkcie, które nam się wydaje rocznie,
mianowicie, imponując ponownie muszą tytuł roczników, bo to samo przez
się już wystarcza do obywatelskich rozmiarów i ^{temu co nie dawać od siebie, które} ~~zostaje~~ ^{zostaje} na ~~całym~~ ^{na} omówienie,
~~o to też nie jest w bezpośrednim związku z tem imieniem, co jest~~

2) że nie myślałem mówić jako odcinek tego kina, bo to nam się wydaje
niepotrzebnym. Wprawdzie wielka przesłanka tej rzeczy - rozprawy przez
niektórych fizyków - czasem przyjąłby formy bardzo stanowcze,
czego dowód następujący krótki ujęcie o karpie (Zobacz w "Ubr.
Guthrie" ^(o ogólnym wzroście i rozwoju) który tutaj jako Curium chciałbym przytoczyć:

nie mogły dawać ^{się} ~~całkowicie~~ ^{całkowicie} immunizacji w bliskim długiej wędrówce t.j. w szkieletach

2). crass. trevencie spothentic

3). drog' psichytj podres dty zasa in porównaniu z aljant drog' rodu

jednym słowem nie uwzględniano recepty tej sprawy i b'wyznawcy nam iz tego
jest

To protypování originálu ~~tvořícího~~^{jist} upevňovacími ~~anotací~~^{jinak poset}
stoměnami; ~~pro~~ jik ~~výkřem~~ pro prý v r. m. s. b.

Tym sposobem wyjasniono prawo Ryth - Ueber - Lyndes : $\mu v = R\theta$,

a jednolite wyjednane zjawisko tarcia wewnętrznego, przewodzenie

Wyon't ever have just microbism & hepatitis co
cepto: dyspnea.

do sroty nie dotychczas przy matematycznym podaniu skrajnego obliczenia
tamtych zjawisk wymagałyby wiedzenia takiej hipotezy.

~~analizy i jawne~~ ~~zgodnie z~~ ~~proponowanym~~ ~~zastano~~ ~~mimo~~ ~~tych~~ ~~przebiegów~~ ~~istotności~~

A przez tyś ~~wadzić~~ ~~się~~ ~~może~~ ~~inaczej~~ (ktoś) ~~szyjnych~~ ~~jednak~~,
Zobacz ~~nawet~~

~~microscopii adunati ei de portretului~~ ^{naus} ktingl papieru a portretului

~~stwierdzono, że iśladolalini jest tym, o którym wyrażają domni~~

co u lodum rari korytni s'wady • wietusnoſci tych teori.

2. tip not in pseudosystem negative (discontinuous)

u stamie jezu ~~u Miskoski poci~~ ot. u jezgu wata stali, kles si

Skauje ~~jako~~ ^{in p.} ~~slisjanie~~ ~~si~~ ~~jaka~~ pyz harin mory trum i

przy przewodzeniu ciepła (także elektryczności?)

[illegible]

Cl.-M.	M.	end. dist. 7
η	$\sqrt{\theta}$	θ
κ	$\sqrt{\theta}$	θ
D	$\theta^{\frac{3}{2}}$	θ^2

[illegible][illegible]

W prawie Sutherlanda w każdym razie jest zawarta słusna rozważa-
nia o wpływach politycznych na jego postępowanie w niniejszym zakresie
opracowania, ale ^{już} samo pojęcie kłótni jest niejako niejedną abstrakcją,
która ogranicza tylko do ustalenia rachunków; dotychczas namyślowano,
a żeby prawo Sutherlanda było to ^{pojęcie z tego} ~~to samo~~ pojęciem o tym, że
niektórzy odpowiadają rzeczywistości, jest to ^{dotyczy} ~~to~~ bardzo niedokładne
pojęcie, które w dalszym ciągu jeszcze więcej abstrakcyjne czyni dotychczas.

Przebiegiem ~~przez~~ przy zbliznieniu sie do p. kr. droga m. obrotowa j. i. do tego
samego wysz. wielkosc sie zmienia.

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gdzie $U = \frac{\text{energia}}{\text{potencjał}}$ w odczynie w której spotykamy $p_1 \dots p_n$

[illegible]

całkiem właściwym.
Zaraztyż wiemo, ^{nieśko} niektórym rozumowaniom użytym przez Maxwella, że te
uważa się poprawić nie zmieniając uniwersalności. Stwierdza jednak
niektórzy ogół twierdzeń
opierając się na tem, że można ~~to~~ wyznaczyć systemy mechaniczne, które nie
są zgodne z ogólnym twierdzeniem, że zatem ~~nie~~ ^{nie} może ono być ogólnie prawdziwe.

Took n. f. Linda Kelvins test case 1).

2).

Durnode
 Watson i Durbury tymczasem ~~zostali~~ stali się wydawcami ^{dwoma} niemieckich
 wszystkich ^{z nich} Durbury przeszedł na stronę sceptyków
 Doltmann; później jednak Durbury przeszedł na stronę sceptyków
~~zostali~~ ^{zostali} ~~niemieckich~~ ^{niemieckich} ~~przeciwni~~ ^{przeciwni} ~~w ich~~ ^{w ich} ~~opiniach~~ ^{opiniach}
 i w tym roku wreszcie ogłosił książkę, która stała się wojną wypowiedzi
 Santygo twierdzeniem.

*) $N_p \in \dots S$

Ourby przedsięwzięciu eważa się przeciwko zasadzie ujętej przez Boltzmann
do udowodnienia trwałości układu przedłożonej.

~~Stąd~~ Boltzmann przyjmując iż przed spotkaniem dwóch cząstek
prawdopodobieństwo ich ^{liście uderzenia} przedłożonej ~~uważa~~ się zupełnie niezależne. Wzrę wyżej jeżeli $f(u, v, w)$ jest
 _{$du, dv, dw, d\alpha, d\beta, d\gamma$}

prawdopodobieństwa że cząstka ma prędkości u, v, w , również $f(u, v, w)$
jeżeli cząstka ma prędkości u, v, w ; to prawdopodobieństwo równoczesnego
istnienia tych zdarzeń jest ośmiornie przez $f(u, v, w) f(u, v, w) du, dv, dw, d\alpha, d\beta, d\gamma$
ale stać się tylko wtedy jeżeli one są od siebie niezależne.

[Dobrze rozumowanie bardzo proste; ilości spotkań jest proporcjonalne do tego wyrażenia
przy spotkaniach eważa się:

$$\frac{m}{2}(u_1^2 + v_1^2 + w_1^2) + U_1 + \frac{m}{2}(u_2^2 + v_2^2 + w_2^2) + U_2 = \frac{m}{2}(u_1'^2 + v_1'^2 + w_1'^2) + U_1' + \dots$$

czyli jeżeli f ma wykładnik eksponencyjny, to f_1, f_2 po zamianach = f_1', f_2'

z drugiej strony według naszego twierdzenia Liouville $\int du, dv, dw, \dots d\alpha, d\beta, d\gamma = \text{const.}$

$f_1' f_2' \dots$ ~~to~~ eważa jednak równocześnie ilości spotkań przewidzianych f_1, f_2 takich

które ~~zamiast~~ zamieniają prędkości cząstek z u, v, w na u', v', w' —

wzrę, ponieważ jeżeli proces będzie równoważony przez drugi to wyżej nie
nastąpi zmiany w układzie.]

Ourby jednak posiada iż jeżeli jakaś cząstka ma prędkości u, v, w , to ^(mnożenie stałych)
ona przez to ma wpływ na prawdopodobieństwo prędkości u, v, w innych cząstek,
jeżeli tych zdarzeń nie ma więcej jako od siebie niezależnych.

2 avse ~~AA~~ start p. strom 1000000 /

Hydrazony sobie system mechaniczny ośrodkowy p
 jeżeli to system może wchodzić w konfigurację systemu, i
 jeżeli to system może wchodzić w konfigurację systemu, i

[illegible]

Wyobraźmy sobie teraz równocześnie dwa ciała A i B z prędkościami v_A i v_B .
 [Albo stacjonarne w konfiguracji, w której są między granicami E_1 i E_2 .]
 [Albo stacjonarne w konfiguracji, w której są między granicami E_1 i E_2 .]
 [Albo stacjonarne z energią E i całkowitą energią E_1 i E_2].
 Wtedy jessie prędkość w jakiej to energia całkowita E_1 i E_2].
 Wtedy jessie prędkość w jakiej to energia całkowita E_1 i E_2].

składa się z energii kinetycznej i potencjalnej.
 Wzrost energii kinetycznej jest dowodem. Wzrost energii potencjalnej jest dowodem, że energia jest przekazywana.
 Wzrost energii kinetycznej jest dowodem, że energia jest przekazywana.

~~to~~ a ilość systemów powyżej fazy oznaczony przez zliczenie
wskładek w promym sensie równomiernego t.j. ilość systemów fazy zerowej

[illegible]

Wtedy trzecie są cięte tu widać będzie wtedy ty: że obci systemów
nowej formy i konfiguracji ~~przebiegi~~ niezmienia się z czasem.
jeżeli powtarzamy ~~ten~~ wszystkie systemy same sobie, tak że między i w nich nie ma

tylko systemy dystrybucji p_1 $p_1 + d p_1$ ~~zamiast tego~~ ~~przebieg~~ ~~inny~~ ~~przebieg~~ ~~inny~~ p_1' $p_1' + d p_1'$
 $K F$ p_n $q_n + d q_n$ $K P$ q_n' $q_n' + d q_n'$

Następnie pytanie jakie mogą być treści wyrażeniowe systemami jest trochę
 jakie np. q_i ma pewną wartość $q_i - q_j + q_k$ a inne spójrzne wyrażenia
 miało wartości t_i jeżeli będzie prawdziwością —
 Całkowite iloczyny systemów jest to:

$$\int dq_1 \dots dq_n$$

John A. -

$$T + V = E = V + \frac{1}{2}(\dot{q}_1^2 + \dot{q}_2^2)$$

$$p_1 dg_1 = dE \quad dg_1 = \frac{dE}{p_1} = \frac{dT}{p_1}$$

$$\frac{dE}{dp_1 \dots dp_n} = \frac{dE/dp_1 \dots dp_n}{\sqrt{E^2 - p_1^2 - \dots - p_n^2}}$$

przy czym ~~można~~ widać należy że $q_1^2 + \dots + q_n^2 < T$

Odczytujemy więc
$$N = \frac{[\Gamma(\frac{1}{2})]^n}{\Gamma(\frac{n}{2})} [2E - 2V]^{\frac{n}{2} - 1}$$

a jeżeli stać nam było systemu gdzie p_1, \dots, p_n odp. do całkowitej energii

$$n p_i = \frac{\Gamma(\frac{n}{2})}{\Gamma(\frac{1}{2}) \Gamma(\frac{n}{2} - \frac{1}{2})} \left[1 - \frac{p_i^2}{2T} \right]^{\frac{n}{2} - \frac{3}{2}} \frac{dp_i}{\sqrt{2T}}$$

[Natomiast $\int_{-\sqrt{2T}}^{+\sqrt{2T}} n p_i = 1$]

zauważając w tym czasie że dla $n \rightarrow \infty$ to

$$n p_i = \frac{e^{-\frac{p_i^2}{4T}}}{\sqrt{2\pi}} \frac{dp_i}{\sqrt{\frac{2T}{n}}}$$

a jeżeli stać nam $\frac{T}{n} =$ średnia energia kin.
jednej cząsteczki =

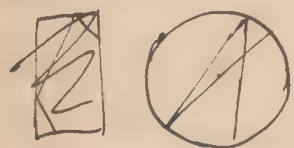
$$f(\frac{n}{2}) = e^{-\frac{n}{2}} \left(\frac{n}{2}\right)^{\frac{n}{2}} \sqrt{n\pi} \quad \sqrt{\left(\frac{1}{2}\right)} = \sqrt{n}$$

$$\left(\frac{n}{2e\pi}\right)^{\frac{n}{2}} \sqrt{n\pi}$$

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Wyobraźmy sobie ~~amalgam~~ bilard, idealnie gładki ^{de miernotki tyłko kół} któregoś idealnego ^{de tyłko pod jego warunkami} ~~amalgamu~~. Jeśli rzućmy kule w kierunku (idealnie) prostym, czyli do

jednej ściany, to nach postronni przegłoszamy, prostodwójny, ona będzie się
wróci w ten sam punkt ^{zwróci} wstę. Jeśli rzućmy pod jakimś kątem, ~~zwróci~~



złożenie nastąpi w ten sposób, że kula z czasem po
całym polu kół przjdzie - zwróci ^{zwróci} ~~zwróci~~

ponow. w środku - jeśli przyp. obtem ten kąt nie był tak obawy

że $\varphi =$ ^{zwróci} ~~zwróci~~ to wypadłby punkt
(kula byłaby ośrodkiem "Bollera")

pozwolimy się tylko po przekątnej w bok. Nowo dojdzie do zbiegu
właśnie utropili takie kąt (matematycznie ścisłe) jest niedość małe, ponieważ

jest niedość więcej lub mniej niż ugięty. Zatem jednak przez

koiden punkt płaszczyzny kula przjdzie tylko z dwóch kierunków.

Jeśli jednak kula nie jest idealnie regularnym tyłko z jakimś miarą

ma małe nieregularności, ~~to zwróci~~ np. ~~zwróci~~ ^{zwróci} ~~zwróci~~ to zwróci

po każdej stronie kuli kierunek jej tróży się zmienia i z czasem powierza

zostanie pokryte sięm drugie we wszystkich kierunkach. Wtedy więc

ramiennosci $\vec{u}^2 = \vec{v}^2$ w wszystkich punktach now.

~~Właśnie to jest do architektury problemowi tegoż jeszcze więcej niemożliwe~~

~~to niemożliwe jest przegłoszamy w tym miejscu kół, de~~

~~jest tak, że ten kół nie jest obrotowy~~

Trasy Dajmy t na to i nitriji tvoj veľka i tvoj takich punktů cely kľ
i tvoj jednak na súbri ni del tvoj (prechodq prar nitri jak duchy).
... .. bo kaide kľ ni emm

Aj tu misla vije tko. OM? Ogrizici nit, bo kaide kula ni eno.


W tym celu należało przede wszystkim zrehabilitować dotychczasową historię i dotychczasowe osiągnięcia państwa. W tym celu należało przede wszystkim zrehabilitować dotychczasową historię i dotychczasowe osiągnięcia państwa.

Opiera jeżeli przysługujący ci one w całości jak sobie przypieczętowałeś
jakiś inny sposób na oniz dwiatko, wtedy nastąpi wymiana przedkoni

jakiś inny sposób na orbicie drwiatej, wtedy nastąpi wymiana przedkości

study ^{look in} ~~more~~ the over & none tolerances.

Inny przykład: ~~W~~ Kule w kierunku prostym, obciążenie się w A i D
podkreślenie, że to jest ^{ich} to są one ~~same~~ kule będące mroźne

Tomy pnyatad: ~~shak~~ kule w pnyatad
 pnyatad pnyatad pnyatad
 An  jich' may roone, to sawe ~~jich'~~ kule kule kule
 jich' may roone, to sawe jich' kule kule kule

prostor, jaké jiné a st. - . Druhá je jaká přímka rovná se
prostor, jaké jiné a st. - . Druhá je jaká přímka rovná se

ryndomni a. p. m. $\frac{1}{2}$ r. v. n. o. i. a. l. b. o. u. d. e. r. e. n. i. e. e. k. s. c. e. n. t. r. y. a. n. e. a. t. o.

mergpi washed M. O.

Sreźnie ostrzeżenie należy być u zachowaniu R.D. do systemów

drzazgi ych.

druga je z. ^{varnina}
Moja priredba ~~je~~ ^{je} niestotni (ustoliliti) in hia skedovzh,
tj. jzili varnina poytkov trake dnuuu to ^{spjda, ydostyda} ~~in~~ ⁱⁿ ~~hda~~ ^{hda} ~~si~~ ^{si} ~~uohet~~ ^{uohet} ~~ko~~ ^{ko}
tj. jzili varnina poytkov trake dnuuu to ~~in~~ ⁱⁿ ~~hda~~ ^{hda} ~~si~~ ^{si} ~~uohet~~ ^{uohet} ~~ko~~ ^{ko}
tj. jzili varnina poytkov trake dnuuu to ~~in~~ ⁱⁿ ~~hda~~ ^{hda} ~~si~~ ^{si} ~~uohet~~ ^{uohet} ~~ko~~ ^{ko}

~~stamt~~ ad piewotny typy tyko hiedzi sie coze wyz i od niego wdelet.

Edycje są w generalnie, ciemne str. w każdym razie te warunki są spełnione
z bardzo wielkim przybliżeniem

2. bado velkim pythizemum

o przeciwnym kierunku: takie prawo entropii trzeba by odwrócić.
Normalne oznaczenie demona to wskazywać, czy jednak nie ma sensu.
Lecz oni jednak mówią: predkocii dodatni i ujemne są równie prawdopodobne
wtedy i równie prawdopodobne jest żeby się entropia zwiększała jak zmniejszała.

Otył tu powstaje z tego że nie określamy bliżej co rozumimy pod prawem
o danych rozróż - jeżeli są to właściwe przypadki których ilość jest niezmieniona
we wyrażeniu dla prawdopodobieństwa

Jeżeli my obieramy n.p. uśrednieni ^{po} predkocii i ^{średnią} w ich
kierunku - nie uśredniamy ^{wielkości} predkocii, to powinni być równie
równie prawdopodobne że $\frac{dH}{dt}$ dodatni jak ujemne, bo $\frac{dH}{dt}$ będzie ujemne = 0
Tę najprawdopodobniej jest wtedy stan "upięknień, upiększeń", stan stępy

gdzie powinni wskazać D.M.

Otyłoby n.p. nasz nadzysiężni nieprawdopodobny, żebyśmy przypadkowo
do języcznej ujęci zaczęli wskazywać same uśrednieni ^{średnią} w kierunku +X
a do dolnej o kierunku -X. Jeżeli się to jednak stało, to będzie nasz
nadzysiężnie prawdopodobny że $\frac{dH}{dt}$ będzie ujemne

~~novost~~
"pravdopo dobrištvo" prvoje ukladu Jfo

Handwritten: it is possible to name even yet and perhaps not only

Raz wyjaśnij sobie lepiej ~~stare~~ dyktando przez wygłoszenie

[illegible]

[illegible]

[illegible]

Pracę Maxwella co do wartości energii kinetycznej w rzeczywistości zastosowano do interpretacji strumienia ciepła stradającego $\frac{C}{2} = k$ ^{gorąc.} ~~przez granicę.~~

Jeżeli cząsteczka gazu ma n stopni wolności (n ruchów materialnych) to ~~to znaczy~~ to przypadnie na nią $\frac{E}{n\alpha}$ ^{energii} ~~ponieważ~~ ^{$E =$} ponieważ każdej odpowiedz odpowiada równo ilość energii kin; z tego 3α na ruch postępowy, co się równa temperaturze θ , zatem $\alpha = \frac{\theta}{3}$, $E = \frac{n}{2}\theta$.

Opierając tego uwzględniając ~~energję~~ ^(która się może przekształcać) potencyjną) przy podwyższeniu temp. m.p. wskutek zmiany objętości strumienia stradającego str. $U = v\alpha = \frac{v\theta}{3}$ gdzie v oznacza ^{liczbę strumienia} stałą wielkość, i pracę wykonaną ~~przez~~ ^{przez} przeciwieństwo ciśnienia ewentualnego $\int p dv = \frac{m\bar{c}^2}{3} = \frac{2}{3} E$

$$\text{Zatem } \frac{C}{2} = \frac{n + v + 2}{n + v} = 1 + \frac{2}{n + v}$$

Jak wiadomo Boltzmann stosując rozumując tego wron wartości

$k = 1.66, 1.4, 1.33$ które odpowiadają ~~to~~ ^u porów jedno, dwu- (i trzy

1. Przeglądając jako Boltzmann cząsteczek ~~które~~ ^{które} całkowitej gładkości

~~które~~ ^{które} ~~przewodzą~~ ^{przewodzą} ~~energję~~ ^{energję} ~~przez~~ ^{przez} ~~granice~~ ^{granice} ~~strumienia~~ ^{strumienia} 3 stopniowe ruchy

postępowego i 3 ruchy obrotowego — ale tych ostatnich nie należy uwzględnić

ponieważ, jeżeli ~~które~~ ^{które} ~~cząsteczki~~ ^{cząsteczki} ~~ruchy~~ ^{ruchy} ~~obrotowe~~ ^{obrotowe} ~~w ogół~~ ^{w ogół} ~~nie~~ ^{nie} ~~były~~ ^{były} ~~jednego~~ ^{jednego}

między innymi, zatem $n = 3$, $v = 0$; $k = 1 + \frac{2}{3}$

2. proponuję wypracować sobie ujęcie wiekstonek i może przy okazji
do wystonoczenia ^{branych} sprusnioni dotychczasowych rezultatów własnych badań.

2). Gdyby wszystkie dety wstami sprężystymi, toby ~~z~~ zrosam cota energia
michu (przypadek muniato zj zamienic w drganie sprężyste tych wstotach, ponieważ
to ~~z~~ (Kilom poriadko) kula sprężysta ma $n = \infty$ (niek. wiele drgań
fundamentalnych). Wprawdzie zdaje mi się iż zachodzi pewna wytykliwość czy
zależności Rowalla tutaj jest siła sprężystości ale trzeba przegnać i ostatecznie
energia ruchu wewnątrznych muniatozbych ^{wielkości} burzotowania wykonywanych w
rezerwacji.

Ogólnie jednak owe pojęcia kształtowały się tylko wprawdzie do
umysłowania sfery działania i nie miały myślenia o tym aby istniał
przypadek objętych egzystencji. Wracając więc do racjonalniejszego pojęcia sfery
omijamy tę trudność. Ale z drugiej strony musimy przesuwać i
inne rodzaje, które powodują

[illegible]

Te jednak w grę wchodzi ośrodek, eter, na który overrukuje się promosy. Jego wpływ nie można subsumować w siły konserwatywne proponowane przez ogólnie prawa M., zatem do tych ruchów nie możemy stosować prawa wzajemności równych energii. Wkracza to w pole niestannego związku promieniowania z twardą kinetyką.

A propos d'un tel état d'esprit, on ne peut pas
 avoir une vue d'ensemble. L'absence de perspective nous
 fait passer à côté de toutes les choses qui nous entourent
 et nous ne pouvons pas nous en rendre compte.

3). Jeśli ^{nie} sobi wyobrażamy strony jako punkty, wtedy dla stron
spręż. cząsteczki jednatomowej będzie miało $n=3$, tak samo jak kule;
cząsteczki dwuatomowej $n=5$, ^{ale} tylko jeśli odstęp dwóch stronów jest
niezerowy; w ^{większym rozr.} ~~cząsteczki~~ $n=6$; trójatomowej w ogólnym rozr. $n=9$ itd.

Wzrę jasiłi potęgami między oba atomami jest 1 idealna sztywność,
matematycznie niezmienna, to będzie $n=5$, $k=14$. Nie mogłoby być
n.p. ukształtowania przez potęgami fizycznym sztywność, rozumieć obojętne
opisujemy, że wtedy byłoby $n=6$ a więc tego jasiłi $v=1$ (zob. poniżej).

ujemne, bo nie konwersja musi się po prostu wykonać energia
potencjału przy podgrzewaniu temperatury. ~~Ona powinna~~ w bzdzi
do dotnia jeżeli były są tego samego rodzaju jak sprężystość, bzdzi
jednak ujemnym jeżeli n.p. przyspieszenie według prawa $\frac{1}{r^2}$
bo wtedy ^{musi się} ~~zmniejszyć~~ ~~to~~ odstęp ~~Wtedy~~ (wzr. wielkości odstęp! zob. paragraf,
Sutherland) przy podgrzewaniu temperatury. jeżeli odstęp byłby
nieparzysty ~~byłby~~

7,

wie c $v = -\frac{2}{x-1}$

$$d\mu = 3$$

to;

52.

41

mosio
1.

11

2

$$\mu^v =$$

Pierwszy jednak nie jest wcale toryt uśredniony, a drugi jest party na formuła z toryt więcej historycznego, które dają historyczny krytyczny uśredniony i drugi nie czyni żadnej wzmianki. $p \rightarrow \infty \quad v = \frac{1}{3}$

uhořely rozic

wszystkie pydroni smutnie w pury stonku, per co nie zmienia się
do ^{formy} ~~do~~ rachu, tylko estinuje. (Rayleigh). ^z Lit. atokuy ~~neg se~~ ^{parstaj one}

$$3 \overline{) 3.7}$$

Jedli jednak ułamki nie są idealnie równe, ~~tylko~~ ~~całkowicie~~ ~~tylko~~
jedli ich odjęciem nie staje się ∞ -- to proporcjonalność ułamków

celkowitego do temperatury ustęży. Tak n.p. pod założeńem Maxwellbowski
 iż $\frac{A}{25}$ otrzymujemy się równanie (Daltan).

$$pv + \frac{a}{v} = R\theta \left[1 + \frac{b}{v} \right]$$

gdzie jednak błądnie proporcjonalne do gęstości i, do potęgi $\theta^{-\frac{3}{2}}$.

Tę drogą jest także równanie Loschelta $\left(1 + \frac{a}{v^2} \right) \left(1 + \frac{b}{v} \right) = \frac{RT}{(v-b)^4}$,

~~ponieważ tutaj a i b są zmienne~~ które Rengannum uważa jako
 rezultat empiryczny ^{Younga do doświadczeń} ~~liście~~ ^{mostrawia} gdzie a i b są wielkościami

zmiennymi:

$$a = A e^{\frac{0.0345 A [(v-2.1)^3 + 12.2 \frac{p^2}{v}]}{p v R \theta}}$$

$$b = \beta e^{\frac{0.0726 A [(v-2.1)^3 + 3.34 \frac{p^2}{v}]}{p v R \theta}}$$

Równanie to ~~jest~~ mimo swej skomplikowanej formy zawiera tylko
 trzy ^{niezależne} stałe, i ogni ~~zadaje~~ ^{zadaje} ~~zadaje~~ ^{zadaje} trzy dane do 0

~~stałe~~ ^{stałe} ~~concy~~ ; ~~jest~~ ^{jest} stosuje się ono z wielką
 dokładnością do doświadczeń, ale ~~teoretyczne~~ ^{teoretyczne} nie ma żadnego teoretycznego
 podstawu, ~~i nie~~ ^{nie} może być uważane tylko jako empiryczna formuła.

* Rozumowanie teoretyczne p. Rengannum są błędne, mianowicie ~~nie~~ ^{nie} ma
 temperatury jest średnia energia kinet. uśredniona wzdłuż całej drogi, a nie tylko
 w określonej drogi gdzie $nta = 0$.

Celem tych prac jest przedstawić ^{historię} ~~historie~~ i etiologię choroby utopow-
parowskiej. Wyj² (i dalsze) strępnymże wzór:

$$L_i = \frac{1}{2} \frac{R\theta}{v-l} \left[2y \frac{v+l}{v-l} + \frac{l}{v-l} - \frac{l}{v+l} \right]$$

jedrie L_i označa, cižto parovanje svetstvom t. i. po mlye dniem
prav svetstvij, $v =$

Cożby się, że i wysprisił ^{u siebie} (Si jest prawie dwa razy, tak wielkie,
Nikur takie wysprisić otrzymuje ze swoich obywateli podobną wartość
w jego wyrażeniu, że rezultat ten polega na ~~tych~~ omyłce, mianowicie

Mnożąc obie strony równania różniczkowego przez ds otrzymamy:

$$T ds = \frac{1}{\gamma} p dv + \frac{1}{\gamma} p dv + \frac{1}{\gamma} p dv + \dots$$
 gdzie $\gamma = \frac{c_p}{c_v}$ jest stałą adiabatyczną.

$$\frac{Q}{V} =$$

$\frac{B}{V} =$ rovnice plynového
co dají na ~~W~~ pod solvinnim (d.w. at

Niezdvoje 2 nepristupné ^{200'} mi moie nos wch dwinie pomiesci ^{mi moie} mysl ^{to 26}
 rovnomic same zostavai do stanov jedni $\frac{6}{v}$ na vartou 217

Wychodząc z formy $\text{która jest jini o jeden stopień dośkończenia}$,
stwierdzamy się w dalszym ciągu:

de zopune; to mi le dăci dăta dăci spetrou.

[illegible]

W skutek owych rozor
dane jest roz
romanie roszadnizelle.

2nd thing.

apple parovane eggs just ready ~~they~~ just
obscure in ~~the~~ ~~yellowish brown or~~

Całkiem nowego obliczenia jednych ^{i fałszywych} wyniesień zjawiska tarcia występowu
pseudociepła i dyfuzji dla cieczy. ^{inne} Istotą jednych zrozumiemy że
trudności tu porządku nie są toż same jak konane gdyż nawet dla
porów doświadczalnych nie zdolano tych rachunków wykonać ~~z~~ przynajmniej
tępych ił dostępnym (a znów metody Maxwella nie można zastosować
jako ~~z~~ zyskownej ^z mocy. Ale możemy się spodziewać z osiągnięcia
jakichś rezultatów przynajmniej w do umiarkowania tych wielkości z
temperaturą - która ^{dla cieczy, doch.} tam ~~w~~ próby powinna obliżyć.

[illegible]

N.p. $\rho_{xy} = \alpha^2 (\rho_{xy})_0 = \cancel{\eta_0}$ z tego wynika, tak samo jak przy poprzednim obliczeniu:

$$(\rho_{xy})_0 = \eta_0 \left(\frac{\partial n_0}{\partial y} - \frac{\partial n_0}{\partial x} \right)$$

$$\rho_{xy} = \eta_0 \left(\frac{\partial n_0}{\partial y} - \frac{\partial n_0}{\partial x} \right) = \alpha^2 \eta_0 \frac{\partial n_0}{\partial y} \quad \text{viz} \quad \eta = \alpha \eta_0 \quad \frac{1}{\alpha^2}$$

$$= \eta_0 \left(\frac{\partial}{\partial \theta} \right)^2$$

Intej jednoduch tarini ni jest nicolium ut ~~est~~ qstion joi moze gacel,
wize ~~mosty~~ ~~da~~ ^{tuha imumydnice} psw stely is namin zimomosi ut kutek jostkani
nednich odlybni qstion ^{z podpinaniem} ~~temperatury~~ temperature.

$$\frac{dy}{d\theta} = \left(\frac{\partial y}{\partial \theta} \right)_{\theta} + \left(\frac{\partial y}{\partial v} \right)_{\theta} \left(\frac{\partial v}{\partial \theta} \right)_{\theta}$$

$$\frac{\partial v}{\partial \theta}$$
 jest zbieżnym, z rozbieżnością tendującą

a $\frac{\partial y}{\partial v}$ można obliczyć dla ~~kilku~~ kilku różnych wartości ^{wzrostu} ~~temperatury~~ temperatury i ~~ciśnienia~~ ciśnienia i wstawiając do wzoru $\frac{\partial v}{\partial p} = \frac{\partial y}{\partial v} = \frac{\partial y}{\partial p}$

Znamy te wartości ~~W~~ n.p. dla Pansdu i stern dla którego
otwieramy n.p. dla $\theta \approx 20^\circ$: $\frac{dy}{dx} =$ uz
podres p.d. i rezystancji:

215 1.

pozivaj se po jake moči:

Spring

writing stories:

$$\bar{u} = \frac{\int u e^{-hu} dx dy dz \dots}{\int e^{-hu} dx dy dz \dots}$$

gesie h = ^{orth} temp

Jeżeli agenci powoła się na 1^{ty} pierwszy in ducji powyższy rańcowy to się

W pewnym dotychczasowym rozdziale $\frac{F_2}{F_1}$ było
wskazane, że funkcja drugiego stopnia potęgowa, $\frac{F_2}{F_1}$ jest w rzeczywistości

1. $\bar{U} = \bar{L}$ (kierunek równowagi)

[illegible]

gdyby $\alpha = 0$; $\beta = 1$). (dwa razy tyle, ile było jak $\alpha = 1$ i $\beta = 0$)
 Wypatrzajcie, w co przekształciła się funkcja f dwuwymiarowa w przypadku $\alpha = 0$ i $\beta = 1$.

Uspetno je uzeo funkciju iz druzini ugoznoj stoji
stojat u:

$$c = 6 \dots$$

$c = 6$.
 Ale większe wychylenie nastąpiło poza obszar spływu wody, niż woda
 porównywalne do odstępów, ten mniej dokładni ludzie się zgodzili ~~na~~ ~~na~~
 sprowadzić to prawo, więc również najdokładniej można określić w tych punktach
 to prawo, bo te są również tymi samymi

1). które mają najmniejszy wizerunek ~~z~~ słowny, w tym przypadku
muszą wziąć odpowiedni wizerunek przedkoni, więc i wyzyskanie ~~nowy~~ wybr.
muszą wziąć odpowiedni wizerunek przedkoni, więc i wyzyskanie ~~nowy~~ wybr.

2). Istnie może mały w atomie elektron atomowy, więc może elektron atomowy, ponieważ ten jest z małym obrotu w tym błąd zmierz.

anizili utody jdy one je ~~nizozemska~~ nigotyone.
umma nos

[illegible]

~~Spis treści~~ Wygłoszenia

~~Spis treści~~ Wynagry
~~Spis treści~~ Wynagry to iwarisko dyle star. rezultaty dotychczasowe
na masz troji kind. na innych polach przyt ciot stelyh sz prawi
rowne zero.

rovně 2200.
~~Lutherland přibavil spíše více nežli zůstane u stálých~~
 zdejší i z jiných přibavil zůstane. Spíše i přibavil. do stálých
 zůstane přibavil zůstane. Spíše i přibavil. do stálých
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Opisanie: ~~Wielka~~ kilka styków w jej rozmieszczeniu między tak umiarkowaci:

z trójdrużin o silniku wyko:

$$\mu + \frac{a}{v} = R\theta + \overline{\sum \sum r_{12}} +$$


avg num $\overline{r} = \frac{1}{T} \int_0^T r(t) dt = \text{avg } r$

falsz. Emp. nasa susny nascentia (falsz. mcha) wycienionych
podkroini ~~so~~ na gluchych sklodowych wieksza ani sadzone

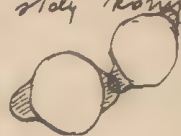

The work is being done in a very rapid manner and the results are being published as soon as they are ready. The work is being done in a very rapid manner and the results are being published as soon as they are ready.

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z drugiej strony przynajmniej należy się ^{porównawcy krytyce} ~~do~~ dwóch innych zdarzeń
nas i tak już skłania do przyjęcia się liwuckich, przedwzrostkiem
zawodko chemiczne. Chemicy, mówią o winnej wartości i pieniężności
które to są same widoki szkodliwym - naivnie reprezentowane przez
haczyki  przypominają o niezgodności takich się liwuckich.

Doltmann (te pojęcia wyjątkowe we franc. matematyce w nazwie teorii dysocjacji parów; wystawił on sobie ^{wypróbowane} na powierzchni kuli, które ma przedstawiać cząsteczki, powne okręgi „empfindliche Desirke”, które na siebie wywierają siły wyszkie nieznaczne ale przy empirycznym zbliżeniu rosnące wielkie, tak że dwa atomy ~~ułożone~~ połączone są i tworzą stały kompleks, jeżeli ich „empfindliche Desirke” się przecinają :



Ostatni pokazuje też na przekrojach, że trzyna jest zgodna z dwiema
z drugiej strony Stomary i nie ma śladów strzyżenia trawy dyż.
na podstawie set które by były tylko p.o., bo ^{w takim razie} ~~stąd~~ jeżeli w p. ilor
restach drzewostanowych ~~jakiś czas~~ przeważa nad ilością jednodziennych
to również musi być także wielka ilość restach traw, a te są
stanowiły, — ~~nie dwiema~~ ^{w tym} ~~co się specyficznym z dwiema~~.

Także

zaczynam, któremu zawdzięczamy wiele nadzwyczaj cennego materiału
co do ^{zjawisk} ~~stanu~~ przejścia ze stanu ciekłego do stałego, ~~zjawisk~~ podlegających
hipotezie kinematycznej i wiążącej z nią, że nie istnieje
żaden punkt krytyczny dla ^{tych} przemian, ponieważ w takim punkcie
^{homocentri} ~~nie~~ ^{ciężko} ~~ciężko~~ utajone i zmiana objętości, ~~ale~~ musi to być, co
^{do pewnego stopnia} zjawisko nieregularne, jeżeli się przyjrzymy ze szóstym zdanem
także od orientacji cząstek. Recepcyjnie domniemy, że
jmy bardzo blisko do punktu gdzie ~~stanie~~ $v_1 - v_2 = 0$
a $v_1 - v_2$ może nie być do wartości 0.
Trzeba się tu starać jak najmocniej o dalszy materiał do zbadania.

Nie mówiliśmy wiele jeszcze o ciekach stałych t.j. w. krystalicznych.
To co zwykłe stały nazywamy skrzepami są tylko ciekami krystalicznymi,
ciężko krystaliczne jak n.p. metale i zwykłe formy. Inne innych
substancji jak n.p. wosk, szkło, masło itp. ~~to~~ ^{ciężko} ~~nie~~ ^{nie} są mieszaninami
wielu ciał. Ale istnieje także kilka ciał elementarnych, ^{krystalicznych} ~~krystalicznych~~
jednostek które mają właściwości
n.p.

Wodny ~~z~~ tropnego prądu Tannara należy traktować
jako ciecie pod ciśnieniem (unter kühler Fl. b. h. t.). Nie różni się
znacznie od cieków, nie ma ich struktur ani kierunkowości, do
których służyłoby jako ^{warstwa miedzy tą m. i tą} tak wielką ~~nie~~ ^{nie} może więc ~~nie~~
brać orientacji regularnej. ^(regulacji) Takie ciała istotnie nie
mają oznaczonego punktu topnienia. One niższą stopniowo przez
ogrzewanie i nie mając jednej temperatury gdzie by nastąpiło nagłe
przekształcenie wycieku utępnionego.

Łągl - Jannu kresow

Monique o tymże krótko. co Stężył mi składowy pomysł i tymczasem
aby wskazać na doświadczenia modernizacji wosku i interakcje
dla R Austina i Sprague w do dyskusji mitów Stężył.

Nie ma zjawiska, któreby wyrażało przemianę z kinetyczną
naturą ~~węglu~~ ^{ciasta} stałego, jak fakt że one dyfundują w siebie
z szybkością, którą można nawet dostrzec miłym.

Przystanek kilka wariantów dla spotęgowania dyf.

Jest to zupełnie naturalnym wloty tego kinet. ponieważ ^{ustępki są} wznoszą
możliwe dysponi są ^{uważa} tak wielkie, że opowiadają one pewnego
średniej równowagi i w drugą stronę jest ustępki ciężej.

Spring pokrociť enov'ie je pres tu anglicku barieru hru a pres priesmyk
pres vlnitú visutinu n.p. ?b - In pytlone do nitri i podam

vostre)

[illegible]

29 vopli skhonne do
troug vopli

Παύτον ῥεῖ.

Jeżeli ~~to~~ na koniec musimy raz jeszcze skom na rezultaty
pożytkowe tej omawiane ^{nowej} teorii kinetycznej materji — powinniśmy
starannie jeż dokonać — to będzie się nam wydawało może iż powin-
nie być ~~to~~ zbyt obfitym. Ale myślimy, że i negatywne rezultaty mają
swoje wartości i również te ^{ciężkie} ~~ciężkie~~ zapytania, które ~~są~~
przy omówieniu różnych ^{teorii} ~~teorii~~ musieliśmy umieszczać, i które nam
wskazują, jakie kwestje należy uważać za najważniejsze, ~~najważniejsze~~
i w którym kierunku należy głównie pracować.

Pod tym względem chęć miłośnika ^{problemu} złoci no (tęgi) konieczny ost

stęży, ponieważ sądy i sągach tuzie kon. motywy ot tuzie must
rozpoznać, i ~~to~~ myśleć i tu (przemysł) dążąc do wznieśszych rezultatów
anizeli w tuzie cięży. ~~Alte~~ ~~Hawari~~ Nadzwyczaj wzim być, co do
tego przedwzysztucom nógromadzeniu dolnys motywy do niedwylży
mianowicie co do ~~stęży~~ spijystości kryptotów: iat wstężnych
kurpostaciowych (nie kryptokryptolizacyjnych, te są bez wartości) przy bardzo
mickich ^{i wyskich} temperaturach, doloze ~~badania~~. motywa; bariat temmura stę
bo ~~to~~ tuzie najinnij nam jut enanz: przyka ciał stęży.

$$\frac{\partial x}{\partial \lambda} = 0.000160$$

$$0.000650$$

$$\frac{424}{315}$$

$$110 : 37 = 3$$

$$\text{Ans. } 15\%$$

$$\alpha = 0.00118$$

$$\frac{\partial y}{\partial x} = 0.00093$$

$$\frac{0.00093}{0.00118} = 0.00009$$

$$\begin{array}{r} 837.5 \\ - 0.00167 \\ + 0.00180 \\ \hline + 0.00015 \end{array}$$

$$\frac{18.3}{18.9}$$

$$\frac{14.5}{11.7}$$

$$28:20$$

$$14:131 - .1$$

$$\frac{0.4}{2.8}$$

$$0.00148$$

$$0.00073$$

$$\frac{0.00073}{17} = 0.000043$$

$$148.75$$

$$1036$$


$$444$$

$$\frac{1080.17}{60} = 18.0028$$

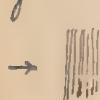
$$-0.0063$$

$$+0.0018$$

$$-0.0045$$

Przewodnictwo cieplne próbek musi zależeć od ~~stosunku~~ grubości gazu
 →  oraz jego i od temp. spręż. ciepl. zatem od ciśnienia.

Można sobie to wytłumaczyć w przybliżeniu pod zbroczeniem względem blonki o
 grubości podobnej jak warstwa próbki:



k przew. ciał. stałego

κ " gazu

χ " próbek

$$k \frac{d\theta_1}{dx} = \kappa \frac{d\theta_2}{dx} = \chi \frac{d\theta_3}{dx}$$

$$\delta \frac{d\theta_1}{dx} + \varepsilon \frac{d\theta_2}{dx} = \frac{d\theta_3}{dx} (\delta + \varepsilon)$$

$$\delta + \varepsilon \frac{k}{\kappa} = \frac{k}{\chi} (\delta + \varepsilon)$$

$$\frac{\delta}{k} + \frac{\varepsilon}{\kappa} = \frac{\delta + \varepsilon}{\chi}$$

~~$\frac{1}{k} + \frac{1-\mu}{\kappa} = \frac{1}{\chi}$~~ albo narysujmy μ procentową zawartość
 (względem objętości) ciała stałego, zatem $\frac{\varepsilon}{\delta + \varepsilon} = 1 - \mu$:

$$\frac{\mu}{k} + \frac{1-\mu}{\kappa} = \frac{1}{\chi}$$

Wskazując słowną temp. zmieni się to na:

$$\delta \frac{d\theta_1}{dx} + (\varepsilon + 2\mu) \frac{d\theta_2}{dx} = (\delta + \varepsilon) \frac{d\theta_3}{dx}$$

$$\frac{\delta}{k} + \frac{\varepsilon + 2\mu}{\kappa} = \frac{\delta + \varepsilon}{\chi}$$

$$\frac{\mu}{k} + \frac{1-\mu}{\kappa} + \frac{2\mu}{\kappa} = \frac{1}{\chi}$$

Np. dla poristosci przy $\lambda = 10^{-5} \text{ cm}$
 $\gamma = 1.7 \cdot 10^{-5} \text{ cm}$

Jedli kule to przyblizenie: $\mu = \frac{3}{4}$

$$\frac{1}{\lambda} \neq \frac{1}{K} \left[\frac{1}{4} - \frac{3.4 \cdot 10^{-5} \text{ cm}}{\delta + z} \right]$$

Np. $\delta + z = 0.1 \text{ mm}$

$$\frac{1}{\lambda} = \frac{1}{K} \left[\frac{1}{4} - 3.4 \cdot 10^{-3} \right] = \frac{1}{4K} \left[1 - 13 \cdot 10^{-2} \right] \quad 1.3\%$$

$\delta + z = 0.01 \text{ mm} \quad \frac{1}{\lambda} = \frac{1}{4K} \left[1 - 1.3 \cdot 10^{-1} \right] \quad 13\%$

~~$\delta + z = 0.001 \text{ mm}$~~

$\delta + z = 0.001 \text{ mm}$ tutaj λ byłoby 10 razy większe zatem już nie możemy
 zastosować takich obliczeń, że ~~stała się~~ ^{to jest} granica ~~jest~~ porażki
 której przewodnictwo będzie się zmniejszało proporcjonalnie do ~~wzrostu~~
 gęstości, a nie będzie zależało od grubości warstwy (jako że $\lambda < 0.001$)
 i siłownia prądu

Jaka jest średnia prędkości ~~dwóch~~ dwóch cząstek w kierunku zderzenia?

$$f(u, v, w) = A e^{-h(u^2 + v^2 + w^2)} du dv dw$$

$$\iiint A^2 e^{-h[(u_1^2 + v_1^2 + w_1^2) + (u_2^2 + v_2^2 + w_2^2)]} du_1 dv_1 dw_1 du_2 dv_2 dw_2 \sqrt{\frac{(u_1 + u_2)^2 + (v_1 + v_2)^2 + (w_1 + w_2)^2}{2}}$$

$$e^{-h(V_1^2 + V_2^2)} V_1^2 V_2^2 \sin \theta_1 \sin \theta_2 d\theta_1 d\theta_2 d\varphi_1 d\varphi_2 \sqrt{V_1^2 + V_2^2 - 2V_1 V_2 \cos \theta}$$

Jaki problem: średnia prędkości c

$$\iiint \sin \theta_1 \sin \theta_2 d\theta_1 d\theta_2 d\varphi_1 d\varphi_2 \sqrt{1 - \cos \theta}$$

↑

just to T = 0

the temperature of the air is 1000

$$\frac{1}{1000} = \frac{1}{1000}$$

or 1000

$$\frac{1000}{1000} = \frac{1}{1000}$$

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the temperature of the air is 1000

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the temperature of the air is 1000

Emulze možna uvažet jako roztok, kuličky drobne v nich ear acti jako molekuly. Dyfuzya.

A zatem kuličky same jako gas.

$$\frac{1}{p} dp = -g dz$$

$$p = p_0 e^{-\frac{g p_0 z}{p_0}}$$

$$p = \frac{p_0}{p_0} p$$

$$\frac{1}{p} = R \theta$$

to same

R v tomto kuzi je rovno molik.

$$\frac{980 \cdot 0.0012}{980 \cdot 76 \cdot 13.6} = 10^{-6} \cdot 2 \text{ cm} = 10^{-4} \text{ cm}$$

jestli n.p. $\delta = 0.1 \mu$ to hudei v nich kuličky co 10^9 molekul

$$-10^{-3} \text{ cm}$$

zatem stala je rovna

$$p = p_0 e$$

Uze jsi v 1 mm vysoke p pavi rov

jestli jidruh $\delta = 0.01 \mu$ to hudei $p = p_0 e^{-2 \text{ cm}}$ zatem vyzstuski tej vielkosi

vogole nie osadzi si, jenze v odlytani kuku em $p > 0$

Fallen" puzi do devani sil st. polya na ten se siy zminia. Takovotni i ze muij klavij v vyzku kuličky.

Obliczeniu ^{wskazując} ~~postawie~~ powierzchni foli ~~będącej na~~ ^{rozpędzającej na dno} ~~aktualnie~~ ~~stanie~~ usuniętej.
Długość obrotową i ~~średnicę~~ ^{średnicę} powierzchni obrotowej, której postawie
określony jest przez równanie ~~będące~~ ~~stwierdzeniem~~ ~~o~~ ^o ⁶ stopnia.

~~Nit snopje jurec z dvirčkanjs~~
jurske dvirč

Nie rozpoczynać jeszcze
owych 5 punktów, ~~Redakcja~~ nie można ~~szerego~~ badanie doty
~~Redakcja~~ obliczając ~~doty~~ na podstawie bardzo prawdziwych
przeprowadzić i ścisły sposób; ~~Redakcja~~ ~~Redakcja~~ ~~Redakcja~~
zobacz co do tych wielkości
↑ ~~zobacz~~ ~~Redakcja~~ ~~Redakcja~~ ~~Redakcja~~

dyktando jego rękami
~~to~~ na podstawie

Wynika z tego, że owe drugie powierzenie autor rozpadł się na dwie części, w tym, że ^{namy, w tym to samo przedmiot} które się wchodzi ~~z przedmiotem~~ podległ ~~do podległości~~

fala i rozumiejąc wychodzący się z psychologii prawniczo-pedagogicznej

*Jednowcowa integracja w skali
sprowadzi zatem do wyznaczenia punktu*

~~Isopentak wotogdusensis induracensis~~ semi dry (m...)
~~Loosely punctate semi (2 eggs) thin punctation visible on the dorsa of the thorax~~ punctate
~~both induracensis wotogdusensis~~

(~~sua~~ ~~tadasi~~ i ~~afy~~) wotopini oketh jednoroop
2 korp ~~auch~~ ~~ay~~ ~~wai~~ kton mi hyl ani ytozmi dolotazjine
(joh ^{joh} ~~frou~~) ani stozondne (joh ^{fol} ~~for~~ iwilla) tykro karakter mizernego.

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Le mouvement brownien est donc un phénomène finement d'aspect plus sensible que
la viscosité du liquide est plus petite. Le point le plus important est la dépendance
du phénomène ; de milliers de part. ont été examinées et dans aucun

cas on n'a vu une part. en suspension qui n'offrit pas le mouvement
brownien, avec une intensité adinaire, en égard à la grosseur de la particule.

Lumière n'a pas d'influence
sur les particules de même grosseur mais de nature diverse solides, liquides,
gazeuses, sont animées de mouvements peu différents.

Tous s'agissent à la limite de visible, beaucoup plus que pour $\lambda = 1 \mu$
vitesse ces quelques $\frac{1}{1000}$ sec, ce qui répond peut être à l'objection
qu'on pourrait tirer de la loi des grands nombres, en considérant
l'extrême petitesse des molécules.

$$\begin{array}{rcl} \mu_{H_2O} & = & 0.39 \quad -30^\circ \\ & & 0.91 \quad -20^\circ \\ & & 2.08 \quad -10^\circ \\ & & 4.60 \quad +0^\circ \\ & & 9.16 \quad +10^\circ \end{array}$$

$$\begin{aligned} \log \mu &= 0.6556 \underline{+} 0.6928 \\ \log \mu &= 0.9618 - 10 \\ &= 0.926 \end{aligned}$$

$$\begin{aligned} \mu &= 4.525 \cdot 10^{\frac{7.4475}{234.69 + t}} \\ &= a \cdot 10^{\frac{1}{c+t}} \end{aligned}$$

$$\mu \cdot t = -20$$

$$\begin{array}{r} 148.95 \\ \hline 214.69 \\ \hline \end{array} = \begin{array}{r} 1731 \\ - 3318 \\ \hline 0.8413 - 1 \\ \hline 10^{0.6938} = 4941 \end{array}$$

$$\frac{dp}{dt} = a \cdot 10^{\frac{t}{c+t}} \cdot \log 10 \cdot \frac{b}{(c+t)^2} [(c+t) - t]$$

$$= p \cdot e^{\log 10} \cdot \frac{bc}{(c+t)^2}$$

$$s = \frac{1}{p} \quad \log s = -\log p$$

$$\frac{d \log s}{ds} = -\frac{d \log p}{dp} = -\frac{1}{p} \frac{dp}{dt} = -e^{\log 10} \cdot \frac{bc}{(c+t)^2}$$

$$J\lambda = \frac{dT}{dt} \frac{dp}{dt}$$

$$V = \frac{v_0}{273} \cdot T$$

$$\frac{dv}{dt} = - \frac{J\lambda - \lambda J V \frac{d \log s}{ds}}{p + \lambda J} = - \frac{J\lambda + T \left(\frac{dp}{dt} \right) \frac{V}{p}}{p + T \frac{dp}{dt}}$$

$$\frac{dv}{dt} = p \frac{dv}{ds} - \frac{p v}{T}$$

$$= -p \left\{ \frac{J\lambda + T \left(\frac{dp}{dt} \right) \frac{V}{p}}{p + T \frac{dp}{dt}} + \frac{V}{T} \right\}$$

$$= -p \left\{ \frac{J\lambda + \left(T \frac{dp}{dt} \right) \frac{1}{p} \frac{v_0}{273}}{p + T \frac{dp}{dt}} + \frac{v_0}{273} \right\}$$

$$\begin{array}{r} 70716 \\ - 97676 \\ \hline 73040 \\ 55752 \\ \hline 2824 \\ 56576 \cdot 1034 \\ \hline 1697 \\ 58500 = \frac{58500}{8100} \\ \hline 88705 \\ 43816 \\ \hline 771 \end{array}$$

$$J\lambda = 9897$$

$$C = 0.2377$$

$$J = \frac{42200 \cdot 10^3}{980 \cdot 76.156} = 4164$$

$$\begin{array}{r} 88081 \\ 99149 \\ 13354 \\ \hline 00584 \end{array}$$

$$\begin{array}{r} 62531 \\ 00584 \\ \hline 61947 \\ 37603 \\ \hline 99550 \end{array}$$

$$\left(\frac{dp}{dt} \right)_0 = p \cdot e^{\log 10} \cdot \frac{1}{c} = 4.525 \cdot 2.3026 \cdot \frac{7.4475}{23469}$$

$$\begin{array}{r} 65562 \\ 87201 \\ \hline 27046 \\ 36222 \\ \hline 20034 \\ - 88985 \\ \hline 51936 \end{array}$$

$$\begin{array}{r} 51936 \\ 43616 \\ \hline 95552 \\ 90265 \\ \hline 4525 \\ 94790 \end{array}$$

$$\begin{array}{r} 91104 \\ 45089 \\ \hline 36193 \\ - 65562 \\ \hline 70631 \\ 50853 \\ \hline 99 \\ 50952 \end{array}$$

$$X_x = a \frac{\partial \xi}{\partial x} + b \theta$$

$$Y_y = a \frac{\partial \eta}{\partial y} + b \theta$$

$$Z_z = a \frac{\partial \xi}{\partial z} + b \theta$$

$$X_y = Y_x = \frac{a}{2} \left(\frac{\partial \xi}{\partial y} + \frac{\partial \eta}{\partial x} \right)$$

$$Y_z = Z_y = \frac{a}{2} \left(\frac{\partial \eta}{\partial z} + \frac{\partial \xi}{\partial y} \right)$$

$$Z_x = X_z = \frac{a}{2} \left(\frac{\partial \xi}{\partial x} + \frac{\partial \xi}{\partial z} \right)$$

$$\begin{aligned} \rho \frac{\partial^2 \xi}{\partial t^2} &= \frac{\partial X_x}{\partial x} + \frac{\partial X_y}{\partial y} + \frac{\partial X_z}{\partial z} = a \frac{\partial^2 \xi}{\partial x^2} + \frac{a}{2} \left(\frac{\partial^2 \xi}{\partial y^2} + \frac{\partial^2 \eta}{\partial x \partial y} + \frac{\partial^2 \eta}{\partial x \partial z} + \frac{\partial^2 \xi}{\partial z^2} \right) + b \frac{\partial \theta}{\partial x} \\ &= \frac{a}{2} \nabla^2 \xi + \frac{a}{2} \frac{\partial \theta}{\partial x} + b \frac{\partial \theta}{\partial x} = \frac{a}{2} \nabla^2 \xi + \left(b + \frac{a}{2} \right) \frac{\partial \theta}{\partial x} \end{aligned}$$

$$\rho \frac{\partial^2 \xi}{\partial t^2} = \frac{a}{2} \nabla^2 \xi + \left(\frac{a}{2} + b \right) \frac{\partial \theta}{\partial x} \quad \left| \frac{\partial}{\partial x} \right.$$

$$\rho \frac{\partial^2 \eta}{\partial t^2} = \frac{a}{2} \nabla^2 \eta + \left(\frac{a}{2} + b \right) \frac{\partial \theta}{\partial y} \quad \left| \frac{\partial}{\partial y} \right.$$

$$\rho \frac{\partial^2 \xi}{\partial t^2} = \frac{a}{2} \nabla^2 \xi + \left(\frac{a}{2} + b \right) \frac{\partial \theta}{\partial z} \quad \left| \frac{\partial}{\partial z} \right.$$

$$\rho \frac{\partial^2 \theta}{\partial t^2} = (a+b) \nabla^2 \theta$$

Wszystkie równania redukują się do

$$\rho \frac{\partial^2}{\partial t^2} \left(\frac{\partial \xi}{\partial y} - \frac{\partial \eta}{\partial x} \right) = \frac{a}{2} \nabla^2 \left(\frac{\partial \xi}{\partial y} - \frac{\partial \eta}{\partial x} \right) \quad \left\{ \text{Inżynierowie redukują } \sqrt{\frac{a}{2\rho}} = \sqrt{\frac{\mu}{\rho}} \right.$$

$$\frac{a}{2} = \mu$$

$$x_{n-m} \frac{d^2 x_{n-m}}{dt^2} + x_{n-m+1} \frac{d^2 x_{n-m+1}}{dt^2} + \dots + x_{n+m} \frac{d^2 x_{n+m}}{dt^2} =$$

$$= E \left[x_{n-m+1} (x_{n-m+1} - 2x_{n-m} + x_{n-m-1}) + x_{n-m} (x_{n-m} - 2x_{n-m+1} + x_{n-m+2}) + \dots \right]$$

$$= E \left[(x_{n-m} - x_{n-m+1})^2 + (x_{n-m+1} - x_{n-m+2})^2 + \dots \right]$$

$$+ E \left[x_{n-m}^2 - 2x_{n-m} x_{n-m+1} + x_{n-m+1}^2 + x_{n+m} x_{n+m+1} - x_{n+m}^2 \right]$$

$$= \frac{1}{dt} \left[x_{n-m} \frac{dx_{n-m}}{dt} + \dots \right] - \left[\left(\frac{dx_{n-m}}{dt} \right)^2 + \left(\frac{dx_{n+m}}{dt} \right)^2 \right]$$

$$\frac{d^2 x_n}{dt^2} = E \left[(x_{n+1} - x_n - l) + (l - x_n - x_{n-1}) \right]$$

$$= E \left[x_{n+1} - 2x_n + x_{n-1} \right]$$

$$\frac{d^2 x_1}{dt^2} = E (x_2 - x_1 - l)$$

$$\frac{d^2 x_2}{dt^2} = E (x_3 - 2x_2 + x_1)$$

$$\frac{d^2 x_3}{dt^2} = E (x_4 - 2x_3 + x_2)$$

$$\frac{d^2 x_4}{dt^2} = E (x_5 - 2x_4 + x_3)$$

$$\frac{d^2 x_n}{dt^2} = E (x_{n+1} - 2x_n + x_{n-1})$$

$$\frac{d^2 x_{n+1}}{dt^2} = E (x_{n+2} - 2x_{n+1} + x_n)$$

$$\frac{d^2 x_n}{dt^2} \frac{dx_n}{dt} = E \left[x_n \frac{dx_{n+1}}{dt} + x_n \frac{dx_{n-1}}{dt} - x_{n+1} \frac{dx_n}{dt} - x_{n-1} \frac{dx_n}{dt} \right]$$

$$+ \frac{d^2 x_{n+1}}{dt^2} \frac{dx_{n+1}}{dt} = E \left[x_{n+1} \frac{dx_{n+2}}{dt} + x_{n+1} \frac{dx_{n-1}}{dt} - x_{n+2} \frac{dx_{n+1}}{dt} - x_{n-1} \frac{dx_{n+1}}{dt} \right]$$

$$\frac{1}{2} \frac{d}{dt} \left[\frac{(x_{n-m+1})^2}{2} + \frac{(x_{n-m})^2}{2} + \frac{(x_{n-1})^2}{2} + \frac{(x_{n+1})^2}{2} \right] = E \left[\frac{d}{dt} (x_{n-m+1} x_{n-m} + x_{n-m} x_{n-1} + x_{n-1} x_{n+1} + x_{n+1} x_{n+2}) \right]$$

$$= E \left[\frac{d}{dt} \left(x_{n-m+1}^2 + x_{n-m}^2 + x_{n-1}^2 + x_{n+1}^2 \right) \right] + x_{n-m+1} \frac{dx_{n-m}}{dt} + x_{n-m} \frac{dx_{n-1}}{dt} + x_{n-1} \frac{dx_{n+1}}{dt} + x_{n+1} \frac{dx_{n+2}}{dt}$$

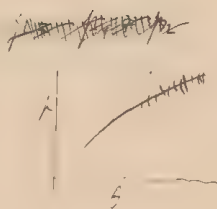
$$dQ = A_p dw + dM \text{ pro kg.}$$

$$0 = A_p dw + c d\theta + r dx$$

$$dx = \frac{\partial x}{\partial p} dp + \frac{\partial x}{\partial \theta} d\theta$$

$$\frac{1}{\rho} \frac{dp}{dz} = g$$

$$\frac{\mu}{\rho} = 2\theta$$



$$x = 20 \theta = 1/2 \mu$$

Wenn 1 kg, x kg θ \sim $\tan \theta$ θ , wie viel wird sich ausbreiten wenn $p+dp$ $\theta+d\theta$

$$20 \theta \sim \mu$$

$$0.6 \text{ erd. } \sim \frac{\mu}{\rho d} = R \theta \quad x = p d.$$

$$0.6 \text{ erd. } \frac{1}{\rho} \frac{dp}{dz} \sim c_{pR} P \quad x = \frac{p d}{\rho} = \frac{1}{\rho p}$$

$$\frac{p}{\rho} = \frac{RT}{P} \quad s = s_0 \frac{T}{T_0} \frac{P_0}{P}$$

$$\begin{array}{r} 750 \\ 18.5 \\ \hline 750 \end{array} \cdot \frac{39.67}{2105} \cdot 55746 \quad \frac{p}{\rho} = R \theta \quad R = \frac{760}{0.001293 \cdot 273}$$

$$2853 \quad s = \frac{1}{0.627} \frac{R_{Lp} T}{P}$$

$$x = \frac{p}{\rho R_n \theta} \quad n = T \frac{dp}{dT} \sim \frac{+ \theta - R_n}{-p} \frac{dT}{dT}$$

$$v dp = g dz$$

$$\rho v = \rho_0$$

$$\rho dv = R d\theta - g dz$$

$$x = \frac{P}{R + \theta} v$$

$$dx =$$

$$\rho = \frac{R\theta}{v}$$

$$v dp = \frac{R\theta}{v} dv$$

$$\rho dv + c d\theta = \frac{R\theta}{v} dv + \frac{\theta^2 R}{P} \frac{dP}{d\theta}$$

$$\rho v = R\theta$$

$$\frac{v}{R\theta} = \frac{1}{\rho}$$

$$v dp = g dz$$

$$\rho v = R\theta$$

$$\frac{AR\theta}{v} dv + c d\theta = A \frac{\theta^2 R}{P} \frac{dP}{d\theta} d\left(\frac{Pv}{R\theta}\right) = \frac{-\theta^2 R}{P} \frac{dP}{d\theta} \left[P d\left(\frac{v}{R\theta}\right) + \frac{v}{R\theta} dP \right]$$

$$A v d\left(\frac{R\theta}{v}\right) = -g dz$$

$$A R d\theta + c d\theta + A g dz = -A \frac{\theta^2 R}{P} \frac{dP}{d\theta} \left[d\left(\frac{1}{\rho}\right) + \frac{1}{\rho} \frac{dP}{P} \right]$$

$$\frac{R\theta}{\rho} d\rho = g dz$$

$$d\theta \left[AR + c + \frac{\theta^2 R}{P} \left(\frac{dP}{d\theta}\right)^2 \right] = -A g dz + \theta \frac{dP}{d\theta} \frac{1}{\rho} g dz$$

$$= \left(A + \frac{\theta}{\rho} \frac{dP}{d\theta} \right) g dz$$

$$\frac{A k k}{k-1}$$

$$\frac{d\theta}{dz} = \frac{g}{R} \frac{1 + \frac{\theta}{\rho} \frac{dP}{d\theta}}{1 + \frac{k}{k-1} + \frac{\theta^2}{\rho P} \left(\frac{dP}{d\theta}\right)^2}$$

$$= \frac{\frac{k-1}{k} \frac{g}{R}}{1 + \frac{k-1}{k} \frac{\theta^2}{\rho P} \left(\frac{dP}{d\theta}\right)^2}$$

$$= 1 \frac{1 + \frac{1}{k} \frac{\theta}{\rho} \frac{dP}{d\theta}}{1 + \frac{k-1}{k} \frac{\theta^2}{\rho P} \left(\frac{dP}{d\theta}\right)^2}$$

	-25°	-15°	-5°	0°	+5°	+10°	+15°
$\frac{dP}{d\theta}$			0.309	0.340	0.451	0.6095	
$\frac{dP}{d\theta}$	θ	P		p			
-30°							
-25°							
-20°	0.074	253	0.91	519	35		
-15°	0.1185	258	1.44	554			
-10°	0.1695	263	2.15	591			
-5°	0.238	268	3.16	629			
0	0.340	273	4.52	671			
5	0.451	278	6.51	715			
10	0.6095	283	9.14	760			

$$\begin{array}{r}
 9.762 \\
 8.548 \\
 \hline
 1.219 : 2 \\
 \\
 6.971 \\
 0.69 \\
 \hline
 0.902 : 2 \\
 \\
 7.989 \\
 5.65 \\
 \hline
 3.40 \\
 \\
 4.569 \cdot 340 \\
 2.977 \cdot 2970 \\
 \hline
 5.6179 \cdot 0.471 \\
 \\
 1.562 \\
 225 \\
 \hline
 237 \\
 \\
 2.327 \\
 1.988 \\
 \hline
 0.339
 \end{array}$$

$$\begin{aligned}
 \theta = 273 \cdot \frac{1 + 273 \cdot \frac{0.340}{7.99}}{1 + 273 \cdot \frac{0.340}{7.99}} &= \frac{273 \cdot 1.04}{1.4} = \frac{283 \cdot 2.26}{1.4} \\
 &= 283
 \end{aligned}$$

$$\frac{7}{2} \cdot \frac{5}{283} = \frac{3500}{104} = 566 = 0.0618$$

$$\frac{7}{2} \cdot \frac{30}{283} = 105 : 283 =$$

$$\begin{aligned}
 \frac{P}{P_0} &= \left[1 - \frac{k-1}{k} \frac{\alpha x}{2\theta_0} \right]^{\frac{k}{k-1}} \left(\frac{\theta}{\theta_0} \right)^{\frac{k}{k-1}} \\
 p &= 760 \cdot \frac{283}{273} \left(\frac{2.26 - 1}{2 \cdot 273} \right)^{\frac{1.4}{0.4}} \\
 &= 760 \left[1 - \frac{k}{k-1} \frac{\Delta}{\theta_0} + \frac{\alpha(\alpha-1)}{1.2} \left(\frac{\Delta}{\theta_0} \right)^2 \right. \\
 &\quad \left. - \frac{\alpha(\alpha-1)(\alpha-2)}{1.2 \cdot 3} \left(\frac{\Delta}{\theta_0} \right)^3 \dots \right]
 \end{aligned}$$

$$\begin{array}{r}
 20103 \\
 84510 \\
 \hline
 45593
 \end{array}$$

~~1.5~~
~~1.2~~
~~1.2~~

$$\frac{7}{2} \cdot \frac{5}{2} \cdot \frac{1}{2} = \frac{35}{8}$$

47712

45179

502533

005066

007599

75

37

00106005

0742035

0371017

1855085

309181

519

110

029

131

760

001124

00028135

847

2405

211235

005417

-037102

00831576

478205

40989

519191

42

44

75

0001199

005417

135425

33856

703762

-0309181

072844760

509908

737064

553614

101354

-048551

082803760

579621

49682

52; 3.7

$$\frac{k-1}{k} \frac{1}{u_0^8} = \frac{2}{7} \cdot \frac{0'00033 \cdot 0'05 \cdot 425 \cdot 980 \cdot 70^2}{0'02 \cdot 10 \cdot 980}$$

$$\frac{A}{P_0} = \left(\frac{P}{P_0} \right)^k$$

$$= \left(\frac{P}{P_0} \right)^{\frac{k}{k-1}}$$

$$\left(\frac{4}{76} \right) \theta_0 = 0$$

$$\frac{A}{P_0} = \left(\frac{P}{P_0} \right)^{\frac{k-1}{k}} = \frac{\theta}{\theta_0}$$

$$= \left(\frac{1}{190} \right)^{\frac{2}{7}} \cdot 283$$

$$22788 \cdot 2$$

$$45576 \cdot 7$$

$$-06514$$

$$+24518$$

$$18007$$

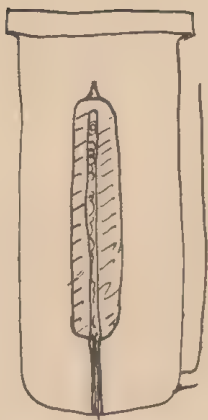
$$\frac{24362}{-06514}$$

$$17854$$

$$273$$

$$632$$

$$210$$



$$100 \text{ cm}^2 \cdot \frac{50^\circ}{1 \text{ cm}} \cdot 0.0001 =$$

$$= 0.5 \frac{\text{cal.}}{\text{sec.}} = 2 \text{ Volt Am}$$

50 Ohm 10 Volt



$$\frac{7}{3} (14)^2 \cdot 9.80 \cdot \frac{12.23}{(76.13.6)^2} \cdot \left(\frac{273}{8}\right)^{1.7} \cdot 1.7 \cdot 10^{-6} \cdot 10^{-6}$$

$$\theta = 3$$

$$\omega = 10$$

$$V_{pc} \frac{\partial \theta}{\partial t} = -0.01 \theta$$

$$J = \theta_{12} - \alpha t$$

$$\alpha = 0.001$$

$$e^{-\alpha t} = 1\%$$

$$\left(\frac{1.4}{76.13.0}\right)^2 \cdot \frac{4.1223.167}{3} \cdot (9.1)^0$$

$$\frac{1}{74}^2$$

$$\left(\frac{9.1^3}{740}\right)^2 \cdot 4.167 \cdot 0.431$$

$$\begin{array}{r} 819 \\ 828 \\ 74529 \\ 8281 \\ \hline 75357 \end{array}$$

$$\left(\frac{754}{740}\right)^2 = 1.04 \cdot \frac{167.172}{(1.7)^2}$$

$$100 = e^{\alpha t}$$

$$t = \frac{\ln 100}{\alpha}$$

$$= \frac{4.6}{10^{-3}}$$

$$= 4.6 \cdot 10^3$$

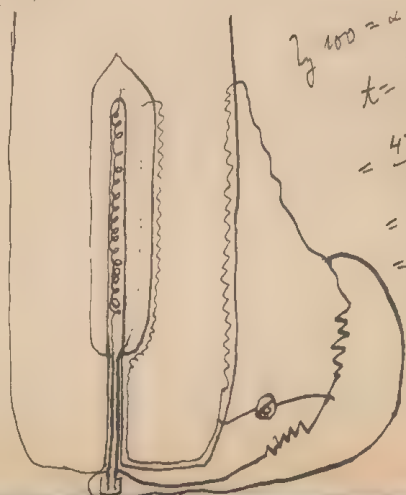
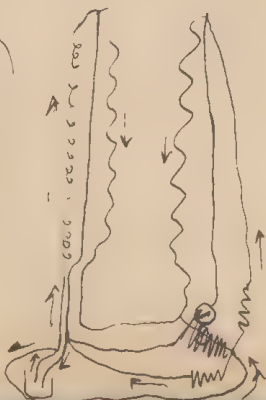
$$= 0.7 \cdot 10^2$$

$$= 70 \text{ min}$$

$$= 1 \text{ hour}$$

$$0.034 \cdot \frac{13.6}{408}$$

$$\frac{544}{0.46}$$



$$\theta = a \int_0^{\frac{x}{\sqrt{t}}} e^{-\frac{c\rho}{4k} y^2} dy + b$$

$$\left. \begin{array}{l} x=0 \quad \theta = \theta_2 \\ t=0 \quad \theta = \theta_1 \end{array} \right\}$$

2.3.6

$$\theta_1 = a \underbrace{\int_0^{\infty} e^{-\frac{c\rho}{4k} y^2} dy}_1 + b$$

$$\left. \begin{array}{l} \theta_1 = a \frac{2\sqrt{k}}{c\rho} \frac{\sqrt{\pi}}{2} + b \\ \theta_2 = b \end{array} \right\} a = (\theta_1 - \theta_2) \frac{\sqrt{c\rho}}{\sqrt{k\pi}}$$

$$\theta = (\theta_1 - \theta_2) \frac{\sqrt{c\rho}}{\sqrt{k\pi}} \int_0^{\frac{x}{\sqrt{t}}} e^{-\frac{c\rho}{4k} y^2} dy + \theta_2$$

$$= (\theta_1 - \theta_2) \frac{2}{\sqrt{\pi}} \int_0^{\frac{x}{\sqrt{t}} \frac{\sqrt{k}}{c\rho}} e^{-y^2} dy + \theta_2 = \frac{2}{\sqrt{\pi}} (\theta_1 - \theta_2) \int_0^{\frac{2k}{\sqrt{t}} \frac{\sqrt{k}}{c\rho}} e^{-y^2} dy + \theta_2$$

vrátce závislosti θ na x

$$\left. \frac{\partial \theta}{\partial x} \right|_{x=0} = \frac{2}{\sqrt{\pi}} (\theta_1 - \theta_2) e^{-\frac{4x^2}{t} \frac{k}{c\rho}} \cdot \frac{2}{\sqrt{t}} \frac{\sqrt{k}}{c\rho} \Big|_{x=0} = \frac{2(\theta_1 - \theta_2)}{\sqrt{t}} \frac{\sqrt{k}}{c\rho}$$

$$k \frac{\partial \theta}{\partial x} = \frac{4}{\sqrt{t}} (\theta_1 - \theta_2) \frac{k}{\sqrt{\pi}} \frac{\sqrt{k}}{c\rho} = \text{na povrchu absorbované množství}$$

0.3
10 min
0 min
1.3.6

Ściana zewnątrz w kontakcie z parą wodną, jeżeli np. parę opuszczamy do cylindra.

$$\frac{\partial \theta}{\partial t} = \frac{k}{c\rho} \frac{\partial^2 \theta}{\partial x^2}$$

Warunek początkowy $t=0 \quad \theta=0 \quad \begin{cases} x=0 \\ x=l \end{cases}$

$t \rightarrow \infty \quad \theta = \theta_1 \quad | \quad x=0$

$$\theta = f\left(\frac{z}{\sqrt{t}}\right)$$

$$\frac{\partial \theta}{\partial t} = f'(z) \frac{1}{2\sqrt{t}} \cdot \frac{z}{\sqrt{t}} = f'(z) \cdot \frac{z}{2t} = f'(z) \frac{1}{2\alpha x^2}$$

$$\sqrt{t} = \alpha z$$

$$\frac{\partial \theta}{\partial x} = f'(z) \frac{1}{x^2} \cdot \frac{\partial \theta}{\partial x} = -f'(z) \frac{\sqrt{t}}{x^2}$$

$$\theta = \frac{\partial^2 \theta}{\partial x^2} = f''(z) \frac{t}{x^4} + 2f'(z) \frac{\sqrt{t}}{x^3} = \frac{f''(z) z^2 + 2f'(z) z}{x^2}$$

$$\frac{f(z)}{2\alpha x^2} = \frac{k}{c\rho} \frac{f''(z) z^2 + 2f'(z) z}{x^2}$$

$$f(z) = e^{\varphi(z)}$$

$$f'(z) = \varphi' e^{\varphi(z)}$$

$$\cancel{F'} + \cancel{F}$$

$$\varphi' \cdot z^2 + 2z - \frac{c\rho}{2kz} = 0$$

$$\varphi' + \frac{z}{2} - \frac{c\rho}{2kz^3} = 0$$

$$\varphi = \frac{c\rho}{4kz^2} - 2 \log z \quad || \quad f(z) = e^{\frac{c\rho}{4kz^2} - 2 \log z}$$

$$\theta = A \int \frac{e^{-\frac{c\rho}{4kz^2}}}{z^2} dz$$

$$z = y$$

$$= A \int e^{-\frac{c\rho}{4k} y^2} dy = A \int e^{-\frac{c\rho}{4k} y^2} dy + \text{const}$$

$$\frac{\partial \theta}{\partial t} = -e^{-\frac{c\rho}{4k} \frac{x^2}{t}} \frac{x^2}{2\sqrt{t}^3}$$

$$\frac{\partial \theta}{\partial x} = -\frac{c\rho}{4k} \frac{x}{\sqrt{t}^3}$$

$$\frac{\partial^2 \theta}{\partial x^2} = \frac{c\rho}{4k} \left[\frac{1}{\sqrt{t}} + \frac{x^2}{t^2} \right]$$

$$\frac{\partial^2 \theta}{\partial x^2} = \frac{c\rho}{4k} \frac{2x}{\sqrt{t}^3} e^{-\frac{c\rho}{4k} \frac{x^2}{t}}$$

Ilon' cipe puev de ongo

237

meuzos

$$0.000066 \cdot \frac{100}{0.8} \cdot 35 = \frac{0.231}{0.8} = 0.3 \frac{\text{g Cal}}{\text{sec}} = \cancel{18} 18 \frac{\text{g Cal}}{\text{min}}$$

puev nkl.

$$0.001 \cdot \frac{100}{0.8} \cdot 2 = 0.25 \frac{\text{g Cal}}{\text{sec}}$$

puev nkl' zilonq $q = 10 \text{ mm}^2$

$$\frac{0.15 \cdot 100}{0.8} \cdot 0.1 = 2 \frac{\text{g Cal}}{\text{sec}}$$



$$\rho_0 (1 + \varepsilon \theta) \frac{d\theta}{dz} = \text{const} = a$$

$$\rho_0 \theta + \rho_0 \varepsilon \frac{\theta^2}{2} = az + \text{const}$$

$$\cancel{\rho_0 \theta_0 + \rho_0 \varepsilon \theta^2} \quad z=0 : \quad \theta=0 \quad \text{const} = 0$$

$$\cancel{\rho_0 \theta + \rho_0 \varepsilon \frac{\theta^2}{2}} \quad \rho_0 \theta \left[1 + \varepsilon \frac{\theta}{2} \right] = az$$

$$\rho_0 \theta_1 \left[1 + \varepsilon \frac{\theta_1}{2} \right] = aL$$

$$\theta \left(1 + \varepsilon \frac{\theta}{2} \right) = \frac{z}{L} \theta_1 \left(1 + \varepsilon \frac{\theta_1}{2} \right)$$

$$\text{N.p. } z = \frac{L}{2} \quad \theta \left(1 + \varepsilon \frac{\theta}{2} \right) = \frac{1}{2} \theta_1 \left(1 + \varepsilon \frac{\theta_1}{2} \right)$$

$$\left(\frac{\theta}{2} - \theta_1 \right) + \varepsilon \left(\frac{\theta^2}{2} - \frac{\theta_1^2}{2} \right) = 0$$

$$\underbrace{\theta - \theta_1}_{\neq 0} + \varepsilon \left(\frac{\theta^2}{2} - \frac{\theta_1^2}{2} \right) = 0$$

$$\int \theta dz = \int_0^{\theta} \frac{\theta \rho_0 (1 + \varepsilon \theta) d\theta}{a} = \frac{\rho_0}{a} \left(\frac{\theta^2}{2} + \varepsilon \frac{\theta^3}{3} \right) = \frac{\rho_0}{a} \frac{\theta^2}{2} \left[1 + \frac{2\varepsilon}{3} \theta \right]$$

$$= L \frac{\frac{\theta^2}{2} \left[1 + \frac{2\varepsilon}{3} \theta \right]}{\theta_1 \left[1 + \frac{\varepsilon}{2} \theta_1 \right]} = \frac{L \theta_1}{2} \left[1 + \frac{1}{6} \varepsilon \theta_1 \right] \quad \text{wzgl. poprawki} \quad \left(\frac{1}{6} \varepsilon \theta_1 \right) \text{ od średniej temp.}$$

$$\text{N.p. } \varepsilon = \frac{1}{273} = 0.0036$$

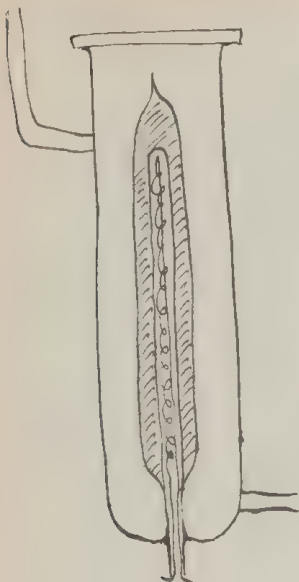
$$\theta_1 = 100$$

$$\frac{\varepsilon \theta_1}{6} = 0.06 = 6\%$$

wzgl. poprawka temperatura $\overset{= 53^\circ \text{C}}{0.3^\circ \text{C}}$
wynika od średniej 50°

Temperatura różnica w ciśnieniu lub objętości $\frac{3}{273} = \frac{1}{90}$

$$\text{t.j. } 8 \text{ mm Hg} = 88 \text{ mm Hg}$$



$$K \cdot \frac{30 \text{ cm}^2}{1 \text{ cm}} \theta = 50$$

$$K_{\text{H}_2\text{O}} = 0.0015$$

glas

5700 V22

$$0.045 \cdot 50 = 2.5$$

$$K_{\text{Luft}} = 0.00006$$

$$0.0018 \cdot 50 = 0.09$$

$$1 \text{ Volt Ampere} = 0.24 \frac{\text{g cal}}{\text{sec}}$$

$$10 \text{ --- } 0.3 \text{ Voltamp}$$

$$i^2 R = \frac{e^2}{R}$$

$$R = 2 \text{ Ohm}$$

$$i^2 = 5 \text{ --- } 0.15$$

$$i = 2 \text{ --- } 0.4 \text{ Amp}$$

12

13

2 1 2

10

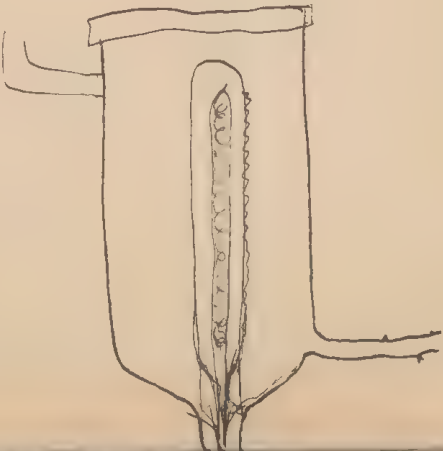
$$K = K_0(1 + \alpha \theta)$$

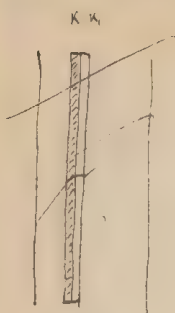
$$= - \frac{dK}{dx} \frac{d\theta}{dx} - x \frac{d^2\theta}{dx^2}$$

juv. *Tryphium* $K=20$

Wproważę problem: $z^2 = -1, \text{ do } \frac{dz}{dx}$

$$\theta = \frac{1}{\lambda_0} - \frac{i^2}{\lambda_0 \kappa_0} x^2 + \frac{i^2}{\lambda_0 \kappa_0} x^4$$

$$V = \int \frac{dx}{\lambda_0} = \int \frac{dx}{\lambda_0 \left(1 + \beta_0 + \frac{\beta_0^2}{\lambda_0 \kappa_0} x - \frac{\beta_0^2}{\lambda_0 \kappa_0} x^2 \right)} = \frac{1}{\lambda_0} \int \frac{dx}{1 + \frac{\beta_0^2}{\lambda_0 \kappa_0} x - \frac{\beta_0^2}{\lambda_0 \kappa_0} x^2}$$




$$\frac{c}{A} f(r) \frac{\partial \theta}{\partial x} = R f(r) \frac{\partial \theta}{\partial x} - w \frac{\partial f}{\partial x} + \mu \left(\frac{\partial u}{\partial r} \right)^2 + K \frac{1}{2} \frac{\partial}{\partial r} \left(R \frac{\partial \theta}{\partial r} \right)$$

$$\left(\frac{c}{A} - R \right) f(r) \frac{\partial \theta}{\partial x} = - \frac{w}{\rho} \frac{2\mu}{r^2 - R^2} f(r) + \mu \left(\frac{\partial u}{\partial r} \right)^2 + K \frac{1}{2} \frac{\partial}{\partial r} \left(R \frac{\partial \theta}{\partial r} \right)$$

$$- \frac{1}{2} (x+y+z)^2 + 3[x^2+y^2+z^2]$$

$$-2(x+y+z) + 6x$$

$$4x - 2y - 2z$$

$$2x^2 + 2xy + 2y^2 + 2z^2 - 2x - 2y$$

$$-(1+\alpha+\beta)^2 + 3[1+\alpha^2+\beta^2]$$

$$= 2[1 + \alpha^2 + \beta^2 - \alpha - \beta - \alpha\beta]$$

$$= [(\alpha-\beta)^2 + (1-\alpha)^2 + (1-\beta)^2]$$

$$\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)^2 + \dots = \left(\frac{\partial u}{\partial x} \right)^2 +$$

$$\frac{\partial W}{\partial t} + \kappa \frac{\partial W}{\partial z} = \frac{\mu}{f} \left[\frac{\partial^2 W}{\partial z^2} + \frac{\partial W}{\partial z} + \frac{1}{2} \frac{\partial W}{\partial z} \right] - \frac{1}{f} \frac{\partial \theta}{\partial z}$$

$$\frac{\partial}{\partial t} \left(\kappa W \frac{\partial \theta}{\partial z} \right) = -\mu \frac{\partial W}{\partial z} + \kappa \left[-\frac{1}{2} \left(\frac{\partial W}{\partial z} \right)^2 + \frac{1}{2} \left(\frac{\partial W}{\partial z} \right)^2 + \left(\frac{\partial W}{\partial z} \right)^2 \right] + \kappa \frac{1}{2} \frac{\partial^2}{\partial z^2} \left(\frac{\partial \theta}{\partial z} \right)$$

$$\theta, \rho, W = f(r, z, t)$$

$$\frac{\mu}{f} = R^2 \theta$$

$$\rho W = f(r, z, t)$$

$$\frac{\partial \theta}{\partial x} = \mu \left(\frac{\partial^2 W}{\partial z^2} + \frac{1}{2} \frac{\partial W}{\partial z} \right)$$

$$\rho W = f(r, z, t)$$

$$\frac{\partial}{\partial t} (\rho W) = 0$$

$$\frac{\mu}{f} = R^2 \theta$$

$$\frac{\partial}{\partial t} \left(\rho W \frac{\partial \theta}{\partial x} \right) = -\mu \frac{\partial W}{\partial x} + \mu \left(\frac{\partial W}{\partial z} \right)^2 + \kappa \left(\frac{\partial^2 \theta}{\partial z^2} + \frac{1}{2} \frac{\partial \theta}{\partial z} \right)$$

$$\rho = f(r, x)$$

$$\frac{\partial}{\partial t} \left(\frac{\partial \theta}{\partial z} \right) + \frac{1}{2} \frac{\partial \theta}{\partial z} = 0$$

$$\frac{\partial \theta}{\partial z} + \frac{1}{2} \frac{\partial \theta}{\partial z} = \gamma(x)$$

$$\frac{\partial \theta}{\partial z} = 2 \gamma(x)$$

$$2 \frac{\partial \theta}{\partial z} = \frac{r^2}{2} \gamma(x) + \gamma(x)$$

$$u = \frac{r^2}{2} \gamma(x) + \gamma(x) \ln(r^2) + \gamma(x)$$

$$u = \frac{r^2 R^2}{2} \gamma(x) = \frac{r^2 R^2}{2} \frac{1}{u} \frac{\partial \theta}{\partial z}$$

$$\rho \frac{r^2 R^2}{2 \mu} \frac{\partial \theta}{\partial x} = f(r)$$

$$\rho \frac{\partial \theta}{\partial x} = \frac{2 \mu}{r^2 R^2} f(r)$$

$$R \frac{\partial \theta}{\partial x} = \frac{W}{f(r)} \frac{\partial \theta}{\partial x} - \rho \frac{\partial}{\partial x} \left(\frac{W}{f(r)} \right)$$

$$= \frac{W}{f(r)} \frac{\partial \theta}{\partial x} - \frac{\rho}{f(r)} \frac{\partial W}{\partial x}$$

$$R f(r) \frac{\partial \theta}{\partial x} = W \frac{\partial \theta}{\partial x} - \rho \frac{\partial W}{\partial x}$$

C, c mit Styrer, Dylg Telt, zisch, crum! stumper!!

Das geschlossene System mit der Luft stoppt ein Styrer:

magnetisch.

elektrisch, ohne Zuerstung?

und das System mit geschlossenen messenden in der!

Unter Kühlen durch Drogen: Drogen CR II Drogen. XII

Leitungssysteme von Selen: Götter Wied. 40 p. 18 (1890)

KCl der Andrews Erdb. Pro. 1884/5 13 p. 275
(zu p. 611. 2) # KCl 3% 950°

Selenkristalle in verd. N. H. M!, dann bei Druck bis zur Zerkleinerung

Kann die Capillartatschente ρ Eis-Wasser theoretisch bestimmt werden?

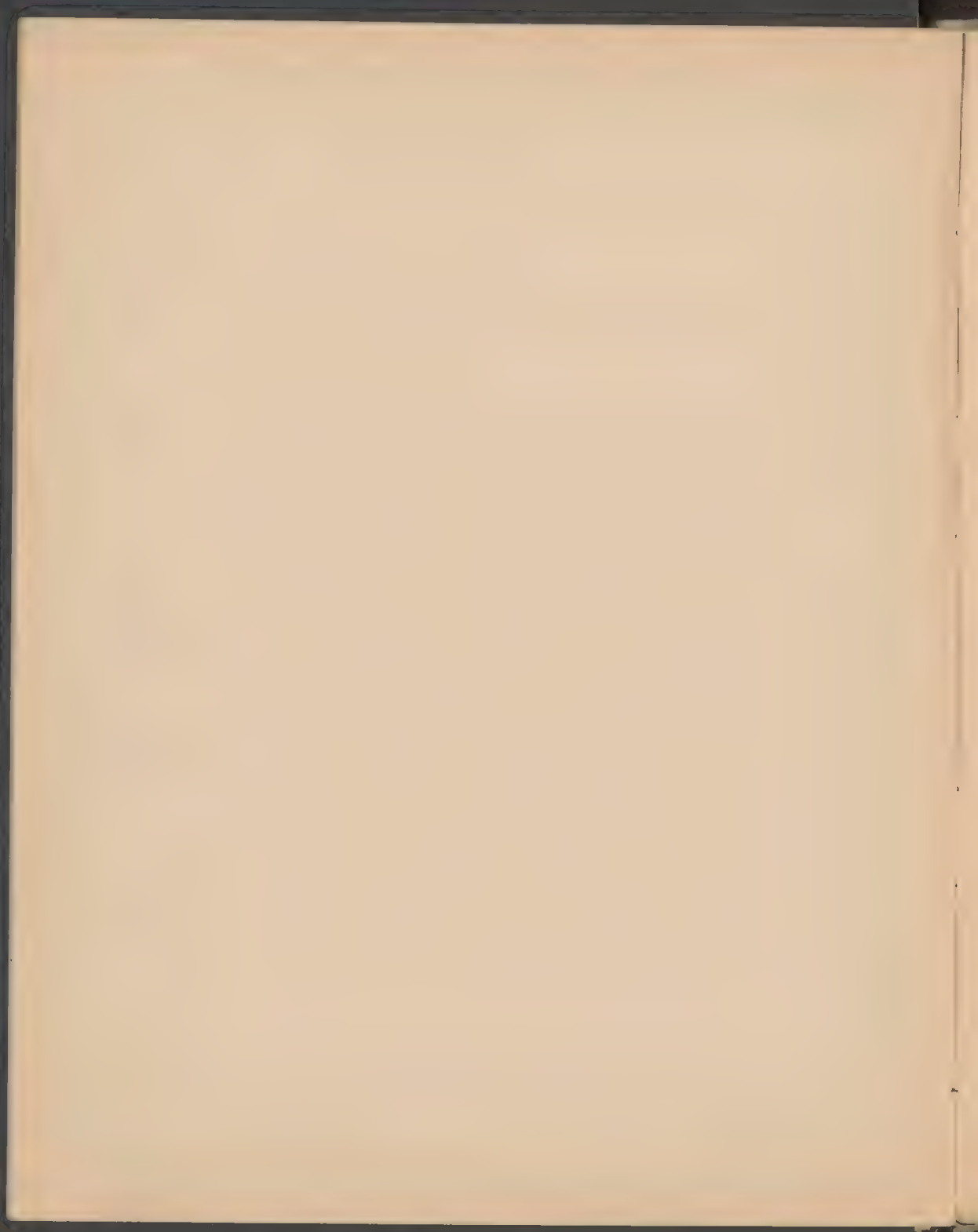
Capillartatschente α von Eis?

Emulsionen: Gröncke Offizier's Archiv 1878 Bd. 19

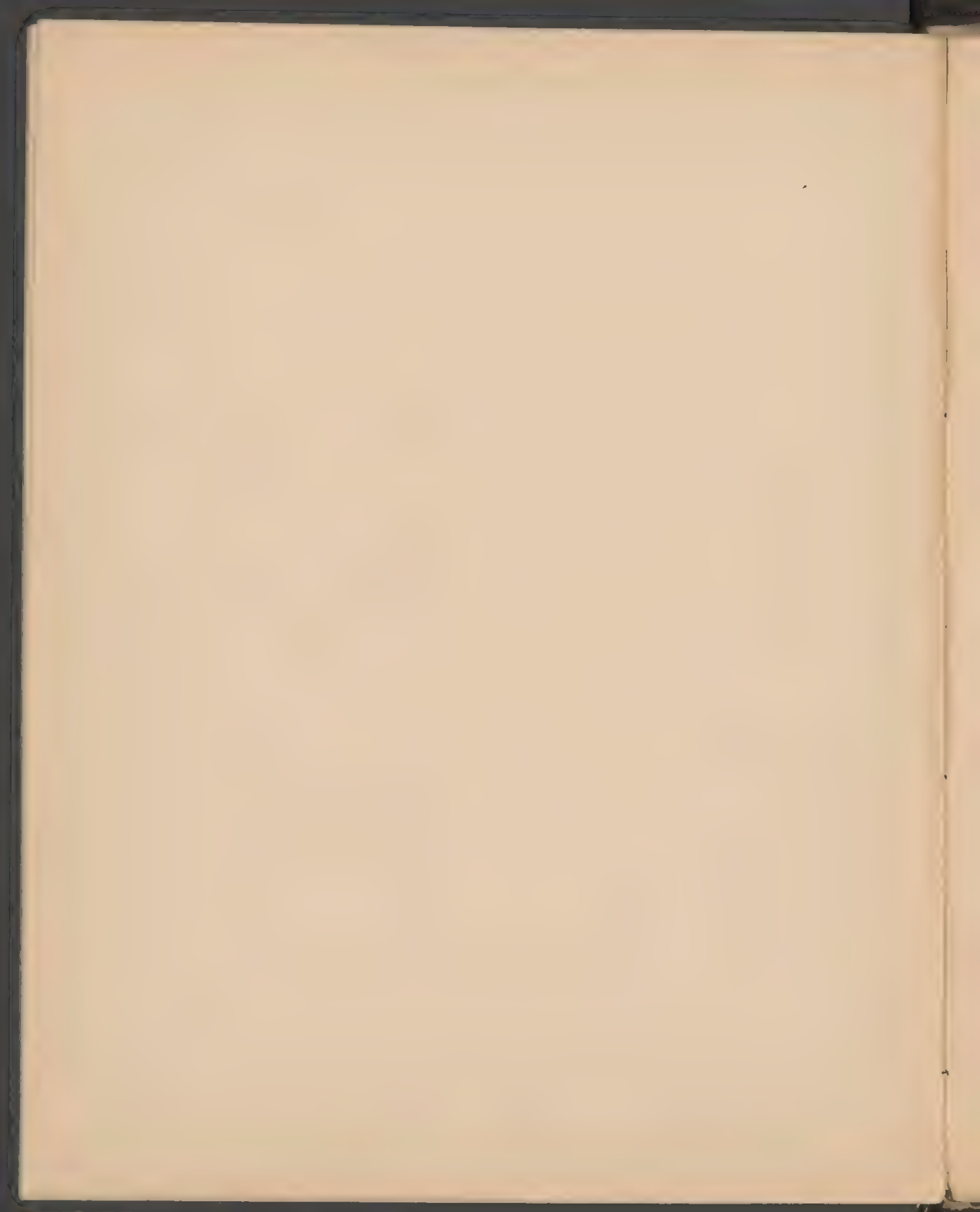
Acht. 1880 p. 110

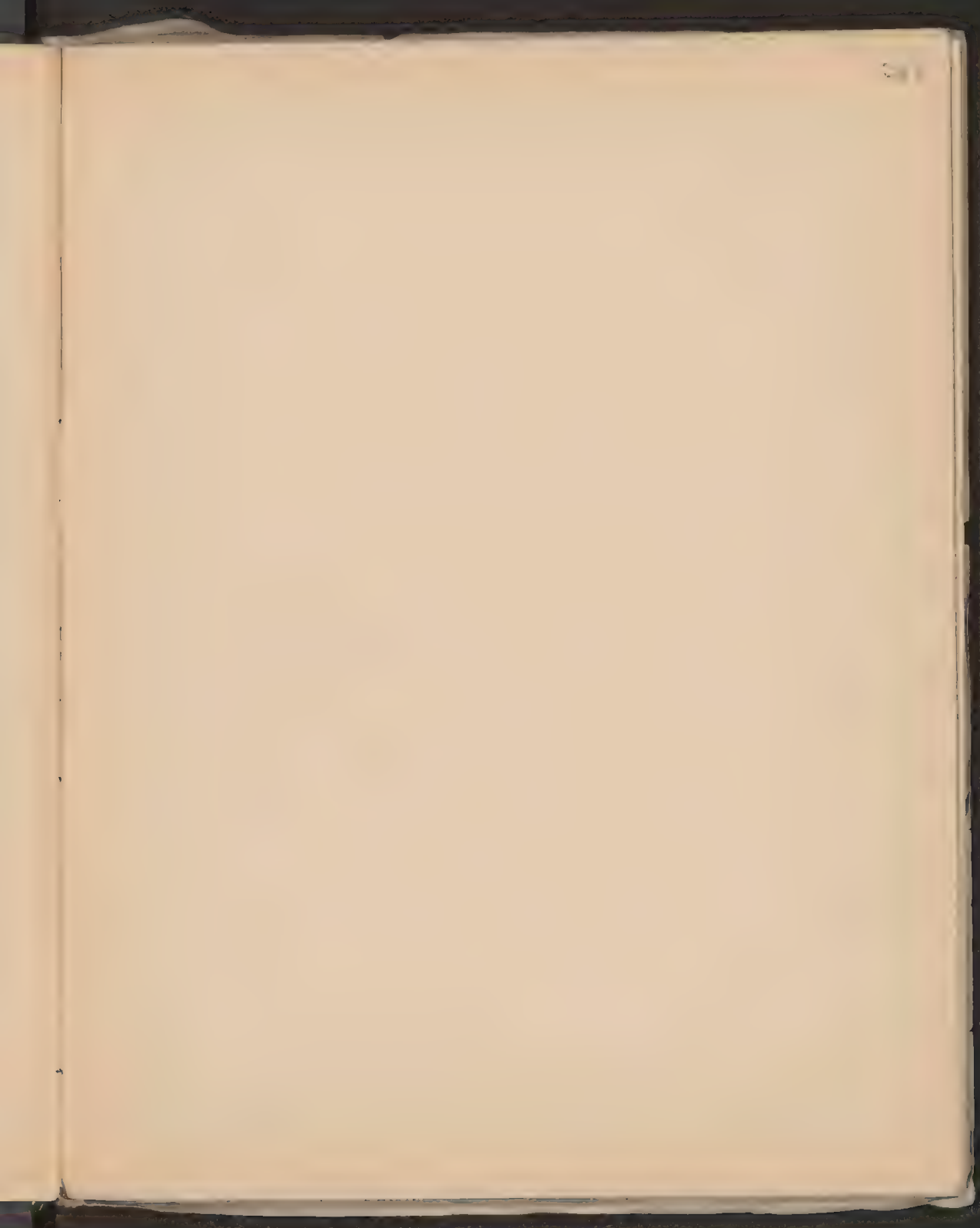
Wick

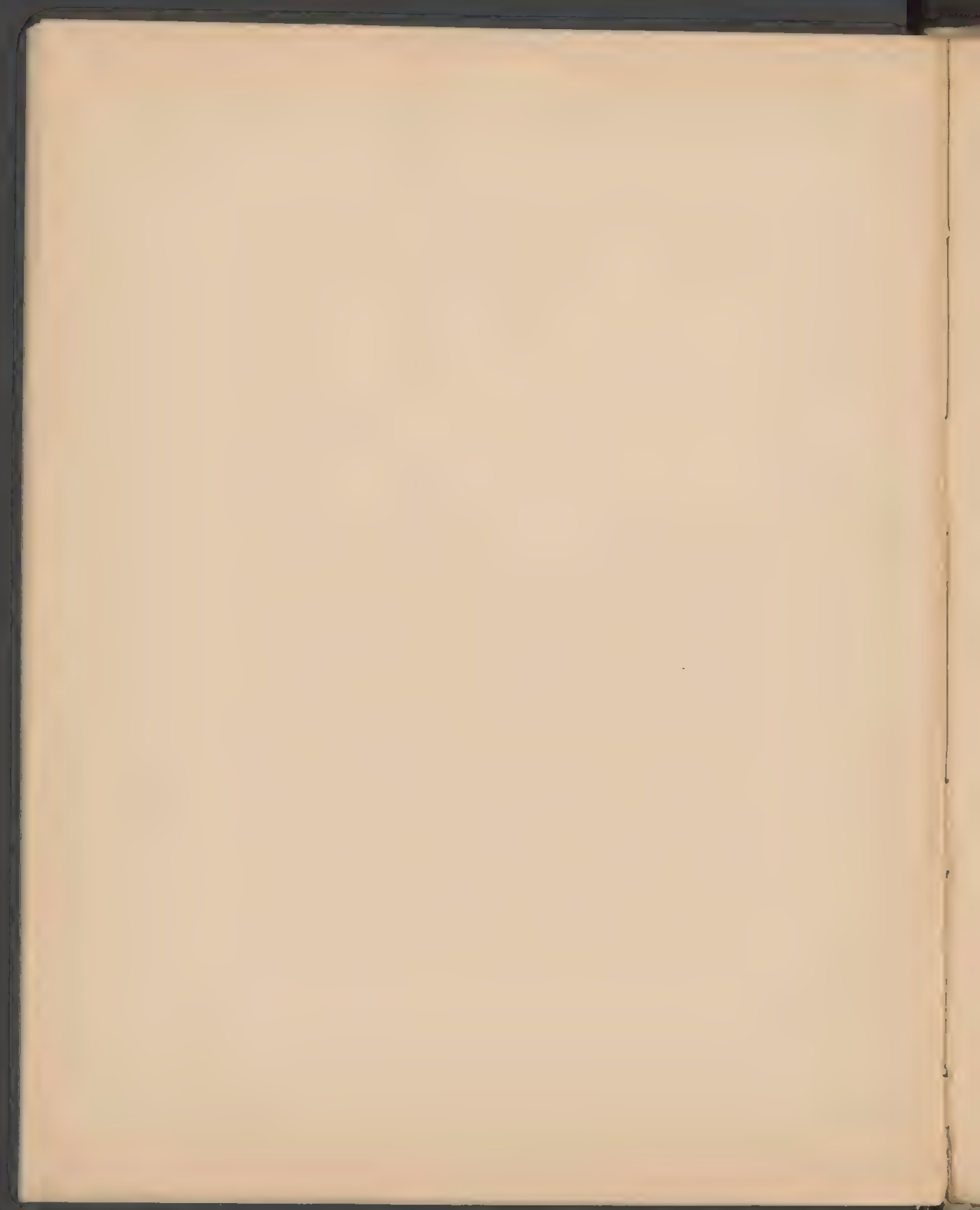
" " p. 109

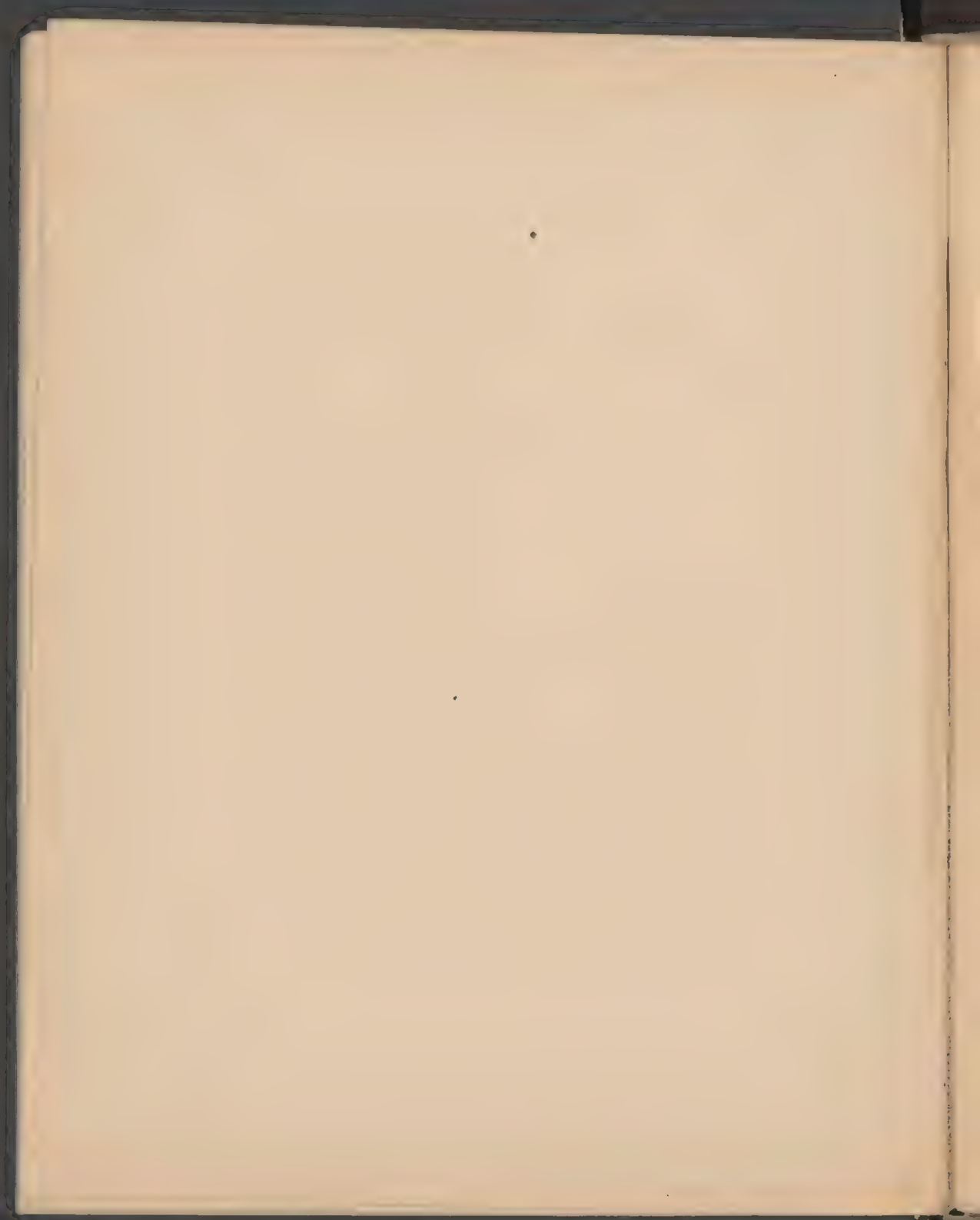


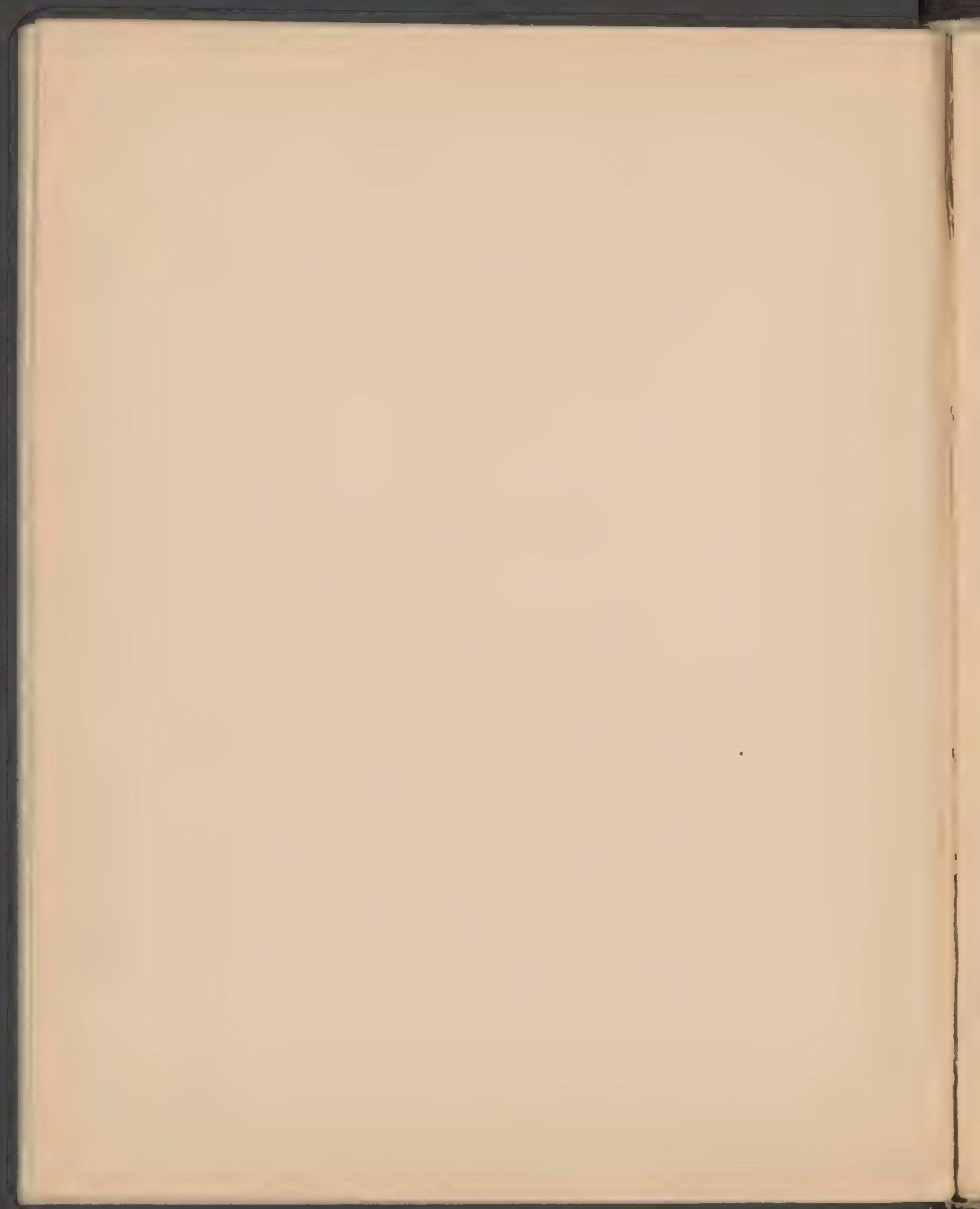




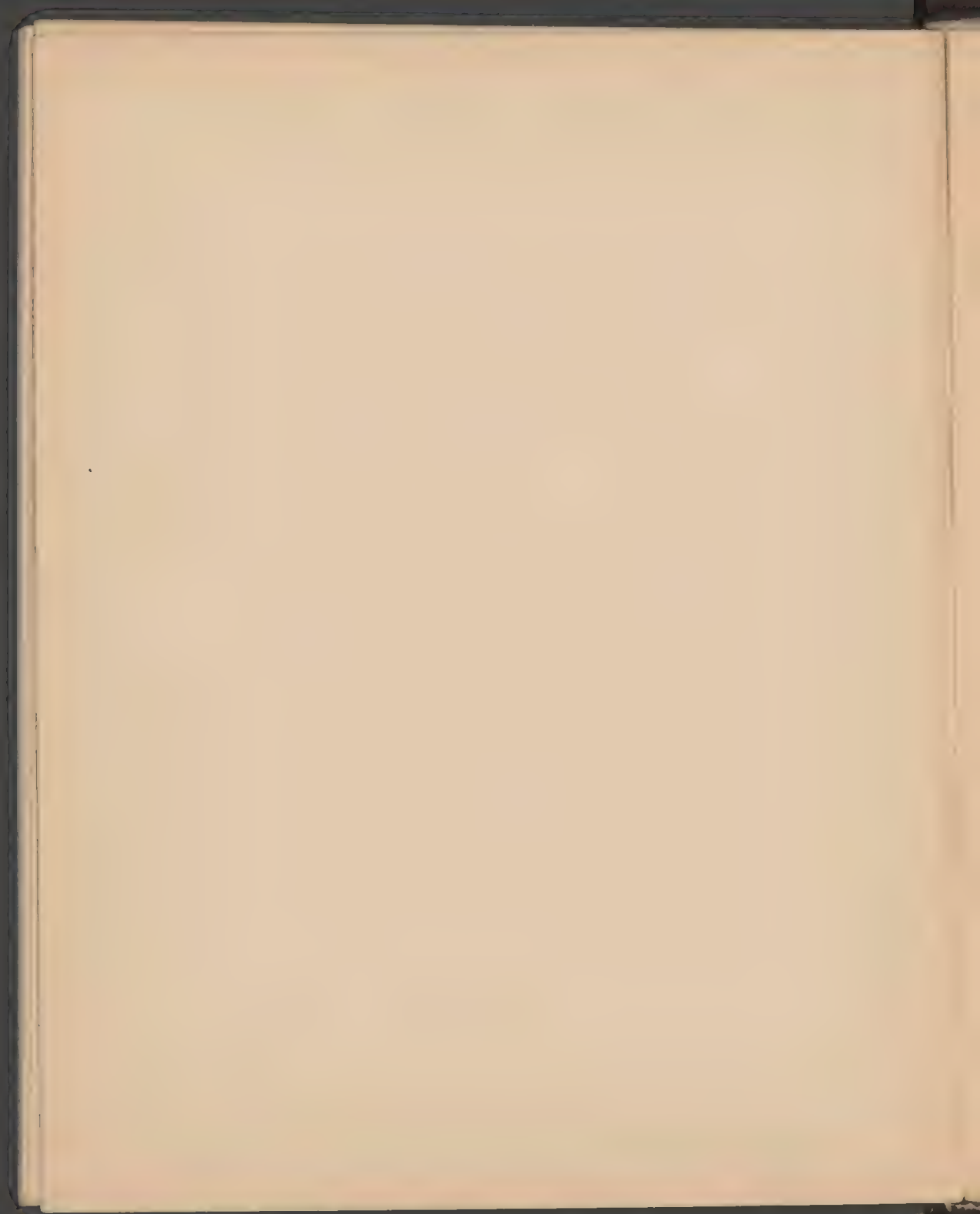














Ths. Am 67 p. 202 (1899) Adon Ang feta makt. 10 58 in 850.

1. 40 e fta k. 2. 2000 = 10 e kmg.

h. k. = 8

2. 8. 0. 1. 2. 3. 4. 5. 6. 7. 8. 9. 10. 11. 12. 13. 14. 15. 16. 17. 18. 19. 20. 21. 22. 23. 24. 25. 26. 27. 28. 29. 30. 31. 32. 33. 34. 35. 36. 37. 38. 39. 40. 41. 42. 43. 44. 45. 46. 47. 48. 49. 50. 51. 52. 53. 54. 55. 56. 57. 58. 59. 60. 61. 62. 63. 64. 65. 66. 67. 68. 69. 70. 71. 72. 73. 74. 75. 76. 77. 78. 79. 80. 81. 82. 83. 84. 85. 86. 87. 88. 89. 90. 91. 92. 93. 94. 95. 96. 97. 98. 99. 100.

$$c_{12} = \frac{2d}{3.0 \cdot 0.0691}$$

$$d = \frac{A}{2.145}$$

1. 1. 2. 3. 4. 5. 6. 7. 8. 9. 10. 11. 12. 13. 14. 15. 16. 17. 18. 19. 20. 21. 22. 23. 24. 25. 26. 27. 28. 29. 30. 31. 32. 33. 34. 35. 36. 37. 38. 39. 40. 41. 42. 43. 44. 45. 46. 47. 48. 49. 50. 51. 52. 53. 54. 55. 56. 57. 58. 59. 60. 61. 62. 63. 64. 65. 66. 67. 68. 69. 70. 71. 72. 73. 74. 75. 76. 77. 78. 79. 80. 81. 82. 83. 84. 85. 86. 87. 88. 89. 90. 91. 92. 93. 94. 95. 96. 97. 98. 99. 100.

$$A \cdot c_v = 3.0 \cdot 0.0691 \cdot 145 = 3.006$$

$$c_v \cdot 16.6^2 = 2c_v = 6.012$$

$$A \cdot c_t = 6.692 - 6.252$$

e 2 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 79 80 81 82 83 84 85 86 87 88 89 90 91 92 93 94 95 96 97 98 99 100.

0.125
1.70
2.24

1. 2. 3. 4. 5. 6. 7. 8. 9. 10. 11. 12. 13. 14. 15. 16. 17. 18. 19. 20. 21. 22. 23. 24. 25. 26. 27. 28. 29. 30. 31. 32. 33. 34. 35. 36. 37. 38. 39. 40. 41. 42. 43. 44. 45. 46. 47. 48. 49. 50. 51. 52. 53. 54. 55. 56. 57. 58. 59. 60. 61. 62. 63. 64. 65. 66. 67. 68. 69. 70. 71. 72. 73. 74. 75. 76. 77. 78. 79. 80. 81. 82. 83. 84. 85. 86. 87. 88. 89. 90. 91. 92. 93. 94. 95. 96. 97. 98. 99. 100.

$$\begin{array}{r} 266 \\ 7 \overline{) 1862} \\ \underline{140} \\ 462 \\ \underline{420} \\ 42 \end{array}$$

4249

1375

$$\begin{array}{r} 1116 \\ 15584 \\ \underline{1116} \\ 4424 \end{array}$$

$$\begin{array}{r} 8830 \\ \underline{8830} \\ 4468 \\ 0156 \\ \underline{4624} \end{array}$$

$$\begin{array}{r} 283. \\ \underline{273} \\ 10 \end{array}$$

$$\begin{array}{r} 4518 \\ \underline{4262} \\ 256 \end{array}$$

$$\begin{array}{r} 4000.0 \\ 200.0 \\ 800.0 \\ 800.0 \\ 480.0 \\ 4.50 \end{array}$$

Then with the 64.405 to 1000

[further to 2000]

$$\left\{ \begin{array}{l} \mu v = a x + b y + c z \\ \mu v = a x + b y + c z \end{array} \right.$$

$$\begin{array}{l} \frac{a}{\mu v} = a x \\ \frac{b}{\mu v} = b y \\ \frac{c}{\mu v} = c z \end{array}$$

$$\mu v = (a + b + c) 5.93$$

$$\mu = \mu v' = a x + b y + c z$$

$$\left[\frac{1}{\mu v} = 0.98835 \frac{1}{\mu} \right] = \frac{1}{5.93}$$

$$\frac{1}{\mu v} = \frac{1}{6.93}$$

1.670 1) Then with the 64.405 to 1000

$\frac{6}{a=0}$ (i) $\sim -\ln \epsilon$ $\sim + \ln \epsilon$ $\sim -6'' \ln \epsilon$ ~ 2 ~ 2

$$\frac{1}{r} \frac{dy}{d\theta} = \frac{1}{r} \frac{\partial y}{\partial \theta} + \left(\frac{1}{r} \frac{\partial y}{\partial \phi} \right) \left(\frac{\partial \phi}{\partial \theta} \right)$$

$$= \frac{1}{r} \frac{\partial y}{\partial \phi} \cdot \frac{\partial \phi}{\partial \theta}$$

$$= \frac{\partial y}{\partial \phi} \cdot \frac{\alpha}{\beta}$$

Then $\theta = 20^\circ$: $\frac{1}{r} \frac{\partial y}{\partial \phi} = 7.30 \cdot 10^{-4}$ / Orund $9.3 \cdot 10^{-4}$

f. Schurph

$$\begin{array}{r} 1.1139 \\ 2.4116 \\ - 3.5255 \\ + 1.5185 \\ \hline 0.9930 - 3 \end{array}$$

$$\frac{1}{r} \frac{dy}{d\theta} =$$

$$\begin{array}{r} 0.001278 \\ 245 \\ \hline 33 \end{array}$$

for 185° : 13.258 0.0098

$\beta =$
Surgeat

$$\begin{array}{r} 254 \\ 13.5 \\ \hline 178 \end{array} \cdot 10^{-6} \quad (1.1)$$

$$\alpha = \begin{array}{r} 0.00148 \\ 13 \\ \hline 0.00161 \end{array}$$

$$\begin{array}{r} 350. \\ 105 \\ 140 \\ 119 \\ \hline 1295 \end{array}$$

$$\begin{array}{r} 0.0018 \\ * 0.0066 \\ - 0.0048 \\ \hline 0.0098 \end{array}$$

$$\begin{array}{r} 7.3 \cdot 10^{-4} \cdot 0.0016 \\ 1.78 \cdot 10^{-4} \end{array}$$

$$\begin{array}{r} 73 \\ 738 \\ \hline 1108 : 1.78 = 656 \end{array}$$

$$0.00739$$

$$561$$

$$178 : 18.645$$

$$\text{for } 210$$

$$\begin{array}{r} 83.0 \\ 54 : 87.1 \\ 17.9 : 91.7 \\ 50 : 111 \end{array}$$

$$\begin{array}{r} 2.8096 \\ 1.2553 \\ - 4.0649 \\ + 1.2504 \\ \hline 0.1855 - 2 \end{array}$$

$$0.0153$$

$$94$$

$$92 \cdot 10^{-6}$$

$$\begin{array}{r} 0.00116 \\ 0.00008 \\ \hline 0.00124 \end{array}$$

$$\begin{array}{r} 9.3 \cdot 10^{-4} \cdot 0.00124 \\ 0.92 \cdot 10^{-4} \end{array}$$

$$\begin{array}{r} 0.0125 \\ + 0.0018 \\ - 0.0107 \\ \hline 0.0153 \text{ m.} \end{array}$$

$$\text{Benzol} \quad \frac{286. (0.00116)^2 \cdot 39}{R} \quad 0.892$$

$$\begin{array}{r} 0645.2 \\ 0.1290 - 6 \\ 2.4564 \\ 1.5911 \\ 0.1765 - 2 \\ - 6.5443 \\ 0.6322 - 9 \end{array}$$

$$\begin{array}{r} 0.9504 - 1 \\ 5.5939 \\ 6.5443 \end{array}$$

$$\text{du } 4.288 \cdot 10^{-9}$$

$$\text{zu } 8.3 \cdot 10^{-11}$$

$$\text{Alk.} \quad \frac{293. (0.00111)^2 \cdot 23}{R} \quad 0.794$$

$$\begin{array}{r} 0.0453 - 3^2 \\ 0.0906 - 6 \\ 2.4669 \\ 1.3617 \\ 0.4061 - 7 \\ 0.3253 - 12.9 \\ - 0.8998 - 1 \\ 0.4255 - 12.9 \end{array}$$

$$\begin{array}{r} - 6.5939 \\ = 0.4061 - 7 \end{array}$$

$$2.66 \cdot 10^{-9}$$

$$1. \cdot 10^{-10}$$

$$\text{Hg:} \quad \frac{273. \left(\frac{1}{550}\right)^2 \cdot 100}{R} \quad 12.6$$

$$\begin{array}{r} 2.7404 \\ 5.4808 \\ 1.1335 \\ 6.4434 \\ 13.0577 \end{array}$$

$$\begin{array}{r} 2.4362 \\ - 13.0577 \\ 0.3785 - 11 \end{array}$$

$$2.39 \cdot 10^{-11}$$

$$\text{zu: } 3.9 \cdot 10^{-12}$$

$$\text{Pent:} \quad \frac{288. (0.00159)^2 \cdot 36}{R} \quad 0.626$$

$$1.51 \cdot 10^{-8}$$

$$\text{zu } 2.9 \cdot 10^{-10}$$

$$\begin{array}{r} 0.2014 - 31.2 \\ 0.4028 - 6 \\ 1.5563 \\ 2.4594 \\ 0.4185 - 2 \\ - 6.2400 \\ 0.1785 - 8 \end{array}$$

$$\begin{array}{r} 0.7966 - 1 \\ 6.4434 \\ 6.2400 \end{array}$$

$$\beta = -\frac{\alpha^2}{\sqrt{2} R \rho} = -\frac{\alpha^2}{\sqrt{2} \cdot n} \left(\frac{n}{\rho}\right)$$

$$\alpha = 0.00116$$

Desol. at 130

$$n = 78, \rho = 0.892$$

$$\rho = 0.000085$$

$$0.00170$$

within 0-50

$$n = 78, \rho = 0.736$$

$$0.000189$$

$$0.00127 \quad 0.00111$$

LS ~~0.00127~~ MK 0-40

$$\rho = \frac{46}{2}$$

$$\rho = 0.794$$

$$0.000100$$

$$\text{Petroleum } 0.00099$$

$$0.000069$$

$$\rho = 0.76$$

$$\text{Carbon } 0.00159$$

0-300

$$0.000292$$

$$n = \frac{72}{2}$$

$$\rho = 0.6263$$

$$90\% \text{ H}_2\text{SO}_4 : 0.00055 = \alpha$$

180

$$\beta = 0.0000462 \cdot 0.730$$

$$\frac{3234}{1386}$$

$$\rho = 1.891$$

$$3.3726 \cdot 10^{-4}$$

$$H_2 : \frac{1}{5500}$$

$$(\text{Amper}) 0.0000039$$

$$\rho = 13.6$$

$$n = \frac{32}{64}$$

$$n = \frac{200}{2}$$

$$R = \frac{n}{\mu}$$

$$= \frac{98}{2}$$

$$\frac{1000}{\cancel{11.156} \cdot 980}$$

$$R = \frac{1000}{0.001293 \cdot 278}$$

$$9912$$

$$5478$$

$$4434$$

$$\frac{1116}{9362} = 5478$$

$$= 2.776 \cdot 10^6$$

$$\log R = 6.4434$$

$$\log R = \frac{0.1505}{6.5939}$$

$$\frac{0.00055^2 \cdot 291.79}{2.78 \cdot 10^6 \cdot 1.84 \cdot 1.42}$$

$$\begin{array}{r} 121.25 \\ 3025.29 \\ 6050 \\ 27225 \\ 87725 \end{array} \quad \begin{array}{r} 87725.49 \\ 350900 \\ 789525 \\ 42985 \end{array}$$

$$\begin{array}{r} 2.78 \cdot 10^6 \\ 2224 \\ 111 \\ 5115.142 \\ 20460 \\ 102 \\ 7263 \end{array}$$

$$42985 : 7222 = 5.918 \cdot 10^{-11}$$

$$CO_2: \frac{2.000196}{1.88} = 8$$

$$\begin{array}{r} 40.3 \\ 32.6 \\ \hline 7.7 \\ 2.3056 \end{array} = \frac{7.7}{2.3056} = 3.34$$

$$8:188 = 0.042$$

$$2.47 = 0.042$$

$$2.12 = 0.033$$

$$7.7: 611 = 0.0126$$

5

$$P = \frac{2.05}{1.88}$$

$$P = \frac{2.05}{1.88} = 1.09$$

$$P = \frac{2.05}{1.88} = 1.09$$

$$P = \frac{2.05}{1.88} = 1.09$$

$$P = \frac{2.05}{1.88} = 1.09$$

$$P = \frac{1}{v} \frac{dv}{d\theta}$$

$$v\beta = -\frac{1}{\sqrt{2} R} \frac{v}{v_0}$$

$$-\frac{1}{v^3} \frac{dv}{d\theta} = \frac{R\sqrt{2}}{v-v_0} - \frac{R\theta\sqrt{2}}{(v-v_0)^2} \frac{dv}{d\theta}$$

$$v\beta = -\frac{\delta^2}{\sqrt{2} R \theta} \quad \text{where } \delta = \frac{v}{v_0}$$

$$\left[-\frac{2\delta}{v^3} + \frac{R\theta\sqrt{2}}{(v-v_0)^2} \right] \frac{dv}{d\theta} = \frac{R\sqrt{2}}{v-v_0}$$

$$\beta = -\frac{\theta \delta^2 v}{\sqrt{2} R}$$

$$\left[-\frac{2R\theta\sqrt{2}}{(v-v_0)v} + \frac{R\theta\sqrt{2}}{(v-v_0)^2} \right] \frac{dv}{d\theta} = \frac{R\sqrt{2}}{v-v_0}$$

$$R\theta\sqrt{2} \left[\frac{-2(v-v_0) + v}{2v(v-v_0)} \right] \frac{dv}{d\theta} = \frac{R\sqrt{2}}{v-v_0}$$

$$\beta = -\frac{\delta^2 \theta}{\sqrt{2} R \rho}$$

$$\frac{dv}{d\theta} = \frac{\delta}{\theta} = \frac{v-v_0}{\theta}$$

$$\int_{-\infty}^{\infty} \frac{1}{(a^2 + y^2)^{3/2}} e^{-h(a^2 + y^2)^{1/2}} dy \dots$$

$$\int_{-\infty}^{\infty} e^{-hx^2} dx = \sqrt{\frac{\pi}{ah}} \quad \text{as } x^2 e^{-hx^2} dx = ax \frac{e^{-hx^2}}{-2h} + \int \frac{e^{-hx^2}}{2h} dx$$

$$= \frac{1}{2h} \sqrt{\frac{\pi}{ah}}$$

$$2 \left(\sqrt{\frac{\pi}{h}} \right)^n$$

$$\int_{-\infty}^{\infty} e^{-h(x^2 + y^2)} dx dy = \left(\sqrt{\frac{\pi}{h}} \right)^n$$

$$\frac{c}{A} \frac{d\theta}{dx} + \frac{p}{b} \frac{du}{dx} = \frac{f_p}{b}$$

$$\frac{1}{p} \frac{dp}{dx} = -g$$

$$p u = b$$

$$\frac{p}{\rho} = R\theta$$

$$\frac{p}{\rho u} \frac{du}{dx} = R\theta \cdot \frac{1}{u} \frac{du}{dx}$$

$$= -R\theta \frac{1}{p} \frac{dp}{dx}$$

$$\left[\bar{p} = \frac{p}{R\theta} \right]$$

$$= -\frac{1}{\bar{p}} \left(\frac{1}{\theta} \frac{dp}{dx} - \frac{p}{\theta^2} \frac{d\theta}{dx} \right)$$

$$= -\frac{1}{\bar{p}} \frac{dp}{dx} + \frac{p}{p\theta} \frac{d\theta}{dx}$$

$$= g + R \frac{d\theta}{dx}$$

$$\frac{k-1}{k} = \frac{2}{7}$$

$$d\rho b = \rho g u_0 = \rho g \frac{dx}{u_0} = dp$$

$$b \rho = R p \frac{d\theta}{dx} \frac{dx}{u_0}$$

$$\delta \phi = \alpha \cdot \phi \cdot \delta x$$

$$= c \cdot \phi \cdot \delta x \cdot \frac{1}{x} \cdot \frac{k-1}{k}$$

$$\frac{\delta x}{\delta \phi} = \frac{\alpha}{c} \frac{R}{g}$$

$$B = \frac{2 \cdot 9 \cdot 9 \cdot 0}{2 \cdot p \cdot R}$$

$$\frac{42.10^3 \cdot 0.00033}{9.10^2 \cdot 20} \cdot \frac{10^6}{10^3} \frac{1}{b}$$

$$= \frac{0.6 \cdot 10^3}{b} \text{ cm} =$$

$$= \frac{0.6 \cdot 10^3}{0.001 \cdot u} \text{ cm} = \frac{6 \cdot 10^5}{u}$$

$$= \frac{6 \cdot 10^3 \text{ m}}{u_0} = \frac{6 \text{ km}}{u_0}$$

111571 4
 111572 11142

111573
 111574

111575
 111576

111577
 111578
 111579
 111580

111581
 111582
 111583

111584
 111585
 111586
 111587

B. N. :

Sygnatura :

Dzielo: (Autor)

(Tytuł)

(Stan dzieła)

tom

wol.

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je w ciągu tygodni przyjmując odpo-
wiedzialność za wszelkie uszkodzenia

We Lwowie dnia

Mieszkanie :

Podpis :

B. N. Sygnatura:

Dzieło : (Autor)

(Tytuł)

(Stan dzieła)

tom

wol.

pożyczyłem z c. k. biblioteki uniwersyteckiej i zwrócę
je w ciągu tygodni przyjmując odpo-
wiedzialność za wszelkie uszkodzenia.

We Lwowie dnia

Mieszkanie :

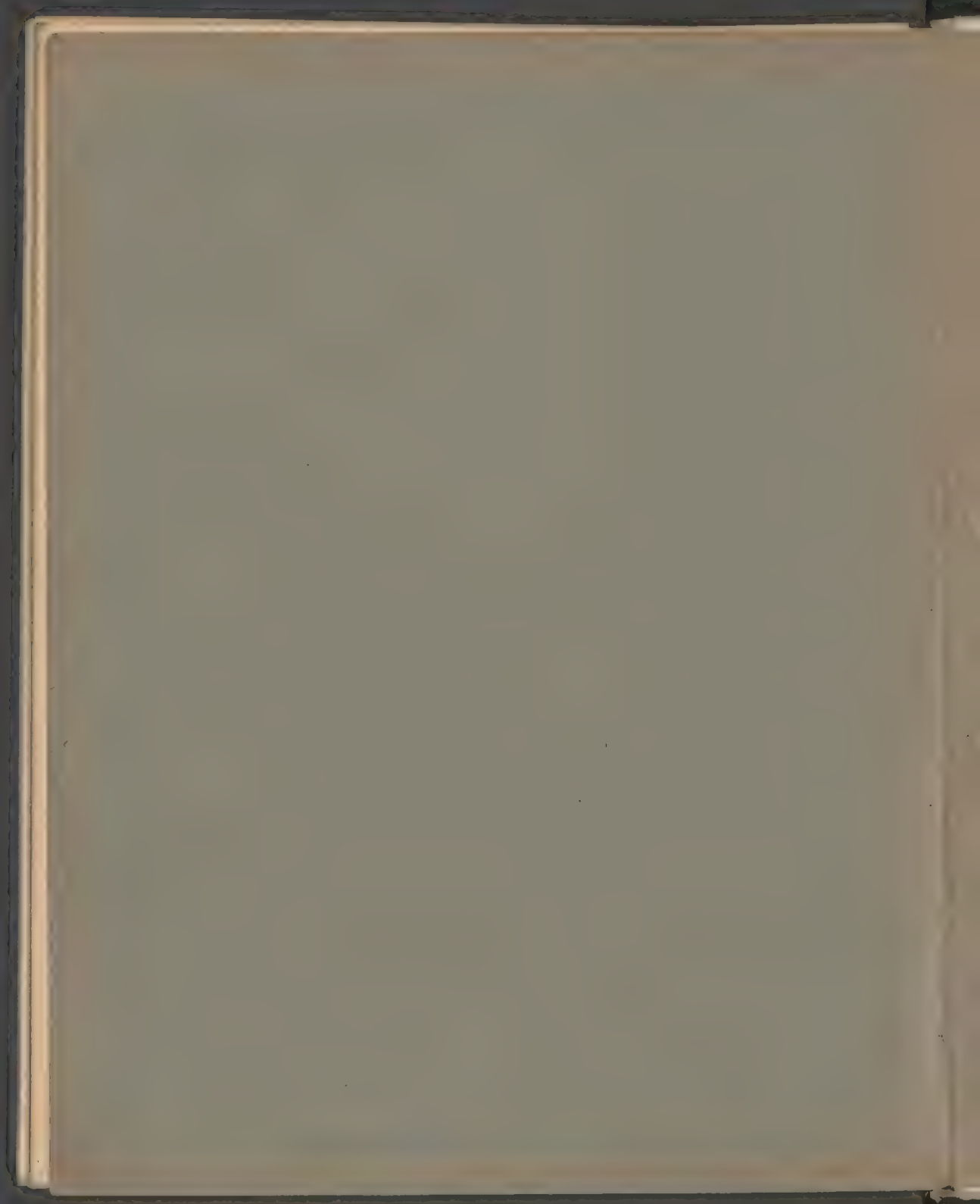
Podpis :

.....
Tytuł dzieła:

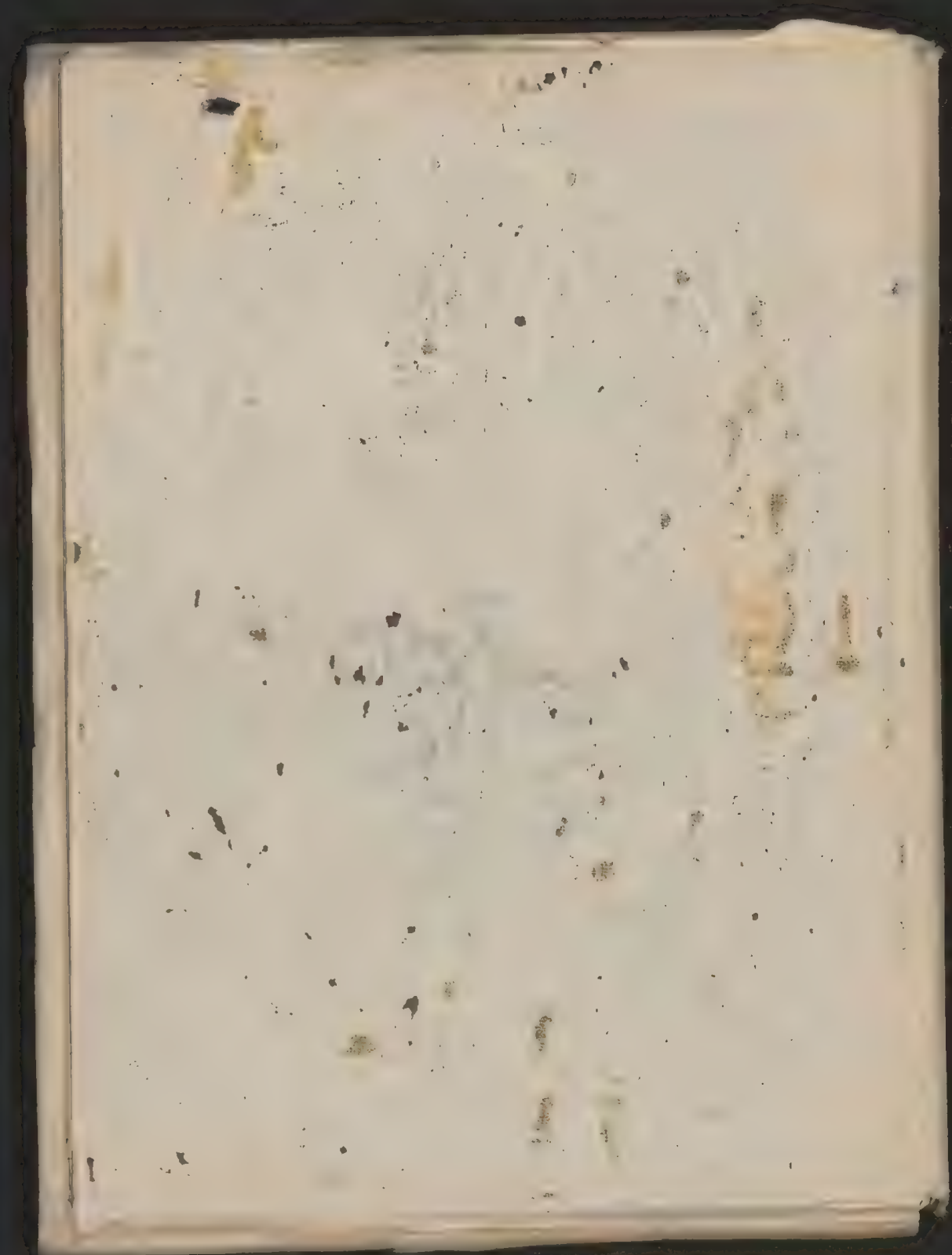
Sygnatura:

.....
D a t a :

Nazwisko pożyczającego :



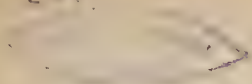




9408

11

259



$$y = -\frac{1}{x} - \frac{1}{2} \ln x - \frac{1}{2}$$

$$y = \frac{1}{2} \ln x - \frac{1}{2}$$

$$y = \frac{1}{2} \ln x - \frac{1}{2}$$

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$$y = \frac{1}{2} \ln x - \frac{1}{2}$$

$$y = \frac{1}{2} \ln x - \frac{1}{2}$$

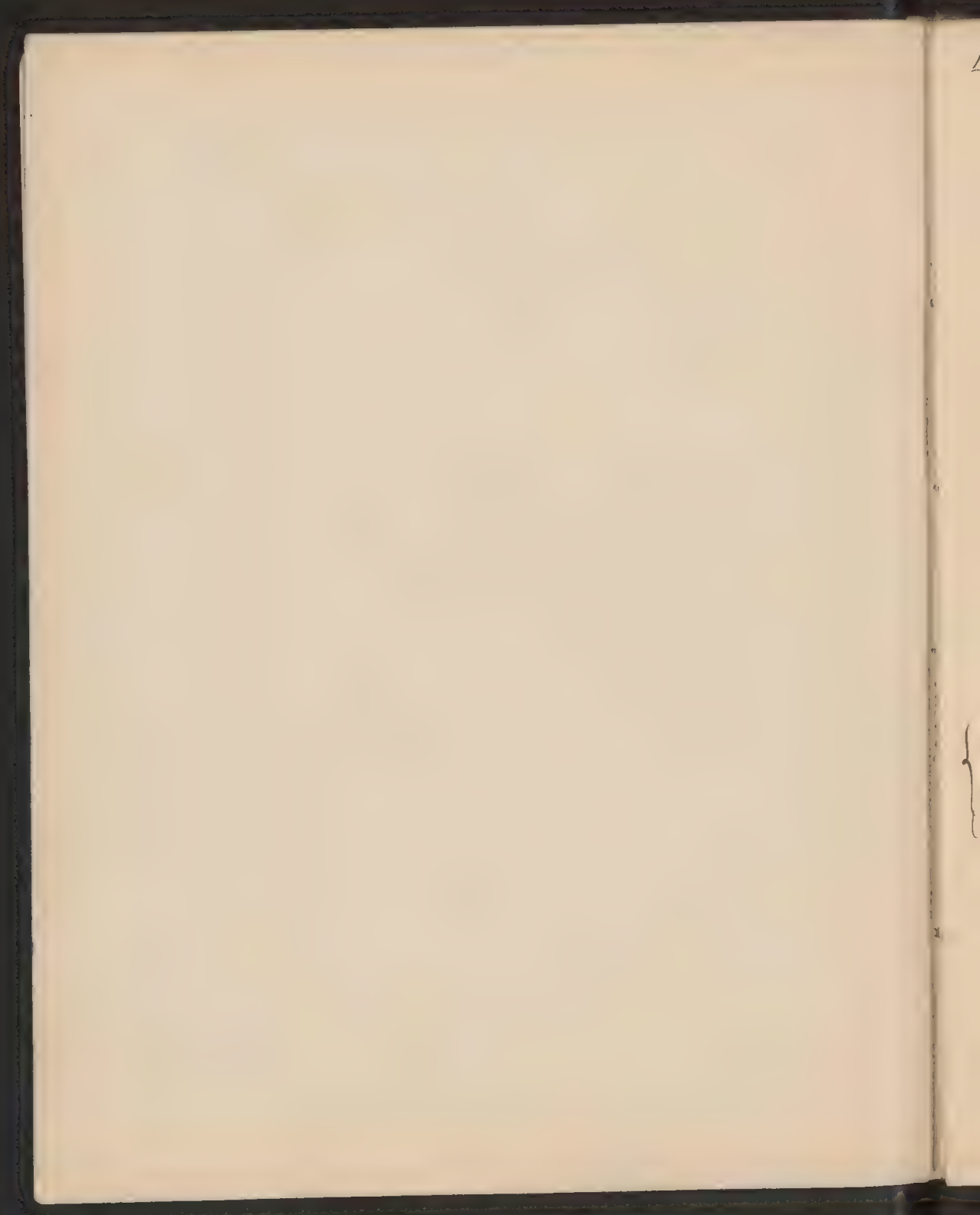
$$y = \frac{1}{2} \ln x - \frac{1}{2}$$

$$y = \frac{1}{2} \ln x - \frac{1}{2}$$

$$y = \frac{1}{2} \ln x - \frac{1}{2}$$

$$y = \frac{1}{2} \ln x - \frac{1}{2}$$

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Δ^2 Puta ung $\Delta^2 \sim = \text{div}'$

$$\left[\frac{27}{32} \frac{a}{x^2} + \frac{3}{4} \left(\frac{x^2}{2^3} - \frac{15}{8} \frac{ax^2}{2^4} - \frac{1}{4} \frac{a^3 x^4}{2^6} \right) = \right.$$

$$\frac{27}{32} \frac{2a}{x^4} + \frac{3}{4} \left[2 \frac{1}{2^3} - \frac{15a}{8} \left(\frac{2}{2^4} - \frac{4x^2}{2^6} - \frac{1}{4} a^3 \left(\frac{2}{2^6} + 6 \frac{x^2}{2^8} \right) \right] \right.$$

$$= \frac{27}{16} \frac{a}{x^4} + \frac{3}{2} \frac{1}{2^3} - \frac{45a}{16x^4} + \frac{45}{8} \frac{ax^2}{2^6} - \frac{3a^3}{8x^6} - \frac{9}{8} \frac{a^3 x^2}{2^8} - \frac{6x^2}{2 \cdot 2^5}$$

$$- \frac{\cancel{18} \cancel{9} a}{\cancel{16} 8 x^4}$$

$$= \frac{3}{2} \frac{1}{x^3} \left[1 - \frac{3}{4} \frac{a}{x} - \frac{1}{4} \frac{a^3}{x^3} \right] - \frac{9}{2} \frac{x^2}{x^5} \left[1 - \frac{5}{4} \frac{a}{x} + \frac{1}{4} \frac{a^3}{x^3} \right]$$

rote $k \text{ div}' = \Delta^2 \left\{ \mu c^2 a \left[\frac{27}{32} \frac{a}{x^2} + \frac{3}{4} \left(\dots \right) \right] \right\}$

$$\text{div}' = \Delta^2 \psi$$

Rangieren systematisch

$$\begin{cases} \frac{\partial \psi'}{\partial x} = \frac{1}{3} \frac{\partial \text{div}'}{\partial x} + \mu \Delta^2 u' \\ \frac{\partial \psi'}{\partial y} = \frac{1}{3} \frac{\partial \text{div}'}{\partial y} + \mu \Delta^2 v' \\ \frac{\partial \psi'}{\partial z} = \frac{1}{3} \frac{\partial \text{div}'}{\partial z} + \mu \Delta^2 w' \end{cases}$$

$$\Delta^2 \psi' = \frac{4\mu}{3} \Delta^2 \text{div}'$$

$$\underline{\underline{\psi' = \frac{4\mu}{3} \text{div}' + \varphi}}$$

$$\Delta^2 \varphi = 0$$

$$\mu \frac{\partial \text{div}'}{\partial x} + \frac{\partial \varphi}{\partial x} = \mu \Delta^2 u'$$

$$u' = \frac{\partial \varphi}{\partial x} + u$$

$$\begin{cases} \frac{\partial \varphi}{\partial x} = \mu \Delta^2 u \\ \frac{\partial \varphi}{\partial y} = \mu \Delta^2 v \\ \frac{\partial \varphi}{\partial z} = \mu \Delta^2 w \end{cases}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

8.11 2. Sommer's partiellableitung

$$U = - \frac{27 \mu c^2 a}{32 k} \left[-\frac{x}{2^3} + \frac{1}{3} \frac{x^3}{2^5} - \frac{q^2 x}{2^5} \left(3 - 5 \frac{x^2}{2^2} \right) \right]$$

$$V = - \frac{27 \mu c^2 a}{32 k} \left[-\frac{y}{2^3} + \frac{1}{3} \frac{x^2 y}{2^5} - \frac{q^2 y}{2^5} \left(1 - 5 \frac{x^2}{2^2} \right) \right]$$

$$W =$$

$$\mu \Delta U = - \frac{27 \mu c^2 a}{32 k} \left(\frac{2x}{2^5} - \frac{10}{3} \frac{x^3}{2^7} \right) = \frac{\partial}{\partial x} \left[- \frac{27 \mu c^2 a}{32 k} \cdot \frac{2}{3} \left(-\frac{1}{3x^3} + \frac{x^4}{2^5} \right) \right] = \frac{q}{16} \frac{\mu c^2 a}{k} \left[\frac{1}{3x^3} - \frac{x^2}{2^5} \right]$$

$$\mu \Delta V = - \frac{27 \mu c^2 a}{32 k} \left(\frac{2}{3} \frac{y}{2^5} - \frac{10}{3} \frac{x^2 y}{2^7} \right) = \frac{\partial}{\partial y}$$

$$\left. \begin{aligned} \frac{2}{3} \frac{\partial}{\partial x} \left(\frac{x^2}{2^5} \right) &= \frac{4x}{3 \cdot 2^5} - \frac{10x^3}{3 \cdot 2^7} \\ - \frac{2}{9} \frac{\partial}{\partial x} \left(\frac{1}{2^3} \right) &= - \frac{3x}{2^5} \cdot \frac{2}{9} \end{aligned} \right\} \frac{\partial}{\partial x} \left[\frac{2}{3} \left(-\frac{1}{3x^3} + \frac{x^4}{2^5} \right) \right]$$

$$\frac{\partial}{\partial y} = \frac{2}{3} \left(+ \frac{y}{2^5} - \frac{5x^2 y}{2^7} \right)$$

$$P = \frac{q}{16} \cdot \frac{\mu c^2 a}{k} \left[\frac{1}{3x^3} - \frac{x^2}{2^5} \right]$$

$$P = P_+(p_0) - \frac{2}{2} \mu c a \frac{x}{2^3} + \frac{1}{p} \left\{ \frac{4\mu}{3k} \left[\frac{2}{2} \mu a c^2 \frac{1}{2^3} \left(1 - \frac{2}{4} \frac{a}{2} - \frac{1}{4} \frac{a^3}{2^3} \right) - \right. \right.$$

$$\left. - \frac{q}{2} \mu c^2 a \frac{x^2}{2^5} \left(1 - \frac{5}{4} \frac{a}{2} + \frac{1}{4} \frac{a^3}{2^3} \right) \right] + \frac{q}{16} \frac{\mu c^2 a}{k} \left[\frac{1}{3x^3} - \frac{x^2}{2^5} \right] \right\}$$

$$\left\{ \right\} = \frac{\mu c^2 a}{k} \left| \begin{aligned} &\frac{2}{2^3} \left(1 - \frac{2}{4} \frac{a}{2} - \frac{1}{4} \frac{a^3}{2^3} \right) + \frac{q}{16} \frac{1}{3x^3} \\ &- \frac{6x^2}{2^5} \left(1 - \frac{5}{4} \frac{a}{2} + \frac{1}{4} \frac{a^3}{2^3} \right) - \frac{q}{16} \frac{x^2}{2^5} \end{aligned} \right|$$

$$\frac{\partial}{\partial x}$$

$$+ \frac{\partial}{\partial y}$$

$$+ \frac{\partial}{\partial z}$$

$$u_0 \frac{\partial u_0}{\partial x} + v_0 \frac{\partial v_0}{\partial y} + w_0 \frac{\partial w_0}{\partial z} = \frac{q}{16} \frac{c^2 a^2}{r^3} \left(1 - \frac{a^2}{r^2}\right) \left[x^2 \left(M + \frac{2}{r^3} - \frac{2a^2}{r^5} \right) + y^2 M + z^2 M \right]$$

$$+ \frac{3}{4} \frac{c^2 a}{r^3} \left(1 - \frac{2}{r} \frac{a}{2} - \frac{1}{4} \frac{a^3}{r^3}\right) \left(1 - \frac{3x^2}{r^2} - \frac{3y^2}{r^2} + \frac{5a^2 x^2}{r^4}\right)$$

$$= \frac{q}{16} \frac{c^2 a^2}{r^3} \left(1 - \frac{a^2}{r^2}\right) \left[-\frac{1}{2} - \frac{3x^2}{r^3} - \frac{a^2}{r^3} + \frac{5a^2 x^2}{r^5} + \frac{2x^2}{r^3} - \frac{2a^2 x^2}{r^5} \right] + \uparrow$$

$$-\frac{1}{2} - \frac{x^2}{r^3} - \frac{a^2}{r^3} + \frac{3a^2 x^2}{r^5}$$

$$= \frac{3}{4} \frac{c^2 a^2}{r^3} \left[\frac{3}{4} \left[-\frac{a^2}{r^2} - \frac{a^2 x^2}{r^4} - \frac{a^2}{r^4} + \frac{3a^2 x^2}{r^6} + \frac{a^2}{r^4} + \frac{a^2 x^2}{r^6} + \frac{a^2}{r^6} - \frac{3a^2 x^2}{r^8} \right] \right]$$

$$= \frac{3}{4} \frac{c^2 a^2}{r^3} \left\{ \frac{3}{4} \left[-\frac{a^2}{r^2} - \frac{a^2 x^2}{r^4} - \frac{a^2}{r^4} + \frac{3a^2 x^2}{r^6} + \frac{a^2}{r^4} + \frac{a^2 x^2}{r^6} + \frac{a^2}{r^6} - \frac{3a^2 x^2}{r^8} \right] \right.$$

$$- 1 + \frac{3x^2}{r^2} + \frac{3a^2}{r^2} - \frac{5a^2 x^2}{r^4} + \frac{3}{4} \frac{a^2}{r^2} - \frac{9}{4} \frac{x^2 a^2}{r^4} - \frac{9a^3}{4r^3} + \frac{15a^3 x^2}{4r^5} + \frac{a^3}{4r^3} -$$

$$\left. - \frac{3a^3 x^2}{4r^5} - \frac{3a^3}{4r^5} + \frac{5a^3 x^2}{4r^7} \right\}$$

$$= \frac{3}{4} \frac{c^2 a^2}{r^3} \left\{ -1 + \frac{3x^2}{r^2} + \frac{3a^2}{r^2} - \frac{5a^2 x^2}{r^4} - \frac{3a^2 x^2}{r^4} - \frac{2a^3}{r^3} + \frac{6a^3 x^2}{r^5} - \frac{a^3 x^2}{r^7} \right\}$$

$$\left. \begin{aligned} & \frac{\partial}{\partial x} \left(u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right) \\ & + \frac{\partial}{\partial y} \left(u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right) \\ & + \frac{\partial}{\partial z} \left(u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} \right) \end{aligned} \right\} = \left(\frac{\partial u}{\partial x} \right)^2 + \frac{\partial u}{\partial x} \frac{\partial u}{\partial y} + \frac{\partial u}{\partial x} \frac{\partial u}{\partial z} + u \frac{\partial}{\partial x} \frac{\partial u}{\partial x} + v \frac{\partial}{\partial y} \frac{\partial u}{\partial x} + w \frac{\partial}{\partial z} \frac{\partial u}{\partial x}$$

$$+ \left(\frac{\partial v}{\partial y} \right)^2 + \frac{\partial v}{\partial y} \frac{\partial v}{\partial x} + \frac{\partial v}{\partial y} \frac{\partial v}{\partial z} + \frac{\partial v}{\partial y} \frac{\partial v}{\partial x} + \frac{\partial v}{\partial y} \frac{\partial v}{\partial y} + \frac{\partial v}{\partial y} \frac{\partial v}{\partial z} + \frac{\partial v}{\partial y} \frac{\partial v}{\partial x} + \frac{\partial v}{\partial y} \frac{\partial v}{\partial y} + \frac{\partial v}{\partial y} \frac{\partial v}{\partial z}$$

$$+ \left(\frac{\partial w}{\partial z} \right)^2 + \frac{\partial w}{\partial z} \frac{\partial w}{\partial x} + \frac{\partial w}{\partial z} \frac{\partial w}{\partial y} + \frac{\partial w}{\partial z} \frac{\partial w}{\partial z} + \frac{\partial w}{\partial z} \frac{\partial w}{\partial x} + \frac{\partial w}{\partial z} \frac{\partial w}{\partial y} + \frac{\partial w}{\partial z} \frac{\partial w}{\partial z} + \frac{\partial w}{\partial z} \frac{\partial w}{\partial x} + \frac{\partial w}{\partial z} \frac{\partial w}{\partial y} + \frac{\partial w}{\partial z} \frac{\partial w}{\partial z}$$

$$= \left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial y} \right)^2 + \left(\frac{\partial w}{\partial z} \right)^2 + 2 \frac{\partial u}{\partial y} \frac{\partial v}{\partial x} + 2 \frac{\partial v}{\partial z} \frac{\partial w}{\partial y} + 2 \frac{\partial w}{\partial x} \frac{\partial u}{\partial z}$$

$$+ \frac{1}{2} \left(\frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right)^2 + \dots$$

$$= \frac{1}{2} \left[\Phi - \{^2 - 4^2 - \}^2 \right]$$

$$\text{by } f_1 = \frac{\partial u}{\partial x} \quad f_2 = \frac{\partial u}{\partial y} ?$$

W. toki rasi unno

$$\frac{\partial f_1}{\partial y} = \frac{\partial f_2}{\partial x}$$

$$\begin{aligned} \frac{\partial}{\partial y} \left(u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right) - \frac{\partial}{\partial x} \left(u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right) = \\ = u \left(\frac{\partial^2 u}{\partial x \partial y} - \frac{\partial^2 v}{\partial y^2} \right) + v \left(\frac{\partial^2 u}{\partial y^2} - \frac{\partial^2 v}{\partial x \partial y} \right) + w \left(\frac{\partial^2 u}{\partial x \partial y} - \frac{\partial^2 v}{\partial y \partial x} \right) \\ + \frac{\partial u}{\partial x} \left(\frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right) + \frac{\partial v}{\partial y} \left(\frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right) + \frac{\partial w}{\partial y} \frac{\partial u}{\partial z} - \frac{\partial v}{\partial x} \frac{\partial v}{\partial z} \\ = - \frac{\partial w}{\partial z} \left(\frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right) \end{aligned}$$

$$\text{A. r. ay } \underbrace{\text{curl } (V \phi)}_{\frac{1}{2} \nabla \phi^2 + V \phi \text{ curl } \phi} = 0 \quad \left. \vphantom{\frac{1}{2} \nabla \phi^2 + V \phi \text{ curl } \phi} \right\} = \text{curl } V \phi \text{ curl } \phi = (V \phi \text{ curl } \phi - (\text{curl } \phi) V) \phi$$

Lo hydro organismi a kridy rasi to spetisone plin rasi toki rasi plin
by migt rasi rasi rasi ~~to hydro organismi rasi rasi rasi~~

$$u \frac{\partial \xi_1}{\partial x} + v \frac{\partial \xi_1}{\partial y} + w \frac{\partial \xi_1}{\partial z} - \left(\xi \frac{\partial u}{\partial x} + \eta \frac{\partial u}{\partial y} + \zeta \frac{\partial u}{\partial z} \right)$$

$$\eta \frac{\partial u}{\partial y} + \zeta \frac{\partial u}{\partial z} = 0$$

$$u \frac{\partial \eta}{\partial x} + v \frac{\partial \eta}{\partial y} + w \frac{\partial \eta}{\partial z} - \left(\xi \frac{\partial v}{\partial x} + \eta \frac{\partial v}{\partial y} + \zeta \frac{\partial v}{\partial z} \right) =$$

$$\frac{\partial \eta}{\partial x} = + \frac{3}{2} \frac{c a x^2}{z^5}$$

$$\frac{\partial \eta}{\partial y} = + \frac{3}{2} \frac{c a y^2}{z^5}$$

$$\frac{\partial \eta}{\partial z} = - \frac{1}{2} \frac{c a}{z^3} + \frac{3}{2} \frac{c a z^2}{z^5}$$

$$= \frac{\mu^2 c^2 a}{h} \left[\frac{1}{n^3} \left(\frac{35}{16} - \frac{3}{2} \frac{a}{n} - \frac{1}{2} \frac{a^3}{n^3} \right) - \frac{3x^2}{n^5} \left(\frac{35}{16} - \frac{5}{2} \frac{a}{n} + \frac{1}{2} \frac{a^3}{n^3} \right) \right]$$

$$P = \frac{\mu^2 c^2 a}{h} \left[\frac{1}{n^3} \left(\frac{35}{8} - \frac{3a}{n} - \frac{a^3}{n^3} \right) - \frac{3x^2}{n^5} \left(\frac{35}{8} - \frac{5a}{n} + \frac{a^3}{n^3} \right) \right]$$

Ramianą $P = \frac{\mu c}{a} \quad \mu c \propto aP$

Łukasz: $\frac{\partial P}{\partial x} \quad \mu \frac{\partial u}{\partial x^2}$ zgodnie z

Równanie termiczne Pascala:

$$K \operatorname{div} \vec{u} = - \left[u_0 \frac{\partial p_0}{\partial x} + v_0 \frac{\partial p_0}{\partial y} + w_0 \frac{\partial p_0}{\partial z} \right] + (K-1) \mu \left[\left(\frac{\partial u_0}{\partial x} \right)^2 + \left(\frac{\partial v_0}{\partial y} \right)^2 + \left(\frac{\partial w_0}{\partial z} \right)^2 \right] + K \Delta \Phi$$

Jednostki nie wolno! K - stała termiczna to Φ - potencjał cyfrowy wlotów: ω - rotacja adiabatyki rotacji mikrocyfrowej!

$$\frac{\partial u_0}{\partial x} = -\frac{3}{4} c a \left[\frac{2x}{n^3} - \frac{3x^3}{n^5} - \frac{2a^2 x}{n^5} + \frac{5a^2 x^3}{n^7} \right] + c \left[\frac{3}{4} \frac{a x}{n^3} + \frac{3}{4} \frac{a^3 x}{n^5} \right]$$

$$\frac{\partial u_0}{\partial x} = -\frac{3}{4} c a \left[\frac{x}{n^3} - \frac{3x^3}{n^5} - \frac{3a^2 x}{n^5} + \frac{5a^2 x^3}{n^7} \right]$$

$$\frac{\partial v_0}{\partial y} = -\frac{3}{4} c a \left[\frac{x}{n^3} - \frac{3x y^2}{n^5} - \frac{a^2 x}{n^5} + \frac{5a^2 x y^2}{n^7} \right]$$

$$\frac{\partial u_0}{\partial z} = -\frac{3}{4} c a \left[\frac{x}{n^3} - \frac{3x z^2}{n^5} - \frac{a^2 x}{n^5} + \frac{5a^2 x z^2}{n^7} \right]$$

$$\frac{\partial u_0}{\partial y} = -\frac{3}{4} c a \left[-\frac{3x^2 y}{n^5} + \frac{5a^2 x^2 y}{n^7} \right] + c \left[\frac{3a y}{4 n^3} + \frac{3a^3 y}{4 n^5} \right]$$

$$\frac{\partial u_0}{\partial y} = -\frac{3}{4} c a \left[-\frac{3x^2 y}{n^5} + \frac{5a^2 x^2 y}{n^7} - \frac{4}{n^3} - \frac{a^2}{n^5} \right]$$

$$\frac{\partial u_0}{\partial z} = -\frac{3}{4} c a \left[-\frac{3x^2 z}{n^5} + \frac{5a^2 x^2 z}{n^7} - \frac{2}{n^3} - \frac{a^2}{n^5} \right]$$

$$\frac{\partial u_0}{\partial x} = -\frac{3}{4} ca \left[\left(1 - \frac{a^2}{z^2}\right) \frac{y}{z^3} - \frac{3x^2 y}{z^5} \left(1 - \frac{a^2}{z^2}\right) + \frac{2a^2 x y}{z^7} \right]$$

$$\frac{\partial u_0}{\partial x} = -\frac{3}{4} ca \left[\left(1 - \frac{a^2}{z^2}\right) \frac{y}{z^3} - \frac{3x^2 y}{z^5} + \frac{5a^2 x^2 y}{z^7} \right]$$

$$\frac{\partial u_0}{\partial z} = -\frac{3}{4} ca \left[\frac{2a^2 x y}{z^7} - \frac{3x y z}{z^5} \left(1 - \frac{a^2}{z^2}\right) \right]$$

$$\frac{\partial u_0}{\partial z} = -\frac{3}{4} ca \left[-\frac{3x y z}{z^5} + \frac{5a^2 x y z}{z^7} \right] =$$

$$\frac{\partial u_0}{\partial y} =$$

$$\frac{\partial u_0}{\partial x} = -\frac{3}{4} ca \left[\left(1 - \frac{a^2}{z^2}\right) \frac{2}{z^3} - \frac{3x^2 z}{z^5} + \frac{5a^2 x^2 z}{z^7} \right]$$

$$\frac{\partial u_0}{\partial x} = -\frac{3}{4} ca \cdot x \left[\frac{1}{z^3} - \frac{3x^2}{z^5} - \frac{a^2}{z^5} + \frac{5a^2 x^2}{z^7} \right]$$

$$\frac{\partial u_0}{\partial y} = -\frac{3}{4} ca \cdot y \left[-\frac{1}{z^3} - \frac{3x^2}{z^5} - \frac{a^2}{z^5} + \frac{5a^2 x^2}{z^7} \right]$$

$$\frac{\partial u_0}{\partial z} = -\frac{3}{4} ca \cdot z \left[\right]$$

$$\frac{\partial u_0}{\partial x} = -\frac{3}{4} ca \cdot y \left[\frac{1}{z^3} - \frac{3x^2}{z^5} - \frac{a^2}{z^5} + \frac{5a^2 x^2}{z^7} \right]$$

$$\frac{\partial u_0}{\partial y} = -\frac{3}{4} ca \cdot x \left[\frac{1}{z^3} - \frac{3y^2}{z^5} - \frac{a^2}{z^5} + \frac{5a^2 y^2}{z^7} \right]$$

$$\frac{\partial u_0}{\partial z} = -\frac{3}{4} ca \cdot \frac{x y z}{z^5} \left[-3 + \frac{5a^2}{z^2} \right]$$

$$\frac{\partial u_0}{\partial y} = -\frac{3}{4} ca \cdot z \left[\frac{1}{z^3} - \frac{3x^2}{z^5} - \frac{a^2}{z^5} + \frac{5a^2 x^2}{z^7} \right]$$

$$\frac{\partial u_0}{\partial x} = -\frac{3}{4} ca \cdot x \left[\frac{1}{z^3} - \frac{3z^2}{z^5} - \frac{a^2}{z^5} + \frac{5a^2 z^2}{z^7} \right]$$

Uprytizone usplechnenie ineregi:

$$\frac{f}{\rho} = R\theta$$

sem vykre R, ten minize p zate tu minize uply ineregi. ~~zate R~~ zate ravniuzi vedly

$$\frac{f}{\rho} = \frac{f_0}{\rho_0}$$

$$\rho \approx \frac{1}{R} \approx \rho_0$$

$$u = u_0 + \rho_0 u' + \frac{\rho_0^2}{2} u'' +$$

$$\rho_0 \frac{f_0}{\rho_0} \left(u_0 \frac{\partial u_0}{\partial x} + \dots \right) + \rho_0 \left[u_0 \frac{\partial u'}{\partial x} + u' \frac{\partial u_0}{\partial x} + \dots \right] = \left\{ + \frac{\partial f_0}{\partial x} + \rho_0 \frac{\partial u'}{\partial x} = \right.$$

$$= \mu \left[\Delta^2 u_0 + \rho_0 \Delta^2 u' + \dots \right]$$

$$\rho_0 \operatorname{div}_0 + \rho_0 (p' \operatorname{div}_0 + \rho_0 \operatorname{div}') + k \left(u_0 \frac{\partial f_0}{\partial x} + \dots \right) + k \rho_0 \left[u' \frac{\partial f_0}{\partial x} + u_0 \frac{\partial f'}{\partial x} + \dots \right] =$$

$$= \Phi_0 + \rho_0 \Psi$$

$$\begin{cases} \frac{\partial f_0}{\partial x} = \frac{\mu}{3} \frac{\partial}{\partial x} \operatorname{div}_0 + \mu \Delta^2 u_0 \\ \rho_0 \operatorname{div}_0 + k \left(u_0 \frac{\partial f_0}{\partial x} + \dots \right) = (\Phi_0) \Phi_0 \end{cases}$$

Popraska.

$$\left. \begin{aligned} \frac{\partial f_0}{\partial x} &= \frac{\mu}{3} \frac{\partial}{\partial x} \operatorname{div}_0 + \mu \Delta^2 u_0 \\ \frac{\partial f_1}{\partial x} &= \frac{\mu}{3} \frac{\partial}{\partial x} \operatorname{div}' + \mu \Delta^2 u' \\ \frac{\partial f_2}{\partial x} &= \frac{\mu}{3} \frac{\partial}{\partial x} \operatorname{div}'' + \mu \Delta^2 u'' \end{aligned} \right\}$$

Isotomizatsie: $f_3 + \frac{\partial f_2}{\partial x} = \frac{\mu}{3} \frac{\partial}{\partial x} \operatorname{div}''' + \mu \Delta^2 u'''$

$$p' \operatorname{div}_0 + \rho_0 \operatorname{div}' + \left(u' \frac{\partial f_0}{\partial x} + \dots \right) + \left(u_0 \frac{\partial f'}{\partial x} + \dots \right) = 0$$

$$\Delta^2 f' + \left(\frac{\partial f_1}{\partial x} + \frac{\partial f_2}{\partial x} + \frac{\partial f_3}{\partial x} \right) = \frac{\mu}{3} \Delta^2 \operatorname{div}'$$

$$\operatorname{div} [\nabla \delta \nabla] = \operatorname{div} \left[\nabla \frac{\delta^2}{2} + \nabla \delta \operatorname{curl} \delta \right] = \nabla^2 \frac{\delta^2}{2} + \delta \operatorname{curl}^2 \delta - (\operatorname{curl} \delta)^2$$

$$= \mathbb{F}$$

$$p' = \frac{\mu}{3} \operatorname{div}' + \int \frac{f_1 dv}{\sin^2} + \varphi$$

$$\frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} = 2 \frac{4z}{z^5} x \left[-3 + \frac{5a^2}{z^2} \right]$$

$$\frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} = 2x \left[-\frac{3x^2}{z^5} - \frac{a^2}{z^5} + \frac{5a^2 x^2}{z^7} \right] = 2x \left[-\frac{a^2}{z^5} + \frac{x^2}{z^5} \left[-3 + \frac{5a^2}{z^2} \right] \right]$$

$$\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} = 2y \left[\begin{array}{c} \uparrow \\ M \end{array} \right]$$

$$\frac{\partial u}{\partial x} = x \left(M + \frac{1}{z^3} - \frac{2a^2}{z^5} \right)$$

$$\frac{\partial v}{\partial y} = x \left(M + \frac{1}{z^3} \right) \quad \left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial y} \right)^2 + \left(\frac{\partial w}{\partial z} \right)^2 =$$

$$\frac{x^2}{z^6} \left\{ \left[\left(1 - \frac{3a^2}{z^2} \right) - \frac{2}{z^2} \left(\frac{3}{z^2} - \frac{5a^2}{z^4} \right) \right]^2 + \left[\left(1 - \frac{a^2}{z^2} \right) - \frac{1}{z^2} \left(\frac{3}{z^2} - \frac{5a^2}{z^4} \right) \right]^2 + \left[\left(1 - \frac{a^2}{z^2} \right) - \frac{1}{z^2} \left(\frac{3}{z^2} - \frac{5a^2}{z^4} \right) \right]^2 \right\}$$

$$= \frac{x^2}{z^6} \left\{ 1 - \frac{6a^2}{z^2} + \frac{9a^4}{z^4} - 2z^2 \left(\frac{3}{z^2} - \frac{5a^2}{z^4} \right) + \frac{3a^2 x^2}{z^2} + \frac{a^2 y^2}{z^2} + \frac{a^2 z^2}{z^2} \right\}$$

$$= \frac{x^2}{z^6} \left\{ 1 - \frac{6a^2}{z^2} + \frac{9a^4}{z^4} - 6 + \frac{10a^2}{z^2} + \frac{4a^2 x^2}{z^2} \left(\frac{3}{z^2} - \frac{5a^2}{z^4} \right) + \frac{6a^2}{z^2} - \frac{10a^4}{z^4} + (x^2 + y^2 + z^2) \left(\frac{3}{z^2} - \frac{5a^2}{z^4} \right)^2 \right\}$$

$$= \frac{x^2}{z^6} \left\{ -3 + \frac{6a^2}{z^2} + \frac{9a^4}{z^4} + \frac{4a^2 x^2}{z^2} \left(\frac{3}{z^2} - \frac{5a^2}{z^4} \right) + (x^2 + y^2 + z^2) \left(\frac{3}{z^2} - \frac{5a^2}{z^4} \right)^2 \right\}$$

$$\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial y} \right)^2 + \left(\frac{\partial w}{\partial z} \right)^2 = \frac{4}{z^6} \left\{ \frac{N^2 x^2 y^2 z^2}{z^4} + (2^2 + y^2) \left[-\frac{a^2}{z^2} + \frac{x^2 N}{z^2} \right]^2 \right\}$$

$$= \frac{4}{z^6} \left\{ \frac{N^2 x^2 y^2 z^2}{z^4} + a^4 (2^2 + y^2) - 2a^2 x^2 (2^2 + y^2) N + x^4 (2^2 + y^2) N^2 \right\}$$

$$\Phi = \frac{2}{n^{10}} \left\{ \begin{aligned} & -3x^2z^4 \\ & a^4x^2 + 6a^2x^2 - 4a^2x^2N + (x^4+y^4+z^4)N^2 + \\ & 2a^2(z^2+y^2) - 4a^2x^2(z^2+y^2)N + 2x^4y^2z^2N^2 + 2N^2x^2y^2z^2 \\ & - 4a^2Nx^2 \left[\underbrace{x^2 + 2z^2 + 2y^2}_{(2x^2+z^2+y^2)} \right] + N^2x^2 \left\{ \underbrace{x^4+y^4+z^4 + 2x^2z^2 + 2x^2y^2 + 2y^2z^2}_{= N^2x^2z^4} \right\} \end{aligned} \right\}$$

$$= \frac{2}{n^{10}} \left\{ \begin{aligned} & -3x^2z^4 \\ & a^4(x^2 + 2z^2 - 2x^2) + 6a^2x^2x^2 - 4a^2Nx^2 \cancel{\dots} + N^2x^2z^4 = \\ & \underbrace{-3x^2z^4}_{-3x^2z^4} = 2x^2a^4 + a^4x^2 + 6a^2x^2x^2 - 4a^2x^2z^2N + \cancel{\dots} + x^2z^4N^2 \end{aligned} \right\}$$

$$N = -3 + 5 \frac{a^2}{n^2}$$

$$\begin{aligned} & -3x^2z^4 \\ & = 2a^4x^2 + a^4x^2 + 6a^2x^2x^2 + 12a^2x^2x^2 - 20a^4x^2 - \cancel{\dots} + \\ & + 9x^2z^4 - 30a^2x^2x^2 + 25a^4x^2 = \\ & = 2a^4x^2 + 4a^4x^2 - 12a^2x^2x^2 - \cancel{\dots} + 6x^2z^4 \end{aligned}$$

$$\begin{aligned} \Phi &= 2 \cdot \frac{9}{16} \frac{c^2 a^2}{n^{10}} \left\{ \dots \right\} \\ &= \frac{9}{8} \frac{c^2 a^2}{n^4} \left\{ \left[2 \frac{a^4}{n^4} - 12 \frac{a^2 x^2}{n^4} + 4 \frac{a^4 x^2}{n^6} \right] - \cancel{\dots} + \dots \right\} \end{aligned}$$

$$k \operatorname{div}' + \left(u_0 \frac{\partial f_0}{\partial x} + \dots \right) = (k-1) \Phi \mu$$

$$\operatorname{div}' = -\frac{1}{k} \left(u_0 \frac{\partial f_0}{\partial x} - \dots \right) + \frac{k-1}{k} \mu \Phi + \dots$$

zatem doch o výrazu Φ jako $\Delta^2 \eta$

Do dyżurnych:

$$\alpha \Delta^2 \left(\frac{x^4}{2^{10}} \right) = 12 \frac{x^2}{2^{10}} + 10 \frac{x^4}{2^{12}}$$

$$\beta \Delta^2 \left(\frac{x^4}{2^8} \right) = 12 \frac{x^2}{2^8} - 8 \frac{x^4}{2^{10}}$$

$$\gamma \Delta^2 \left(\frac{x^2}{2^8} \right) = \frac{2}{2^8} + 24 \frac{x^2}{2^{10}}$$

$$\delta \Delta^2 \left(\frac{x^2}{2^6} \right) = \frac{2}{2^6} + 6 \frac{x^2}{2^8}$$

$$\varepsilon \Delta^2 \left(\frac{x^2}{2^4} \right) = \frac{2}{2^4} - 4 \frac{x^2}{2^6}$$

$$\zeta \Delta^2 \left(\frac{1}{2^4} \right) = \frac{12}{2^6}$$

$$\eta \Delta^2 \left(\frac{1}{2^2} \right) = \frac{2}{2^2}$$

$$\vartheta \Delta^2 \left(\frac{1}{2^6} \right) = \frac{30}{2^8}$$

$$\alpha = a^6$$

$$\beta = \frac{3}{4} a^4$$

$$\mu = -\frac{1}{8} a^6$$

$$\delta = -\frac{29}{6} a^4$$

$$\vartheta = \frac{3}{40} a^6$$

$$\varepsilon = -\frac{9}{4} a^2$$

$$\eta = +\frac{9}{4} a^2$$

$$\zeta = \frac{29}{36} a^4$$

~~10 a^6~~

$$10 \alpha \neq 10 a^6$$

$$+ 8 \beta \neq 6 a^4$$

$$12 \alpha + 24 \beta \neq 9 a^6$$

$$12 \beta + 6 \delta = -20 a^4$$

$$+ 30 \vartheta$$

$$2 \mu \neq 2 a^6$$

$$-4 \varepsilon \neq 9 a^2$$

$$2 \delta + 12 \zeta = 0$$

$$2 \varepsilon + 2 \eta = 0$$

$$4 \alpha + 8 \mu = 3 a^6$$

$$\mu = \frac{3 a^6 - 4 a^6}{8}$$

$$3 \delta = -10 a^4 - 6 \beta = -10 a^4 - \frac{9}{2} a^4 = -\frac{29}{2} a^4$$

$$30 \vartheta = 2 a^6 + \frac{1}{4} a^6 = \frac{9}{4} a^6$$

$$\Phi = \Delta^2 \chi$$

$$\chi = \frac{9 c^2}{8} \left[\frac{a^6 x^4}{2^{10}} + \frac{3}{4} \frac{a^4 x^4}{2^8} - \frac{1}{8} \frac{a^6 x^2}{2^8} - \frac{29}{6} \frac{a^4 x^2}{2^6} - \frac{9}{4} \frac{a^2 x^2}{2^4} + \frac{29}{36} \frac{a^4}{2^4} + \frac{9}{4} \frac{a^2}{2^2} + \frac{3}{40} \frac{a^6}{2^6} \right]$$

$$\frac{k-1}{k} \mu = \frac{k-1}{k} \mu \frac{q c^2}{8} \left[\frac{a^6 x^4}{2^{10}} + \frac{2}{4} \frac{a^4 x^4}{2^8} - \frac{1}{8} \frac{a^6 x^2}{2^8} - \frac{29}{6} \frac{a^4 x^2}{2^6} - \frac{9}{4} \frac{a^2 x^2}{2^4} \right. \\ \left. + \frac{3}{40} \frac{a^6}{2^6} + \frac{29}{26} \frac{a^4}{2^4} + \frac{9}{4} \frac{a^2}{2^2} \right]$$

$$\frac{\partial}{\partial x} = \frac{k-1}{k} \mu \frac{q c^2}{8} \left[4 \frac{a^6 x^3}{2^{10}} + 3 \frac{a^4 x^3}{2^8} - \frac{1}{4} \frac{a^6 x}{2^8} - \frac{29}{3} \frac{a^4 x}{2^6} - \frac{9}{2} \frac{a^2 x}{2^4} + \right. \\ \left. - 10 \frac{a^6 x^5}{2^{12}} - 6 \frac{a^4 x^5}{2^{10}} + \frac{a^6 x^3}{2^{10}} + 29 \frac{a^4 x^3}{2^8} + 9 \frac{a^2 x^3}{2^6} \right. \\ \left. - \frac{9}{20} \frac{a^6 x}{2^8} - \frac{29}{9} \frac{a^4 x}{2^6} - \frac{9}{2} \frac{a^2 x}{2^4} \right]$$

$$x=a: \quad [] = -16 \frac{x^5}{a^6} + 46 \frac{x^3}{a^4} - \frac{2033}{90} \frac{x}{a}$$

$$\begin{array}{r} 3 \\ + 54 \\ \hline 116 \\ \frac{116}{17.3} + \frac{99}{20} + \frac{29}{9} = \\ \frac{173}{12} + \frac{865}{2595} + \\ \hline = \frac{2595}{180} \end{array}$$

$$\begin{array}{r} 2595 \\ 891 \\ \hline 580 \\ 4066 \\ \hline 180 \end{array} = \frac{2033}{90}$$

$$(6D)4 =$$

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$$- \frac{9}{8} \frac{c^2 a^2 x^3}{2^8} \left(1 - \frac{a^2}{2^2}\right) + \frac{3}{2} \frac{c^2 a^2 x^2}{2^5} \left(1 - \frac{2}{4} \frac{a}{2} - \frac{1}{4} \frac{a^3}{2^3}\right) +$$

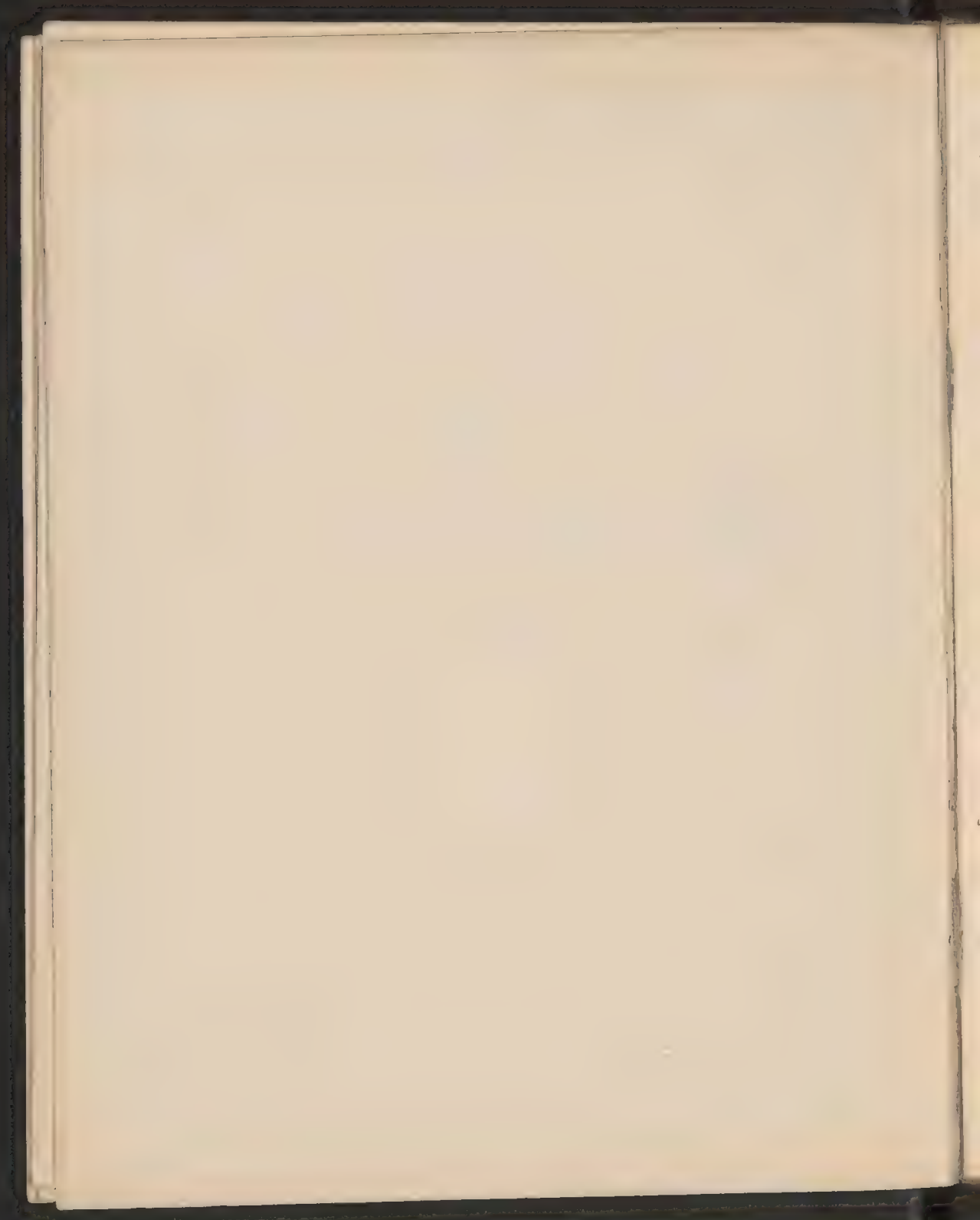
$$- \frac{9}{8} \frac{c^2 a^2 x y^2}{2^8} \left(\right) - \frac{9}{8} \frac{c^2 a^2 x^2}{2^8} \left(\right) + \frac{3}{8} \frac{c^2 a^2 x^2}{2^6} \left(1 - \frac{a^2}{2^2}\right)$$

$$= - \frac{9}{8} \frac{c^2 a^2 x^2}{2^6} \left(\right) + \frac{3}{8} \dots$$

$$= - \frac{3}{4} \frac{c^2 a^2 x^2}{2^6} \left(1 - \frac{a^2}{2^2}\right) + \frac{3}{2} \frac{c^2 a^2 x^2}{2^5} \left(\right)$$

$$- \left\{ \frac{3}{8} \frac{c^2 a^2 x^2}{2^3} \left[\frac{4}{2^3} - \frac{3y^2}{2^5} - \frac{a^2}{2^5} + \frac{5y^4}{2^7} \right] - \frac{3}{8} \frac{c^2 a^2 x y^2}{2^8} \left[2 + \frac{5a^2}{2^2} \right] \right\}$$

$$= \frac{3}{4} \frac{c^2 a^2 x^2}{2^6} \left\{ -1 + \frac{a^2}{2^2} + \frac{2x}{a} - \frac{3}{2} - \frac{1}{2} \frac{a^2}{2^2} - \frac{1}{2} + \frac{a^2}{2^2} \right\}$$



$$u \frac{\partial v}{\partial x} + v \frac{\partial u}{\partial y} + u \frac{\partial v}{\partial z} = \frac{9}{16} c^2 a^2 (1 - \frac{a^2}{2^2}) \frac{x}{2^3} \left\{ xy \left[\frac{1}{2^3} - \frac{3x^2}{2^5} - \frac{a^2}{2^5} + \frac{5a^2 x^2}{2^7} \right] + \right. \\ \left. xy \left[\frac{1}{2^3} - \frac{3x^2}{2^5} - \frac{a^2}{2^5} + \frac{5a^2 x^2}{2^7} \right] + \frac{xy z^2}{2^5} \left[-3 + \frac{5a^2}{2^2} \right] \right\} - \frac{3c^2 a^2}{4} y \uparrow (1 - \frac{3}{4} \frac{a^2}{2} - \frac{1}{4} \frac{a^2}{2^3})$$

$$= \frac{9}{16} c^2 a^2 (1 - \frac{a^2}{2^2}) \frac{x}{2^3} \left\{ 2xy \left(\frac{1}{2^3} - \frac{a^2}{2^5} \right) - \frac{3xy}{2^3} + \frac{5a^2 xy}{2^5} \right\} - \uparrow$$

$$- \frac{xy}{2^3} + \frac{5a^2 xy}{2^5}$$

$$= \frac{9}{16} c^2 a^2 (1 - \frac{a^2}{2^2}) \frac{xy}{2^6} \left[-1 + \frac{3a^2}{2^2} \right] - \frac{3}{4} c^2 a^2 y \frac{1}{2^3} \left[1 - \frac{3}{4} \frac{a^2}{2} - \frac{1}{4} \frac{a^2}{2^3} \right] \left[1 - \frac{3a^2}{4^2} - \frac{a^2}{2^2} + \frac{5a^2 x^2}{2^4} \right]$$

$$= -\frac{3}{4} c^2 a^2 y \frac{1}{2^3} \left[1 - \frac{3x^2}{2^2} - \frac{a^2}{2^2} + \frac{5a^2 x^2}{2^4} \right] + \frac{3}{4} c^2 a^2 y \left\{ \frac{3}{4} a^2 x^2 \left(-1 + \frac{2a^2}{2^2} - \frac{6a^2}{2^4} \right) + \right.$$

$$\left. + \frac{3}{4} a^2 \left(x^2 - \frac{3x^2}{2^2} - \frac{a^2}{2^2} + \frac{5a^2 x^2}{2^4} \right) + \frac{1}{4} a^3 \left(1 - \frac{3x^2}{2^2} - \frac{a^2}{2^2} + \frac{5a^2 x^2}{2^4} \right) \right\}$$

$$\{ \} = +\frac{3}{4} a^2 x^2 - 3a^2 x^2 - \frac{1}{2} a^3 + \frac{3x^2}{2^2} - \frac{1}{4} \frac{a^5}{2^2} - \frac{13}{4} \frac{a^5 x^2}{2^4}$$

$$= -\frac{3}{4} c^2 a^2 y \frac{1}{2^3} \left[1 - \frac{3x^2}{2^2} - \frac{a^2}{2^2} + \frac{5a^2 x^2}{2^4} \right] + \frac{3}{4} c^2 a^2 y \left\{ \right.$$

$$u \frac{\partial u}{\partial x} + \dots = -\frac{3}{4} c^2 a^2 \frac{1}{2^3} \left[1 - \frac{3x^2}{2^2} - \frac{a^2}{2^2} + \frac{5a^2 x^2}{2^4} \right] + \frac{3}{4} c^2 a^2 \left\{ \right.$$

$$\Phi = \frac{1}{2} c^2 a^2 \left[\frac{1}{4} \left(\frac{2^2}{2^6} + \frac{4^2}{2^6} \right) + \frac{3}{2} c^2 a^2 \left[\frac{1}{2^3} + \frac{3x^2}{2^5} + \frac{3x^2}{2^5} - \frac{5a^2 x^2}{2^7} - \frac{3a^2}{2^6} - \frac{6a^2}{2^6} + \frac{6a^2 x^2}{2^6} - \right. \right.$$

$$- \frac{5a^2}{2^{10}} - \frac{3x^2}{2^5} \left[x + \frac{3x^2}{2^2} + \frac{3x^2}{2^2} - \frac{5a^2 x^2}{2^4} - \frac{3a^2}{2^3} - \frac{2a^2}{2^3} + \frac{6a^2 x^2}{2^5} - \frac{5a^2 x^2}{2^7} \right] + \frac{x}{2^3} \left[\frac{6a^2}{2^2} - \right.$$

$$- \frac{6a^2}{2^4} - \frac{6a^2 x^2}{2^4} - \frac{10a^2 x^2}{2^4} + \frac{40a^2 x^2}{2^6} - \frac{6a^2 x^2}{2^6} + \frac{9a^2 x^2}{2^6} + \frac{6a^2 x^2}{2^6} + \frac{12a^2 x^2}{2^6} - \frac{30a^2 x^2}{2^7} - \frac{2a^2 x^2}{2^7} + \frac{7a^2 x^2}{2^9} \left. \right]$$

$$- \frac{2}{2^3} \left[x - \frac{3x^2}{2^2} - \frac{3x^2}{2^2} + \frac{5a^2 x^2}{2^4} \right] + \frac{2}{2^6} \left[\frac{3}{4} a^2 x^2 - \frac{3a^2 x^2}{2^2} - \frac{1}{2} a^3 + \frac{3x^2}{2^2} - \frac{1}{4} \frac{a^5}{2^2} - \frac{13}{4} \frac{a^5 x^2}{2^4} \right]$$

$$- (y^2 + z^2) \left[\frac{15x^2}{2^7} + \frac{5a^2}{2^7} - \frac{35a^2 x^2}{2^9} + 3 \frac{a^2}{2^6} - 18 \frac{a^2 x^2}{2^8} + 3 \frac{a^3}{2^8} - 8 \frac{a^3 x^2}{2^{10}} + 2 \frac{a^5}{2^{10}} + \frac{65a^5 x^2}{2^{12}} \right]$$

$$\Phi = \frac{c^2 a^2}{4} \left(\frac{r^2 - x^2}{2b} \right) + \frac{3}{2} c^2 a$$

$$-6 \frac{x^3}{2^6} - \frac{3}{2} \frac{x^4}{2^4} + \frac{x^2}{2^8} + \frac{3x^2}{2^5} - \frac{3}{2^3}$$

Any particular u or v ought to be:

$$\rho \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + \cancel{u \frac{\partial \rho}{\partial x}} + \cancel{v \frac{\partial \rho}{\partial y}} + \cancel{w \frac{\partial \rho}{\partial z}} = 0 \quad \underline{\underline{\text{div} = 0}}$$

istotni delo da x=0

istotini di' 20 dla $x=2$
to enozi; sklopoje x, y ^{zato stane da paimshu!} $\sqrt{}$ kaimuk predu i vuvdini

$$\frac{\partial u}{\partial z} = 0 \text{ | powierzchni } v=0, \quad \frac{\partial v}{\partial x} = 0, \quad \frac{\partial w}{\partial x} = 0, \quad \frac{\partial w}{\partial y} = 0$$

$$u=0 \quad \frac{\partial u}{\partial x} = 0 \quad \frac{\partial u}{\partial y} = 0 \quad \frac{\partial u}{\partial z} \geq 0$$

$$u=0 \quad \frac{\partial u}{\partial x}=0 \quad \frac{\partial u}{\partial y}=0 \quad \frac{\partial u}{\partial z}=0$$

Jinli jednoduše rozostřování III:

Jediné řešení $\frac{III}{k-1}$
 $\frac{k-1}{k-1} + \left(\frac{\partial k}{\partial \theta} \right) = (k-1) \left[\frac{\Phi}{\gamma} + \kappa \Delta \theta \right]$

$$0 = \cancel{\left(\frac{\partial u}{\partial z}\right)^2} + \kappa \Delta^2 \theta$$

then in any point of the surface $\kappa \frac{\partial^2 \theta}{\partial n^2} = \frac{1}{R} \left(\frac{\partial u}{\partial x} \right)^2$

wie so wichtig ist Stern?

wie für die folgenden ist dann? $\int \frac{1}{x^2} dx = -\frac{1}{x} + C$ $\int \frac{1}{x^3} dx = -\frac{1}{2x^2} + C$ $\int \frac{1}{x^4} dx = -\frac{1}{3x^3} + C$

K is misce mechanism : $K = 0.00058 \cdot 42 \cdot 10^6 = 42.58 = 243$

Nie zanikające κ stażyna się jako równanie III:

270
Φ

$$\theta = \theta_0 + \frac{1}{p} \theta'$$

$$k \operatorname{div}' = -\left(u_0 \frac{\partial \rho_0}{\partial x} + v_0 \frac{\partial \rho_0}{\partial y} + w_0 \frac{\partial \rho_0}{\partial z}\right) + (k-1) \left[\Phi_0 + \kappa \Delta^2 \theta_0\right]$$

$$\rho = \rho_0 + \frac{1}{p} \rho' + \frac{1}{2} \frac{1}{p^2} \rho'' + \dots$$

$$\left\{ \begin{array}{l} \frac{\partial \rho_0}{\partial x} = \frac{\mu}{\gamma} \frac{\partial \operatorname{div}_0}{\partial x} + \mu \Delta^2 u_0 \\ \dots \end{array} \right.$$

$$\frac{\partial \rho'}{\partial x} = \frac{\mu}{\gamma} \frac{\partial \operatorname{div}'}{\partial x} + \mu \Delta^2 u'$$

$$\operatorname{div}_0 = 0$$

występują do anasemia p, u, v, w , ~~z~~

$$\frac{\partial}{\partial x} (\rho_0 u_0) + \frac{\partial}{\partial y} (\rho_0 v_0) + \frac{\partial}{\partial z} (\rho_0 w_0) = 0$$

$$\rho_0 \operatorname{div}_0 + u_0 \frac{\partial \rho_0}{\partial x} + v_0 \frac{\partial \rho_0}{\partial y} + w_0 \frac{\partial \rho_0}{\partial z} = 0$$

hydrodynamiczne przez $\rho_0 = \text{const}$

~~zatem~~

(ale czy koniecznie?)

Przebiegi:

$$\frac{dx}{u_0} = \frac{dy}{v_0} = \frac{dz}{w_0} = \dots$$

składowe prędkości linii prądu

zatem one są równymi współrzędnymi wzdłuż

linii prądu i niezależnymi, ale od położenia

drugiej współrzędnej niezależne, zatem jednocześnie,

bo w mechanicznych ρ hydrodynamiczne niezależne

zatem w ogóle $\rho = \text{const}$

$$\left(\rho + \frac{1}{p} \rho' + \dots \right) = R \left(\theta_0 + \frac{1}{p} \theta' + \dots \right) / \left(\cos \theta + \frac{1}{p} \theta' + \dots \right)$$

zatem θ_0 ~~niezależne~~ = const

$$\frac{d\lambda}{\lambda} = \frac{d\theta}{\theta} + \frac{d\rho}{\rho}$$

$$II. \frac{\partial \lambda}{\partial x} = \frac{\mu}{3} \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \mu \nabla^2 u$$

$$IV. \rho = R \theta \rho$$

$$III. \frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} = 0$$

$$IV. k \rho \operatorname{div} + \left(u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} \right) = (k-1) \left[\mu \Phi + \kappa \Delta^2 \theta \right]$$

$$II. \rho \operatorname{div} + u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} = 0$$

$$II. \operatorname{div} + \frac{u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z}}{\rho} = - \frac{u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z}}{\theta} = 0$$

$$III. (1-k) \left(u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} \right) + k \frac{\rho}{\theta} \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) = (k-1) \left[\mu \Phi + \kappa \Delta^2 \theta \right]$$

$$\frac{k R \rho}{k-1} \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) = \mu \Phi + \kappa \Delta^2 \theta + \left(u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} \right)$$

jeżeli ρ mała w pewnym miejscu to taki div będzie mała
 a więc $\dots \rho = \rho_0 + \frac{1}{\rho_0} \rho' + \dots$

$$\rho = \rho_0 + \rho' \quad \text{inst}$$

$$II). (\rho_0 + \rho') \left(\text{div}_0 + \frac{1}{\rho_0} \text{div}' + \dots \right) + \left(u_0 + \frac{1}{\rho_0} u' + \dots \right) \frac{\partial \rho'}{\partial x} + \left(v_0 + \frac{1}{\rho_0} v' + \dots \right) \frac{\partial \rho'}{\partial y} + \dots = 0$$

$$1). \text{div}_0 = 0$$

$$2). \cancel{\rho \text{div}_0} + \text{div}' + u_0 \frac{\partial \rho'}{\partial x} + v_0 \frac{\partial \rho'}{\partial y} + \dots = 0$$

$$\text{div}' = - \left(u_0 \frac{\partial \rho'}{\partial x} + v_0 \frac{\partial \rho'}{\partial y} + u_0 \frac{\partial \rho'}{\partial z} \right)$$

$$IV). \rho_0 + \frac{1}{\rho_0} \rho' + \dots = R \left(\theta_0 + \frac{1}{\rho_0} \theta' + \dots \right) (\rho_0 + \rho')$$

jeżeli ρ_0 to samo, wtedy $\rho = \rho_0$ etc.

$$1). \rho_0 = R \theta_0 \rho_0$$

$$2). \rho' = R \theta' + R \theta_0 \rho'$$

$$I). \frac{\partial \rho_0}{\partial x} = \frac{1}{\rho_0} \frac{\partial \rho_0}{\partial x} + \dots \nabla^2 u_0$$

$$2). \frac{\partial \rho'}{\partial x} = \frac{1}{\rho_0} \frac{\partial \rho'}{\partial x} + \dots \nabla^2 u'$$

$$II). k \left(\rho_0 + \frac{1}{\rho_0} \rho' + \dots \right) \left(\cancel{\text{div}_0} + \frac{1}{\rho_0} \text{div}' + \dots \right) + \left(u_0 + \frac{1}{\rho_0} u' + \dots \right) \left(\frac{\partial \rho_0}{\partial x} + \frac{1}{\rho_0} \frac{\partial \rho'}{\partial x} + \dots \right) =$$

$$= (k-1) \left[\mu \left(\Phi_0 + \frac{1}{\rho_0} \Phi' + \dots \right) + k \left(\Delta^2 \theta_0 + \frac{1}{\rho_0} \Delta^2 \theta' + \dots \right) \right]$$

\star $\Delta \theta_0$:

$$\frac{kR}{k-1} (\rho_0 + \rho') \left[\left(u_0 + \frac{1}{\rho_0} u' + \dots \right) \left(\frac{\partial \theta_0}{\partial x} + \frac{1}{\rho_0} \frac{\partial \theta'}{\partial x} + \dots \right) + \dots \right] = \mu \Phi_0 + \frac{1}{\rho_0} \Phi' + \dots$$

$$+ \mu \left(u_0 + \frac{1}{\rho_0} u' + \dots \right) \left(\nabla^2 u_0 + \frac{1}{\rho_0} \nabla^2 u' + \dots \right) + k \Delta^2 \theta_0 + \frac{1}{\rho_0} \Delta^2 \theta' + \dots$$

$$k \frac{\mu \rho_0}{\rho_0} \text{div}' + u_0 \frac{\partial \rho_0}{\partial x} = (k-1) \left[\mu \Phi_0 + k \Delta^2 \theta_0 \right]$$

$$kR \theta_0 \text{div}' + u_0 \frac{\partial \rho_0}{\partial x} = \nearrow$$

czy dla θ równani formy:

$$\Delta^2 \theta + \theta \varphi(x, y, z) = \varphi(x, y, z)$$

$$p = \text{const}$$

$$= f(\underbrace{P, \Theta}_{\text{parametry}}, x, y, z)$$

$\frac{1}{P}$ - parametry P : każdy raz inny wykład p i
 $\frac{1}{P}$ = parametry

Czy będzie można staric:

$$p = \text{const} + p_0 + \frac{1}{P} p' + \frac{1}{P^2} p'' + \dots$$

$$= f(0, \Theta, x, y, z) + \frac{1}{P} \frac{\partial f}{\partial p} + \dots$$

można będzie napisać II dla ω :

stąd się równani dla θ o 2 typy równań II dla ω

złomujemy dla 2 II III:

$$II. (1-k) \left(u \frac{\partial \theta}{\partial x} + \dots \right) + k \frac{1}{\theta} \left(u \frac{\partial \theta}{\partial x} + \dots \right)$$

$$= (k-1) \left[\frac{1}{\theta} \Phi \ln \frac{\theta}{\theta_0} \right]$$

zmienna mechaniczna
 $= 0.000057 \cdot 4.1 \cdot 10^6$

Obróżyć jako pierwszą przybliżenie wykład adiacat:

$$\mu \Phi + \kappa \Delta^2 \theta = 0$$

2 typy θ' o 2 typy równań I dla

Obróżyć jako pierwszą przybliżenie wykład istnienia

$$\mu \Phi + \kappa \Delta^2 \theta' = - \left(u \frac{\partial \theta}{\partial x} + \dots \right)$$

Która 2 metody tych metod najwygodniejsza?

Metoda:

Przemyślenie: $\text{div} = 0$

$$\text{I). } \nabla^2 \Phi_0 = \mu \Delta^2 u_0$$

$$\left\{ \begin{array}{l} \text{div}_0 = 0 \end{array} \right.$$

~~Drugie~~ ~~III~~ ~~IV~~. $u_0 \frac{\partial \rho_0}{\partial x} + v_0 \frac{\partial \rho_0}{\partial y} + w_0 \frac{\partial \rho_0}{\partial z} = (k-1) [\mu \Phi_0 + \kappa \Delta^2 \theta_0]$

2 typy θ_0

Drugie przemyślenie:

$$\text{IV). } \frac{dp}{\rho} = \frac{d\mu}{\mu} - \frac{d\theta}{\theta}$$

$$\text{II). } \text{div}' = - \frac{u_0 \frac{\partial \rho_0}{\partial x} + v_0 \frac{\partial \rho_0}{\partial y} + w_0 \frac{\partial \rho_0}{\partial z}}{\rho_0} + \frac{u_0 \frac{\partial \theta_0}{\partial x} + \dots}{\theta_0}$$

$$\text{I). } \frac{\partial \rho'}{\partial x} = \frac{\partial}{\partial x} \frac{\text{div}'}{\mu} + \mu \Delta^2 u'$$

$$\nabla^2 \rho' = \frac{4}{3} \nabla^2 \text{div}'$$

$$\rho' = \frac{4}{3} \text{div}' + \text{kt}$$

Pytanie jak poprosiłam

$$\text{II). } \text{div} + \frac{u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z}}{\rho} - \frac{u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z}}{\theta} = 0$$

$$\text{III). } \kappa \rho \text{div} + (u \frac{\partial \rho}{\partial x} + \dots) = (k-1) [\mu \Phi + \kappa \Delta^2 \theta]$$

u drugie przemyślenie

u drugie przemyślenie: $\text{div} = 0$ stąd mamy $\frac{d\rho}{\rho} = + \frac{d\theta}{\theta}$
 $\rho \sim \theta$

2 typy rozważań III:

$$\text{div} = \dots$$

~~$$(k-1) \mu \Phi + \kappa \Delta^2 \theta = \dots$$~~

rozważmy I i III:

$$(k-1) \mu \operatorname{div} = - \frac{\mu}{\theta} \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) + (k-1) [\mu \Phi + \kappa \Delta \theta]$$

Wzrost θ charakteryzować będzie [przydane κ etc.] przekładanie, mianem:

$\mu \Phi$ i (1)

Kierunki, jakie Φ bierze dwie: (1) bierze dwie w porównaniu do $\frac{\partial \Phi}{\partial \theta}$

Wtedy $\operatorname{div} = 0$

zatem wch. przez I i II wziętych strzałkami

θ jest wtedy objętość ~~istotnie nie podlega zmianom~~

musi być obliczone z III z uwzględnieniem przekładanych wartości Φ i:

$$(1-k) \mu \frac{\partial \theta}{\partial x} + \dots = -k \frac{\mu}{\theta} \left(u \frac{\partial \theta}{\partial x} + \dots \right) + (k-1) (\mu \Phi + \kappa \Delta \theta)$$

Sprowadzając równanie pierwsze

1. $\frac{1}{\mu} \frac{\partial \mu}{\partial x} \ll \frac{1}{\theta} \frac{\partial \theta}{\partial x}$

Wtedy: II przyjmujemy kształt: $u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} = 0$

$C = \text{const}$ istotnie.

2. $\frac{1}{\mu} \frac{\partial \mu}{\partial x} \gg \frac{1}{\theta} \frac{\partial \theta}{\partial x}$

$$(1-k) \left(u \frac{\partial \theta}{\partial x} + \dots \right) = (k-1) [\mu \Phi + \kappa \Delta \theta]$$

$$u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} + \mu \Phi = -\kappa \Delta \theta$$

to same bytoby drugim
przekładaniem z (1)

Ogólnie czy istnieje równanie III istnieje:

zatem oryginalnie lepiej nazywać
tego Φ po prostu

2. θ : μ to get minimum mass right - II). through this

in general I needed previously

same solution to
 $\{ \frac{2a^4}{r^4} + (6 - \frac{12a^2}{r^2} + \frac{4a^4}{r^4}) \cos \theta \}$
 minimum at $\theta = 0$
 $= 6[1 - \frac{a^2}{r^2}]^2 \geq 0$

$$\Phi = \frac{\rho}{8} \frac{c^2 a^2}{r^4} \left\{ 6 \frac{x^2}{r^2} + \frac{2a^4}{r^4} - \frac{12a^2 x^2}{r^4} + \frac{4a^4 x^2}{r^6} \right\}$$

$$\Delta^2 \left(\frac{x^2}{r^2} \right) = \frac{2}{r^2} + 24 \frac{x^2}{r^{10}}$$

$$\Delta^2 \left(\frac{x^2}{r^6} \right) = \frac{2}{r^6} + 6 \frac{x^2}{r^8}$$

$$\Delta^2 \left(\frac{x^2}{r^4} \right) = \frac{2}{r^4} - 4 \frac{x^2}{r^6}$$

$$\Delta^2 \left(\frac{1}{r^4} \right) = \frac{12}{r^6}$$

$$\Delta^2 \left(\frac{1}{r^2} \right) = \frac{2}{r^4}$$

$$\Delta^2 \left(\frac{1}{r^6} \right) = \frac{30}{r^8}$$

| | | |
|------------|----------------------------|---|
| α | $24\alpha = 4a^4$ | $\alpha = \frac{a^4}{6}$ |
| β | $30\beta + 2\alpha = 2a^4$ | $15\beta = a^4 - \frac{a^4}{3} = \frac{2a^4}{3} \Rightarrow \beta = \frac{a^4}{18}$ |
| γ | $0\gamma = -12a^2$ | $\gamma = -\frac{a^2}{2}$ |
| δ | $2\gamma + 12\delta = 0$ | $\delta = \frac{\gamma}{12} = -\frac{a^2}{24}$ |
| ϵ | $-4\epsilon = 6$ | $\epsilon = -\frac{3}{2}$ |
| ζ | $2\gamma + 2\zeta = 0$ | $\zeta = \frac{3}{2}$ |
| $\{$ | | |

$$\Phi = \Delta^2 \left\{ \frac{\rho}{8} c^2 a^2 \left[\frac{1}{6} \frac{x^2}{r^2} - \frac{1}{2} \frac{a^2 x^2}{r^6} + \frac{1}{18} \frac{a^4}{r^6} - \frac{3}{2} \frac{x^2}{r^4} + \frac{1}{12} \frac{a^2}{r^4} + \frac{3}{2} \frac{1}{r^2} \right] \right\}$$

$$u_0 \frac{\partial \rho}{\partial x} + v_0 \frac{\partial \rho}{\partial y} + w_0 \frac{\partial \rho}{\partial z} = \Delta^2 \left\{ -\mu c^2 a^2 \left[\frac{27}{32} \frac{1}{r^2} + \frac{45}{32} \frac{x^2}{r^4} - \frac{3}{16} \frac{a^2 x^2}{r^6} \right] - \mu c^2 a^2 \cdot \frac{3}{4} \frac{x^2}{r^3} \right\}$$

$$\Delta^2 \theta = \Delta^2 \psi$$

$$\theta = \psi + u$$

$$\Delta^2 u = 0$$

$$r=a \quad \theta_0 = \psi_0 + u_0$$

$$r=\infty \quad u=0$$

$$u = \frac{\mu}{h} c^2 a^2 \left[-\frac{27}{32} \frac{1}{r^2} + \frac{9}{32} \frac{x^2}{r^4} - \frac{3}{32} \frac{a^2}{r^4} - \frac{71}{162} \frac{a^4}{r^6} + \frac{3}{8} \frac{a^2 x^2}{r^6} - \frac{3}{16} \frac{a^4 x^2}{r^8} \right] + \frac{\mu}{h} c^2 a^2 \frac{x^2}{r^3}$$

$$U_0|_{r=a} = \frac{\mu}{\kappa} c^2 \left[\underbrace{-\frac{27}{32} - \frac{3}{32} - \frac{3}{48}}_{-\frac{3}{8} \left(\frac{9}{4} + \frac{1}{4} + \frac{1}{6} \right)} + \underbrace{\left(\frac{9}{32} + \frac{3}{8} - \frac{2}{16} \right) \frac{x^2}{a^2} + \frac{3}{4} \frac{x^2}{a^2}}_{\frac{9+12-6+24}{32} = \frac{39}{32}} \right]$$

$$-\frac{3}{8} \frac{64}{24} = -1$$

$$U_0|_{r=a} = \frac{\mu}{\kappa} c^2 \left[1 - \frac{39}{32} \frac{x^2}{a^2} \right]$$

$$U = \theta_0 + \frac{A}{r^2} + B \left(\frac{1}{r^3} - \frac{3x^2}{r^5} \right)$$

$$\left. \begin{aligned} \frac{1}{a^2} + \frac{B}{a^3} &= \frac{\mu c^2}{\kappa} \\ \frac{3B}{a^3} &= -\frac{39}{32} \frac{\mu c^2}{\kappa} \end{aligned} \right\} \begin{aligned} 3 \frac{A}{a} &= \left(2 - \frac{7}{32} \right) \frac{\mu c^2}{\kappa} \\ &= \frac{57}{32} \frac{\mu c^2}{\kappa} \\ \frac{A}{a} &= \frac{19}{32} \frac{\mu c^2}{\kappa} \\ \frac{B}{a^3} &= -\frac{13}{32} \frac{\mu c^2}{\kappa} \end{aligned}$$

$$U = \theta_0 + \frac{\mu c^2}{32 \kappa} \left[19 \frac{a}{r^2} + 13 \left(\frac{a^3}{r^3} - \frac{3x^2 a^3}{r^5} \right) \right]$$

$$\theta = \theta_0 + \frac{\mu c^2}{\kappa} \left\{ \frac{3a^2}{32} \left[-\frac{9}{r^2} + \frac{3x^2}{24} - \frac{a^2}{24} - \frac{2}{3} \frac{a^4}{26} + 4 \frac{a^2 x^2}{26} - 2 \frac{a^4 x^2}{28} \right] + \frac{a}{r} \left[\frac{19}{32} + \frac{13}{32} \frac{a^2}{r^2} + \frac{3}{4} \frac{x^2}{r^2} - \frac{39}{32} \frac{x^2 a^2}{r^4} \right] \right\}$$

Gdyby się to udało zmierz do III

— Po prostu prędkość światła wynosi $\frac{c \mu}{A \theta \kappa} = \frac{c}{42.273}$

$$\frac{k}{k-1} \frac{1}{\theta} \left(u \frac{\partial \theta}{\partial x} + \dots \right) = \frac{k}{k-1} \frac{1}{\theta} \frac{\mu c^3}{K} [\dots]$$

$$\text{podczas gdy } \left(u \frac{\partial \theta}{\partial x} + \dots \right) = \mu c^2 [\dots]$$

$$\text{zatem stosunek poprawki: } \frac{c}{k \theta} = \frac{c \cdot 10^6}{0.000057 \cdot 42 \cdot 10^6 \cdot 273} = \frac{c}{0.6}$$

$$\text{zatem już wówczas nie tantaż już } c > 0.6 \frac{\text{cm}}{\text{m}} !$$

$$\frac{\mu c^2}{K} = \frac{0.00019 \cdot c^2}{42 \cdot 10^6 \cdot 0.000057} = \frac{c^2}{15 \cdot 10^6} \quad \text{zatem to osiągnąć by dopiero } 10^6$$

$$= \frac{c^2}{15 \cdot 10^6} \neq \frac{2}{3} \quad \text{gdzie } c = \frac{4 \cdot 10^3 \text{ cm}}{\text{sec}} !$$

Zatem ten prób rozwinąć tę kwestię nieopracowaną

W równaniu III:

$$\left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) - \frac{k}{k-1} \frac{P}{\theta} \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) + \mu \Phi + k \Delta^2 \theta = 0$$

(1) (2) (3) (4)

$$1 \text{ i } 3 \text{ są wtedy wielkość } \frac{\mu c^2}{a^2} = 0.00019 \cdot \frac{c^2}{a^2}$$

(4) = 2400. $\Delta^2 \theta$

~~te~~ czyli więc 4 stała się wielkością tego samego rzędu, mianowicie $\Delta^2 \theta \neq \frac{\mu c^2}{K a^2}$

$$\Delta^2 \theta \neq \frac{0.00019}{42 \cdot 10^6 \cdot 0.000057} \frac{c^2}{a^2} = \frac{1}{15 \cdot 10^6} \frac{c^2}{a^2} \quad \text{co zatem osiągnąć}$$

$$\text{podczas gdy (2): } \frac{10^6}{273} c \frac{\partial \theta}{\partial x}$$

$$\frac{\mu c^2}{K}$$

By uzyskać z warunków wyznaczyć drugie stopnie
wynika iż ρu^2 może być $\mu \frac{\partial u}{\partial x}$

$$\rho u \ll \frac{\mu}{x}$$

$$\rho p \ll \mu$$

$$(A). \Delta^2 \theta + u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} = \psi$$

Jakiż transformacja θ_1, θ_2 , to mamy:

$$\Delta^2(\theta_1 + \theta_2) + u \frac{\partial(\theta_1 + \theta_2)}{\partial x} + v \frac{\partial(\theta_1 + \theta_2)}{\partial y} + w \frac{\partial(\theta_1 + \theta_2)}{\partial z} = 2\psi \quad \left. \begin{array}{l} \text{zatem i indukcyjnie} \\ \text{także zadani ugi} \end{array} \right\}$$

$$\text{inaczej } \Delta^2(\theta_1 - \theta_2) + u \frac{\partial(\theta_1 - \theta_2)}{\partial x} + \dots = 0$$

Jakiż mamy transformację zadani. równanie

$$(B). \Delta^2 \theta + u \frac{\partial \theta}{\partial x} + \dots = 0$$

$$\parallel \text{N.p. } \theta = e^{\psi(x,y,z)}$$

$$\frac{\partial \theta}{\partial x} = \frac{\partial \psi}{\partial x} e^{\psi}$$

$$\frac{\partial^2 \theta}{\partial x^2} = \frac{\partial^2 \psi}{\partial x^2} e^{\psi} + \left(\frac{\partial \psi}{\partial x}\right)^2 e^{\psi}$$

$$\Delta^2 \theta + \left[\left(\frac{\partial \psi}{\partial x}\right)^2 + \left(\frac{\partial \psi}{\partial y}\right)^2 + \left(\frac{\partial \psi}{\partial z}\right)^2 \right] e^{\psi} + u \frac{\partial \psi}{\partial x} e^{\psi} + v \frac{\partial \psi}{\partial y} e^{\psi} + w \frac{\partial \psi}{\partial z} e^{\psi} = 0$$

Jakiż możemy dla θ na podstawie $\theta = \text{const}$, to gdzie $\theta = \text{const}$ jest jedynym

rozwiązaniem dla danego równania $\Delta^2 \theta + u \frac{\partial \theta}{\partial x} + \dots = 0$

Z tego wynika że $\theta_1 - \theta_2 = \text{const}$, zatem tylko jedno rozwiązanie możliwe

Stwierdza $\psi = \Delta^2 \chi$ równanie (A).

i podstawia $\theta = \vartheta + \chi$ stwierdza się:

$$\Delta^2 \vartheta + u \frac{\partial \vartheta}{\partial x} + \dots = - \left(u \frac{\partial \chi}{\partial x} + v \frac{\partial \chi}{\partial y} + w \frac{\partial \chi}{\partial z} \right)$$

Podstawia $\vartheta = \vartheta + \chi$: $\Delta^2 \chi = 0$

$$\Delta^2 \vartheta + u \frac{\partial \vartheta}{\partial x} + \dots + u \frac{\partial \chi}{\partial x} + v \frac{\partial \chi}{\partial y} + w \frac{\partial \chi}{\partial z} = 0$$

$$\boxed{\vartheta = \theta - \chi}$$

$$\rightarrow \varphi = \frac{Ax^2}{2^6} + \frac{B}{2^8} + \frac{Cx^2}{2^8} + \frac{Dx^2}{2^{10}}$$

$$\varphi = \sum m_k \frac{x}{2^k} \quad \text{Ponieważ } \varphi \text{ parzysta potęga } u \text{ i } v$$

$$\varphi = \sum \theta \text{ musi zawierać mieszane potęgi i nieparzyste}$$

Skąd $\Phi=0$ to niedługożycie jedno miejsce wierszanie

$$\theta = \theta_0 + \alpha r$$

$$(u \frac{\partial \varphi}{\partial x} + \dots) \left[1 - \frac{k}{k-1} \frac{P}{\theta} \alpha \right] + k \frac{\Delta^2}{r} = 0$$

$$\text{tzn. } \alpha = \frac{k-1}{k} \frac{\theta}{P}$$

$$\theta = \theta_0 + \frac{k-1}{k} \frac{\theta}{P} r \quad \text{to nie byłoby jużde i spełniamy 2 warunki dla } z=9$$

zatem to mi musi być ostatni

$$\text{Skąd } k=0 \text{ to musi być } \frac{\partial \varphi}{\partial x} = 0$$

Czyli to jest ostatni do omówienia rachunku?

Znajdź wierszanie

$$\Delta^2 \theta + u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + \dots = \Phi \quad \text{stąd już z III przez podstawienie } \theta = \vartheta + \alpha r$$

$$u^2 + v^2 + w^2 = 0^2 \left\{ \frac{9}{16} \frac{a^2}{2^4} \left(1 - \frac{a^2}{2^2} \right)^2 x^2 - \frac{3}{2} \frac{a}{2^3} \left(1 - \frac{a^2}{2^2} \right) \left(1 - \frac{3}{4} \frac{a}{2} - \frac{1}{4} \frac{a^3}{2^3} \right) x^2 + \left(1 - \frac{3}{4} \frac{a}{2} \right)^2 \right\}$$

$$x^2 \left[\frac{9}{16} \left(1 - \frac{a^2}{2^2} \right) \left[-\frac{3}{2} \frac{a}{2^3} + \frac{3}{2} \frac{a^2}{2^4} \left(\frac{3}{4} + \frac{1}{4} \frac{a^2}{2^2} \right) + \frac{9}{16} \frac{a^2}{2^4} \left(1 - \frac{a^2}{2^2} \right) \right] \right] + \dots$$

$$\frac{a^2}{2^4} \left(\frac{27}{16} - \frac{3}{16} \frac{a^2}{2^2} \right)$$

Wskazujmy wyrażenie zadane dwómierowe; przy uw

$$u = -\frac{1}{\omega} \frac{\partial \psi}{\partial x}$$

$$v = \frac{1}{\omega} \frac{\partial \psi}{\partial y}$$

$$2 \frac{\partial^2 (\theta r)}{\partial r^2} + \frac{1}{\sin \phi} \frac{\partial}{\partial \phi} \left(\sin \phi \frac{\partial \theta}{\partial \phi} \right) +$$

$$\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} = -\frac{1}{\omega^2}$$

$$y = \omega \sin \phi$$

$$z = \omega \cos \phi$$

$$\frac{\partial \psi}{\partial y} = \frac{\partial \psi}{\partial \phi} \frac{\partial \phi}{\partial y} = \frac{\partial \psi}{\partial \phi} \frac{1}{\omega}$$

$$\frac{\partial \psi}{\partial y} = \frac{\partial \psi}{\partial \phi} \frac{\partial \phi}{\partial y} = \frac{\partial \psi}{\partial \phi} \frac{1}{\omega}$$

$$\frac{\partial^2 \psi}{\partial y^2} = \frac{\partial}{\partial \phi} \left(\frac{\partial \psi}{\partial \phi} \frac{1}{\omega} \right) \frac{1}{\omega} = \frac{\partial^2 \psi}{\partial \phi^2} \frac{1}{\omega^2} - \frac{\partial \psi}{\partial \phi} \frac{1}{\omega^3}$$

$$\frac{\partial \psi}{\partial y} + \frac{\partial \psi}{\partial x} = \frac{\partial \psi}{\partial \phi} - \frac{1}{\omega} \frac{\partial \psi}{\partial \omega}$$

$$\frac{\partial \psi}{\partial x^2} + \frac{\partial \psi}{\partial \omega^2} - \frac{1}{\omega} \frac{\partial \psi}{\partial \omega} = \frac{\partial \psi}{\partial \phi} - \frac{1}{\omega} \frac{\partial \psi}{\partial \omega} + \frac{1}{\omega} \frac{\partial \psi}{\partial \omega} \frac{\partial \phi}{\partial \omega} = \frac{\partial \psi}{\partial \phi}$$

Sądy są poprawne i zgodne

$$\frac{\partial^2 \psi}{\partial x^2} = \frac{\partial^2 \psi}{\partial \phi^2} \left(\frac{\partial \phi}{\partial x} \right)^2 + \frac{\partial^2 \psi}{\partial \phi \partial \omega} \left(\frac{\partial \phi}{\partial x} \right) \left(\frac{\partial \omega}{\partial x} \right) + \frac{\partial^2 \psi}{\partial \omega^2} \left(\frac{\partial \omega}{\partial x} \right)^2 + \frac{\partial^2 \psi}{\partial \phi \partial \omega} \frac{\partial \phi}{\partial x} \frac{\partial \omega}{\partial x} + \frac{\partial^2 \psi}{\partial \omega^2} \frac{\partial \phi}{\partial x} \frac{\partial \omega}{\partial x}$$

$$\frac{\partial^2 \psi}{\partial x^2} = \frac{1}{2} \frac{\partial^2 \psi}{\partial \phi^2} - \frac{x^2}{\omega^3} \frac{\partial^2 \psi}{\partial \phi^2} + \frac{x^2}{\omega^3} \frac{\partial^2 \psi}{\partial \phi \partial \omega}$$

$$\frac{\partial^2 \psi}{\partial x^2} = \frac{\partial^2 \psi}{\partial \phi^2} \left(\frac{\partial \phi}{\partial x} \right)^2 + \frac{\partial^2 \psi}{\partial \phi \partial \omega} \left(\frac{\partial \phi}{\partial x} \right) \left(\frac{\partial \omega}{\partial x} \right) + 2 \frac{\partial^2 \psi}{\partial \phi \partial \omega} \frac{\partial \phi}{\partial x} \frac{\partial \omega}{\partial x} + \frac{\partial^2 \psi}{\partial \omega^2} \left(\frac{\partial \omega}{\partial x} \right)^2 + \frac{\partial^2 \psi}{\partial \phi \partial \omega} \frac{\partial \phi}{\partial x} \frac{\partial \omega}{\partial x}$$

$$\frac{\partial^2 \psi}{\partial x^2} = \frac{\partial^2 \psi}{\partial \phi^2} \frac{\partial \phi}{\partial x} + \frac{\partial^2 \psi}{\partial \phi \partial \omega} \frac{\partial \omega}{\partial x}$$

$$\frac{\partial \psi}{\partial x^2} = \frac{\partial \psi}{\partial \phi} \left(\frac{\partial \phi}{\partial x} \right)^2 + \frac{\partial \psi}{\partial \omega}$$

$$\frac{\partial \theta}{\partial x} = \frac{\partial \theta}{\partial x} \frac{x}{2} + \frac{\partial \theta}{\partial \omega} \frac{\omega}{2}$$

$$\frac{\partial \theta}{\partial \omega} = \frac{\partial \theta}{\partial x} \frac{x}{2}$$

gdy gdy ω to

$$\frac{dx}{u\Phi} = \frac{dy}{v\Phi} = \frac{dz}{w\Phi} = d\theta$$

$$2 \frac{\partial \theta}{\partial x} + \theta$$

$$\omega \varphi \frac{\partial \theta}{\partial \varphi} + \omega \varphi \frac{\partial \theta}{\partial \varphi^2}$$

$$i \frac{\partial \theta}{\partial \omega} + 2 \frac{\partial \theta}{\partial x} \cdot x$$

$$2 \frac{\partial^2 \theta}{\partial x^2} + 2x \frac{\partial \theta}{\partial x} + \frac{\partial \theta}{\partial \varphi^2} + \frac{\omega \varphi}{2} \frac{\partial \theta}{\partial \varphi} + \text{etc.}$$



$$-u \omega \theta + \varphi \omega \theta =$$

$$= -u \frac{\omega}{2} + \varphi \frac{x}{2}$$

$$= + \frac{3}{2} \frac{c a}{2^3} (1 - \frac{a^2}{2i}) \frac{x^2 \omega}{2} -$$

$$- \frac{c \omega}{2} (1 - \frac{3}{4} \frac{a}{2} - \frac{1}{4} \frac{a^2}{i})$$

$$\rightarrow \frac{\partial \theta}{\partial x^2} + \frac{\partial \theta}{\partial \omega^2} - \frac{1}{\omega} \frac{\partial \varphi}{\partial \omega} \frac{\partial \theta}{\partial x} + \frac{1}{\omega} \left(\frac{\partial \varphi}{\partial x} - 1 \right) \frac{\partial \theta}{\partial \omega} = \Phi$$

$$R=1$$

$$P = -\frac{1}{\omega} \frac{\partial \varphi}{\partial \omega}$$

$$Q$$

$$S=0$$

$$T=1$$

$$k^2 + 1 = 0$$

$$k = \pm i$$

$$\frac{\partial \xi}{\partial x} = i \frac{\partial \xi}{\partial \omega}$$

$$\frac{\partial \eta}{\partial x} = -i \frac{\partial \eta}{\partial \omega}$$

$$\xi = x \pi i \omega$$

$$\eta = x - i \omega$$

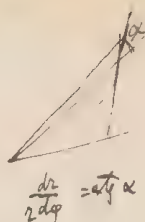
$$4 \frac{\partial \xi}{\partial \varphi} \frac{\partial \eta}{\partial \omega} = +4$$

$$\frac{\partial^2 \theta}{\partial \xi \partial \eta} + \frac{1}{4 \omega} \frac{\partial \varphi}{\partial \omega} \frac{\partial \theta}{\partial \xi} = + \frac{\Phi}{4}$$

$$\text{By solution: } LM + \frac{\partial L}{\partial \xi} = 0 ?$$

$$\psi = -\frac{c}{2} \left(1 - \frac{2}{2} \frac{a}{2} + \frac{1}{2} \frac{a^3}{r^3} \right) r^2 \sin^2 \theta$$

$$\delta\psi = \frac{\partial\psi}{\partial r} \delta r + \frac{\partial\psi}{\partial \theta} \delta\theta$$



$$\cancel{J} = \frac{\partial\psi}{\partial r} dr + \frac{\partial\psi}{\partial \theta} d\theta$$

$$\frac{1}{2} \frac{dr}{d\theta} = -\frac{\frac{\partial\psi}{\partial \theta}}{2 \frac{\partial\psi}{\partial r}} = -\frac{1}{2} \frac{\partial\psi}{\partial \theta}$$

$$\delta = \frac{\partial\psi}{\partial r} \delta r \cos \theta$$

$$\delta\psi \int_0^\infty \omega \frac{\partial\omega}{\partial\psi} \Phi(x, \omega) dx = \delta\psi \int_0^\infty \omega \frac{\Phi}{\frac{\partial\psi}{\partial\omega}} dx$$

$$= \delta\psi \int_0^\infty \frac{\Phi(x, \omega)}{\frac{\partial\psi}{\partial\omega}} dx$$

$$\psi = -\frac{c}{2} \left(1 - \frac{2}{2} \frac{a}{\sqrt{x^2 + \omega^2}} + \frac{1}{2} \frac{a^3}{(x^2 + \omega^2)^{3/2}} \right) \omega^2$$

$$\frac{\partial\psi}{\partial\omega^2} = -\frac{c}{2} \left[1 - \frac{2}{2} \frac{a}{\sqrt{x^2 + \omega^2}} + \frac{1}{2} \frac{a^3}{(x^2 + \omega^2)^{3/2}} \right]$$

$$- \frac{c}{2} \omega^2 \left[\frac{3}{4} \frac{a}{(x^2 + \omega^2)^{3/2}} - \frac{3}{4} \frac{a^3}{(x^2 + \omega^2)^{5/2}} \right]$$

$$= -\frac{c}{2} \left[1 - \frac{3}{2} \frac{a}{2} + \frac{1}{2} \frac{a^3}{2^3} + \frac{3}{4} \frac{a\omega^2}{2^3} - \frac{3}{4} \frac{a^3\omega^2}{2^5} \right]$$

$$\omega^2 = r^2 - x^2$$

$$= -\frac{c}{2} \left[1 - \frac{3}{2} \frac{a}{2} + \frac{1}{2} \frac{a^3}{2^3} + \frac{3}{4} \frac{a}{2} - \frac{3}{4} \frac{a x^2}{2^3} - \frac{3}{4} \frac{a^3}{2^3} + \frac{3}{4} \frac{a^3 x^2}{2^5} \right]$$

$$1 - \frac{3}{4} \frac{a}{2} - \frac{1}{4} \frac{a^3}{2^3} + \frac{3}{4} \frac{a x^2}{2^3} - \frac{3}{4} \frac{a^3}{2^3} + \frac{3}{4} \frac{a^3 x^2}{2^5} = -\frac{11}{2}$$

$$\Phi = \frac{q}{8} \frac{c^2 a^2}{r^2} \left\{ \frac{2a^4}{r^4} + 6 - \frac{6a^2}{r^2} - \frac{12a^2}{r^2} + \frac{12a^2 r^2}{r^4} + \frac{4a^4}{r^4} - \frac{4a^4 \omega^2}{r^6} \right\}$$

$$\left\{ 6 - \frac{12a^2}{r^2} + \frac{6a^4}{r^4} - \left(6 - \frac{12a^2}{r^2} + \frac{4a^4}{r^4} \right) \frac{\omega^2}{r^2} \right\}$$

$$dx = \frac{x}{r} dr = \frac{dr}{r} \sqrt{r^2 - \omega^2}$$

$$\frac{q}{8} c^2 a^2 \frac{1}{2} \int_{\rho}^{\infty} dr \left[\frac{1}{r^5} \left[6 \left(1 - \frac{2a^2}{r^2} + \frac{a^4}{r^4} \right) + \left(6 - \frac{12a^2}{r^2} + \frac{4a^4}{r^4} \right) \frac{24}{c r^2 \left(1 - \frac{3}{2} \frac{a^2}{r^2} + \frac{1}{2} \frac{a^4}{r^4} \right)} \right] - \frac{c}{2} \left[1 - \frac{3}{2} \frac{a^2}{r^2} + \frac{1}{2} \frac{a^4}{r^4} + \frac{3}{4} \frac{a^2}{r^2} \left(1 - \frac{a^2}{r^2} \right) \frac{24}{c \left(1 - \frac{3}{2} \frac{a^2}{r^2} + \frac{1}{2} \frac{a^4}{r^4} \right)} \right] \right]$$

$$\left(i \sqrt{r^2 - \frac{24}{c \left(1 - \frac{3}{2} \frac{a^2}{r^2} + \frac{1}{2} \frac{a^4}{r^4} \right)}} \right)$$

$$\psi = \text{const}$$

zrobić w tym miejscu

$$\Delta \psi + u \frac{\partial \psi}{\partial x} + v \frac{\partial \psi}{\partial y} + w \frac{\partial \psi}{\partial z} = 0$$

zrobić potęgę tyłu i dłużej

$$\psi = \log v \quad \text{istotne } \psi = e^{\psi}$$

$$\frac{\partial \psi}{\partial x} = \frac{1}{v} \frac{\partial v}{\partial x}$$

$$v = e^{\psi}$$

$$\Delta \psi + u \frac{\partial \psi}{\partial x} + v \frac{\partial \psi}{\partial y} + w \frac{\partial \psi}{\partial z} = 0$$

$$\theta = e^{\psi} \quad \text{zrobić to matematycznie}$$

zrobić Partikulary

$$\Delta \psi = 0$$

$$u \frac{\partial \psi}{\partial x} + \dots = 0$$

$$\theta = \frac{a}{2} + b \frac{\partial}{\partial x} \left(\frac{1}{2} \right) + c \frac{\partial}{\partial x} \left(\frac{1}{2} \right) + \dots$$

$$\theta = \frac{a}{2} + b \frac{\partial}{\partial x} \left(\frac{1}{2} \right) + c \frac{\partial}{\partial x} \left(\frac{1}{2} \right) + \dots$$

$$\frac{\partial \theta}{\partial x} = a \frac{\partial}{\partial x} \left(\frac{1}{2} \right) + b \frac{\partial^2}{\partial x^2} \left(\frac{1}{2} \right) + \dots = \frac{x}{2} \left[a + b \frac{\partial}{\partial x} \right] + F_2$$

$$\frac{\partial \theta}{\partial y} = a \frac{\partial}{\partial y} \left(\frac{1}{2} \right) + b \frac{\partial^2}{\partial x \partial y} \left(\frac{1}{2} \right) + \dots = \frac{y}{2} \left[\dots \right]$$

$$\frac{\partial \theta}{\partial z} = a \frac{\partial}{\partial z} \left(\frac{1}{2} \right) + \dots = \frac{z}{2} \left[\dots \right]$$

$$u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} = - \frac{1}{4} \frac{\partial}{\partial x} \left(\frac{1}{2} \right) \times F_1 + \dots = 0$$

$$= \frac{c x}{2} \left(1 - \frac{3}{2} \frac{a}{2} + \frac{1}{2} \frac{a^3}{2^3} \right) F_1 + F_2 u$$

$$\frac{\partial}{\partial x} \left(\frac{1}{2} \right) = - \frac{x}{2^3} \quad \frac{\partial}{\partial y} \left(\frac{1}{2} \right) = - \frac{y}{2^3}$$

$$\frac{\partial^2}{\partial x^2} \left(\frac{1}{2} \right) = + \frac{3x^2}{2^5} - \frac{1}{2^3}$$

$$\frac{\partial^2}{\partial y^2} \left(\frac{1}{2} \right) = + \frac{3xy}{2^5}$$

$$\frac{\partial^3}{\partial x^3} = - \frac{15x^3}{2^7} + \frac{3x}{2^5} + \frac{6xy}{2^5} \quad \frac{\partial^3}{\partial x^2 \partial y} = - \frac{15x^2 y}{2^7} + \frac{3y}{2^5}$$

$$F_1 = \left[- \frac{ax}{2^3} + b \left[\frac{3x^2}{2^5} - \frac{1}{2^3} \right] + c \left[- \frac{15x^3}{2^7} + \frac{3x}{2^5} \right] + \dots \right]$$

$$F_2 = - \frac{b}{2^3} + \frac{6cx}{2^5}$$

$$\theta = \varphi \psi$$

$$\frac{\partial \theta}{\partial x} = \frac{\partial \varphi}{\partial x} \psi + \varphi \frac{\partial \psi}{\partial x}$$

$$\frac{\partial^2 \theta}{\partial x^2} = \frac{\partial^2 \varphi}{\partial x^2} \psi + 2 \frac{\partial \varphi}{\partial x} \frac{\partial \psi}{\partial x} + \varphi \frac{\partial^2 \psi}{\partial x^2}$$

$$\Delta \varphi \cdot \psi + 2 \left[\frac{\partial \varphi}{\partial x} \frac{\partial \psi}{\partial x} + \frac{\partial \varphi}{\partial y} \frac{\partial \psi}{\partial y} + \frac{\partial \varphi}{\partial z} \frac{\partial \psi}{\partial z} \right] + \varphi \Delta \psi + \varphi \left[u \frac{\partial \varphi}{\partial x} + \dots \right] + \varphi \left[u \frac{\partial \psi}{\partial x} + \dots \right] = 0$$

Решив систему А жинли у сплани А * поделю жды φ :

$$\Delta^2 \varphi + 2 \left[\frac{\partial \varphi}{\partial x} \frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial \varphi}{\partial y} \frac{\partial^2 \varphi}{\partial y^2} + \frac{\partial \varphi}{\partial z} \frac{\partial^2 \varphi}{\partial z^2} \right] + u \frac{\partial \varphi}{\partial x} + \dots = 0$$

rotacijski se deindek toku φ cikly

$$2 \frac{\partial \varphi}{\partial x} \frac{\partial^2 \varphi}{\partial x^2} + \dots = \Phi$$

$$\Delta^2 \theta + u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} = 0$$

$$\iint \frac{\partial \theta}{\partial n} dS + \iint \left[u \theta \frac{\partial \theta}{\partial x} + v \theta \frac{\partial \theta}{\partial y} + w \theta \frac{\partial \theta}{\partial z} \right] dS - \iint \theta \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) dS$$

$$\iint \frac{\partial \theta}{\partial n} dS + \iint \theta v_n dS = 0$$



Zastavimo to do mack predn cikly

$$\Delta^2 \theta + u \frac{\partial \theta}{\partial x} + \dots = 0$$

$$\Delta^2 \theta' + u \frac{\partial \theta'}{\partial x} + \dots = 0$$

$$\Delta^2 (\theta - \theta') + u \frac{\partial (\theta - \theta')}{\partial x} + v \frac{\partial (\theta - \theta')}{\partial y} + w \frac{\partial (\theta - \theta')}{\partial z} = 0$$

$$\Delta^2 (\theta + \theta') + u \frac{\partial (\theta + \theta')}{\partial x} + v \frac{\partial (\theta + \theta')}{\partial y} + w \frac{\partial (\theta + \theta')}{\partial z} = 0$$

homogenizirane zadane jednačine

~~$$u \frac{\partial u}{\partial x} + \frac{1}{p} \frac{\partial p}{\partial x} = \frac{1}{3} \frac{\partial u}{\partial x} + \frac{1}{3} \frac{\partial u}{\partial x}$$~~

$$D. \rho u \frac{\partial u}{\partial x} + \frac{\partial p}{\partial x} = \frac{\gamma u}{3} \frac{\partial u}{\partial x}$$

$$II. \frac{\partial(\rho u)}{\partial x} = 0$$

$$\rho u = \text{const} = b$$

$$III. \quad k p \frac{\partial u}{\partial x} + u \frac{\partial p}{\partial x} = (k-1) \frac{\gamma}{3} \left(\frac{\partial u}{\partial x} \right)^2 + \kappa \frac{\partial^2 u}{\partial x^2}$$

$$I. \quad b \frac{\partial u}{\partial x} + \frac{\partial p}{\partial x} = \frac{\gamma u}{3} \frac{\partial^2 u}{\partial x^2}$$

$$b u + p = \frac{\gamma u}{3} \frac{\partial u}{\partial x} + a$$

$$\frac{du}{dx} = \frac{b u + p - a}{\frac{\gamma u}{3}}$$

~~$$k p \frac{b u + p - a}{\frac{\gamma u}{3}} + u \frac{dp}{du} = (k-1) \frac{\gamma u}{3} \left(\frac{du}{dx} \right)^2$$~~

$$k p + u \frac{dp}{du} = (k-1) (b u + p - a)$$

$$u \frac{dp}{du} = \underbrace{(k-1) b u - p - (k-1) a}_{= z}$$

$$p = (k-1) b u - (k-1) a - z$$

$$\frac{dp}{du} = \frac{(k-1) b}{du} \frac{du}{du} - \frac{dz}{du}$$

$$u (k-1) b - u \frac{dz}{du} = z$$

$$\frac{dz}{du} + \frac{z}{u} = (k-1) b$$

$$u dz + z du = (k-1) b du u$$

~~$$u dz + z du = (k-1) b \frac{u^2}{2} + c$$~~

$$z = (k-1) \frac{b u}{2} + \frac{c}{u}$$

$$\frac{dp}{du} < 0 \quad z < 0$$

$$\text{otuda } c < 0$$

$$p = (k-1)bu - (k-1)a - (k-1)\frac{bu}{2} + -\frac{c}{u}$$

$$p = \frac{(k-1)b}{2}u - \frac{c}{u} - (k-1)a$$

$$\frac{u(k-1)b}{2} + \frac{c}{u} = \frac{(k-1)b}{2}u + \frac{c}{u} + \frac{u(k-1)a}{2} - \frac{u(k-1)a}{2}$$

$$\begin{aligned} \frac{4u}{3} \frac{du}{dx} &= bu - a + \frac{(k-1)b}{2}u - \frac{c}{u} - (k-1)a \\ &= (k+1)\frac{b}{2}u - \frac{c}{u} - ka \end{aligned}$$

$$\frac{\frac{4u}{3} u du}{(k+1)\frac{b}{2}u^2 - ka u - c} = dx$$

quadratisches Polynom in u mit a und c im Nenner:

$$A = \frac{a k}{(k+1)\frac{b}{2}}$$

$$C = \frac{-c}{(k+1)\frac{b}{2}}$$

$$a = \frac{(k+1)b}{k} \frac{A}{2}$$

$$c = -(k+1)\frac{b}{2}C$$

$$\frac{u du}{u^2 - Au + C} = \frac{(k+1)\frac{b}{2}}{\frac{4u}{3}} dx = \underbrace{\left(u - \frac{A}{2} \right) \frac{du}{u^2 - Au + C}}_{\frac{1}{2} \log(u^2 - Au + C)} + \frac{\frac{A}{2} du}{u^2 - Au + C}$$

man darf $A > 0$
 $C > 0$

$$\int \frac{du}{u^2 - Au + C} = \frac{2}{\sqrt{4C - A^2}} \operatorname{arctg} \frac{2u - A}{\sqrt{4C - A^2}} \quad 4C > A^2$$

$$= \frac{1}{\sqrt{A^2 - 4C}} \log \left\{ \frac{2u - A - \sqrt{A^2 - 4C}}{2u - A + \sqrt{A^2 - 4C}} \right\} \quad A^2 > 4C$$

$$= \frac{1}{\sqrt{A^2 - 4C}} \frac{\log \left(\left(u - \frac{A}{2} - \sqrt{\left(\frac{A}{2} \right)^2 - C} \right) \left(u - \frac{A}{2} + \sqrt{\left(\frac{A}{2} \right)^2 - C} \right) \right)}{\left(u - \frac{A}{2} + \sqrt{\left(\frac{A}{2} \right)^2 - C} \right)^2}$$

$$= \frac{1}{\sqrt{A^2 - 4C}} \left[\log(u^2 - uA + \frac{A^2}{4} - \frac{A^2}{4} + C) - 2 \log \left(u - \frac{A}{2} + \sqrt{\left(\frac{A}{2} \right)^2 - C} \right) \right]$$

W. prędkość hyponeracyjną:

$$u^2 - Au + C > 0$$

$$A^2 > C$$

$$(1a) \quad \frac{(k+1) \frac{b}{2}}{\frac{4\mu}{3}} x + \text{const} = \left[\frac{1}{2} + \frac{A_2}{\sqrt{A^2 - 4C}} \right] \log \left(u - \frac{A}{2} - \sqrt{\frac{A^2}{4} - C} \right) \\ + \left[\frac{1}{2} - \frac{A_2}{\sqrt{A^2 - 4C}} \right] \log \left(u - \frac{A}{2} + \sqrt{\frac{A^2}{4} - C} \right)$$

arty:

$$u^2 - Au + C > 0$$

$$A^2 < C$$

$$(1b) \quad \frac{(k+1) \frac{b}{2}}{\frac{4\mu}{3}} x + \text{const} = \frac{1}{2} \log(u^2 - Au + C) + \frac{A}{\sqrt{4C - A^2}} \arctg \frac{2u - A}{\sqrt{4C - A^2}}$$

$$(2) \quad p = \frac{b}{2} \left\{ (k-1)u + (k+1) \frac{C}{u} - \frac{(k-1)(k+1)}{k} A \right\} \quad \parallel \text{wynik nie zawiera } p!$$

$$(3) \quad \theta = \frac{p u}{R p u} = \frac{p u}{R b} = \frac{1}{2R} \left\{ (k-1) u^2 - \frac{(k^2-1)}{k} A u + (k+1) C \right\} \parallel \text{nie zawiera } \theta b!$$

$$(1) : \frac{(k+1) \frac{b}{2}}{\frac{4\mu}{3}} x + \text{const} = \left[f_1(u, A, C) - \text{const} \right] \frac{b}{2} \varphi(u, A, C)$$

$$(2) \quad p x = \frac{4\mu}{3} \frac{1}{k+1} \left[f(u, A, C) - \text{const} \right] \varphi(u, A, C)$$

Widzimy, że θ zależy tylko od u i nie zależy od A, C
 gdzie θ jest wartością $p x$ przy $u = 0$ to wynika z wartości const

$$\left. \begin{array}{l} \text{K.p. dla } x=0 \\ \text{dla} \end{array} \right\} \begin{array}{l} u = u_0 \\ u = u_1 \end{array} \quad \left. \begin{array}{l} \theta = \theta_0 \\ \theta = \theta_1 \end{array} \right\} \begin{array}{l} \text{2 typ rozprzesc (3; otwierajac} \\ \text{A, C} \end{array}$$

rozprzesc (1): const

dolny: robienie ($\frac{1}{2}$): $\rho x = \text{znana funkcja z B\&P}$

$$R\&P x = \frac{4}{3} \rho \frac{1}{k+1} (f - \cos t) \rho$$

zatem $\rho = \frac{\frac{4}{3} \rho \frac{1}{k+1} (f - \cos t) \rho}{R\&P x} = \frac{\frac{4}{3} \rho \frac{1}{k+1} (f - \cos t)}{\frac{1}{2} u x}$

zatem $b = \rho u = \frac{\frac{4}{3} \rho \frac{1}{k+1} (f - \cos t)}{\frac{1}{2} x}$

$\frac{dp}{dx}$ musi w kazdej rown. byc rownie wielkie, inaczey by nie bylo nastepne

$$\begin{aligned} \frac{dp}{dx} &= \frac{dp}{du} \frac{du}{dx} = \frac{b}{2} \left\{ (k-1) - \frac{(k+1)C}{u^2} \right\} \frac{(k+1) \frac{b}{2}}{\frac{4\rho}{3}} \frac{u^2 - Au + C}{u} \\ &= \frac{b^2}{4} \frac{k+1}{\frac{4\rho}{3}} \frac{\left[k-1 - \frac{(k+1)C}{u^2} \right] [u^2 - Au + C]}{u} < 0 \end{aligned}$$

wyga albo $k-1 < \frac{(k+1)C}{u^2}$ } stanowi w kazdej rown. piny granice dla u

albo $u^2 - Au + C < 0$

Pierwsza: ostatni rown. wyznacza I II III

$$\begin{aligned} & \frac{b}{\frac{4\rho}{3}} \frac{(k+1) \frac{b}{2}}{u} \frac{u^2 - Au + C}{u} + \frac{b^2}{4} \frac{k+1}{\frac{4\rho}{3}} \frac{\left[k-1 - \frac{(k+1)C}{u^2} \right] [u^2 - Au + C]}{u} \\ &= \frac{\frac{4\rho}{3}}{u} \left\{ \frac{2u - A}{u} - \frac{u^2 - Au + C}{u^2} \right\} \frac{u^2 - Au + C}{u} = \frac{4u^2 - Au - u^2 + Au - C + Au - C}{u^2} \end{aligned}$$

$$\frac{\frac{b^2}{2}(k+1)}{\frac{4\mu}{3}} + \frac{\frac{b^2}{4}(k^2-1)}{\frac{4\mu}{3}} - \frac{\frac{b^2}{4}(k+1)^2}{\frac{4\mu}{3}} \frac{C}{u^2} = \frac{4\mu}{3} \left(1 - \frac{C}{u^2}\right)$$

Spisujem tyto zpravy:

$$\frac{b^2}{2}(k+1) + \frac{b^2}{4}(k^2-1) = \left(\frac{4\mu}{3}\right)^2 = \frac{b^2}{4} [k^2-1 + 2(k+1)] = \frac{b^2}{4} [k^2+2k+1] = \frac{b^2}{4}(k+1)^2$$

$$\frac{b^2}{4}(k+1)^2 = \left(\frac{4\mu}{3}\right)^2$$

Identity case !!

$$\frac{b(k+1)}{2} = \frac{4\mu}{3}$$

$$b = \frac{8\mu}{3(k+1)}$$

Dva rovnice přejímáme kontrolu:

$$(1) a \quad x + \text{const} = \left[\frac{1}{2} + \frac{1}{r} \right] \dots$$

=

$$(2) \quad \mu = \frac{4\mu}{3(k+1)} \left\{ (k-1)u + (k+1) \frac{C}{u} - \frac{(k-1)(k+1)}{k} A \right\}$$

$$(3) \quad \theta = \frac{1}{2R} \left\{ (k-1)u^2 + (k+1)C - \frac{(k^2-1)}{k} A u \right\}$$

$$\rho = \frac{b}{u} = \frac{8\mu}{3(k+1)} \frac{1}{u}$$

$$u = \frac{8\mu}{3(k+1)} \frac{1}{\rho}$$

$$\text{N.f.} \quad \mu = 0.00019$$

$$\rho = 0.0012$$

$$u = \frac{1}{10} \text{ ?}$$

$$\left\{ k \frac{1}{f} \left\{ \cancel{(k-1)u} + (k+1) \frac{C}{u} - \frac{(k-1)(k+1)}{k} A \right\} - (k-1) \cancel{\frac{1}{f}} \frac{(k+1)}{f} \left[u^2 - A + \frac{C}{u} \right] \right\}$$

$$= \cancel{u} \frac{1}{f} \left\{ \cancel{(k-1)} - \cancel{(k+1)} \frac{C}{u^2} \right\}$$

Wiederholung v. II:

$$k \frac{1}{f} \left\{ (k-1)u + (k+1) \frac{C}{u} - \frac{(k-1)(k+1)}{k} A \right\} \cancel{\left(\frac{(k-1)}{f} \frac{u^2 - A + C}{u} \right)} + u \cancel{\left(\frac{(k-1)}{f} \left[\frac{(k+1)C}{u^2} \right] \right)} \cancel{\left(u^2 - A + \frac{C}{u} \right)}$$

$$= (k-1) \cancel{\frac{1}{f}} \frac{(k+1)}{f} \left(\frac{u^2 - A + C}{u} \right) \cancel{\frac{1}{f}}$$

$$(k^2 - k)u + \frac{(k-1)C}{u} - \frac{(k^2 - 1)A}{k} + \frac{k(k+1)C}{u} - \frac{(k+1)C}{u} - \frac{(k^2 - 1)C}{u} +$$

$$\cancel{k(k-1)A} + \cancel{(k-1)(k+1)A} = 0$$

$$I). \cancel{k} \frac{(k+1)}{f} \frac{u^2 - A + C}{u} + \cancel{\frac{1}{f}} \frac{(k+1)}{f} \left[\frac{(k+1)C}{u^2} \right] \left[\frac{u^2 - A + C}{u} \right]$$

$$= \cancel{\frac{1}{f}} \frac{(k+1)}{f} \left(\frac{u^2 - A + C}{u} \right) \frac{u^2 - C}{u^2} \frac{u^2 - A + C}{u}$$

$$\underbrace{2 + k-1}_{k+1} \frac{(k+1)C}{u^2} (k+1) \left(\frac{u^2 - A + C}{u} \right)$$

Wiederholung

jeśli możliwe będzie mieć u to tam będzie
i zastąpię $\frac{1}{2}$ i tamtych wartości x :

$\lim u \dots$

$$\rho = \frac{b}{2} \frac{C}{u}$$

$$\theta = \frac{(k+1)C}{2R}$$

$$\rho = \frac{b}{2} = \frac{1}{u}$$

(1a) niemożliwe

(1b): ~~$\frac{b}{2} \frac{C}{u} = \frac{1}{2}$~~ $\text{czy } C = \frac{A}{\sqrt{4C-A^2}} \arctg \frac{-A}{\sqrt{4C-A^2}}$

Pyt (1a) najniższe możliwe ρ określone:

$$u > \frac{A}{2} + \sqrt{\frac{A^2}{4} - C}$$

zatem:

$$u - \frac{A}{2} > \sqrt{\frac{A^2}{4} - C}$$

$$u^2 - Au + \frac{A^2}{4} > \frac{A^2}{4} - C$$

$$u^2 - Au + C > 0$$

Pyt (1a) warunkiem: $\frac{A^2}{4} > C$

$$\theta < \frac{1}{2R} \left\{ (k-1)u^2 - \frac{(k-1)}{k} Au + (k+1) \frac{A^2}{4} \right\}$$

$$\rho < \frac{b}{2} \left\{ (k-1)u + \frac{(k+1)}{u} \frac{A^2}{4} - \frac{(k-1)(k+1)}{k} A \right\}$$

$$\rho < \frac{b}{2} \left\{ \frac{kA}{2} - \frac{k-1}{k} A + \frac{(k+1)A^2}{4(u-C)} \right\}$$

$$\theta < \frac{1}{2R} \left\{ (k-1) \frac{A^2}{4} \frac{k+1}{k} + (k+1) \frac{A^2}{4} - \frac{(k-1)}{k} Au \right\}$$

$$< \frac{1}{2R} (k+1) \left\{ \frac{A^2}{2} - \frac{k-1}{k} Au \right\}$$

$$\frac{A^2}{4} > C > Au - u^2$$

$$\frac{A^2}{4} > Au - u^2$$

$$u^2 - Au + \frac{A^2}{4} > 0 \quad (u - \frac{A}{2})^2 > 0$$

najniższe możliwe ρ i θ przy

że $\frac{d\rho}{du} = 0$:

$$u^2 < \frac{(k+1)C}{k-1}$$

$$Au - C < u^2 < \frac{k+1}{k-1} C < \left(1 + \frac{2}{k-1}\right) C$$

$$Au < \left(\frac{k+1}{k-1} + 1\right) C$$

$$Au < \frac{2k}{k-1} C$$

$$u < \left(\frac{2k}{k-1}\right) \frac{C}{A}$$

$$\frac{C}{A} < \frac{A}{4}$$

$$u < \frac{k}{2(k-1)} A$$

Wskazanie: $u^2 < \frac{k+1}{k-1} \frac{A^2}{4}$

$$u < \frac{A}{2} \sqrt{\frac{k+1}{k-1}}$$

$$\frac{k}{k-1} = \frac{1.4}{0.4} = \frac{7}{2} = 3.5$$

$$\sqrt{\frac{k+1}{k-1}} = \sqrt{\frac{2.4}{0.4}} = \sqrt{6} = 2.5$$

W (1a) i (1b) warunki konieczne $u^2 - Au + C > 0$

zatem $\frac{du}{dx} > 0$ prędkość wzrasta się z odległości x

zatem siły były spełnione $\frac{dy}{dx} < 0$

musi być $\frac{dy}{dx} < 0$ w) ~~z~~ $u^2 < \frac{k+1}{k-1} C$

$$\text{const} = \left[\frac{1}{2} \right] \log \left(u_1 - \frac{A}{2} - \sqrt{\frac{A^2}{4} - C} \right) + \left[\frac{1}{2} \right] -$$

$$\frac{(k+1) \frac{b}{2} x}{\frac{u_1}{3}} = \left[\frac{1}{2} + \frac{1}{\sqrt{A^2 - 4C}} \right] \log \left(\frac{u - \frac{A}{2} - \sqrt{\frac{A^2}{4} - C}}{u_1 - \frac{A}{2} - \sqrt{\frac{A^2}{4} - C}} \right) + \left[- \right]$$

$$\frac{b}{2} (k+1) C = k p_0 \alpha \quad C = \frac{k p_0 \alpha}{(k+1) \frac{b}{2}}$$

$$\frac{b}{2} \frac{(k+1) A}{x} = p_0 \quad A = \frac{k p_0}{(k+1) \frac{b}{2}}$$

$$\frac{1}{2} \log \frac{u - A}{u_1 - A} = \frac{1}{2} \log \frac{1 - \frac{u}{A}}{1 - \frac{u_1}{A}} = \frac{1}{2} \frac{u_1 - u}{A} = \frac{1}{2} \frac{u_1 - u}{k p_0} \frac{b}{2}$$

$$\frac{1}{2} \log \frac{\frac{u}{A} + \frac{A}{2} \left[-1 + \left(1 - \frac{4C}{A^2} \right)^{\frac{1}{2}} \right]}{\frac{u_1}{A} + \frac{A}{2} \left[-1 + \left(1 - \frac{4C}{A^2} \right)^{\frac{1}{2}} \right]} = \frac{1}{2} \log \frac{\frac{u}{A} + \frac{A}{2} \left[-1 + 1 - \frac{2C}{A^2} \right]}{\frac{u_1}{A} + \frac{A}{2} \left[-1 + 1 - \frac{2C}{A^2} \right]} =$$

$$= \frac{1}{2} \log \frac{\frac{u}{A} - \frac{C}{A^2}}{\frac{u_1}{A} - \frac{C}{A^2}} = \frac{1}{2} \log \frac{u - \frac{C}{A}}{u_1 - \frac{C}{A}} = \frac{1}{2} \log \frac{u - \alpha}{u_1 - \alpha}$$

$$\text{Zatem } \frac{(k+1) \frac{b}{2} x}{\frac{u_1}{3}} = \frac{1}{2} \left[\frac{(u_1 - u) (k+1)}{k p_0} \frac{b}{2} + \log \frac{u - \alpha}{u_1 - \alpha} \right]$$

Co jeli $u^2 - Au + C < 0$

jeli $\frac{C > 0}{A > u + \frac{C}{A}}$

$$\int \frac{u \, du}{u^2 - Au + C} = \int \frac{(u - \frac{A}{2}) \, du}{(u - \frac{A}{2})^2 - (\frac{A^2}{4} - C)} = - \int \frac{u \, du}{Au - u^2 - C}$$

$$= \int \frac{(\frac{A}{2} - u) \, du}{Au - u^2 - C} = \frac{A}{2} \int \frac{du}{\frac{A^2}{4} - C - (u - \frac{A}{2})^2}$$

$$= \frac{A}{2} \int \frac{du}{\sqrt{\frac{A^2}{4} - C} - (u - \frac{A}{2})^2}$$

$$= \frac{A}{2} \ln \left| \frac{\sqrt{\frac{A^2}{4} - C} - (u - \frac{A}{2})}{\sqrt{\frac{A^2}{4} - C} + (u - \frac{A}{2})} \right|$$

U granici npr. $C = \frac{A^2}{4}$

$$\frac{(k+1) \frac{A}{2}}{\frac{A}{3}} x + \text{const} = \ln(u - \frac{A}{2}) - \frac{A}{2(u - \frac{A}{2})}$$

dla $x=0$: u bardzo male $\approx u_0$

$$\theta \approx \theta_0$$

$$k \approx k_0$$

$$\theta_0 = \frac{(k+1)C}{2R}$$

~~$$k_0 = \frac{C}{2u_0}$$~~

$$C = \frac{2R\theta_0}{k+1}$$

~~$$k = \frac{1}{2} \frac{u_0}{\theta_0}$$~~

~~$$\text{const} = \frac{1}{2} \log C + \frac{A}{\sqrt{4C-A^2}} \operatorname{arctg} \frac{-A}{\sqrt{4C-A^2}}$$~~

Całkujemy u:

arctg może być do $\frac{\pi}{2}$ gdy u od 0 do ∞ , ponieważ log. urośnie stale z u zatem dla willbach u będzie już tyłko:

~~$$x = \frac{1}{b(k+1)} \log u$$

$$u = e^{\frac{b(k+1)}{2} x}$$~~

$$\frac{(k+1)}{\frac{u}{2}} x = \frac{1}{2} \log \frac{u^2 - Au + C}{C} + \frac{A}{\sqrt{4C-A^2}} \left[\operatorname{arctg} \frac{2u-A}{\sqrt{4C-A^2}} + \operatorname{arctg} \frac{A}{\sqrt{4C-A^2}} \right]$$

$$\operatorname{tg}(\varphi + \psi) = \frac{\operatorname{tg} \varphi + \operatorname{tg} \psi}{1 - \operatorname{tg} \varphi \operatorname{tg} \psi}$$

$$\varphi + \psi = \operatorname{arctg} \frac{\operatorname{tg} \varphi + \operatorname{tg} \psi}{1 - \operatorname{tg} \varphi \operatorname{tg} \psi}$$

Dla u bardzo dużego:

$$\frac{u}{2} = e^{\frac{(k+1)}{2} x}$$

$$= \operatorname{arctg} \frac{\frac{2u}{\sqrt{4C-A^2}}}{1 - \frac{(2u-A)A}{4C-A^2}} = \operatorname{arctg} \frac{\frac{2u}{\sqrt{4C-A^2}}}{\frac{4C-2uA}{4C-A^2}}$$

$$= \operatorname{arctg} \frac{2u \sqrt{4C-A^2}}{2C-uA}$$

dla miedzy u potu przyblizenie:

$$\frac{(k+1)^{\frac{1}{2}}}{\frac{4}{3}} x = \frac{A}{\sqrt{4C-A^2}} \cdot \frac{\sqrt{4C-A^2} \cdot u}{2C} = \frac{Au}{2C}$$

$$\frac{(k+1)^{\frac{1}{2}}}{\frac{4}{3}} \frac{10u_0}{2R\theta_0} x = \frac{Au(k+1)}{2R\theta_0}$$

$$\frac{du}{dx} = \frac{(k+1)^{\frac{1}{2}}}{\frac{4}{3}} \frac{u - Au + C}{u} = \frac{(k+1)^{\frac{1}{2}}}{\frac{4}{3}} \cdot \frac{C}{u_0} = \frac{(k+1)^{\frac{1}{2}}}{\frac{4}{3}} \frac{10u_0}{R\theta_0} \frac{R\theta_0}{k+1} = \frac{10u_0}{\frac{4}{3}}$$

wic tam bedzie: $u = u_0 + \frac{10u_0}{\frac{4}{3}} x$

$$\frac{du}{dx} \Big|_{now} = \frac{1}{x} \frac{[x + \frac{C}{A}] [x - Au + C]}{u_0} \left(\frac{10u_0}{R\theta_0} \right)^2$$

$$= \frac{1}{x} = \frac{10^2}{\frac{4}{3} u_0}$$

$$\frac{(k+1)^{\frac{1}{2}}}{\frac{4}{3}} x + \text{const} = \frac{1}{2} \log(u^2 - Au + C) + \frac{A}{2} \frac{1}{\sqrt{A^2 - 4C}} \log \left[\frac{A + \sqrt{A^2 - 4C} - 2u}{A - \sqrt{A^2 - 4C} - 2u} \right]$$

Gdy u od miedzy wartosci porowazamy dla ktorego: $\frac{(k+1)^{\frac{1}{2}}}{\frac{4}{3}} x + \text{const} = \frac{1}{2} \log C + \frac{A}{2} \frac{1}{\sqrt{A^2 - 4C}} \log \frac{A + \sqrt{A^2 - 4C}}{A - \sqrt{A^2 - 4C}}$

zliwiz do $u = \frac{A}{2} - \sqrt{\frac{A^2}{4} - C}$ to otrzymujemy przyjmiem kontakt:

$$\frac{(k+1)^{\frac{1}{2}}}{\frac{4}{3}} x + \text{const} = -\infty + \Delta$$

stady bedzie $\frac{du}{dx} \rightarrow \infty$ Now - dla u

gdz A, C wialosci:

$$u = \frac{A}{2} \left[1 - \left(1 - \frac{4C}{A^2} \right)^{\frac{1}{2}} \right] = \frac{A}{2} \left[1 - 1 + \frac{2C}{A^2} \right]$$

$$= \frac{C}{A} \quad // = \alpha$$

Obliczmy naj wartości $-\infty + \infty$.

~~Wzrost~~

$$\lim_{u \rightarrow \frac{A}{2} - \sqrt{\frac{A^2}{4} - C}} \left\{ \frac{1}{2} \log \frac{\left(\frac{A}{2} - \sqrt{\frac{A^2}{4} - C} - u \right) \left(\frac{A}{2} + \sqrt{\frac{A^2}{4} - C} \right)}{\left(\frac{A}{2} - \sqrt{\frac{A^2}{4} - C} + u \right) \left(\frac{A}{2} + \sqrt{\frac{A^2}{4} - C} \right)} \right\}$$

\downarrow

$$\left(\frac{A}{2} - \sqrt{\frac{A^2}{4} - C} - u \right) \left(\frac{A}{2} + \sqrt{\frac{A^2}{4} - C} \right)$$

$\underbrace{\hspace{2cm}}_{\delta}$

$$= \frac{1}{2} \log \frac{[\delta + \sqrt{A^2 - 4C}]^{1 + \frac{A}{\sqrt{A^2 - 4C}}}}{\delta \left(\frac{A}{\sqrt{A^2 - 4C}} - 1 \right)}$$

$\frac{A}{2} + \sqrt{\frac{A^2}{4} - C} = \delta + \sqrt{A^2 - 4C}$

wzrost będzie $= +\infty$ jeżeli ponieważ $A > \sqrt{A^2 - 4C}$

zatem dla $x = \infty$ u osiąga wartości nieskończoność $u = \frac{A}{2} - \sqrt{\frac{A^2}{4} - C} = \alpha$

$$u^2 = \frac{A^2}{4} - C - A\sqrt{\frac{A^2}{4} - C}$$

~~Przebieg~~

$x = \infty \quad u = \alpha$
 $x \neq 0 \quad u = u(x)$

Tem będzie.

$$\theta = \frac{1}{2R} \left\{ (k-1) \left(\frac{A^2}{2} - C - A\sqrt{\frac{A^2}{4} - C} \right) - \frac{(k+1)}{k} \left(\frac{A^2}{2} - A\sqrt{\frac{A^2}{4} - C} \right) + (k+1) C \right\}$$

$$\theta = \frac{1}{2R} \left\{ \frac{1-k}{k} \frac{A^2}{2} + 2C + \frac{k-1}{k} A \sqrt{\frac{A^2}{4} - C} \right\}$$

$\alpha^2 - \alpha A + C = 0$
 $A = \frac{\alpha^2 + C}{\alpha}$

$$\theta_{\infty} = \frac{1}{2R} \left[-\frac{k-1}{k} A \left(\frac{A}{2} - \sqrt{\frac{A^2}{4} - C} \right) + 2C \right] = \frac{1}{2R} \left[2C - \frac{(k-1)}{k} (\alpha^2 + C) \right]$$

$$\theta_{\infty} = \frac{1}{2R} \left[C \left(2 - \frac{k-1}{k} \right) - \frac{k-1}{k} \alpha^2 \right] = \frac{1}{2kR} \left[(k+1)C - (k-1)\alpha^2 \right]$$

$$f_{\infty} = \frac{R b \theta_{\infty}}{\alpha} = \frac{b}{2k\alpha} \left[(k+1)C - (k-1)\alpha^2 \right]$$

$$\begin{aligned} \sqrt{A^2 - 4C} &= \sqrt{\left(\frac{\alpha^2 + C}{\alpha} \right)^2 - 4C} \\ &= \sqrt{\frac{\alpha^4 + 2\alpha^2 C + C^2 - 4\alpha^2 C}{\alpha^2}} \\ &= \frac{\alpha^2 - C}{\alpha} \end{aligned}$$

$$\frac{p}{p_0} = K\alpha \frac{[(K-1)u + (K+1)\frac{C}{u} - \frac{(K^2-1)}{2} \frac{\alpha^2+C}{\alpha}]}{(K+1)C - (K-1)\alpha^2}$$

$$\begin{aligned} \frac{(K+1)\frac{b}{2}}{\frac{4\mu}{3}} x + \text{const} &= \frac{1}{2} \log \left[u^2 - \frac{\alpha^2+C}{\alpha} u + C \right] \\ &+ \frac{\alpha^2+C}{2\alpha} \frac{\alpha}{\alpha^2-C} \log \frac{\alpha + \frac{\alpha^2-C}{\alpha} - u}{\alpha - u} \\ &= \frac{1}{2} \log \left[u^2 - \alpha u - \frac{C}{\alpha} u + C \right] + \frac{\alpha^2+C}{2(\alpha^2-C)} \log \left[\frac{2 - \frac{C}{\alpha^2} - \frac{u}{\alpha}}{1 - \frac{u}{\alpha}} \right] \end{aligned}$$

punkt für $u=0$: $x=0$

$$\text{const} = \frac{1}{2} \log C + \frac{\alpha^2+C}{2(\alpha^2-C)} \log \left(2 - \frac{C}{\alpha^2} \right)$$

$$\frac{(K+1)\frac{b}{2}}{\frac{4\mu}{3}} x = \frac{1}{2} \log \left[\frac{u^2 - \alpha u}{C} - \frac{u}{\alpha} + 1 \right] + \frac{\alpha^2+C}{2(\alpha^2-C)} \log \left[\frac{1 - \frac{u\alpha}{2\alpha^2-C}}{1 - \frac{u}{\alpha}} \right]$$

$$p_0 = \frac{b}{2} (K+1) \frac{C}{u_0} = \frac{(K+1)C}{2} p_0$$

tan tot $\frac{du}{dx} = \infty$ punkt wölben

$C = 1 \alpha^2 C$

linien pythéenne:

$$\theta = \theta_0 + \frac{\mu c^2}{32\kappa} \left\{ 3a^2 \left[-\frac{q}{n^2} + \frac{3x^2}{n^2} - \frac{a^2}{n^4} - \frac{2}{3} \frac{a^4}{n^6} + 4a^2 \frac{x^2}{n^6} - 2 \frac{a^4 x^2}{n^8} \right] + \right. \\ \left. + \frac{a}{n} \left[19 + 13 \frac{a^2}{n^2} + 24 \frac{x^2}{n^2} - 39 \frac{x^2 a^2}{n^4} \right] \right\}$$

da $x=a$:

$$\left\{ \right\} = 3 \left[\underbrace{-9 - 1 - \frac{2}{3}}_{-32} + 3 \frac{x^2}{a^2} + 4 \frac{x^2}{a^2} - 2 \frac{x^2}{a^2} \right] + \left[19 + 13 - 15 \frac{x^2}{a^2} \right] \\ - 32 + 15 \frac{x^2}{a^2} + 32 - 15 \frac{x^2}{a^2} = 0$$

da $x=0$:

$$\theta = \theta_0 + \frac{\mu c^2}{32\kappa} \left\{ -3a^2 \left[\frac{q}{n^2} + \frac{a^2}{n^4} + \frac{2}{3} \frac{a^4}{n^6} \right] + \frac{a}{n} \left[19 + 13 \frac{a^2}{n^2} \right] \right\}$$

$$\frac{\partial \theta}{\partial x} = \frac{\mu c^2}{32\kappa} \left\{ 3a^2 \left[\frac{18}{n^3} + \frac{4a^2}{n^5} + \frac{4a^4}{n^7} \right] - \frac{a}{n^2} \left[19 + 39 \frac{a^2}{n^2} \right] \right\}_{x=0}$$

$$= \frac{\mu c^2}{32\kappa a} \left\{ \frac{18}{78} - 58 \right\} = \frac{5}{8} \frac{\mu c^2}{\kappa a}$$

$x=2$

$$\theta = \theta_0 + \frac{\mu c^2}{32\kappa} \left\{ 3a^2 \left[-\frac{q}{n^2} + \frac{3x^2}{n^2} - \frac{a^2}{n^4} - \frac{2}{3} \frac{a^4}{n^6} + 4a^2 \frac{x^2}{n^6} - 2 \frac{a^4 x^2}{n^8} \right] + \right. \\ \left. + \frac{a}{n} \left[19 + 13 \frac{a^2}{n^2} + 24 - 39 \frac{a^2}{n^2} \right] \right\}$$

$$\left\{ \right\} = \left\{ 3a^2 \left[-\frac{6}{n^2} + \frac{3a^2}{n^4} - \frac{2}{3} \frac{a^4}{n^6} \right] + \frac{a}{n} \left[43 - 20 \frac{a^2}{n^2} \right] \right\}$$

$$\frac{\partial \theta}{\partial x} = 3a^2 \left[\frac{12}{n^3} - \frac{12a^2}{n^5} + \frac{48}{3} \frac{a^4}{n^7} \right] - \frac{a}{n^2} \left[43 - \frac{78}{32} \frac{a^2}{n^2} \right]$$

$$\frac{\mu c^2}{2\kappa} \left[\frac{48}{32} + \frac{35}{32} \right] = \frac{\mu c^2}{2\kappa} \frac{83}{32} = \frac{\mu c^2}{2\kappa} \left(2 + \frac{19}{32} \right)$$

$$\frac{\partial \theta}{\partial x} = \frac{\mu c^2}{32k} \left\{ 3a^2 \left[\frac{18x}{n^4} - \frac{12x^3}{n^6} + \frac{4a^2x}{n^6} + \frac{4a^4x}{n^8} - \frac{24a^2x^3}{n^8} + \frac{16a^4x^3}{n^{10}} + \right. \right. \\ \left. \left. + \frac{6x}{n^4} + \frac{8a^2x}{n^6} - \frac{4a^4x}{n^8} \right] + \left[-19 \frac{a^3x}{n^3} - 39 \frac{a^3x}{n^5} - 72 \frac{a^3x^3}{n^5} + 5.39 \frac{a^3x^3}{n^7} + \frac{68xa}{n^3} - 2.39 \frac{a^3x}{n^5} \right] \right\}$$

$$= \frac{\mu c^2}{32k} \left\{ 3a^2 \left[\frac{24x}{n^4} + \frac{12a^2x}{n^6} - \frac{12x^3}{n^6} - \frac{24a^2x^3}{n^8} + \frac{16a^4x^3}{n^{10}} \right] + \right. \\ \left. + \left[29 \frac{ax}{n^3} - 9.13 \frac{a^3x}{n^5} - 72 \frac{ax^3}{n^5} + 15.13 \frac{a^3x^3}{n^7} \right] \right\} = Mx + Nx$$

$$\frac{\partial \theta}{\partial y} = \frac{\mu c^2}{32k} \left\{ 3a^2 \left[\frac{18}{n^4} - \frac{12x^2}{n^6} + \frac{4a^2}{n^6} + \frac{4a^4}{n^8} - \frac{24a^2x^2}{n^8} + \frac{16a^4x^2}{n^{10}} \right] y + \right. \\ \left. + \left[-\frac{19a}{n^3} - 39 \frac{a^3}{n^5} - 72 \frac{ax^2}{n^5} + 5.39 \frac{a^3x^2}{n^7} \right] y \right\} = My$$

$$\frac{\partial \theta}{\partial z} = 2 \dots$$

$$\mu \frac{\partial \theta}{\partial x} + \nu \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} = -\frac{3}{4} c a \left(1 - \frac{a^2}{n^2} \right) \frac{x}{n} M + c \left(1 - \frac{3}{4} \frac{a}{n} - \frac{1}{4} \frac{a^3}{n^3} \right) Mx$$

$$+ Nux$$

$$= M c x \left[1 - \frac{3}{4} \frac{a}{n} - \frac{1}{4} \frac{a^3}{n^3} - \frac{3}{4} \frac{a}{n} + \frac{3}{4} \frac{a^3}{n^3} \right] + Nux$$

$$= M c x \left[1 - \frac{3}{2} \frac{a}{n} + \frac{1}{2} \frac{a^3}{n^3} \right] + Nux$$

$$N = 3a^2 \left[\frac{6}{n^4} + \frac{8a^2}{n^6} - \frac{4a^4}{n^8} \right] + \frac{68a}{n^3} - 2.39 \frac{a^3}{n^5}$$

$$\begin{aligned}
& \left[\frac{18}{2^4} - \frac{12x^2}{2^6} + \frac{4x^4}{2^8} + \frac{4x^4}{2^8} - \frac{24x^2x^2}{2^{10}} + \frac{16x^2x^2}{2^{10}} \right] 3x^2 + \left[\frac{-19x^4}{2^5} - \frac{39x^3}{2^5} - 72 \frac{x^2x^2}{2^5} + 5.39 \frac{x^2x^2}{2^7} \right] \\
& + 3x^2 \left[\frac{19}{2^{14}} + \frac{36x^2}{2^6} + \frac{39x^2}{2 \cdot 2^6} - \frac{5.39x^2x^2}{2 \cdot 2^8} \right] - \frac{81x^3}{2^5} + \frac{54x^2x^2}{2^7} - \frac{18x^5}{2^7} - \frac{18x^7}{2^9} + \frac{108x^5x^2}{2^9} - \frac{72x^7x^2}{2^{11}} \\
& - \frac{19x^4}{2 \cdot 2^6} - \frac{39x^4}{2 \cdot 2^6} - 36 \frac{x^2x^4}{2^8} + \frac{5.39}{2} \frac{x^2}{2^{10}} + \frac{27x^5}{2^7} - \frac{18x^5x^2}{2^9} + \frac{6x^7}{2^9} + \frac{6x^7}{2^{11}} - \frac{36x^7x^2}{2^{11}} + \frac{24x^9x^2}{2^{13}} \\
& - 36 \frac{x^2x^2}{2^4} - 12 \frac{x^4}{2^6} - 36 \frac{x^2x^2}{2^6} + 36 \frac{x^4x^2}{2^6} + 48 \frac{x^2x^2}{2^3} \\
& + 18 \frac{x^2}{2^4} - \frac{27}{2} \frac{x^3}{2^5} - \frac{9}{2} \frac{x^5}{2^7} - \frac{27x^3x^2}{2^7} + \frac{27x^5x^2}{2^9} \\
& + 24 \frac{x^4}{2^6} - 18 \frac{x^5}{2^7} - 6 \frac{x^7}{2^9} - 18 \frac{x^5x^2}{2^9} + 18 \frac{x^7x^2}{2^{11}} \\
& - 12 \frac{x^6}{2^8} + 9 \frac{x^8}{2^9} + 3 \frac{x^9}{2^{11}} + 9 \frac{x^7x^2}{2^{11}} - 9 \frac{x^9x^2}{2^{13}} \\
& + \frac{2}{2} \cdot 13 \frac{x^4}{2^6} + \frac{2}{2} \cdot 13 \frac{x^6}{2^8} + \frac{9}{2} \cdot 13 \frac{x^4x^2}{2^8} - \frac{9}{2} \cdot 13 \frac{x^6x^2}{2^{10}} - 6.13 \frac{x^3}{2^5}
\end{aligned}$$

$$\begin{aligned}
& = \frac{x^2}{2^4} \left[3.18 + \frac{3.19}{2} - 36 + 18 \right] - \frac{x^2x^2}{2^6} \left[3.12 - 3.36 + 36 \right] + \frac{x^4}{2^6} \left[12 + \frac{3.39}{2} - \frac{18}{2} - 12 \right. \\
& \quad \left. + 24 + \frac{9}{2} \cdot 13 \right] \\
& + \frac{x^6}{2^8} \left[12 - \frac{39}{2} - 12 + \frac{9}{2} \cdot 13 \right] + \frac{x^4x^2}{2^8} \left[-72 - \frac{3.5.39}{2} - 36 + 36 + \frac{9}{2} \cdot 13 \right] + \\
& + \frac{x^6x^2}{2^{10}} \left[48 + \frac{5.39}{2} - 9 \cdot \frac{13}{2} \right] + \frac{x^2}{2^5} \left[-10 \right] + \frac{x^3}{2^5} \left[-39 - 81 - \frac{27}{2} - 6.13 \right] + \\
& + \frac{x^5}{2^5} \left[-72 \right] + \frac{x^3x^2}{2^7} \left[5.39 + 54 - \frac{27}{2} \right] + \frac{x^5}{2^7} \left[-18 + 27 - \frac{9}{2} - 18 \right] + \\
& + \frac{x^7}{2^9} \left[-18 + 18 - 18 + 9 \right] + \frac{x^5x^2}{2^9} \left[108 - 18 + \frac{27}{2} - 18 \right] + \frac{x^7x^2}{2^{11}} \left[-72 - 36 + 18 + 9 \right] \\
& + \frac{x^9}{2^{11}} \left[6 + 3 \right] + \frac{x^7x^2}{2^{13}} \left[24 - 9 \right]
\end{aligned}$$

$$= \frac{2^2}{2^4} + \frac{\frac{129}{2}}{\frac{54}{2}} + \frac{a^2 \cdot 2}{2^6} \cdot 36 + \frac{a^4}{2^8} \cdot \frac{114}{24} = \frac{263}{2} + \frac{2 \cdot 113}{2 \cdot 24} + \frac{a^4 \cdot (-306)}{2^8} + \frac{39}{48}$$

$$+ \frac{a}{2^3} \cdot 29 + \frac{a^3}{2^5} \cdot \frac{120}{78} \cdot \frac{36}{24} - \frac{a^4}{2^5} \cdot 72 + \frac{a^2}{2^7} \cdot \frac{105}{54} \cdot \frac{249}{498} = \left(+ \frac{471}{2} \right)$$

$$+ \frac{a^5}{2^7} \cdot \left(-\frac{27}{2} \right) + \frac{a^7}{2^9} \cdot (-9) + \frac{a^5}{2^9} \cdot \frac{105}{24} + \frac{a^7}{2^{11}} \cdot (-81) + 4 \frac{a^4}{2^{11}} + 15 \frac{a^9}{2^{13}}$$

$$u \frac{20}{2^2} + v \frac{20}{2^2} + w \frac{20}{2^2} = \frac{\mu c x}{32} \left[\frac{129}{2} \frac{a^2}{2^4} + 30 \frac{a^4}{2^6} + \frac{263}{2} \frac{a^6}{2^6} - 306 \frac{a^8}{2^8} + 29 \frac{a^{10}}{2^{10}} + 23 \frac{a^{12}}{2^{12}} - \frac{423}{2} \frac{a^{14}}{2^{14}} - 72 \frac{a^{16}}{2^{16}} + \frac{471}{2} \frac{a^{18}}{2^{18}} - \frac{27}{2} \frac{a^{20}}{2^{20}} - \frac{9}{2} \frac{a^{22}}{2^{22}} + \frac{17}{2} \frac{a^{24}}{2^{24}} - 81 \frac{a^{26}}{2^{26}} + 9 \frac{a^{28}}{2^{28}} + 15 \frac{a^{30}}{2^{30}} \right]$$

$$u = \frac{\mu c x}{32} \left[\frac{129}{2} \frac{a^2}{2^4} + 30 \frac{a^4}{2^6} + \frac{263}{2} \frac{a^6}{2^6} - 306 \frac{a^8}{2^8} + 29 \frac{a^{10}}{2^{10}} + 23 \frac{a^{12}}{2^{12}} - \frac{423}{2} \frac{a^{14}}{2^{14}} - 72 \frac{a^{16}}{2^{16}} + \frac{471}{2} \frac{a^{18}}{2^{18}} - \frac{27}{2} \frac{a^{20}}{2^{20}} - \frac{9}{2} \frac{a^{22}}{2^{22}} + \frac{17}{2} \frac{a^{24}}{2^{24}} - 81 \frac{a^{26}}{2^{26}} + 9 \frac{a^{28}}{2^{28}} + 15 \frac{a^{30}}{2^{30}} \right]$$

$$\begin{array}{r} 196 \\ 29 \\ \hline 225 \end{array} \quad \begin{array}{r} 306 \\ 225 \\ \hline 531 \\ 225 \\ \hline -306 \\ \hline 153 \end{array}$$

$$\begin{array}{r} 42 \\ 15 \\ \hline +57 \end{array}$$

$$\begin{array}{r} 222 \\ 52 \\ \hline -105 \end{array}$$

$$\begin{array}{r} 129 \\ 2 \\ \hline 263 \\ 29 \\ \hline -423 \\ 2 \end{array}$$

$$\frac{342}{2} = 171$$

$$456 \cdot 225$$

$$48$$

$$144$$

$$-27$$

$$u \frac{20}{2^2} = \frac{\mu c^2}{32} \left[(29 - 72) \frac{a^2}{2^2} + \frac{a^2}{2^4} \left(-\frac{423}{2} + \frac{471}{2} \right) + \frac{a^5}{2^5} \left(-\frac{27}{2} + \frac{171}{2} \right) + \frac{a^7}{2^7} (-9 - 81) + 24 \frac{a^9}{2^{10}} \right]$$

$$= \frac{\mu c^2}{32} \left[(29 - 72) \frac{a^2}{2^2} + \frac{a^2}{2^4} \left(-\frac{423}{2} + \frac{471}{2} \right) + \frac{a^5}{2^5} \left(-\frac{27}{2} + \frac{171}{2} \right) + \frac{a^7}{2^7} (-9 - 81) + 24 \frac{a^9}{2^{10}} \right]$$

$$u = a$$

$$+9$$

$$u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} = \nabla \theta \cdot \frac{1}{r} \nabla r \cos(\alpha, \theta)$$

$$= \frac{\mu c^2}{32 \kappa} \left\{ \frac{129}{2} \frac{a^2 x^2}{2^4} + 36 \frac{a^2 x^3}{2^6} + \frac{263}{2} \frac{a^2 x^4}{2^6} - 306 \frac{a^4 x^2}{2^8} + 87 \frac{a^6 x^3}{2^{10}} \right. \\ \left. + 29 \frac{a^2 x^5}{2^3} - \frac{423}{2} \frac{a^2 x^6}{2^5} - 72 \frac{a^2 x^7}{2^5} + \frac{471}{2} \frac{a^2 x^8}{2^7} - \frac{27}{2} \frac{a^5 x^2}{2^7} - 9 \frac{a^7 x^3}{2^9} + \frac{171}{2} \frac{a^5 x^5}{2^9} - \right. \\ \left. - 81 \frac{a^7 x^3}{2^{11}} + 9 \frac{a^9 x^3}{2^{11}} + 15 \frac{a^9 x^3}{2^{13}} \right\}$$

$$\Delta^2 \left(\frac{x}{2^3} \right) = -2 \frac{x}{2^3}$$

$$\Delta^2 \left(\frac{x}{2^2} \right) = \frac{x}{2^4}$$

$$\Delta^2 \left(\frac{x}{2^3} \right) = 0$$

$$\Delta^2 \left(\frac{x}{2^4} \right) = 4 \frac{x}{2^6}$$

$$\Delta^2 \left(\frac{x}{2^5} \right) = 10 \frac{x}{2^7}$$

$$\Delta^2 \left(\frac{x}{2^6} \right) = 18 \frac{x}{2^8}$$

$$\Delta^2 \left(\frac{x}{2^7} \right) = 28 \frac{x}{2^9}$$

$$\Delta^2 \left(\frac{x}{2^8} \right) = 40 \frac{x}{2^{10}}$$

$$\Delta^2 \left(\frac{x}{2^9} \right) = 54 \frac{x}{2^{11}}$$

$$\Delta^2 \left(\frac{x^3}{2^3} \right) = \frac{6x^3}{2^3} - 12 \frac{x^3}{2^5}$$

$$\Delta^2 \left(\frac{x^3}{2^4} \right) = \frac{6x^3}{2^4} - 12 \frac{x^3}{2^6}$$

$$\Delta^2 \left(\frac{x^3}{2^5} \right) = \frac{6x^3}{2^5} - 10 \frac{x^3}{2^7}$$

$$\Delta^2 \left(\frac{x^3}{2^6} \right) = \frac{6x^3}{2^6} - 6 \frac{x^3}{2^8}$$

$$\Delta^2 \left(\frac{x^3}{2^7} \right) = \frac{6x^3}{2^7} - 8 \frac{x^3}{2^9}$$

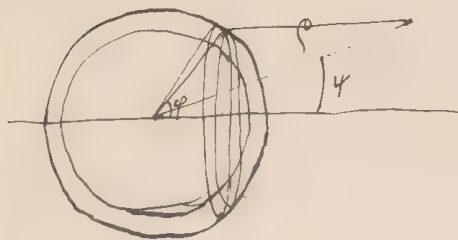
$$\Delta^2 \left(\frac{x^3}{2^8} \right) = \frac{6x^3}{2^8} - 8 \frac{x^3}{2^{10}}$$

$$\Delta^2 \left(\frac{x^3}{2^9} \right) = \frac{6x^3}{2^9} - 18 \frac{x^3}{2^{11}}$$

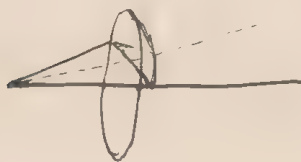
$$\Delta^2 \left(\frac{x^3}{2^{10}} \right) = \frac{6x^3}{2^{10}} - 44 \frac{x^3}{2^{12}}$$

$$\text{pot}\left(\frac{x}{r^2}\right) = \text{pot} \frac{\cos \varphi}{r^2} = \text{pot} \frac{\partial}{\partial x} \left(\frac{1}{r^2} \right)$$

$$\cos \chi = \cos \varphi \cos \psi + \sin \varphi \sin \psi \cos \varepsilon$$



$$\frac{1}{\rho} = \frac{1}{\sqrt{r^2 + R^2 - 2Rr \cos \chi}}$$



$$\int_0^{2\pi} \int_0^\pi \int_0^R \frac{dr \, d\psi \, \sin \varphi \, d\varepsilon \cdot \cos \varphi}{r^2 \sqrt{r^2 + R^2 - 2Rr \cos \chi}}$$

$$\begin{aligned} a &= R^2 \\ b &= -2Rr \cos \chi \\ c &= 1 \end{aligned}$$

$$\int_a^R \frac{dr}{r^2 \sqrt{r^2 + R^2 - 2Rr \cos \chi}} = -\frac{1}{R^2 r} + \frac{2R \cos \chi}{2R^2} \int \frac{dr}{r \sqrt{r^2 + R^2 - 2Rr \cos \chi}} = \frac{1}{R} \ln \frac{2R \sqrt{r^2 + R^2 - 2Rr \cos \chi} - (2R^2 - 2Rr \cos \chi)}{r}$$

$$\text{pot}\left(\frac{x}{r^n}\right) = -\text{pot} \frac{\partial}{\partial x} \left(\frac{1}{r^{n-2}} \right) = -\frac{1}{n-2} \frac{\partial}{\partial x} \text{pot}\left(\frac{1}{r^{n-2}}\right)$$

$$\int_a^R \frac{r^2 dr}{r^{n-2}} = \int_a^R r^{4-n} dr = \frac{r^{5-n}}{(5-n)} \Big|_a^R = \frac{R^{5-n} - a^{5-n}}{(5-n)} = \frac{R^{5-n}}{(5-n)} = \frac{1}{n-2} \frac{x}{R^{n-2}} = \text{pot}\left(\frac{x}{r^n}\right)$$

$$\frac{\partial}{\partial x} \left(\frac{1}{x^2} \right) = -\frac{x}{x^3}$$

$$\frac{\partial^2}{\partial x^2} = -\frac{1}{x^3} + \frac{2x^2}{x^5}$$

$$\frac{\partial^3}{\partial x^3} = -\frac{3x}{x^5} + \frac{6x}{x^5} - \frac{15x^3}{x^7} = \frac{3x}{x^5} - \frac{15x^3}{x^7}$$

$$\frac{\partial}{\partial x} \left(\frac{1}{x^3} \right) = -\frac{3x}{x^5}$$

$$\frac{\partial^2}{\partial x^2} = -\frac{3}{x^5} + \frac{15x^2}{x^7}$$

$$\frac{\partial^3}{\partial x^3} = +\frac{15x}{x^7} + \frac{30x}{x^7} - \frac{2 \cdot 5 \cdot 7 \cdot x^3}{x^9} = \frac{45x}{x^7} - \frac{105x^3}{x^9}$$

$$105 \frac{x^3}{x^9} = -\frac{\partial^3}{\partial x^3} \left(\frac{1}{x^3} \right) + \frac{45}{x^5} \frac{\partial}{\partial x} \left(\frac{1}{x^5} \right)$$

$$\frac{x^3}{x^9} = -\frac{1}{105} \frac{\partial^3}{\partial x^3} \left(\frac{1}{x^3} \right) - \frac{3}{35} \frac{\partial}{\partial x} \left(\frac{1}{x^5} \right)$$

$$\text{put } \left(\frac{x^3}{x^9} \right) = -\frac{1}{105} \frac{\partial^3}{\partial x^3} \text{put} \left(\frac{1}{x^3} \right) - \frac{3}{35} \frac{\partial}{\partial x} \text{put} \left(\frac{1}{x^5} \right)$$

$$\int \frac{r^2 dr}{x^3} = \log R \quad \frac{\log R}{\frac{1}{x^2}}$$

$$\int \frac{r^2 dr}{x^5} = \int \frac{dr}{x^3} = -\frac{1}{2x^2}$$

$$\frac{\partial}{\partial x} \left(\log \frac{x}{x^2} \right) = \left(\frac{1}{x^2} - \frac{\log x}{x^2} \right) \frac{x}{x^2}$$

$$\frac{x}{x^3} \quad \frac{x}{x^4} \quad \frac{x}{x^3} \log x$$

$$\frac{\partial}{\partial x} \left(\frac{x}{25} \log 2 \right) = \frac{1}{25} \log 2 - \frac{3x^2}{25} \log 2 + \frac{x^2}{25}$$

$$\begin{aligned} \frac{\partial}{\partial x} (\quad) &= -\frac{3x}{25} \log 2 + \frac{x}{25} - \frac{6x}{25} \log 2 + \frac{15x^3}{27} \log 2 - \frac{3x^3}{27} + \frac{2x}{25} - \frac{5x^3}{27} \\ &= \frac{3x}{25} - \frac{8x^3}{27} - \frac{9x}{25} \log 2 + \frac{15x^3}{27} \log 2 \end{aligned}$$

$$\frac{\partial}{\partial x} \left(\frac{x}{25} \log 2 \right) = -\frac{3x}{25} \log 2 + \frac{x}{25}$$

$$\begin{aligned} \frac{\partial^2}{\partial x^2} &= -\frac{3x}{25} \log 2 + \frac{15x^2}{27} \log 2 - \frac{3x^2}{27} + \frac{x}{25} - \frac{5x^2}{27} \\ &= \frac{x}{25} - \frac{8x^2}{27} - \frac{3x}{25} \log 2 + \frac{15x^2}{27} \log 2 \end{aligned}$$

$$\Delta^2 \left(\frac{x}{25} \log 2 \right) = \frac{5x}{25} - \frac{8x}{25} - \frac{15x}{25} \log 2 + \frac{15x}{25} \log 2 = -\frac{3x}{25}$$

$$\frac{\partial^3}{\partial x^3} \left(\frac{x}{25} \log 2 \right) = \dots + \frac{45x^2}{27} \log 2 - \frac{9}{25} \log 2 + \frac{75x^2}{27} \log 2 - \frac{15 \cdot 7x^4}{29} \log 2$$

$$\frac{\partial^2}{\partial x^2} \left(\frac{x}{25} \log 2 \right) = \frac{2x}{27} \log 2 - \frac{7x^3}{29} \log 2 + \frac{x^3}{29} \log 2 = -\frac{7x^2}{29} \log 2 + \frac{x^2}{29}$$

$$\begin{aligned} \frac{2}{27} \log 2 - \frac{85x^2}{29} \log 2 - \frac{1x}{29} \log 2 + \frac{63x^2}{29} \log 2 + \frac{2x^2}{29} - \frac{7x^4}{29} + \frac{3x^4}{25} - \frac{9x^4}{29} \\ - \frac{7x^2}{29} \log 2 + \frac{63x^2}{29} \log 2 - \frac{7x^2}{29} + \frac{x^2}{25} - \frac{9x^2}{29} \end{aligned}$$

$$\Delta^2 \left(\frac{x}{27} \log 2 \right) = \frac{2}{27} \log 2 - \frac{49x^2}{29} \log 2 + \frac{63x^2}{29} \log 2 + \frac{2x^2}{29} - \frac{7x^2}{29} + \frac{5x^2}{29} - \frac{9x^2}{29}$$

$$= \frac{2}{27} \log 2 + \frac{14x^2}{29} \log 2 - \frac{9x^2}{29}$$

$$\frac{\partial}{\partial x} \left(\frac{x}{2^5} \log_2 \right)$$

$$\frac{\partial}{\partial x}$$

$$\frac{1}{2^5} \log_2 - \frac{5x^1}{2^7} \log_2 + \frac{x^2}{2^7}$$

$$-\frac{15x}{2^7} \log_2 + \frac{35x^3}{2^9} \log_2 + \frac{x}{2^7} - \frac{5x^3}{2^9} + \frac{2x}{2^7} - \frac{7x^3}{2^9}$$

$$-\frac{5x^4}{2^7} \log_2 + \frac{x^4}{2^7}$$

$$-\frac{5x}{2^7} \log_2 + \frac{35x^4}{2^9} \log_2 + -\frac{5x^4}{2^9} + \frac{x}{2^7} - \frac{7x^4}{2^9}$$

$$-\frac{25x}{2^7} \log_2 + \frac{35x}{2^7} \log_2 + \frac{5x}{2^7} - \frac{12x}{2^7}$$

$$= \frac{10x}{2^7} \log_2 - \frac{7x}{2^7}$$

$$\frac{x^3}{2^7} \log_2$$

$$\frac{\partial}{\partial x}$$

$$\frac{3x^2}{2^7} \log_2 - \frac{7x^4}{2^9} \log_2 + \frac{x^4}{2^9}$$

$$\frac{6x}{2^7} \log_2 - \frac{49x^3}{2^9} \log_2 + \frac{63x^5}{2^{11}} \log_2 + \frac{3x^3}{2^9} - \frac{7x^5}{2^{11}} + \frac{4x^3}{2^9} - \frac{9x^5}{2^{11}}$$

$$-\frac{7x^3}{2^9} \log_2 + \frac{x^3}{2^9}$$

$$-\frac{7x^3}{2^9} \log_2 + \frac{63x^3}{2^{11}} \log_2$$

$$-\frac{7x^3}{2^{11}} + \frac{x^3}{2^9} - \frac{9x^3}{2^{11}}$$

$$\Delta = \frac{6x}{2^7} \log_2 + \frac{x^3}{2^9} - \frac{x^3}{2^9} - \frac{7x^3}{2^9}$$

$$\frac{x^3}{2^9} = \frac{6x}{2^7} \log_2 - \Delta \left(\frac{x^3}{2^7} \log_2 \right) \Big|_5$$

$$\frac{x}{2^7} = \Delta \left(\frac{x}{102^5} \right)$$

$$\frac{x}{2^7} = \frac{10x}{2^7} \log_2 - \Delta \left(\frac{x}{2^5} \log_2 \right) \Big|_5$$

$$\frac{5x^3}{2^9} - \frac{3x}{2^7} = \Delta \left(\frac{3x}{2^5} \log_2 - \frac{5x^3}{2^7} \log_2 \right)$$

$$\frac{5x^3}{2^9} = \Delta^2 \left(\frac{3}{10} \frac{x}{2^5} + \frac{3x}{7 \cdot 2^5} \log x - \frac{5x^3}{7 \cdot 2^7} \log^2 x \right)$$

$$\frac{x^3}{2^9} = \Delta^2 \left\{ \frac{3}{50} \frac{x}{2^5} + \frac{3x}{35 \cdot 2^5} \log x - \frac{x^3}{7 \cdot 2^7} \log^2 x \right\} = \Delta^2 \left\{ \frac{3x}{5 \cdot 2^5} \left[\frac{1}{10} + \frac{\log x}{7} \right] - \frac{x^3}{7 \cdot 2^7} \log^2 x \right\}$$

$$\frac{x}{2^5} = -\frac{1}{3} \Delta^2 \left(\frac{x}{2^5} \log^2 x \right)$$

$$\frac{x^5}{2^{11}}$$

$$\frac{x^3 \log^2 x}{2^{11}}$$

$$\rho \frac{\partial u}{\partial t} = -\frac{\partial p}{\partial x}$$

$$\frac{\partial p}{\partial t} + \rho \frac{\partial u}{\partial x} = 0$$

$$\rho \frac{\partial v}{\partial t} = -\frac{\partial p}{\partial x} + \mu \frac{\partial^2 v}{\partial x^2}$$

$$\frac{\partial p}{\partial t} + \kappa \rho \frac{\partial u}{\partial x} + \mu \frac{\partial^2 v}{\partial x^2} = (k-1) \left[\mu \Phi + \kappa \frac{\partial^2 v}{\partial x^2} \right]$$

$$v = A e^{-\alpha x} \cos(\rho x + y t)$$

$$\frac{\partial v}{\partial x} = A e^{-\alpha x} [-\alpha \cos - \rho \sin]$$

$$\frac{\partial v}{\partial t} = -A e^{-\alpha x} y \sin$$

$$\frac{\partial^2 v}{\partial x^2} = A e^{-\alpha x} [\alpha^2 \cos + \alpha \rho \sin - \rho^2 \cos]$$

$$\alpha x \Gamma = \alpha \cdot y$$

$$\frac{dx}{dt} = \Gamma$$

$$-\rho y = \mu \alpha \rho$$

$$\alpha = \rho$$

$$\alpha = \sqrt{\frac{\rho y}{\mu}}$$

$$v = A e^{-x \sqrt{\frac{\rho y}{\mu}}} \cos(x \sqrt{\frac{\rho y}{\mu}} - y t)$$

epitrymnik samkani $\sqrt{\frac{\mu}{\rho y}}$

$$\text{prędkość fali: } = \frac{y}{\sqrt{\frac{\rho y}{\mu}}} =$$

ten wyznosze z wykresem

$$\text{Kip. } y = 22 \text{ m} \quad \text{Kip. } u = 140$$

$$y = 1000$$

$$\frac{\partial p}{\partial t} + \mu \frac{\partial^2 v}{\partial x^2} + \kappa \rho \frac{\partial u}{\partial x} = (k-1) \left[\mu \left(\frac{\partial v}{\partial x} \right)^2 + \kappa \frac{\partial^2 v}{\partial x^2} \right]$$

$$\rho \frac{\partial u}{\partial t} = -\frac{\partial p}{\partial x}$$

$$\mu = \frac{1000}{6 \cdot 100000} = 10 \frac{\text{cm}}{\text{sec}}$$

$$\sqrt{\frac{\mu}{\rho y}} = 0.01$$

$$\frac{\partial p}{\partial t} + \rho \frac{\partial u}{\partial x} = 0$$

$$\text{Gdyby } u \text{ było } 0, \text{ } \rho = \text{const} \quad \frac{\partial^2 v}{\partial x^2} = A e^{-2\alpha x} [\cos + \sin(\alpha y t)]$$

$$= \alpha^2 A^2 e^{-2\alpha x} [1 + 2 \sin \alpha y t]$$

$$= \alpha^2 A^2 e^{-2\alpha x} [1 + \sin 2(\alpha y t)]$$

$$\theta = B e^{-\alpha x} [1 + m \cos(\alpha x + c t)]$$

$$\frac{\partial \theta}{\partial x} = B e^{-\alpha x} [a' + (a^2 - b^2) \sin \omega x + ab \sin \omega t] = \frac{\alpha^2 A^2}{\frac{\kappa}{\mu}} e^{-2\alpha x} [1 + \sin 2(\alpha x - \gamma t)]$$

$$a = b$$

$$bx + ct = 2\alpha x - \gamma t$$

$$a = 2\alpha$$

$$b = 2\alpha$$

$$c = -\gamma$$

$$4\alpha^2 B \frac{\kappa}{\mu} = A^2$$

$$m = 1$$

$$B = \frac{A^2}{4 \frac{\kappa}{\mu}}$$

$$4\alpha^2 m B \frac{\kappa}{\mu} = \alpha^2 A^2$$

$$\theta = M + \frac{A^2}{4 \frac{\kappa}{\mu}} e^{-2\alpha x} [1 + \sin 2(\alpha x - \gamma t)] + \text{ca}$$

$$\theta_0 = F(t) + \frac{A^2}{4 \frac{\kappa}{\mu}} [1 + \sin 2\gamma t]$$

$$F(t) = \theta_0 - \frac{A^2}{4 \frac{\kappa}{\mu}} [1 + \sin 2\gamma t]$$

$$\theta = \theta_0 + \frac{A^2}{4 \frac{\kappa}{\mu}} \left\{ e^{-2\alpha x} [1 + \sin 2(\alpha x - \gamma t)] - 1 - \sin 2\gamma t \right\}$$

$$\alpha = \sqrt{\frac{\rho}{\mu}} \gamma$$

$$\frac{1}{\rho} \frac{\partial \theta}{\partial t} = \frac{1}{\rho} \frac{\partial \theta_0}{\partial t} + \frac{1}{\rho} \frac{\partial \theta}{\partial t}$$

$$\frac{\partial \theta}{\partial t} = R(\theta) \frac{\partial \theta}{\partial t} + \left(\frac{\partial \theta}{\partial t} \right)' = -\gamma \frac{\partial u}{\partial x} + R(\theta) \frac{\partial \theta}{\partial t}$$

$$\text{Zweiter Schritt } u \frac{\partial \theta}{\partial x} = -\rho u \frac{\partial u}{\partial t}$$

$$(k-1) \gamma \frac{\partial u}{\partial x} + R(\theta) \frac{\partial \theta}{\partial t} = (k-1) \left[u \left(\frac{\partial u}{\partial x} \right)^2 + \kappa \frac{\partial \theta}{\partial x} \right]$$

$$\text{Zweiter Schritt } \frac{\partial u}{\partial x} = 0 \text{ falls } k=1$$

$$\alpha' = \sqrt{\frac{\rho}{\mu}} \gamma$$

$$\theta = \frac{A^2}{4 \frac{\kappa}{\mu}} \left\{ e^{-2\alpha x} [1 + \sin 2(\alpha x - \gamma t)] - e^{-2\alpha' x} \sin 2(\alpha' x - \gamma t) \right\} + \theta_0$$

$$\alpha' = \sqrt{\frac{\rho}{\mu}} \gamma$$

$$\frac{R}{\kappa} = \sqrt{\frac{\rho}{\mu}} = \sqrt{\frac{0.0013 \cdot 243}{0.0006 \cdot 15}} = \sqrt{\frac{0.000316}{0.0006 \cdot 15}} = \sqrt{\frac{0.000316}{0.009}} = \sqrt{0.0351} = 0.187$$

2. Atem α' berechnen

$$0.03$$

0 ile wyrażenie ciepła wartości przody smie !

$$\int_0^{\infty} \Phi dx = \alpha^2 A^2 \int_0^{\infty} e^{-2\alpha x} [1 + \sin 2(\alpha x - y t)] dx =$$

$$= \alpha^2 A^2 \int_0^{\infty} [e^{-2\alpha x} + e^{-2\alpha x} \sin 2\alpha x \cos y t - e^{-2\alpha x} \cos 2\alpha x \sin y t] dx$$

$$\int_0^{\infty} e^{-y} \sin y dy = -e^{-y} \sin y \Big|_0^{\infty} + \int_0^{\infty} e^{-y} \cos y dy = \frac{1}{2}$$

$$\int_0^{\infty} e^{-2\alpha x} \sin 2\alpha x dx = \frac{1}{2\alpha} \cdot \frac{1}{2} = \frac{1}{4\alpha}$$

$$\int_0^{\infty} e^{-2\alpha x} dx = \frac{1}{2\alpha}$$

$$\int \Phi = \alpha^2 A^2 \left[\frac{1}{2\alpha} + \frac{1}{4\alpha} \cos y t - \frac{1}{4\alpha} \sin y t \right]$$

$$= \frac{\alpha A^2}{4} [2 + \cos y t - \sin y t] = \frac{\alpha A^2}{4} \left[2 + \frac{\cos y t - \sin y t}{2} \right]$$

Wz. wyrażenia przody. grawa

Tryblin - the magnet method is very ~~interesting~~:

$$\left. \begin{aligned} \rho \frac{\partial u}{\partial t} &= -\frac{\partial p}{\partial x} + \mu \frac{\partial \text{div}}{\partial x} + \mu \Delta^2 u \\ \rho \frac{\partial v}{\partial t} &= -\frac{\partial p}{\partial y} + \mu \frac{\partial \text{div}}{\partial y} + \mu \Delta^2 v \\ &= \dots \end{aligned} \right\}$$

$$\begin{aligned} \frac{\partial \rho}{\partial t} + \rho \text{div} + u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} &= 0 \\ \frac{\partial \rho}{\partial t} + \rho \frac{\partial \text{div}}{\partial t} + \text{div} \frac{\partial \rho}{\partial t} + \frac{\partial u}{\partial x} \frac{\partial \rho}{\partial x} + \frac{\partial v}{\partial y} \frac{\partial \rho}{\partial y} + \frac{\partial w}{\partial z} \frac{\partial \rho}{\partial z} &= 0 \end{aligned}$$

$$\rho \frac{\partial \text{div}}{\partial t} + \left(\frac{\partial \rho}{\partial x} \frac{\partial u}{\partial t} + \frac{\partial \rho}{\partial y} \frac{\partial v}{\partial t} + \dots \right) = -\nabla^2 p + \mu \nabla^2 \text{div} + \mu \nabla^2 \text{div} \\ = -\nabla^2 p + \frac{4}{3} \mu \nabla^2 \text{div}$$

$$\left[\frac{\partial \rho}{\partial t} + \frac{\partial \rho}{\partial t} \text{div} + u \frac{\partial \rho}{\partial x} + \dots \right] = \nearrow$$

$$\rho \frac{\partial}{\partial t} \left(\frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right) + \frac{\partial \rho}{\partial y} \frac{\partial u}{\partial t} - \frac{\partial \rho}{\partial x} \frac{\partial v}{\partial t} = \mu \Delta^2 \left(\frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right)$$

]

[illegible]

$$\left. \begin{aligned} b &\equiv \alpha \frac{m}{n} \equiv \frac{b n}{n} \\ m b &= \cancel{\alpha m} = \beta \frac{n}{n} \end{aligned} \right\} \begin{aligned} \alpha \frac{m^2}{n} &\equiv \beta \frac{n}{n} & \frac{n}{n} &\equiv 1 \\ \beta &= \alpha \frac{m^2}{n} & \underline{\underline{n}} &= \underline{\underline{n}} \\ b &= \frac{\beta}{m} \end{aligned} \quad \begin{aligned} m &= \sqrt{\frac{n \beta}{\alpha}} \\ b &= \underline{\underline{\frac{\beta}{m}}} \end{aligned}$$

$$\begin{aligned} \nabla^2 \psi &= -\epsilon \nabla^2 \psi - \left[\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} + \frac{\partial^2 \psi}{\partial z^2} \right] + \nabla^2 \psi \\ \int \nabla^2 \psi \, d\tau &= -\epsilon \int \nabla^2 \psi \, d\tau - \int \left(\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} + \frac{\partial^2 \psi}{\partial z^2} \right) d\tau + \int \nabla^2 \psi \, d\tau \\ &= -\epsilon \int \nabla^2 \psi \, d\tau - \int \left(\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} + \frac{\partial^2 \psi}{\partial z^2} \right) d\tau + \int \nabla^2 \psi \, d\tau \end{aligned}$$

ε er mindre tykkelse i krummen n $\parallel \quad \frac{\partial \varepsilon}{\partial x} = \frac{\partial \varepsilon}{\partial n}$ ~~ikke~~ $\frac{\partial \varepsilon}{\partial x} = \frac{\partial \varepsilon}{\partial n}$

" " " " stygium
 " " " " isohyges

$$\frac{\partial \mathcal{L}}{\partial x} = \frac{\partial \mathcal{L}}{\partial n} \frac{\partial n}{\partial x} + \dots$$

$$\left. \begin{aligned} \frac{\partial \psi}{\partial x} &= 1 + \mu \frac{\partial u}{\partial x} = -\varepsilon \frac{\partial u}{\partial x} + \mu \frac{\partial u}{\partial x} \\ \frac{\partial \psi}{\partial y} &= 1 + \mu \frac{\partial v}{\partial y} = -\varepsilon \frac{\partial u}{\partial y} + \mu \frac{\partial v}{\partial y} \\ \frac{\partial \psi}{\partial z} &= 2 + \mu \frac{\partial w}{\partial z} = -\varepsilon \frac{\partial u}{\partial z} + \mu \frac{\partial w}{\partial z} \end{aligned} \right\} \begin{aligned} \nabla \psi &= -\varepsilon \nabla u + \mu \nabla v \end{aligned}$$

A nie zmienia się znacznie u dyfuzji δ

$$\left[\underbrace{\frac{\partial \psi}{\partial x} \cos nx + \frac{\partial \psi}{\partial y} \cos ny + \dots}_{\frac{\partial \psi}{\partial n}} \right] = -\varepsilon \left[\frac{\partial u}{\partial x} \cos nx + \dots \right] + \mu \left[\frac{\partial v}{\partial x} \cos nx + \dots \right]$$

~~$$u = u_0 + \xi u_1 + \xi^2 u_2$$

$$v = v_0 + \eta v_1 + \eta^2 v_2$$~~

nie tylko u punkcie 0 = 0 ale u poszczególnych n i m

$$\text{dla } \xi \cos nx + \eta \cos ny + \dots = 0$$

$$\text{dyfuzji takimi } u = v = 0$$

rozwiązanie dyfuzji
u dyfuzji = 0

$$u = u_0 + \xi \left(\frac{\partial u}{\partial x} \right)_0 + \eta \left(\frac{\partial u}{\partial y} \right)_0 + \xi^2 \left(\frac{\partial^2 u}{\partial x^2} \right)_0 + \dots$$

$$\xi \cos nx = -(\xi \cos nx + \eta \cos ny)$$

$$0 = \xi \left[\underbrace{\frac{\partial u}{\partial x} \cos nx - \frac{\partial u}{\partial z} \cos nx}_{=0} \right] + \eta \left[\underbrace{\frac{\partial u}{\partial y} \cos ny - \frac{\partial u}{\partial z} \cos ny}_{=0} \right]$$

$$\text{Zatem } \frac{\partial u}{\partial x} = \frac{\partial u}{\partial y} = \frac{\partial u}{\partial z} = \frac{\partial u}{\partial n}$$

$$\text{Zatem: } u = \left(\frac{\partial u}{\partial n} \right)_0 \left[\xi \cos nx + \eta \cos ny + \xi \cos n2 \right] + \frac{\xi^2}{2} \left(\frac{\partial^2 u}{\partial x^2} \right)_0 + \dots$$

$$v =$$

$$w =$$

} zatem roz. dyfuzji

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0 \quad \text{Zatem: } \left(\frac{\partial u}{\partial x}\right)_0 \cos \alpha + \left(\frac{\partial v}{\partial y}\right)_0 \cos \gamma + \left(\frac{\partial w}{\partial z}\right)_0 \cos \beta = 0$$

Zm. że wartości cosinusów są równe do jednostki.

$$\Delta^2 u = \left(\frac{\partial^2 u}{\partial x^2}\right)_0 + \dots$$

$$\underbrace{\int \frac{\partial^2 u}{\partial x^2} d\omega} = - \underbrace{\int \varepsilon \frac{\partial u}{\partial x} d\omega} + \mu \int \nabla^2 u d\omega$$

$$\begin{aligned} \mu \int \nabla^2 u d\omega &= \cancel{\int \frac{\partial^2 u}{\partial x^2} d\omega} = \int \frac{\partial u}{\partial x} d\omega \int \varepsilon d\omega + \end{aligned}$$

• krawędź styka się linij prosta w stół odległości w od powierzchni.

$$\frac{\partial^2 u}{\partial s^2} = \varepsilon \frac{\partial u}{\partial s} + \mu \nabla^2 u_s$$

powierz. w pionie przybliżeniu w równoległość do powierzchni, tyłko różnicę przybliżenia (lamell).

$$\text{zatem } \nabla^2 u_s = \frac{\partial^2 u_s}{\partial n^2}$$

$$\frac{\partial u}{\partial s} = \text{tęże w styku}$$

$$\begin{aligned} \underbrace{\int \frac{\partial^2 u}{\partial s^2} d\omega} &= \frac{1}{4\pi} \frac{\partial \varphi}{\partial r} \frac{\partial u}{\partial s} + \mu \frac{\partial u_s}{\partial s} + \text{ant} \\ &= \underbrace{\left(\frac{\partial^2 u}{\partial s^2}\right)_0}_{\text{przybliżenie}} = 0 \end{aligned}$$

$$\varepsilon = \frac{1}{4\pi} \frac{\partial \varphi}{\partial r^2}$$

$$\text{zatem } \mu u_s = - \frac{1}{4\pi} (\varphi_1 - \varphi_2) \frac{\partial u}{\partial s}$$

ale gdzie tyś istniejesz! ?

powierz $\nabla^2 u = 0$

zatem takie przekroje powierzchniowe jak góry i były potem całe przekroje
w rurek cienych hydro równowagi

$$\frac{\partial u}{\partial x} = \mu \nabla^2 u$$

$$\frac{\partial u}{\partial y} = \mu \nabla^2 u$$

$$\frac{\partial u}{\partial z} = \mu \nabla^2 u$$

one hydrostatyczne ciśnienie przez

$$\begin{aligned} u &\sim \frac{\partial u}{\partial x} \\ v &\sim \frac{\partial u}{\partial y} \text{ etc.} \\ w &\sim \frac{\partial u}{\partial z} \\ p &= \text{const.} \end{aligned}$$

zatem przekroje powierzchniowe, bo $\nabla^2 u = 0$

$u \sim \frac{\partial u}{\partial x}$ ~~to~~ ^{Naprawdę: bo jeżeli to było przekrojem nie uwzględnione $\nabla^2 u$} przekrojem etc.

uważa się, że takie całe przekroje były przekrojami dla $u \sim v$

$$\text{przekroji przez } \frac{1}{4\pi\mu} \frac{p_i - p_e}{\mu}$$

Czyżbyż? $u \cdot \frac{p_i - p_e}{4\pi\mu}$ jako potencjał przekroju rotacyjnie symetrycznego

przekroju odpowiednio przysto symetrycznego! na powierzchni i powierzchni

równowagi hydro. Ciężar $p = \text{const.}$ [ale p_{xx} etc ≥ 0 !]

żeby otrzymać jednak nierówności dla $r \rightarrow \infty$ trzeba by symetryczności

rozważanie: ruch $= \frac{p_i - p_e}{4\pi\mu} \frac{\partial u}{\partial x}$ dla $r \rightarrow \infty$ spoczynek dla $r = a$

^{niestandard} t.j. kula o ciężej promieniu a niż p i otwór

$$\text{zatem ciśnienie : } p = \frac{p_i - p_e}{4\pi\mu} \left(\frac{\partial u}{\partial x} \right) \frac{x}{r^3}$$

" A

Energia i cięta:

$$\Phi = \mu \left[2 \left(\frac{\partial u}{\partial x} \right)^2 + \dots \right] + \left\{ \frac{\partial u}{\partial y} + \frac{\partial v}{\partial z} + \dots \right\}$$

$$u = \alpha \frac{\partial \mathcal{U}}{\partial x}$$

$$\frac{\partial u}{\partial y} + \frac{\partial v}{\partial z} = 2 \frac{\partial^2 \mathcal{U}}{\partial y \partial z}$$

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$$\Phi = \mu \alpha^2 \left[2 \left(\frac{\partial^2 \mathcal{U}}{\partial x^2} \right)^2 + \left(\frac{\partial^2 \mathcal{U}}{\partial y^2} \right)^2 + \dots \right] + 4 \left\{ \frac{\partial^2 \mathcal{U}}{\partial y \partial z} + \dots \right\} = - \mu \int \frac{\partial(\sigma^2)}{\partial n} dS$$

$$p_{xx} = -p + 2\mu \frac{\partial u}{\partial x} = -p + 2\mu \alpha \frac{\partial^2 \mathcal{U}}{\partial x^2}$$

$$p_{xy} = \mu \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) = 2\mu \alpha \frac{\partial^2 \mathcal{U}}{\partial x \partial y}$$

$$p_x = -p \cos \alpha + 2\mu \alpha \left[\frac{\partial^2 \mathcal{U}}{\partial x^2} \cos \alpha + \frac{\partial^2 \mathcal{U}}{\partial x \partial y} \cos \gamma + \frac{\partial^2 \mathcal{U}}{\partial x \partial z} \cos \delta \right]$$

$$\int p_x = 2\mu \alpha \int \left[\frac{\partial^2 \mathcal{U}}{\partial x^2} \cos \alpha + \dots \right] d\omega$$

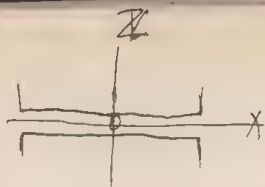
$$\int \frac{\partial}{\partial x} \cos \alpha + \frac{\partial}{\partial y} \cos \gamma + \dots = \int \frac{\partial}{\partial n} \frac{\partial \mathcal{U}}{\partial x} d\omega$$

wypadkowe wartości na krawędzi i kierunku $X = 2\mu \alpha \int \frac{\partial^2 \mathcal{U}}{\partial x \partial n} d\omega$

ponieważ jeżeli $\frac{\partial \mathcal{U}}{\partial n} = 0$ wtedy cały poruszenie jest $P = 0$

$$\int \mathcal{U} \frac{\partial^2 \mathcal{U}}{\partial n^2} d\omega = \int \mathcal{U} \frac{\partial^2 \mathcal{U}}{\partial n^2} d\omega - \int \left(\frac{\partial \mathcal{U}}{\partial n} \right)^2 d\omega$$

Praca poruszeniowa $\int (p_x \cdot u + p_y \cdot v + p_z \cdot w) d\omega$



Dwa kątyki po zbliżeniu się w ciężyłkowy

Zadani równowagi:

$$u = u_m \cdot \frac{2(\delta - z)}{\delta^2}$$

$$\int_0^\delta u dz = u_m \cdot \frac{2}{3} \delta$$

Niesiobliwość: $2x \frac{d\delta}{dt} = \int_0^\delta u dz = \frac{2}{3} \delta u_m$

$$u_m = 3x \frac{d\delta}{dt} = \frac{3x}{\delta} \cdot c$$

$$u = 12x \frac{2(\delta - z)}{\delta^3} \cdot c$$

$$\mu \nabla^2 u = \frac{\partial p}{\partial x} = - \frac{24x}{\delta^3} \cdot c$$

$$p = -12 \frac{x^2 c \mu}{\delta^3} + \text{const}$$

$$p = -12 (b^2 - x^2) \frac{c \mu}{\delta^3} + p_0$$

$$\int_{-b}^{+b} p dx = \frac{12 c \mu}{\delta^3} \cdot 2 \left[\frac{b^3}{3} - \frac{b^3}{3} \right] = 16 \cdot \frac{b^3 c \mu}{\delta^3}$$

$$\begin{aligned}\frac{\partial \varphi}{\partial x} &= -\varepsilon \frac{\partial U}{\partial x} + \mu \Delta^2 U \\ \frac{\partial \varphi}{\partial y} &= -\varepsilon \frac{\partial U}{\partial y} + \mu \Delta^2 U \\ \frac{\partial \varphi}{\partial z} &= -\varepsilon \frac{\partial U}{\partial z} + \mu \Delta^2 U\end{aligned}$$

zakładamy, że nie ma dodatkowej potęg ε i μ w równaniu, więc nie musimy się spierać, jakie to ε i μ jak to δ

$$\begin{aligned}\frac{\partial \varphi}{\partial x} &= -\varepsilon \frac{\partial U}{\partial x} + \mu \Delta^2 U \\ \frac{\partial \varphi}{\partial y} &= -\varepsilon \frac{\partial U}{\partial y} + \mu \Delta^2 U \\ \frac{\partial \varphi}{\partial z} &= -\varepsilon \frac{\partial U}{\partial z} + \mu \Delta^2 U\end{aligned}$$

$$\Delta^2 \varphi = \left[\frac{\partial^2}{\partial x^2} \frac{\partial U}{\partial x} + \frac{\partial^2}{\partial y^2} \frac{\partial U}{\partial y} + \frac{\partial^2}{\partial z^2} \frac{\partial U}{\partial z} \right]$$

[przyjmujemy, że ε zmienia tylko w równaniu ~~stwierdzenie~~ normy]

$$\begin{aligned}&= \int \varepsilon \frac{\partial U}{\partial x} dx + \int \varepsilon \frac{\partial U}{\partial y} dy + \int \varepsilon \frac{\partial U}{\partial z} dz \quad \text{it tylko i strona} \\ &= - \int \varepsilon \frac{\partial U}{\partial x} dx + \int \varepsilon \frac{\partial U}{\partial y} dy\end{aligned}$$

zatem bierzemy to tylko w równaniu dopóki nie pojawią się V i v i porównujemy do δ t.j. dla endomorfizmu elektry.

$$= \int \varepsilon \Delta^2 U$$

$$= 0$$

zatem μ może mieć Maxima i Minima tylko na powierzchni wewnątrz

i ponieważ $\Delta^2 \varphi = 0$ tożsamość ta gwarantuje, że nie ma wogóle Maxima i Minima tylko w środku albo na powierzchni (miejscu) wst.

$$\begin{aligned}1. & \quad \dots \\ 2. & \quad \dots \\ 3. & \quad \dots \\ 4. & \quad \dots \\ 5. & \quad \dots\end{aligned}$$

Wzrosty i spadek

$$\rho = \rho_0 - \frac{1}{2} \frac{\mu c^2}{2^3} x = \rho_0 - \frac{1}{2} \frac{\mu c^2}{2^3} \cos \theta$$

$$\frac{\partial \varphi}{\partial x} = \Delta^2 \varphi = + \frac{1}{2} \frac{\mu c^2}{2^3} \cos \theta$$

$$\Delta^2 \varphi = \frac{3}{2^3} \frac{\mu c^2}{2^3} \cos \theta$$

2. Potenziale:

$$v = f(n)$$

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$$\frac{\partial \phi}{\partial s} = -\epsilon \frac{\partial u}{\partial s} + \mu \frac{\partial^2 v}{\partial s^2} = -\epsilon \frac{\partial u}{\partial s} + \mu \frac{d^2 v}{dn^2}$$

$$\frac{\partial \phi}{\partial n} = -\epsilon \frac{\partial u}{\partial n}$$

$$\phi_0 + \delta n \left(\epsilon \frac{\partial u}{\partial n} + \mu \frac{d^2 v}{dn^2} \right) = \phi_0 + \delta n \left(\epsilon \frac{\partial u}{\partial n} + \mu \frac{d^2 v}{dn^2} \right) + \frac{1}{2} \delta^2 n^2 \left(\epsilon \frac{\partial^2 u}{\partial n^2} + \mu \frac{d^3 v}{dn^3} \right)$$

$$\frac{\partial \phi}{\partial s} = -\epsilon \frac{\partial u}{\partial s} = -\epsilon \frac{\partial u}{\partial s} + \mu \frac{d^3 v}{dn^3} - \frac{\partial \epsilon}{\partial n} \frac{\partial u}{\partial s} !$$

$$\frac{d^3 v}{dn^3} = 0$$

$$\frac{d^2 v}{dn^2} = \text{const}$$

$$\frac{\partial \phi}{\partial s} = -\epsilon \frac{\partial u}{\partial s} + c \cdot n$$

$$\frac{\partial \phi}{\partial n} = -\epsilon \frac{\partial u}{\partial n}$$

$$\phi = -\int \epsilon \frac{\partial u}{\partial n} dn + \int \epsilon \frac{\partial u}{\partial s} ds + c \cdot s \mu$$

$$\phi = \phi_0 + c \cdot n - \int \epsilon \frac{\partial u}{\partial n} dn = \phi_0 + c \cdot n - \frac{1}{2} \epsilon \frac{\partial^2 u}{\partial n^2}$$

v wird mir helfen zu verstehen, dass wir hier

$$\frac{dv}{dn} = c \cdot n + d$$

$$v = \frac{c \cdot n^2}{2} + a \cdot n + b$$

$$0 = c \cdot \frac{n^2}{2} + a \cdot n + b$$

$$a = -\frac{c \cdot n}{2}$$

$$v = \frac{c}{2} (n^2 - 2 \cdot n \cdot b)$$

$$\frac{\partial^2 v}{\partial n^2} = c$$

$$\phi = \int \left(\epsilon \frac{\partial u}{\partial x} dx + \frac{\partial u}{\partial z} dz \right) + \mu \int \frac{d^2 v}{dz^2} dz$$

$$= \phi_0 + \int \left(\epsilon \frac{\partial u}{\partial x} + \mu \frac{d^2 v}{dz^2} \right) dx$$

$$\frac{d^2 v}{dz^2} = -\epsilon \frac{\partial u}{\partial x} = -\frac{1}{n} \frac{\partial^2 u}{\partial z^2} \frac{\partial u}{\partial x}$$

$$v = \frac{1}{4n} (\phi_0 - \phi_0) \frac{\partial u}{\partial x} + \frac{c}{2} (z^2 - 2 \cdot z \cdot b)$$

= elektrische
Induktion

Wie sieht ein starrer Körper aus? ist ein abgerundetes U'
 stoch. v. starrer nicht bekannt:

~~$$\lambda \nabla^2 U + \mu \frac{\partial \varepsilon}{\partial x} + \nu \frac{\partial \varepsilon}{\partial y} + \omega \frac{\partial \varepsilon}{\partial z} = 0$$~~

die $[\lambda \nabla(U-U') + \varepsilon v] = 0$

$$\lambda \nabla^2 U + \mu \frac{\partial \varepsilon}{\partial x} + \nu \frac{\partial \varepsilon}{\partial y} + \omega \frac{\partial \varepsilon}{\partial z} = -\cancel{\lambda \nabla^2 U} = -4\pi\lambda \varepsilon$$

jeder Punkt in der Masse des stoch. Körpers
 z.B.:

$$4\pi\lambda(\varepsilon' - \varepsilon) + \mu \frac{\partial \varepsilon}{\partial x} + \nu \frac{\partial \varepsilon}{\partial y} + \omega \frac{\partial \varepsilon}{\partial z} = 0$$

$$\varepsilon = \varepsilon' + v$$

$$4\pi\lambda v = \mu \frac{\partial \varepsilon'}{\partial x} + \nu \frac{\partial \varepsilon'}{\partial y} + \omega \frac{\partial \varepsilon'}{\partial z} + \underbrace{(\mu \frac{\partial v}{\partial x} + \nu \frac{\partial v}{\partial y} + \omega \frac{\partial v}{\partial z})}_{\neq 0}$$

pot $\varepsilon = \text{pot } \varepsilon' + \text{pot } v$ | z.B.: $U = U' + V - \frac{1}{2} \Phi$

$$\text{pot } v = \underbrace{\frac{v}{r}}_{\neq 0} = \frac{1}{4\pi\lambda} \underbrace{\left[\mu \frac{\partial \varepsilon'}{\partial x} + \nu \frac{\partial \varepsilon'}{\partial y} + \omega \frac{\partial \varepsilon'}{\partial z} \right]}_{\text{pot } \varepsilon'}$$

potenz v. stoch.
 physikalisch
 $v = \frac{1}{2} \left(\frac{\partial u}{\partial x} \right)$

$$= \frac{1}{4\pi\lambda} \int \frac{v_n \frac{\partial \varepsilon'}{\partial n}}{r} dv = \frac{1}{4\pi\lambda} \int \frac{dv}{r} \int \frac{\partial \varepsilon'}{\partial n} d\Omega \cdot \frac{\partial \varepsilon'}{\partial n}$$

$$v_n = v_{n0} + \frac{\partial v_n}{\partial z} \frac{\partial v_n}{\partial n} = \frac{\partial v_n}{\partial z} \frac{\partial v_n}{\partial n}$$

$$\int \frac{1}{2} \frac{\partial \varepsilon'}{\partial z} dz$$

$$= \int \frac{\partial^3 U'}{\partial z^3} \frac{1}{2} dz$$

$$= \frac{\partial^2 U}{\partial z^2} \frac{1}{2} = \frac{\partial^2 U'}{\partial z^2} \frac{1}{2} = \cancel{\text{...}}$$

$$U = U' + V + \Phi$$

zauważaj, co prowadzi tyko jęz. V

$$V = \frac{\rho_0 \phi_0}{4\pi\lambda} \iint \frac{\partial^2 v_n}{\partial n^2} \cdot \frac{d\sigma}{2}$$

$$\frac{\partial \phi}{\partial n} = -\varepsilon \frac{\partial U}{\partial n} + \mu \Delta^2 v_n$$

$$\frac{\partial^2 v_n}{\partial n^2} + \frac{\partial^2 v_n}{\partial n^2} + \frac{\partial^2 v_n}{\partial n^2}$$

$$\neq \frac{\phi_1 - \phi_0}{4\pi\lambda\mu} \int \frac{1}{2} \frac{\partial \phi}{\partial n} d\sigma$$

zatem V. Adk. jęz. ^{matru} wzogranow. byder: $V = \frac{\phi_1 - \phi_0}{4\pi\lambda\mu} \mu$

otdnie transformacje tyko jęz. $\frac{\partial^2 v_n}{\partial n^2} = \frac{\partial \phi}{\partial n}$

f. j. jęz. $\frac{\partial U}{\partial n} = 0$

zatem: Na podum. jęz. wto izolow. byder:

$$\lambda \frac{\partial (U - U')}{\partial n} = 0$$

$$\text{zatem } \frac{\partial (U - U')}{\partial n} = 0$$

$$\mu \frac{\partial U}{\partial n} = \frac{\partial \phi}{\partial n}$$

podstawiamy w $\Delta^2 v_n = \frac{\partial^2 v_n}{\partial n^2} \dots$

$$\text{zatem: } \frac{\partial^2 v_n}{\partial n^2} = \frac{1}{\mu} \frac{\partial \phi}{\partial n} + \varepsilon \frac{\partial U'}{\partial n}$$

zauważ tyko $\Delta^2 v_n$, nie $\Delta^2 \phi$, $\Delta^2 U'$

$$V = \frac{\phi_1 - \phi_0}{4\pi\lambda\mu} \iint \frac{1}{2} \frac{\partial \phi}{\partial n} d\sigma + \underbrace{\frac{\phi_1 - \phi_0}{4\pi\lambda} \iint \frac{1}{2} \varepsilon \frac{\partial U'}{\partial n} d\sigma}_{f(2)}$$

warowanie matru.

$$\bar{V} = \frac{\phi_1 - \phi_0}{4\pi\lambda\mu} \mu + f(2)$$

$$v_2 = -u \frac{\partial}{\partial z} + v \frac{\partial}{\partial z} = -u \sin \theta + v \cos \theta$$

$$= -c \sin \theta \left[1 - \frac{3}{4} \frac{\partial}{\partial z} - \frac{1}{4} \frac{\partial^2}{\partial z^2} \right]$$

$$\frac{\partial v_2}{\partial z} = -c \sin \theta \left[\frac{3}{4} \frac{\partial}{\partial z} + \frac{1}{4} \frac{\partial^2}{\partial z^2} \right]$$

$$\frac{\partial^2 v_2}{\partial z^2} = +c \sin \theta \left[\frac{3}{2} \frac{\partial}{\partial z} + 3 \frac{\partial^2}{\partial z^2} \right]$$

W tutaj rozkładzie $U = U' + V + \Phi$

analogicznie U' = pot. wartości podw. (w sobie)

Φ = zewnętrzny potencjał

V = energia składowa w kierunku mechanicznym.

$$u = -\frac{3}{4} \frac{ca}{r^2} \left(1 - \frac{a^2}{r^2}\right) \cos \theta + c \left(1 - \frac{3}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3}\right)$$

$$q = -\frac{3}{4} \frac{ca}{r^2} \left(1 - \frac{a^2}{r^2}\right) \sin \theta \cos \theta$$

$$v_r = u \frac{x}{r} + v \frac{z}{r} = u \cos \theta + v \sin \theta$$

$$= -\frac{3}{4} \frac{ca}{r^2} \left(1 - \frac{a^2}{r^2}\right) \cos \theta + c \sin \theta \left(1 - \frac{3}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3}\right)$$

$$= c \sin \theta \left[1 - \frac{3}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3} - \frac{3}{4} \frac{a}{r} + \frac{3}{4} \frac{a^3}{r^3}\right]$$

$$v_r = c \sin \theta \left[1 - \frac{3}{2} \frac{a}{r} + \frac{1}{2} \frac{a^3}{r^3}\right]$$

$$\frac{\partial v_r}{\partial r} = c \sin \theta \left[\frac{3}{2} \frac{a}{r^2} - \frac{3}{2} \frac{a^3}{r^4}\right]$$

$$\frac{\partial^2 v_r}{\partial r^2} = c \sin \theta \left[-\frac{3a}{r^3} + \frac{6a^3}{r^5}\right]$$

$$\frac{\partial v_r}{\partial r} \Big|_{r=a} = 0$$

$$\frac{\partial^2 v_r}{\partial r^2} \Big|_{r=a} = \frac{3ca \sin \theta}{a^2}$$

$$p = p_0 - \frac{3}{2} \frac{\mu ca}{r^2} \cos \theta$$

$$\frac{\partial p}{\partial r} = 3\mu \frac{ca}{r^3} \cos \theta$$

$$\frac{\partial p}{\partial r} \Big|_{r=a} = \frac{3\mu c}{a^2} \cos \theta$$

$$\therefore \frac{\partial p}{\partial r} = \mu \frac{\partial v_r}{\partial r}$$

~~$$\Delta^2 u = \frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2}$$~~

$$= \frac{1}{r} \frac{\partial p}{\partial r} \frac{\partial \theta}{\partial r} = \frac{3}{2} \frac{ca \sin \theta}{r^3}$$

Formanie mechanizme

Dozyski mech : nowy
molekuly

W stanie spoczynku :

~~$\frac{\partial \mathcal{L}}{\partial x} = \frac{\partial \mathcal{L}}{\partial x}$~~ $u = v = w = 0$
 $\mathcal{U} = \mathcal{U}' + \Phi$ \leftarrow tutaj to się sprowadza do sumowania \dots

$$\varepsilon = \varepsilon'$$

$$\frac{\partial \mathcal{L}}{\partial x} = \varepsilon' \frac{\partial \mathcal{U}'}{\partial x} = \varepsilon' \frac{\partial \mathcal{U}}{\partial x}$$

$$\frac{\partial \mathcal{L}}{\partial x} = -\varepsilon \frac{\partial \mathcal{U}}{\partial x} + \mu \Delta^2 u$$

$$\frac{\partial \mathcal{L}}{\partial y} = -\varepsilon \frac{\partial \mathcal{U}}{\partial y} + \mu \Delta^2 v$$

$$\frac{\partial \mathcal{L}}{\partial z} = -\varepsilon \frac{\partial \mathcal{U}}{\partial z} + \mu \Delta^2 w$$

$$\Delta^2 \mathcal{L} = -\left[\frac{\partial \varepsilon}{\partial x} \frac{\partial \mathcal{U}}{\partial x} + \frac{\partial \varepsilon}{\partial y} \frac{\partial \mathcal{U}}{\partial y} + \frac{\partial \varepsilon}{\partial z} \frac{\partial \mathcal{U}}{\partial z} \right] - \varepsilon \Delta^2 \mathcal{U}$$

$$\begin{aligned} \int \Delta^2 \mathcal{L} \, d\omega &= - \int \left[\frac{\partial \varepsilon}{\partial x} \frac{\partial \mathcal{U}}{\partial x} + \frac{\partial \varepsilon}{\partial y} \frac{\partial \mathcal{U}}{\partial y} + \frac{\partial \varepsilon}{\partial z} \frac{\partial \mathcal{U}}{\partial z} \right] d\omega - \int \varepsilon \Delta^2 \mathcal{U} \, d\omega \\ &= - \int \varepsilon \frac{\partial \mathcal{U}}{\partial n} \, d\sigma + \int \varepsilon \Delta^2 \mathcal{U} \, d\omega = - \int \varepsilon \frac{\partial \mathcal{U}}{\partial n} \, d\sigma \end{aligned}$$

Rozwiązanie : $f = \mathcal{L}_1 + \mathcal{L}_2$

$$\frac{\partial \mathcal{L}_1}{\partial x} = -\varepsilon \frac{\partial \mathcal{U}_1}{\partial x}$$

$$\frac{\partial \mathcal{L}_1}{\partial y} = -\varepsilon \frac{\partial \mathcal{U}_1}{\partial y}$$

$$\frac{\partial \mathcal{L}_1}{\partial z} = -\varepsilon \frac{\partial \mathcal{U}_1}{\partial z}$$

$$\frac{\partial \mathcal{L}_2}{\partial x} = -\varepsilon \frac{\partial \mathcal{U}_2}{\partial x} + \mu \Delta^2 u$$

$$\frac{\partial \mathcal{L}_2}{\partial y} = -\varepsilon \frac{\partial \mathcal{U}_2}{\partial y} + \mu \Delta^2 v$$

$$\frac{\partial \mathcal{L}_2}{\partial z} = -\varepsilon \frac{\partial \mathcal{U}_2}{\partial z} + \mu \Delta^2 w$$

$$\frac{\partial \mathcal{L}_2}{\partial x} = -\varepsilon \frac{\partial \mathcal{U}_2}{\partial x} + \mu \Delta^2 u$$

~~$$\Delta^2 \lambda_2 = \dots$$

$$\Delta^2 \lambda_2 = \dots$$~~

~~$$\lambda_2 = \dots$$~~

$$\varepsilon \Delta^2 u + \frac{\partial \varepsilon}{\partial x} \frac{\partial u}{\partial x} + \frac{\partial \varepsilon}{\partial y} \frac{\partial u}{\partial y} + \frac{\partial \varepsilon}{\partial z} \frac{\partial u}{\partial z} = \Delta^2 \lambda$$

2 drugi strony przekształcamy:

$$\varepsilon \Delta^2 u + \frac{\partial \varepsilon}{\partial x} \frac{\partial u}{\partial x} + \frac{\partial \varepsilon}{\partial y} \frac{\partial u}{\partial y} + \frac{\partial \varepsilon}{\partial z} \frac{\partial u}{\partial z} = -4\pi \lambda \varepsilon \varepsilon'$$

czyli możemy zapisać:

~~$$\frac{\partial \lambda}{\partial x} = \frac{1}{\varepsilon} \frac{\partial u}{\partial x}$$

$$\Delta^2 \lambda = -4\pi \lambda \varepsilon \varepsilon'$$

$$\Delta^2 u = \frac{1}{\varepsilon} \left(\frac{\partial \varepsilon}{\partial x} \frac{\partial u}{\partial x} + \frac{\partial \varepsilon}{\partial y} \frac{\partial u}{\partial y} + \frac{\partial \varepsilon}{\partial z} \frac{\partial u}{\partial z} \right) + \dots$$~~

$$\lambda = \lambda_1 + \lambda_2 \quad u = u' + v + \bar{v}$$

$$\left\{ \begin{aligned} \frac{\partial \lambda_1}{\partial x} &= -\varepsilon \frac{\partial u'}{\partial x} \\ \frac{\partial \lambda_1}{\partial y} &= \dots \end{aligned} \right.$$

$$\frac{\partial \lambda_2}{\partial x} = -\varepsilon \frac{\partial (v + \bar{v})}{\partial x} + \frac{1}{\varepsilon} \Delta^2 u$$

$$\frac{\partial \lambda_2}{\partial y} = \dots$$

$$\Delta^2 \lambda_2 = - \left[\frac{\partial \varepsilon}{\partial x} \frac{\partial (v + \bar{v})}{\partial x} + \dots \right] + \varepsilon \Delta^2 (v + \bar{v})$$

~~$$\lambda_2 = \frac{1}{\varepsilon} \frac{\partial}{\partial x} \frac{\partial u}{\partial x} + \dots$$~~

$$\Delta^2 \lambda_2 \, d\sigma = - \varepsilon \frac{\partial (v + \bar{v})}{\partial n} \, d\sigma + \frac{1}{\varepsilon} \Delta^2 (v + \bar{v}) \, d\sigma$$

$$\stackrel{V}{=} 0$$

$$\frac{\partial (v + \bar{v})}{\partial n} = 0$$

$$\Delta^2 (v + \bar{v}) = u \frac{\partial \varepsilon}{\partial x} + v \frac{\partial \varepsilon}{\partial y} + \bar{v} \frac{\partial \varepsilon}{\partial z}$$

Take get wronskian $\Delta^2 \psi$ by substituting $\psi = \frac{\partial \psi_0}{\partial x^2}$?

$$\Delta^2 \psi = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \psi$$

$$r = r_0 - \frac{3\mu c a}{2^2} \cos \theta \quad \psi_r = c \left[1 - \frac{3}{2} \frac{a}{r} + \frac{1}{2} \frac{a^3}{r^3} \right] \cos \theta$$

$$\psi_{\theta} = -c \sin \theta \left[\frac{1}{4} - \frac{3}{4} \frac{a}{r} + \frac{1}{4} \frac{a^3}{r^3} \right]$$

$$\frac{\partial}{\partial r} \psi_{\theta} = -c \sin \theta \left[\frac{3}{4} \frac{a}{r^2} + \frac{3}{4} \frac{a^3}{r^4} \right] \quad \Big|_{r=a} = -\frac{3}{2} \frac{c \sin \theta}{a}$$

$$\frac{\partial^2}{\partial r^2} \psi_{\theta} = +c \sin \theta \left[\frac{3}{2} \frac{a}{r^3} + \frac{3}{2} \frac{a^3}{r^5} \right] = \frac{9}{2} \frac{c \sin \theta}{a^2}$$

$$\psi = \sqrt{\psi_r^2 + \psi_{\theta}^2} = c \sqrt{\left(1 + \frac{9}{4} \frac{a^2}{r^2} + \frac{1}{4} \frac{a^6}{r^6} - \frac{3}{2} \frac{a}{r} - \frac{3}{4} \frac{a^3}{r^3} + \frac{1}{2} \frac{a^5}{r^5} \right) \cos^2 \theta + \left(1 + \frac{9}{16} \frac{a^2}{r^2} + \frac{1}{16} \frac{a^6}{r^6} - \frac{3}{4} \frac{a}{r} - \frac{3}{16} \frac{a^3}{r^3} - \frac{1}{4} \frac{a^5}{r^5} \right) \sin^2 \theta}$$

$$= c \sqrt{1}$$

$$\frac{\partial^2 \psi}{\partial x^2} = \Delta^2 \left(\frac{\partial \psi}{\partial x} - \frac{\partial \psi}{\partial x} \right) = \frac{\partial^2}{\partial x^2} \frac{\partial \psi}{\partial x} - \frac{\partial^2}{\partial x^2} \frac{\partial \psi}{\partial x}$$

$$\mu \Delta^2 \psi = \uparrow$$

$$\mu \Delta^2 \psi = \begin{vmatrix} 1 & \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial}{\partial x} & \frac{\partial^2}{\partial x^2} & \frac{\partial^2}{\partial x \partial y} & \frac{\partial^2}{\partial x \partial z} \\ \frac{\partial}{\partial y} & \frac{\partial^2}{\partial x \partial y} & \frac{\partial^2}{\partial y^2} & \frac{\partial^2}{\partial y \partial z} \\ \frac{\partial}{\partial z} & \frac{\partial^2}{\partial x \partial z} & \frac{\partial^2}{\partial y \partial z} & \frac{\partial^2}{\partial z^2} \end{vmatrix}$$

Wronskian

Upravi z ovih zadanih:

$$\varepsilon \frac{\partial u}{\partial x} = \mu \Delta^2 u$$

$$\varepsilon \frac{\partial u}{\partial y} = \mu \Delta^2 u$$

$$\varepsilon \frac{\partial u}{\partial z} = \mu \Delta^2 u$$

$$u = \left(\frac{\varepsilon}{4\pi x} \right) \Delta^2 u + \psi$$

$$= \frac{1}{4\pi} \int \frac{\partial u}{\partial x} d\sigma + \frac{1}{4\pi} \int \frac{\partial u}{\partial x} d\sigma + \frac{1}{4\pi} \int \frac{\partial u}{\partial x} d\sigma$$

u prostoru usloznoj u, v, w. Tada je i jedna jednačina

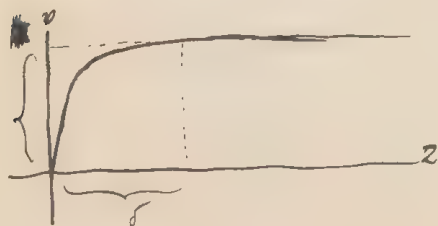
Tonit materije se zjedini
2 jednačina $\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} = 0$
da neobjektivno izgleda bi:
 $\varepsilon \Delta^2 u + \left(\frac{\partial \varepsilon}{\partial x} \frac{\partial u}{\partial x} + \dots \right) = 0$

$$\varepsilon \frac{\partial u}{\partial x} = \mu \Delta^2 u = \mu \left[\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right]$$

$$\int d\sigma \cdot \varepsilon \frac{\partial u}{\partial x} = \frac{\partial u}{\partial x} \frac{1}{4\pi} \int \frac{\partial^2 u}{\partial x^2} d\sigma = \frac{1}{4\pi} \frac{\partial u}{\partial x} \left(\frac{\partial^2 u}{\partial x^2} \right) = \mu \left[\begin{aligned} & \int \frac{\partial^2 u}{\partial x^2} d\sigma \\ & + \int \frac{\partial^2 u}{\partial y^2} d\sigma \\ & + \int \frac{\partial^2 u}{\partial z^2} d\sigma \end{aligned} \right]$$

$$= \frac{1}{4\pi} \frac{\partial u}{\partial x} \left[\frac{\partial^2 u}{\partial x^2} \cdot \frac{1}{2} - \left(\frac{\partial^2 u}{\partial y^2} \cdot \frac{1}{2} \right) \right] = \frac{1}{4\pi} \frac{\partial u}{\partial x} (\varphi_1 - \varphi_2) =$$

$$\int_0^{\delta} \varphi f dx = f(x) \int_0^{\delta} \varphi dx$$



$$\int_0^{\delta} \frac{\partial^2 u}{\partial x^2} dx = \left[\frac{\partial u}{\partial x} \right]_0^{\delta}$$

$$= \frac{\partial u}{\partial x} \Big|_0^{\delta} = \delta \cdot M \left(\frac{\partial^2 u}{\partial x^2} \right)$$

$$= \frac{\delta^2}{2} M \left(\frac{\partial^2 u}{\partial x^2} \right)$$

$$= \frac{\partial u}{\partial x} \Big|_0^{\delta} M(2) = \frac{\partial u}{\partial x} \Big|_0^{\delta} M(2)$$

czyli 1: $\frac{\partial U}{\partial x}$ musi być równe zero i pochodna zero

2: musimy w ten sposób wyznaczyć δ i $r = f(\delta, t)$

$$u = \frac{1}{4\pi} \frac{\partial U}{\partial x} \int_0^{\infty} d\omega \int_{-\infty}^{\infty} \frac{1}{x} dx + \frac{1}{4\pi} \int_0^{\infty} \frac{1}{x} \frac{\partial U}{\partial x} d\omega \int_{-\infty}^{\infty} dx + \dots$$

~~Widzimy, że...~~

~~Widzimy, że...~~

$$\frac{\partial}{\partial x} \left(\frac{1}{x} \frac{\partial U}{\partial x} \right) = \frac{1}{x^2} \frac{\partial U}{\partial x}$$

$$\int_0^R \frac{2\pi \rho d\rho}{\sqrt{x^2 + \rho^2}} = 2\pi \sqrt{x^2 + \rho^2} \Big|_0^R = 2\pi \sqrt{x^2 + R^2} - 2\pi x$$

$$2\pi \int_0^x (\sqrt{R^2 + x^2} - x) \frac{dx}{4\pi} \frac{\partial \varphi}{\partial x}$$

$$= \frac{1}{2} \frac{\partial \varphi}{\partial x} \left[\sqrt{R^2 + x^2} - x \right] - \frac{1}{2} \int_0^x \frac{\partial \varphi}{\partial x} \left[\frac{x}{\sqrt{R^2 + x^2}} - 1 \right] dx$$

$$= \frac{1}{2} \left[\frac{\partial \varphi}{\partial x} (\sqrt{R^2 + x^2} - x) - R \frac{\partial \varphi}{\partial x} \right] - \dots$$

$$+ \frac{\partial \varphi}{\partial x}$$

$$\sqrt{R^2 + x^2} - x = R \left[\left(1 + \frac{x^2}{R^2} \right)^{\frac{1}{2}} - \frac{x}{R} \right] = R \left(1 + \frac{1}{2} \frac{x^2}{R^2} - \frac{x}{R} \right) = R - x + \frac{1}{2} \frac{x^2}{R}$$

W koroidze reszki wazne:

$$\frac{\partial \psi}{\partial n} = \varepsilon \frac{\partial \psi}{\partial n} + \mu \frac{\partial \psi}{\partial n} = \frac{1}{4\pi} \frac{\partial \psi}{\partial n} \frac{\partial \psi}{\partial n} \quad \parallel \quad \mu \frac{\partial \psi}{\partial n} = \frac{1}{4\pi} \frac{\partial \psi}{\partial n} \frac{\partial \psi}{\partial n}$$

$$\int \mu \, d\mu$$

$$\mu \, d\mu = \frac{1}{4\pi} (\varphi_i - \varphi_o) \frac{\partial \psi}{\partial n}$$

$$\left(\frac{\partial \psi}{\partial n} - \frac{\partial \psi}{\partial n_o} \right) d\mu = \varphi_o - \varphi_i - \delta \cdot \psi$$

To wystarczy do oznaczenia potencjału w wazni prostokątnym będącej

(L. 10-1)

$$\frac{\partial \psi}{\partial n} \left\{ \begin{array}{l} \Delta \psi = 0 \\ \frac{\partial \psi}{\partial n} = \frac{\varphi_i - \varphi_o}{4\pi n} \end{array} \right. \frac{\partial \psi}{\partial n}$$

$$u = \frac{\partial \psi}{\partial x}$$

$$v =$$

$$w =$$

Me to wazne tytko jank. rzeczywistosci takie warunki jednoznacznie mowia co nie widzieliśmy w tym samym kierunku odpowiedni.

Byc moze moze tego samego kierunku wazni i w ogolnie przykladu

$$\frac{\partial \psi}{\partial n} = -\varepsilon \frac{\partial \psi}{\partial n} + \mu \Delta \psi$$

$$\Delta \psi = \frac{\partial^2 \psi}{\partial x^2} + \left(\frac{\partial^2 \psi}{\partial y^2} \right)$$

$$\frac{\partial \psi}{\partial x} = -\frac{1}{4\pi} \frac{\partial \psi}{\partial x} \frac{\partial \psi}{\partial n} + \mu \frac{\partial \psi}{\partial x}$$

da

$$\mu = -\frac{1}{4\pi} \frac{\partial \psi}{\partial x} \frac{\partial \psi}{\partial n} + \mu \frac{\partial \psi}{\partial x} + \text{const}$$

$$\int \mu \, dz = -\frac{1}{4\pi} \varphi \cdot \frac{\partial \psi}{\partial n} + \mu \psi + 2 \cdot \text{const} + \text{const}$$

$$\int \mu \, dz = -\frac{\varphi_o - \varphi_i}{4\pi} \frac{\partial \psi}{\partial n} + \mu (\psi_i - \psi_o) + \delta \cdot \text{const}$$

$$= \mu \cdot \delta$$

$$\mu \, d\mu = \frac{\varphi_o - \varphi_i}{4\pi} \frac{\partial \psi}{\partial n}$$

To nie wystarczy jednak do oznaczenia potencjału bo tutaj mamy $\mu \Delta \psi = -\frac{\partial \psi}{\partial x}$ etc.

$$\psi = \frac{\varphi_o - \varphi_i}{4\pi n} \frac{\partial \psi}{\partial n}$$

Czy możemy rozkładać

$$u = u_1 + u_2$$

$$v = v_1 + v_2$$

$$w = w_1 + w_2$$

$$\frac{\partial \phi_1}{\partial x} + z \frac{\partial \psi}{\partial x} = \mu \Delta^2 u_1$$

$$\frac{\partial \phi_2}{\partial x} = \mu \Delta^2 u_2$$

$$\frac{\partial \phi_1}{\partial y} + z \frac{\partial \psi}{\partial y} = \mu \Delta^2 v_1$$

$$\frac{\partial \phi_2}{\partial y} = \mu \Delta^2 v_2$$

$$\frac{\partial \phi_1}{\partial z} + z \frac{\partial \psi}{\partial z} = \mu \Delta^2 w_1$$

$$\frac{\partial \phi_2}{\partial z} = \mu \Delta^2 w_2$$

Takie, że $p_1 = 0$ po warstwie

po warstwie musiałby to

imponować

by ruch potencjalny; będzie on równy jeżeli prędkości na powierzchni tejże żelazki

$$\Delta^2 \psi = 0 \quad u = \frac{\partial \psi}{\partial x} ; \quad \text{odpowiedzą za dany potencjał}$$

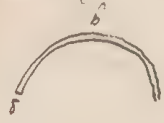
Co do prędkości normalnych ~~do tej powierzchni~~ mamy

$$v_n = \frac{\partial \psi}{\partial n} = \frac{p_2 - p_1}{4\pi\mu} \frac{\partial \psi}{\partial n} \quad | \text{Stąd otrzymujemy } \Delta^2 \psi = 0$$

~~to by było~~ to by było $v_n = 0$

To prawda bo v_n będzie do zera dążyć w promieniu ~~z prędkości~~ strumienia jeżeli δ dąży do zera

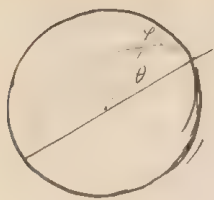
$$v_n = v_{n0} + z \left(\frac{\partial v_n}{\partial z} \right)_0 + \frac{z^2}{2} \left(\frac{\partial^2 v_n}{\partial z^2} \right)_0$$



v_n do v_δ będzie w stosunku $\delta : b$

porównaj równania węglów : $v_n \cdot b = v_\delta \cdot \delta$

$$v_n : v_\delta = \delta : b$$



$$\Delta^2_{(u)} = \frac{1}{r} \left[\frac{\partial^2 (ru)}{\partial r^2} + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} \left[\sin \theta \frac{\partial u}{\partial \theta} \right] + \frac{1}{r \sin^2 \theta} \frac{\partial^2 u}{\partial \phi^2} \right]$$

$$r = a + z$$

$$\Delta^2_{(v)} = \frac{1}{a} \left[\frac{\partial^2}{\partial z^2} [a+z, v] + \frac{1}{a \sin \theta} \frac{\partial}{\partial \theta} \left[\sin \theta \frac{\partial v}{\partial \theta} \right] + \frac{1}{a \sin^2 \theta} \frac{\partial^2 v}{\partial \phi^2} \right]$$

$$\left[\sin \theta \frac{\partial^2 v}{\partial \theta^2} + \cos \theta \frac{\partial v}{\partial \theta} \right]$$

$$\frac{\partial}{\partial z} [(a+z) v]$$

$$= \frac{\partial v}{\partial z} (a+z) + v$$

$$\frac{\partial^2}{\partial z^2} = \frac{\partial^2}{\partial z^2} (a+z) + 2 \frac{\partial v}{\partial z}$$

$$\Delta^2_{(v)} = \left(1 + \frac{2}{a}\right) \frac{\partial^2 v}{\partial z^2} + \frac{2}{a} \frac{\partial v}{\partial z} + \frac{1}{a} \frac{\partial^2 v}{\partial \theta^2} + \frac{1}{a} \frac{1}{\sin \theta} \frac{\partial v}{\partial \theta}$$

$$v_{20} = -c \cos \theta \left[1 - \frac{2}{3} \frac{a}{2} - \frac{1}{4} \frac{a^2}{2^3} \right]$$

$$\frac{\partial}{\partial \theta} v_{20} = \sin \theta \left[- \right]$$

$$\frac{\partial^2}{\partial \theta^2} = \cos \theta \left[- \right]$$

$$n=2 \quad \left. \vphantom{\frac{\partial}{\partial \theta}} \right\} = 0$$

$$\Delta^2_{(v)} = \frac{\partial^2 v_{20}}{\partial z^2} + \frac{2}{a} \frac{\partial v_{20}}{\partial z} = \frac{\partial^2 v_{20}}{\partial z^2} + \frac{2}{a} \frac{\partial v_{20}}{\partial z}$$

integrate

$$\Delta^2 = \frac{2}{3} \frac{c \cos \theta}{z^3} \Big|_0^a = \frac{2}{3} \frac{c}{a^2} \cos \theta$$

$$\frac{\partial^2}{\partial z^2} = -\frac{2}{3} \frac{c \cos \theta}{a^3} \quad \frac{\partial^2}{\partial z^2} + \frac{2}{a} \frac{\partial}{\partial z} =$$

$$\frac{\partial^2}{\partial z^2} = \frac{2}{3} \frac{c \cos \theta}{a^3} \quad \left. \vphantom{\frac{\partial^2}{\partial z^2}} \right\} \frac{2}{3} \frac{c \cos \theta}{a^3}$$

Integrate, multiply by r^2 and $\frac{1}{r}$ $\Delta^2_{(v)} = \frac{\partial^2 v_{20}}{\partial z^2} + \frac{2}{a} \frac{\partial v_{20}}{\partial z}$

$$\Delta^2 \cdot 2 dz = \int \frac{\partial^2}{\partial z^2} 2 dz + \frac{2}{a} \int \frac{\partial^2}{\partial z^2} 2 dz = v_0 - v_8 + \frac{2}{a} \frac{1}{10} M(z)$$

$$\lim_{z \rightarrow 0} \frac{(v_8 - v_0) \frac{10}{a}}{2} = v$$

- tem istotini:

$$\int_0^{\delta} \frac{\partial \phi}{\partial z} z dz = -\frac{1}{4\pi} \frac{\partial U}{\partial z} \frac{\partial \phi}{\partial z} z dz + \mu (v_0 - \frac{\partial \phi}{\partial z})$$

$\lim_{\delta \rightarrow 0} = 0$

$$v_0 = \frac{\phi_1 - \phi_0}{4\pi\mu} \frac{\partial U}{\partial z}$$

veine pri zbiranju:

1. $\lim_{\delta \rightarrow 0} \frac{\delta}{a} = 0$
2. $\frac{\partial U}{\partial z} = \text{const}$ v obliki δ
3. $v_0 = 0$
4. $\phi = \text{konst}$
5. $z = \frac{\partial \phi}{\partial z}$

zelo pomembno:

$$U = U' + V + \phi$$

prej preizkusimo: $\frac{\partial}{\partial n}(V + \phi) = 0$

$$\frac{\partial U}{\partial n} = \frac{\partial U'}{\partial n}$$

$$\frac{\partial U'}{\partial n} = 0$$

$$\frac{\partial U}{\partial n} = \frac{\partial (V + \phi)}{\partial n}$$

toliko v prostoru razpršeno:

$$\frac{\partial \phi}{\partial n} = \frac{\partial \phi}{\partial z}$$

$$\begin{cases} \frac{\partial \phi}{\partial x} = \mu \Delta U \\ \frac{\partial \phi}{\partial y} = \mu \Delta U \\ \frac{\partial \phi}{\partial z} = \mu \Delta U \end{cases}$$

toliko v prostoru razpršeno:

$$z = \frac{1}{4\pi} \Delta U = \frac{1}{4\pi} \left[\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right]$$

zajeto v prostoru:

$$\frac{\partial^2 U}{\partial x \partial y} = 0 \quad \left\{ \begin{array}{l} \text{v prostoru} \\ \text{zajeto} \end{array} \right. \quad \frac{\partial U'}{\partial n} = 0 \quad \frac{\partial}{\partial n}(V + \phi) = 0$$

$$= \frac{\partial^2 U'}{\partial x \partial y} + \frac{\partial^2 (V + \phi)}{\partial x \partial y}$$

a przy założeniu $\int z dz$ i lin. odpowiadającemu wyrażeniu
 zatem ostatek będzie ściśle równy.

$$v_0 \delta = \frac{U_1 - U_0}{4\pi\mu} \frac{\partial U}{\partial s} = \frac{U_1 - U_0}{4\pi\mu} \frac{\partial (V + \Phi)}{\partial s}$$

z warunku 5 wynika V, Φ będą jednak wielk. i pochodzącymi z $\varphi_1 - \varphi_0$

$$v_0 \delta = \frac{\varphi_1 - \varphi_0}{4\pi\mu} \frac{\partial (V + \Phi)}{\partial s} = \frac{\varphi_1 - \varphi_0}{4\pi\mu} \left[\frac{\varphi_1 - \varphi_0}{4\pi\mu} \frac{\partial \Phi}{\partial s} + \frac{\partial \Phi}{\partial s} \right]$$

$$V = \frac{\varphi_1 - \varphi_0}{4\pi\mu} \mu + \Phi$$

Zatem zadanie : $\nabla^2 \Phi = 0$ i właściwy wybór $\frac{\partial \Phi}{\partial s} = 0$

$$\begin{cases} \frac{\partial \Phi}{\partial x} = \mu \nabla^2 u \\ \frac{\partial \Phi}{\partial y} = \mu \nabla^2 v \\ \frac{\partial \Phi}{\partial z} = \mu \nabla^2 w \end{cases}$$

$$v_{s0} = \frac{\varphi_1 - \varphi_0}{4\pi\mu} \left[\frac{\varphi_1 - \varphi_0}{4\pi\mu} \frac{\partial \Phi}{\partial s} + \frac{\partial \Phi}{\partial s} \right]$$

$$v_{s0} = 0$$

$$\nabla^2 \Phi = 0$$

zatem $\frac{\varphi_1 - \varphi_0}{4\pi\mu} \mu + \Phi$ przez Ψ

$$\Delta^2 \Psi = 0$$

jest warunkiem granicznym $v_{s0} = \frac{\varphi_1 - \varphi_0}{4\pi\mu} \frac{\partial \Psi}{\partial s}$

$$\text{dlatego } v_{s0} = 0$$

zatem będzie rozwiązanie naszego

$$v = \nabla \Psi \cdot \frac{\varphi_1 - \varphi_0}{4\pi\mu}$$

$$\text{zatem : } \Phi = \frac{\varphi_1 - \varphi_0}{4\pi\mu} \nabla^2 \Psi + v_0$$

$$\begin{aligned} v_{s0} &= 0 \\ v_{n0} &= 0 \end{aligned}$$

$$\begin{cases} \frac{\partial \Phi}{\partial x} = \mu \nabla^2 u \\ \frac{\partial \Phi}{\partial y} = \mu \nabla^2 v \\ \frac{\partial \Phi}{\partial z} = \mu \nabla^2 w \end{cases}$$

$$\Delta^2 \Psi = 0$$

czyli także

Zatem rozjdz do danych konstatacji parich i str. wzajemnie
~~potencjałów~~ przewodnictwa elektrycznego ψ i tarcia mechanicznego v_0
 można wyznaczyć:

$$v = \frac{\psi_i - \psi_0}{4\pi\mu} \nabla\psi + v_0$$

dane doświadczalne będą: ciśnienia p_1, p_2

potencjałów obserwacji elektrometrycznej A_1, A_2

lub potencjałów ϕ_1, ϕ_2

przewodność $\frac{1}{4\pi\mu}$

$$i = \lambda \nabla(\psi - \psi') + \epsilon v$$

$$= \lambda \nabla(V + \phi) + \epsilon v$$

$$\begin{aligned} \int i \, ds &= \lambda \int \frac{\partial}{\partial n} (V + \phi) \, ds + \underbrace{\int \frac{1}{4\pi} \frac{\partial \phi}{\partial z} v \, ds}_{\tilde{q}} \\ &= \int \frac{ds}{4\pi} \int \frac{\partial \phi}{\partial z} 2 \left(\frac{\partial v}{\partial z} \right) dz \\ &= \int \frac{ds}{4\pi} (\psi_i - \psi_0) \left(\frac{\partial \psi_0}{\partial z} \right) \end{aligned}$$

A zatem np. w dany potencjał i str. w danych danych

$$\rho \cdot \frac{\partial w}{\partial z} = \rho g - \frac{\partial p}{\partial z} + \frac{\mu}{3} \frac{\partial}{\partial z} \Delta w + \mu \Delta w$$

$$\frac{\partial(\rho w)}{\partial z} = 0$$

$$w \frac{\partial p}{\partial z} + k \mu \frac{\partial w}{\partial z} = (k-1) \mu \left[\frac{4}{3} \left(\frac{\partial w}{\partial z} \right)^2 + \left(\frac{\partial w}{\partial r} \right)^2 + \left(\frac{\partial w}{\partial \theta} \right)^2 \right] + (k-1) \kappa \left(\frac{\partial^2 \theta}{\partial r^2} + \frac{\partial^2 \theta}{\partial \theta^2} + \frac{\partial^2 \theta}{\partial z^2} \right)$$

$$\frac{\partial w}{\partial z} = \frac{dw}{dz} \cdot \frac{z}{z}$$

$$\frac{\partial w}{\partial r^2} = \frac{d^2 w}{dz^2} \cdot \frac{z^2}{z^2} + \frac{dw}{dz} \cdot \frac{1}{z} - \frac{dw}{dz} \cdot \frac{z^2}{z^3}$$

$$\frac{\partial w}{\partial \theta^2} = \frac{d^2 w}{dz^2} \cdot \frac{z^2}{z^2} + \frac{dw}{dz} \cdot \frac{1}{z} - \frac{dw}{dz} \cdot \frac{z^2}{z^3}$$

$$\Delta w = \frac{d^2 w}{dz^2} + \frac{1}{z} \frac{dw}{dz} = \frac{1}{z} \frac{\partial}{\partial z} \left(z \frac{\partial w}{\partial z} \right)$$

$$\frac{\partial}{\partial z} (r w) = w + r \frac{\partial w}{\partial z}$$

$$\rho w \frac{\partial w}{\partial z} = \rho g - \frac{\partial p}{\partial z} + \frac{4\mu}{3} \frac{\partial^2 w}{\partial z^2} + \mu \left(\frac{\partial^2 w}{\partial r^2} + \frac{1}{z} \frac{\partial w}{\partial z} \right)$$

$$\frac{\partial(\rho w)}{\partial z} = 0$$

$$w \frac{\partial p}{\partial z} + k \mu \frac{\partial w}{\partial z} = (k-1) \mu \left[\frac{4}{3} \left(\frac{\partial w}{\partial z} \right)^2 + \left(\frac{\partial w}{\partial r} \right)^2 \right] + (k-1) \kappa \left[\frac{\partial^2 \theta}{\partial z^2} + \frac{\partial^2 \theta}{\partial r^2} + \frac{1}{z} \frac{\partial \theta}{\partial z} \right]$$

Pytanie, czy to może być rozwiązaniem pod założeniami

$$\frac{\partial p}{\partial r} = \frac{\partial p}{\partial \theta} = 0 \quad (u = v = 0)$$

1) Pomijamy $\frac{\partial^2 \theta}{\partial z^2}$ i $\frac{\partial^2 \theta}{\partial r^2}$ i $\frac{\partial \theta}{\partial z}$ i $\frac{\partial w}{\partial z}$:

$$\rho w = f_c(z)$$

$$\left(\rho w \frac{\partial w}{\partial z} \right) = \rho g - \frac{dp}{dz} + \mu \left(\frac{\partial^2 w}{\partial r^2} + \frac{1}{z} \frac{\partial w}{\partial z} \right)$$

$$w \frac{\partial p}{\partial z} + k \mu \frac{\partial w}{\partial z} = (k-1) \kappa \left[\frac{\partial^2 \theta}{\partial z^2} + \frac{1}{z} \frac{\partial \theta}{\partial z} \right]$$



W równaniu termicznym:

$$u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} + k \rho \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = (k-1) \Phi + (k-1) \kappa \Delta^2 \theta$$

co pochodzą z ciepła przewodzenia?

$$c_p \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) = c \left[\frac{\partial}{\partial x} (\rho u \theta) + \frac{\partial}{\partial y} (\rho v \theta) + \dots \right] - c \theta \underbrace{\left[\frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} \right]}_{=0}$$

$$= \frac{c}{R} \left[\frac{\partial}{\partial x} (p u) + \frac{\partial}{\partial y} (p v) + \frac{\partial}{\partial z} (p w) \right]$$

Wzrost c_v strącający się: $\frac{c_v}{R} = \frac{1}{k-1}$

$$\text{zatem: } u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} + p \left[\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right] = (k-1) \kappa \Delta^2 \theta$$

Wzrost c_p :

$$k \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) + k p \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = (k-1) \kappa \Delta^2 \theta$$

Wzrost tutaj przynajmniej pośredni, między c_v i c_p .

$$\begin{cases} \frac{\partial p}{\partial x} = \frac{\rho}{3} \frac{\partial}{\partial x} \text{div} + \mu \Delta^2 u \\ \frac{\partial p}{\partial y} = \end{cases} \quad \frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} = 0$$

$$\frac{\partial p}{\partial z} = \rho g + \frac{\rho}{3} \frac{\partial}{\partial z} \text{div} + \mu \Delta^2 w$$

~~Wzrost~~ Zwiększenie p oznacza to przy wytyczeniu przekroczenia termodynamicznego.

zmiany w p będą prawie wyrażone pochodnymi z zmiany w θ
można zatem stwierdzić

$$p = p_0 (1 - \alpha \theta)$$

$$\rho \operatorname{div} \mathbf{u} = \rho_0 \left[u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right]$$

$$\frac{\partial}{\partial x} \operatorname{div} = \alpha \left[\frac{\partial u}{\partial x} \frac{\partial \theta}{\partial x} + \dots + u \frac{\partial^2 \theta}{\partial x^2} + \dots \right]$$

Supponiamo che θ sia costante, in tal caso $\Delta \theta = 0$.

$$\frac{\partial p}{\partial x} = \mu \Delta u$$

$$\frac{\partial p}{\partial y} = \mu \Delta v$$

$$\frac{\partial p}{\partial z} = \rho g + \mu \Delta w = f_z(x) + \mu \Delta w$$

$$\Delta p = \frac{\partial f_z}{\partial z} + \mu \Delta^2 \operatorname{div}$$

Supponiamo che θ sia costante:

$$\Delta p = \frac{4}{3} \mu \Delta^2 \operatorname{div} + g \frac{\partial \rho}{\partial z}$$

$$\rho = \rho_0 \theta$$

$$u \frac{\partial p}{\partial x} + v \frac{\partial p}{\partial y} + w \frac{\partial p}{\partial z} + K p \operatorname{div} = (K-1) \mu \Delta^2 \theta$$

Derivando le equazioni precedenti:

$$u \frac{\partial p}{\partial x} + v \frac{\partial p}{\partial y} + K p \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = (K-1) \mu \left(\frac{\partial^2 \theta}{\partial x^2} + \frac{\partial^2 \theta}{\partial y^2} \right)$$

$$\frac{\partial p}{\partial x} + \frac{\partial p}{\partial y} = g \frac{\partial \rho}{\partial y}$$

$$\frac{\partial p}{\partial x} = \mu \Delta u$$

$$\frac{\partial p}{\partial y} = \mu \Delta v + \rho g$$

Spôlníj: α máve by' rovinanie $p = \text{const}$ priu totick' medok?

$$\rho = \frac{\mu}{3} \frac{\partial}{\partial r} + \mu \Delta u + \rho X \quad \rho = R \rho \theta$$

$$\begin{aligned} 0 &= \frac{1}{\rho} \frac{\partial}{\partial y} \text{div} + \mu \Delta^2 v + \rho V \\ 0 &= \quad \quad \quad + \rho Z \end{aligned}$$

$$k_{f_0} \operatorname{div} = (k-1) \Phi + (k-1) \kappa \Delta^2 \theta$$

$$0 = \frac{4\pi}{3} \rho^2 dr + \frac{2}{\rho} \left(\rho^2 + \frac{2}{\rho} \left(\rho^2 + \frac{2}{\rho} (\rho^2) \right) \right)$$

Donnerstag Φ : $\dim = \frac{k-1}{k} \cdot k \cdot 28$

Kep. peng. diti:

$$0 = \frac{4\mu}{3} \Delta^2 \text{div} + g \frac{\partial \rho}{\partial z} \quad \rho = \frac{\rho_0}{R\theta}$$

$$\frac{4\pi}{3} \cdot \frac{1}{k} \cdot \frac{1}{p_0} \cdot \frac{1}{\Delta T} = \frac{1}{\rho} \cdot \frac{1}{\Delta T} \cdot \frac{1}{\Delta T}$$

$$\left. \begin{aligned} 0 &= \frac{\mu}{3} \frac{\partial}{\partial x} \cdot \text{div} + \mu \Delta^2 u \\ 0 &= \frac{\mu}{3} \frac{\partial}{\partial y} \cdot \text{div} + \mu \Delta^2 v \\ 0 &= \frac{\mu}{3} \frac{\partial}{\partial z} \cdot \text{div} + \mu \Delta^2 w + \rho g \end{aligned} \right\} \begin{aligned} \frac{\partial \rho}{\partial z} g &= - \frac{4}{3} \mu \Delta^2 \text{div} \\ \frac{\partial \rho}{\partial y} g &= - \mu \Delta^2 \left(\frac{\partial w}{\partial y} - \frac{\partial v}{\partial z} \right) \\ \frac{\partial \rho}{\partial x} g &= - \mu \Delta^2 \left(\frac{\partial w}{\partial x} - \frac{\partial u}{\partial z} \right) \end{aligned}$$

$$g \Delta^2 p = -\mu \Delta^2 \left[\Delta^2 \omega - \frac{2}{\partial^2} \text{div} + \frac{4}{3} \frac{2}{\partial^2} \text{div} \right]$$

$$= -\mu \Delta^2 \left[\Delta^2 \omega + \frac{4}{3} \frac{2}{\partial^2} \text{div} \right] \quad \text{not a div!}$$

any just jishi and motion v cu co

~~$$\rho u \frac{\partial u}{\partial x} + \frac{\partial p}{\partial x} = \frac{\mu}{3} \frac{\partial^2 u}{\partial x^2} + \rho u \frac{\partial u}{\partial y} + \rho u \frac{\partial u}{\partial z}$$~~

$$\rho u \frac{\partial u}{\partial x} + \frac{\partial p}{\partial x} = \frac{\mu}{3} \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} \right) + \rho \Delta^2 u$$

$$\frac{\partial p}{\partial y} = \frac{\mu}{3} \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial x} \right)$$

$$\frac{\partial p}{\partial z} = \frac{\mu}{3} \frac{\partial}{\partial z} \left(\frac{\partial u}{\partial x} \right)$$

$$\frac{\partial(\rho u)}{\partial x} = 0$$

$$u \frac{\partial p}{\partial x} + k \rho \frac{\partial u}{\partial x} = (k-1) \left[\frac{\mu}{3} \rho \left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial y} \right)^2 + \left(\frac{\partial u}{\partial z} \right)^2 \right] + (k-1) \kappa \Delta^2 u$$

any just motion $\rho = \rho_0 + \frac{\mu}{3} \frac{\partial u}{\partial x}$

$$\rho u \frac{\partial u}{\partial x} = \rho \Delta^2 u$$

$$\rho u \frac{\partial u}{\partial x} = \rho \Delta^2 \frac{\partial u}{\partial x}$$

?

$$u \frac{\partial p}{\partial x} + v \frac{\partial p}{\partial y} + w \frac{\partial p}{\partial z} = \frac{\mu}{3} \left[\mu \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} \right) + \dots \right] + \rho \left[u \Delta^2 u + v \Delta^2 v + w \Delta^2 w \right]$$

$$= \frac{\partial}{\partial x} \left(u \frac{\partial u}{\partial x} \right) - \left(\frac{\partial u}{\partial x} \right)^2 + \frac{\partial}{\partial y} \left(u \frac{\partial u}{\partial y} \right) - \left(\frac{\partial u}{\partial y} \right)^2 + \dots$$

$$= \frac{\rho \Delta^2 (u^2 + v^2 + w^2)}{2} - \left[\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial y} \right)^2 + \left(\frac{\partial u}{\partial z} \right)^2 + \dots \right]$$

$$\frac{\partial p}{\partial x} = \rho \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) \quad \left\{ \begin{array}{l} \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0 \end{array} \right.$$

$$\frac{\partial p}{\partial y} = \rho \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0$$

$$\left. \begin{aligned} \frac{\partial f}{\partial x} &= \frac{1}{3} \frac{\partial}{\partial x} \operatorname{div} + \Delta u \\ \text{II. } \frac{\partial f}{\partial y} &= \dots \\ \frac{\partial f}{\partial z} &= \rho g + \dots \end{aligned} \right\} \Delta f = \frac{4\mu}{3} \Delta^* \operatorname{div} + g \frac{\partial \theta}{\partial z}$$

$$\text{II. } \frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} = 0 \quad \rho = R_f \theta \quad \rho = \frac{k}{2\theta}$$

$$\text{III. } u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + w \frac{\partial f}{\partial z} + k \rho \operatorname{div} = (k-1) \Phi + (k-1) \Delta^* \theta$$

$$\frac{\partial}{\partial x} \left(\frac{k u}{\theta} \right) + \dots = 0$$

$$\frac{k}{\theta} \operatorname{div} + \frac{1}{\theta} \left(u \frac{\partial k}{\partial x} + \dots \right) - \frac{k}{\theta^2} \left(u \frac{\partial \theta}{\partial x} + \dots \right) = 0$$

$$k \operatorname{div} + \left(u \frac{\partial k}{\partial x} + \dots \right) = \frac{k}{\theta} \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right)$$

$$\text{III. a). } k \operatorname{div} = \frac{-1}{k-1} \frac{k}{\theta} \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) + k \Delta^* \theta$$

$$\text{b). } u \frac{\partial k}{\partial x} + v \frac{\partial k}{\partial y} + w \frac{\partial k}{\partial z} = \frac{-k}{k-1} \frac{k}{\theta} \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) + k \Delta^* \theta$$

W każdym razie: $\frac{1}{\theta} \frac{\partial k}{\partial x}$ będzie malarz powinn być $\frac{1}{\theta} \frac{\partial \theta}{\partial x}$
i ten malarz umi wyobrazić sobie, zatem z wielkim przybliżeniem:

$$k \operatorname{div} = \frac{k}{\theta} \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right)$$

$$\text{IV. } \operatorname{div} = \frac{1}{\theta} \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) = \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}$$

$$u \frac{\partial \theta}{\partial x} - \theta \frac{\partial u}{\partial x} + v \frac{\partial \theta}{\partial y} - \theta \frac{\partial v}{\partial y} + w \frac{\partial \theta}{\partial z} - \theta \frac{\partial w}{\partial z} = 0$$

$$\frac{\partial}{\partial x} \left(\frac{u}{\theta} \right) + \frac{\partial}{\partial y} \left(\frac{v}{\theta} \right) + \frac{\partial}{\partial z} \left(\frac{w}{\theta} \right) = 0$$

$$\text{III b): } \frac{k}{k-1} \frac{1}{\theta} \left[u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right] = \kappa \cdot \Delta \theta = \frac{k}{k-1} \rho \operatorname{div}$$

$$\text{I). } \Delta \rho = \frac{4\mu}{3} \Delta \operatorname{div} + \underbrace{\frac{g\mu}{R\theta} \frac{\partial \rho}{\partial z}}_{\text{mole, ...}} - \underbrace{\frac{g\mu}{R\theta^2} \frac{\partial \theta}{\partial z}}_{\text{...}} \neq \frac{4\mu}{3} \Delta \operatorname{div} - \frac{g\mu}{R\theta^2} \frac{\partial \theta}{\partial z}$$

$$\rho = \frac{4\mu}{3} \operatorname{div} \text{ ... } + A \quad \nabla A = 0$$

$$\mu \frac{\partial}{\partial x} \operatorname{div} \dots$$

$$\text{I). } \frac{\partial \rho}{\partial x} = \frac{4\mu}{3} \frac{\partial}{\partial x} \operatorname{div} + \rho \Delta u$$

$$\frac{\partial \rho}{\partial y} = \frac{4\mu}{3} \frac{\partial}{\partial y} \operatorname{div} + \rho \Delta v$$

$$\frac{\partial \rho}{\partial z} = \frac{4\mu}{3} \frac{\partial}{\partial z} \operatorname{div} + \rho \Delta w - \frac{g\mu}{R\theta^2} \frac{\partial \theta}{\partial z}$$

$$\frac{b}{m} = \frac{b_m}{R \cdot t} \quad \rho_m = \frac{b_m}{m}$$

$$\mu \Delta \xi = - \frac{g\mu}{R\theta^2} \frac{\partial \theta}{\partial x}$$

$$\mu \Delta \eta = - \frac{g\mu}{R\theta^2} \frac{\partial \theta}{\partial y}$$

$$\Delta \gamma = 0$$

Grenzwert propadeti

$$1) \dots \kappa = \infty$$

$$\text{II). } \Delta \theta = 0$$

$$\theta = f(x, y, z)$$

$$\left\{ \begin{array}{l} \text{II} \\ \text{I} \end{array} \right.$$

Ergebnis:

$$\frac{\partial \rho}{\partial x} = \rho \Delta u$$

$$\frac{\partial \rho}{\partial y} = \rho \Delta v - \frac{g\mu}{R\theta^2} \frac{\partial \theta}{\partial y}$$

$$\operatorname{div} = \frac{1}{\theta} \left(\mu \frac{\partial \theta}{\partial z} + \dots \right)$$

$$\frac{\partial \rho}{\partial x} = \dots$$

$$\frac{\partial \rho}{\partial y} = \dots$$

$$\frac{\partial \rho}{\partial z} = \dots$$

$$\dots$$

$$\dots$$

Lepig Toti:

I. Inyphizim: $\text{div} = 0$

$$\Delta \theta = 0$$

$$\frac{\partial f}{\partial x} = \mu \Delta u$$

$$\frac{\partial f}{\partial y} = \mu \Delta v$$

$$\frac{\partial f}{\partial z} = \mu \Delta w - \frac{g f}{R \theta^2}$$

$$\Delta f = \frac{g f}{R \theta^2} \frac{\partial \theta}{\partial z}$$

$$u, v, w = 0 \dots$$

II. Inyphizim:

$$\Delta (x^2 + y^2 + z^2) = 6$$

$$\text{div} = \frac{1}{\theta} \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right)$$

$$\Delta (x^2) = 6$$

$$\kappa \Delta \theta = \frac{k}{k-1} \mu \text{div}$$

$$\frac{\partial^2 x^2}{\partial x^2} = \frac{2}{1}$$

$$\frac{\partial f}{\partial x} = \dots$$

$$\frac{\partial f}{\partial y} = \dots$$

$$\frac{\partial f}{\partial z} = \dots$$

$$\theta_0 = \frac{T}{n} \frac{n_1}{n}$$

$$\alpha = -3T n_1$$

$$\Delta f_1 = -3T n_1 \frac{z}{z^3}$$

$$f_1 = \frac{\alpha x}{2n}$$

$$f_1 = \alpha z \left[A + \frac{1}{2n} + \frac{B}{z^3} \right] + \frac{C}{n}$$

$$\left. \begin{aligned} \Delta^2 u_1 &= -\alpha 2x \left[\frac{1}{2r^3} + \frac{3B}{2r^5} \right] - \frac{C_x}{r^3} \\ \Delta^2 v_1 &= -\alpha 2y \left[\quad \right] + \frac{C_y}{r^3} \\ \Delta^2 w_1 &= +\alpha \left[A + \frac{1}{2r} + \frac{B}{r^3} \right] - \frac{C_z}{r^3} - \alpha 2^2 \left[\frac{1}{2r^3} + \frac{3B}{2r^5} \right] - \alpha \left[\frac{1}{r} \right] \\ &= \alpha \left[A + \frac{1}{2r} + \frac{B}{r^3} \right] - \frac{C_z}{r^3} - \alpha 2^2 \left[\frac{1}{2r^3} + \frac{3B}{2r^5} \right] \end{aligned} \right\}$$

$$u_1 = \alpha x 2 \left[\frac{1}{8r} + \frac{B}{2r^3} \right]$$

$$v_1 = \alpha y 2 \left[\frac{1}{8r} + \frac{B}{2r^3} \right]$$

$$w_1 = \alpha \left[\frac{A}{10} (2r^2 - r^2) + \frac{B}{2r^3} + \frac{1}{8} (2r^2 - 3r) \right]$$

To satisfy the r.c.o.

$$\left. \begin{aligned} u_\infty &= \frac{\alpha}{8} r \cos \varphi \\ v_\infty &= \frac{\alpha}{8} r \sin \varphi \end{aligned} \right\} \begin{aligned} A &= 0 \\ g &= \frac{\alpha}{8} 2 \cos \varphi \end{aligned}$$

$$w_\infty = \frac{\alpha}{8} r (\cos \varphi - 3)$$

In special particular case of uniform & incompressible: $u = v = w = 0$

Also to no expansion & II agree: $u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z}$

choisir une couronne constante : $\Delta^2 \theta = a \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right)$

transférer $\Delta^2 \varphi = 0 = \cancel{u \Delta^2 u} + \cancel{v \Delta^2 v} + 2 \frac{\partial u}{\partial x} \frac{\partial v}{\partial x} + 2 \frac{\partial u}{\partial y} \frac{\partial v}{\partial y}$

$$\varphi = \chi \cdot \chi$$

$$\frac{\partial \varphi}{\partial x} = u \frac{\partial v}{\partial x} + v \frac{\partial u}{\partial x}$$

$$\frac{\partial^2 \varphi}{\partial x^2} = u \frac{\partial^2 v}{\partial x^2} + 2 \frac{\partial u}{\partial x} \frac{\partial v}{\partial x} + v \frac{\partial^2 u}{\partial x^2}$$

$$\Delta^2 \varphi = \chi \Delta^2 \chi + \chi \Delta^2 \chi + 2 \left[\frac{\partial \chi}{\partial x} \frac{\partial \chi}{\partial x} + \frac{\partial \chi}{\partial y} \frac{\partial \chi}{\partial y} + \frac{\partial \chi}{\partial z} \frac{\partial \chi}{\partial z} \right]$$

hypothèse 2ème :

$$\chi = 0$$

$$u = \frac{\partial \varphi}{\partial x}$$

$$v = \frac{\partial \varphi}{\partial y}$$

$$w = \frac{\partial \varphi}{\partial z}$$

$$\Delta^2 \varphi = 0$$

$$u = \frac{\partial}{\partial x} (\log \varphi) \quad v = \frac{\partial}{\partial y} (\log \varphi) \quad w = \frac{\partial}{\partial z} (\log \varphi)$$

$$\Delta^2 \varphi = \frac{1}{\varphi} \Delta^2 \varphi - \frac{1}{\varphi^2} \left[\left(\frac{\partial \varphi}{\partial x} \right)^2 + \left(\frac{\partial \varphi}{\partial y} \right)^2 + \left(\frac{\partial \varphi}{\partial z} \right)^2 \right]$$

Jeżeli zatem u, v, w mogą być wyrażone przez taką funkcję φ że

$$-\frac{a}{2}u = \frac{\partial}{\partial x}(\log \varphi); -\frac{a}{2}v = \frac{\partial}{\partial y}(\log \varphi); \frac{a}{2}w = \frac{\partial}{\partial z}(\log \varphi) \quad \Delta^2 \varphi = 0$$

to stądże $\theta = \frac{\varphi}{\varphi}$, gdzie $\Delta^2 \varphi = 0$

Widziemy więc wznowienie równania: $\Delta^2 \theta = a \left(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) = 0$

Zatem wyprowadzamy i rachujemy

$$\text{div} = \frac{1}{\theta} \left[u \frac{\partial \theta}{\partial x} + \dots \right]$$

Przy podsumowaniu $u=v=w=0$ $\text{div} = 0$ $\Delta^2 \theta = 0$ $\frac{\partial \theta}{\partial x} = 0$ $\frac{\partial \theta}{\partial y} = 0$

$$\theta = \theta_0 + n \left(\frac{\partial \theta}{\partial n} \right)_0 + \frac{n^2}{2} \left(\frac{\partial^2 \theta}{\partial n^2} \right)_0 + \frac{n^3}{6} \frac{\partial^3 \theta}{\partial n^3} + \frac{n^4}{24} \frac{\partial^4 \theta}{\partial n^4} + \dots$$

$$\Delta^2 \theta = a \int v \cdot \nabla \theta$$

Specjalny przykład: $v = u = 0$ $w = u = 0$

$$\text{div} = \frac{1}{\theta} \left[v \frac{\partial \theta}{\partial y} \right] = \frac{\partial v}{\partial y} = \dots$$

~~$\frac{\partial \theta}{\partial y} = \dots$~~ ~~$\frac{\partial \theta}{\partial x} = \dots$~~ ~~$\frac{\partial \theta}{\partial z} = \dots$~~

$$\frac{1}{\theta} \frac{\partial \theta}{\partial y} = \frac{1}{v} \frac{\partial v}{\partial y}$$

$$\frac{\partial v}{\partial x} = \frac{1}{3} \frac{\partial v}{\partial x} \text{ div} = \frac{1}{3} \frac{\partial v}{\partial x} \text{ div}$$

$$\frac{\partial v}{\partial y} = \frac{1}{3} \frac{\partial v}{\partial y} \text{ div} = \frac{1}{3} \frac{\partial v}{\partial y} \text{ div}$$

$$\frac{\partial v}{\partial y} = \frac{1}{3} \frac{\partial v}{\partial y} \text{ div} + \dots = \frac{1}{3} \frac{\partial v}{\partial y} + \dots$$

$$\Delta^2 \theta = \frac{4n}{3} \Delta^2 \frac{\partial v}{\partial y} + g \frac{\rho_0}{\theta_0} \frac{\partial \theta}{\partial y}$$

Przybliżenie jeżeli $\frac{\partial \theta}{\partial y} = \frac{\partial v}{\partial y} = 0$

$$p = p_0(y)$$

$$\frac{\partial \theta}{\partial x} = 0$$

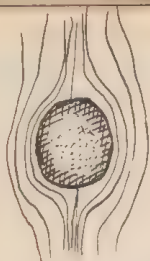
$$\frac{\partial \theta}{\partial x} = \frac{\theta_1 - \theta_2}{s}$$

$$\frac{dp}{dy} = n \left(\rho_0 \frac{\partial v}{\partial x} + g \rho_0 \left[1 + \frac{\theta}{\theta_0} \right] \right)$$

$$\frac{\partial v}{\partial x} = \frac{\partial v}{\partial x} = \frac{\theta_1 - \theta_2}{s}$$

$$v = \left(\frac{\theta_1 - \theta_2}{s} \right) \frac{1}{6} + 4x^2 + 6x + \dots$$

$$\frac{dp}{dy} = n \left(\rho_0 \frac{\theta_1 - \theta_2}{s} + 2g \right) + g \rho_0 \left[1 + \dots \right]$$



Pręgiem i ruch „lamellarny”

korze sponowai i tyłko warstwy i kupa i ruchy i symonii
i kupa i ruchy i symonii

$$\Delta^2 \theta = \alpha \nabla^2 (\nabla \theta)$$

$\nabla \theta$ przyświeca $\perp s$
 $\nabla \parallel s$

$$\left. \begin{array}{l} \Delta^2 \theta = 0 \\ \text{div} = 0 \end{array} \right\}$$

$$\frac{\partial \theta}{\partial x} = 0$$

$$\frac{\partial \theta}{\partial x} = \mu \frac{\partial \theta}{\partial x^2} + \rho \rho_0 \left[1 - \frac{\rho}{\rho_0} \right] \frac{\partial \theta}{\partial x}$$

$$\mu \frac{\partial^2 \theta}{\partial x^2} = \rho \rho_0 \theta$$

$$\mu \frac{\partial^2 \theta}{\partial x^2} = \rho \rho_0 \frac{\partial \theta}{\partial x}$$

$$\text{div} = \alpha \left(\mu \frac{\partial^2 \theta}{\partial x^2} \right)$$

Zamroziłbyś ciepłotę wewnątrz p w kolumnie parowania:

$$\frac{\partial \theta}{\partial x} + \rho g = \frac{\theta}{\theta_0} \rho_0 g$$

$$0 = \mu \frac{\partial^2 \theta}{\partial x^2} + \rho \theta_0$$

$$0 = \mu \frac{\partial^2 \theta}{\partial x^2} + \rho \theta_0$$

$$0 = \mu \frac{\partial^2 \theta}{\partial x^2} + \rho \theta_0 + \frac{\theta}{\theta_0} \rho_0 g$$

$$\frac{\partial \theta}{\partial x} = \mu \left(\frac{\partial^2 \theta}{\partial x^2} \right)$$

$$0 = g \frac{\partial \theta}{\partial x} + \frac{\theta}{\rho} \frac{\partial^2 \theta}{\partial x^2}$$

$$\frac{\partial \theta}{\partial x} = \mu \kappa \frac{\partial^2 \theta}{\partial x^2}$$

$$\mu \frac{\partial^2 \theta}{\partial x^2} = \kappa \frac{\partial^2 \theta}{\partial x^2}$$

$$\frac{\partial \theta}{\partial x} = \mu \kappa \frac{\partial^2 \theta}{\partial x^2} = \mu \kappa \frac{\partial \theta}{\partial x} \frac{\partial \theta}{\partial x}$$

$$\alpha \left[\mu \frac{\partial^2 \theta}{\partial x^2} + \rho \frac{\partial \theta}{\partial x} + \frac{\theta}{\theta_0} \rho_0 g \right] = \Delta^2 \theta$$

$$\theta = - \frac{\eta}{\rho} \frac{1}{g} \frac{\partial^2 \theta}{\partial x^2}$$

$$\begin{aligned} \frac{\partial \theta}{\partial x} &= \frac{\kappa}{\mu} \frac{\partial^2 \theta}{\partial x^2} \\ \frac{\partial \theta}{\partial x} &= \frac{\kappa}{\mu} \frac{\partial \theta}{\partial x} \frac{\partial \theta}{\partial x} \\ \frac{\kappa}{\mu} &= \frac{\kappa}{\mu} \frac{\partial \theta}{\partial x} \frac{\partial \theta}{\partial x} \\ a &= 20 \text{ K} \end{aligned}$$

$$W = \frac{K}{\theta} \frac{\partial \theta}{\partial x}$$

$$\frac{\partial W}{\partial x} = -\frac{K}{\theta^2} \frac{\partial \theta}{\partial x} \frac{\partial \theta}{\partial x} + \frac{K}{\theta} \frac{\partial^2 \theta}{\partial x^2}$$

$$\frac{\partial^2 W}{\partial x^2} = + \frac{2K}{\theta^3} \left(\frac{\partial \theta}{\partial x} \right)^2 \frac{\partial \theta}{\partial x} - \frac{K}{\theta^2} \left(\frac{\partial^2 \theta}{\partial x^2} \right)^2 - 2 \frac{K}{\theta} \frac{\partial \theta}{\partial x} \frac{\partial^2 \theta}{\partial x^2} + \frac{K}{\theta} \frac{\partial^3 \theta}{\partial x^3} = -\frac{2K}{\theta^3} \frac{\partial \theta}{\partial x} \frac{\partial^2 \theta}{\partial x^2} + \frac{K}{\theta} \frac{\partial^3 \theta}{\partial x^3}$$



$$\frac{dW}{dx} = p$$

$$\frac{d^2 W}{dx^2} = p \frac{dp}{dx}$$

$$\frac{d^3 W}{dx^3} = \frac{d}{dx} \left(p \frac{dp}{dx} \right) = p \frac{d^2 p}{dx^2} + \left(\frac{dp}{dx} \right)^2$$

$$\frac{d^3 W}{dx^3} = \left(\frac{dp}{dx} \right)^2 + p \frac{d^2 p}{dx^2}$$

$$\frac{d^4 W}{dx^4} = p \left[\left(\frac{dp}{dx} \right)^3 + 4p \frac{dp}{dx} \frac{d^2 p}{dx^2} + p^2 \frac{d^3 p}{dx^3} \right]$$

$$W \frac{dp}{dx} = K \left[p^2 \frac{d^3 p}{dx^3} + 4p \frac{dp}{dx} \frac{d^2 p}{dx^2} + \left(\frac{dp}{dx} \right)^3 \right]$$

$$u = \frac{\partial}{\partial x} (\gamma^2 \gamma) + u'$$

$$v = +v'$$

$$w = +w'$$

folgende: $\psi = \frac{c}{2} \frac{a^2 z}{r^3} + c z + b$

$\frac{\partial \psi}{\partial z} = \frac{c a^2}{2 r^3} + c = \frac{3 c a^2 z}{2 r^5} = \frac{3}{2} \frac{c a^2}{r^3} z$
 $\frac{\partial \psi}{\partial x} = -\frac{3 c a^2 z}{2 r^5} \cdot \frac{x}{r} = -\frac{3}{2} \frac{c a^2}{r^5} x z$

$\frac{\partial \psi}{\partial z} = -\frac{1}{2} \sin^2 \varphi$

$\Delta \psi = 0$

$\varphi = 0,4$

$\frac{\partial \psi}{\partial u} \Big|_{r=0} = -\frac{1}{2} \sin^2 \varphi$

$r=a \quad \varphi = \theta_1 \left[b + \frac{3c}{2} a \cos \varphi \right]$
 $r=\infty \quad \varphi = \theta_0 \cos \varphi$

$\psi = c$

$\psi = \psi$

$\psi = c$

$r=a \quad \varphi = \theta_1 e^{b + \frac{3c}{2} a \cos \varphi} = \theta_2 e^{\frac{3c a}{2} \cos \varphi} = \theta_2 e^{\frac{3c}{2} x}$
 $r=\infty \quad \varphi = \theta_0 e^{c z_0} = \theta_0 e^{c z_0 \cos \varphi} = \theta_0 e^{c x}$

Wiederum: konstante Werten $\Delta \psi + a \left(\frac{\partial \psi}{\partial x} + \dots \right) = 0$

mithin: allgemeine Lösung: $\psi = \dots$

$\psi = A_0 + A_1 P_1 + A_2 P_2 + \dots$
 $+ \frac{A_0}{r} + \frac{A_1 P_1}{r^2} + \frac{A_2 P_2}{r^3} + \dots$

$\int_{-1}^{+1} e^{ax} P_n dx$

[8]

2. Ansatz : $\frac{\partial \theta}{\partial y} = \frac{\partial v}{\partial y} = 0$

$\frac{\partial \theta}{\partial x} = 0 \rightarrow \theta = f(y)$

$\text{div} = 0$

$v = f(x)$

~~$\mu \frac{\partial \theta}{\partial x} + \nu \frac{\partial \theta}{\partial y} = 0$~~

$\theta = f(x)$

$\frac{d^2 \theta}{dx^2} = 0$

$\theta = \theta_1 + (\theta_2 - \theta_1) \frac{x}{\delta}$

$\frac{dp}{dy} = \mu \frac{dv}{dx^2} + \rho g \left[\theta_1 + (\theta_2 - \theta_1) \frac{x}{\delta} \right] = \mu \frac{dv}{dx^2} + \rho g \frac{\theta_2 - \theta_1}{\theta_1} \frac{x}{\delta} + \rho g \theta_1$

$\frac{d^2 v}{dx^2} = 0$

$p = p_0 + \gamma \frac{p_1 - p_0}{h}$

~~$0 = \mu \frac{dv}{dx^3} + \rho g \frac{\theta_2 - \theta_1}{\theta_1} \frac{x}{\delta}$~~

$\frac{dp}{dy} = \frac{p_1 - p_0}{h} =$

$\left(\frac{p_1 - p_0}{h} \right) \frac{x}{\delta} = \mu \frac{dv}{dx^2} + \rho g \frac{\theta_2 - \theta_1}{\theta_1} \frac{x^2}{2\delta} + b$

$\frac{p_1 - p_0}{h} \frac{x^2}{2} = \mu v + \rho g \frac{\theta_2 - \theta_1}{\theta_1} \frac{x^3}{6\delta} + bx + c$

$\left. \begin{matrix} x=0 \\ x=\delta \end{matrix} \right\} \begin{matrix} v=0 \\ c=0 \end{matrix}$

$\frac{p_1 - p_0}{h} \frac{\delta^2}{2} = \rho g \frac{\theta_2 - \theta_1}{\theta_1} \frac{\delta^3}{6} + b\delta$

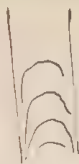
$\left[\rho g \theta_1 - \frac{p_1 - p_0}{h} \right] \frac{x^2 - \delta^2}{2} = \mu v + \rho g \frac{\theta_2 - \theta_1}{\theta_1} \frac{x^3 - \delta^3}{6}$

II). $\mu \neq 0$

$\nabla^2 \theta = (ax + bx^2 + cx^3) \frac{\partial \theta}{\partial y} = x^2 \left(\frac{\partial^2 \theta}{\partial x^2} + \frac{\partial^2 \theta}{\partial y^2} \right) = \frac{\partial^2 \theta}{\partial x^2} + \frac{\partial^2 \theta}{\partial y^2}$

$\theta = f(y)$

$\frac{d^2 \theta}{dy^2} = \left(\mu \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 \theta}{\partial y^2} \right) + \rho g \frac{\theta}{\theta_1}$



$$\frac{\partial p}{\partial x} = \rho \frac{\partial v}{\partial x} + \rho \theta \neq 0$$

$$\frac{\partial p}{\partial y} = \rho \frac{\partial v}{\partial y} + \rho \Delta v + \rho g \frac{\theta}{\theta_0}$$

$$p = f(y)$$

$$\theta = f(x, y)$$

$$\alpha \Delta \theta = u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + \theta \operatorname{div}$$

$$u=0$$

$$\frac{dp}{dy} = \mu \frac{\partial^2 v}{\partial x^2} + \rho_0 g \frac{\theta}{\theta_0}$$

$$0 = \mu \frac{\partial^3 v}{\partial x^3} + \rho_0 g \frac{\partial \theta}{\partial x}$$

$$\alpha \left(\frac{\partial^2 \theta}{\partial x^2} + \frac{\partial^2 \theta}{\partial y^2} \right) = v \frac{\partial \theta}{\partial y} = \theta \frac{\partial v}{\partial y}$$

$$\theta = \frac{\mu \theta_0}{g \rho_0} \frac{\partial^2 v}{\partial x^2} + \varphi(y)$$

$$\alpha \left[\frac{\mu \theta_0}{g \rho_0} \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) + \frac{\partial \varphi}{\partial y} \right] = \frac{\mu \theta_0}{g \rho_0} v \frac{\partial^3 v}{\partial x^2 \partial y} + v \frac{d\varphi}{dy}$$

$$\frac{\partial}{\partial y} \left(\frac{v}{\theta} \right) = 0$$

$$\frac{v}{\theta} = f(x)$$

$$v = \theta \cdot \psi(x)$$

$$\alpha \left(\frac{\partial^2 \theta}{\partial x^2} + \frac{\partial^2 \theta}{\partial y^2} \right) = \theta \frac{\partial \theta}{\partial y} \psi(x)$$

$$\theta = \frac{\mu \theta_0}{g \rho_0} \left[\frac{\partial^2 \theta}{\partial x^2} \psi + 2 \frac{\partial \theta}{\partial x} \frac{d\psi}{dx} + \theta \frac{d^2 \psi}{dx^2} \right] + \varphi(y)$$

Skoro wiemy, że w każdym punkcie $\theta = \text{const}$
zatem $\frac{d^2 \psi}{dx^2} = a$

$$\psi = a \frac{x^2}{2} + bx + c$$

$$\text{Wzrostki: } \frac{\partial \theta}{\partial y} = \frac{\partial \theta}{\partial x} = 0$$

$$\varphi(y) = \text{const}$$

$$\theta = \frac{\mu \theta_0}{g \rho_0} \frac{\partial v}{\partial x} + \text{const}$$

$$\theta = \text{const.}$$

in linij slothovej: $\frac{\partial \theta}{\partial x} = 0$ $\frac{dy}{dx} = a$

$$\theta \left[1 - \frac{\mu \theta_0}{g \rho_0} a \right] = \frac{\mu \theta_0}{g \rho_0} \left(a \frac{x^2}{2} + b x + c \right) \frac{\partial \theta}{\partial x} + \text{const} \quad \left| \frac{\partial}{\partial x} \right.$$

$$\theta \frac{\partial \theta}{\partial y} \quad \left| \frac{\partial}{\partial y} \right. = a^2 \frac{\partial \theta}{\partial x} \quad \left| \frac{\partial}{\partial x} \right. \quad \left| \frac{\mu \theta_0}{g \rho_0} \right.$$

$$a^2 \theta \left[1 - \frac{\mu \theta_0}{g \rho_0} a \right] - \frac{\mu \theta_0}{g \rho_0} \theta \frac{d\theta}{dy} \left(\frac{y}{2} \right) = a^2 \cdot \text{const}$$

$$\theta = m + n y$$

$$\theta \frac{d\theta}{dy} + A \theta = B$$

$$\frac{\theta d\theta}{\theta - A\theta} = dy$$

$$y =$$

I stacionarni rešenja (dla crnog.)

Razn. klasi. je stoji:

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \nabla^2 u$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

$$\frac{\partial u}{\partial t} + \frac{\partial}{\partial x} (u^2 + p) + \frac{\partial}{\partial y} (uv) + \frac{\partial}{\partial z} (uw) = \frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \nabla^2 u$$

$$\frac{\partial u}{\partial t} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \nabla^2 u - \left[u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right]$$

$$\frac{\partial v}{\partial t} + (v \cdot \nabla) v = \frac{1}{\rho} \nabla p + \nu \nabla^2 v$$

$$\frac{\partial \text{curl } v}{\partial t} + \text{curl } (v \cdot \nabla) \text{curl } v = \mu \nabla^2 \text{curl } v$$

$$\frac{\partial \text{curl}(v+v)}{\partial t} + \text{curl} (v+v) \cdot \text{curl}(v+v) = \mu \nabla^2 \text{curl}(v+v)$$

$$\frac{\partial \text{curl } v}{\partial t} + \text{curl} [v \cdot \text{curl } v + v \cdot \text{curl } v] = \mu \nabla^2 \text{curl } v$$

$$\frac{\partial p_{xx}}{\partial x} + \frac{\partial p_{xy}}{\partial y} + \frac{\partial p_{xz}}{\partial z} = -\frac{\partial p}{\partial x} + \lambda \frac{\partial}{\partial x} \text{div} + 2\mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right)$$

$$= \mu \left[2 \frac{\partial^2 u}{\partial x^2} + \left(\frac{\partial^2 v}{\partial y \partial x} + \frac{\partial^2 u}{\partial x \partial y} + \frac{\partial^2 u}{\partial z \partial x} + \frac{\partial^2 u}{\partial x \partial z} \right) \right]$$

$$= -\frac{\partial p}{\partial x} + (\lambda + \mu) \frac{\partial}{\partial x} \text{div} + \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right)$$

$$\lambda = -\frac{2}{3}\mu$$

$$= -\frac{\partial p}{\partial x} + \frac{1}{3} \frac{\partial}{\partial x} \text{div} +$$

$$p = p_0 + \alpha \text{div}$$

$$p \text{div} + u \frac{\partial p}{\partial x} + \dots = 0$$

$$p = p_0 + \alpha \text{div}$$

$$p + (2\mu + \lambda) \frac{\partial u}{\partial x}$$

$$2\mu + \lambda = 3\mu \quad \text{OK Reyn}$$

$$\lambda = \mu$$

$$\rho \frac{\partial u}{\partial t} = -\frac{\partial p}{\partial x} + \nu \frac{\partial}{\partial x} \text{div} + \mu \frac{\partial^2 u}{\partial x^2} = -\frac{\partial p}{\partial x} + (v+\mu) \frac{\partial^2 u}{\partial x^2}$$

$$\frac{\partial(\rho u)}{\partial x} + \frac{\partial p}{\partial t} = 0$$

$$\frac{\partial p}{\partial t} + u \frac{\partial p}{\partial x} + k p \frac{\partial u}{\partial x} = (k-1) \Phi$$

$$\frac{\partial p}{\partial t} + \rho \frac{\partial u}{\partial x} = 0$$

$$\rho \frac{\partial u}{\partial t} = -\frac{\partial p}{\partial x} + (v+\mu) \frac{\partial^2 u}{\partial x^2}$$

$$\frac{\partial p}{\partial t} + k p \frac{\partial u}{\partial x} = (k-1) \Phi$$

Wohin vgl. manifizierung dynam. v. turbulenz?

$$I). \frac{\partial p}{\partial t^2} = -\frac{\partial}{\partial t} \frac{\partial u}{\partial x} = -\rho \frac{\partial^2 u}{\partial x \partial t}$$

$$\frac{\partial p}{\partial x} \frac{\partial u}{\partial t} + \rho \frac{\partial^2 u}{\partial x \partial t} = -\frac{\partial p}{\partial x} + (v+\mu) \frac{\partial^2 u}{\partial x^2}$$

$$\frac{\partial p}{\partial x} \frac{\partial u}{\partial t} + \rho \frac{\partial^2 u}{\partial x \partial t} + \rho \frac{\partial^2 u}{\partial x^2}$$

$$\frac{\partial p}{\partial x} = \left(\frac{\partial p}{\partial x} \right)^k$$

$$II). \frac{\partial p}{\partial x} \frac{\partial u}{\partial t} + \rho \frac{\partial^2 u}{\partial x^2} = -\frac{\partial^2 p}{\partial x \partial t} + (v+\mu) \frac{\partial^3 u}{\partial x^3}$$

$$3). \frac{\partial u}{\partial t^2} = \alpha^2 \frac{\partial^2 u}{\partial x^2} + (v+\mu) \frac{\partial^2 u}{\partial x \partial t}$$

$$u = \sin(\alpha x + \beta t) e^{-\gamma t}$$

$$\frac{\partial u}{\partial t} = \beta \cos(\alpha x + \beta t) e^{-\gamma t} - \gamma \sin(\alpha x + \beta t) e^{-\gamma t}$$

$$\frac{\partial^2 u}{\partial t^2} = -\beta^2 \sin(\alpha x + \beta t) e^{-\gamma t} - 2\gamma \beta \cos(\alpha x + \beta t) e^{-\gamma t} + \gamma^2 \sin(\alpha x + \beta t) e^{-\gamma t}$$

$$(\beta^2 - \gamma^2) \sin(\alpha x + \beta t) - 2\gamma \beta \cos(\alpha x + \beta t) = \alpha^2 \sin(\alpha x + \beta t) + (v+\mu) [-\alpha^2 \gamma \sin(\alpha x + \beta t) - \alpha^2 \beta \cos(\alpha x + \beta t)]$$

$$\beta^2 - \gamma^2 = -\alpha^2 \alpha^2 + (v+\mu) \alpha^2 \gamma$$

$$\gamma = \frac{\alpha^2}{2} (v+\mu)$$

$$\beta^2 = \alpha^2 \alpha^2 + \frac{\alpha^4 (v+\mu)^2}{4}$$

$$\beta = \alpha \sqrt{\alpha^2 + \frac{(v+\mu)^2}{4\alpha^2}}$$

$$II). \quad \rho \frac{\partial u}{\partial t} = - \frac{\partial F}{\partial x \partial t}$$

$$\frac{\partial F}{\partial t} = -k_f \frac{\partial u}{\partial x} + (k-1) \frac{4}{3} \mu \left(\frac{\partial u}{\partial x} \right)^2$$

$$\frac{\partial F}{\partial x \partial t} = -k_f \frac{\partial^2 u}{\partial x^2} - k \frac{\partial F}{\partial x} \frac{\partial u}{\partial x} + \frac{8}{3} (k-1) \frac{\partial u}{\partial x} \frac{\partial^2 u}{\partial x^2}$$

mało w tym celu

Kula swobodna w



zwiększającej inercji to statystycznie

prędkością hydrodynamiczną

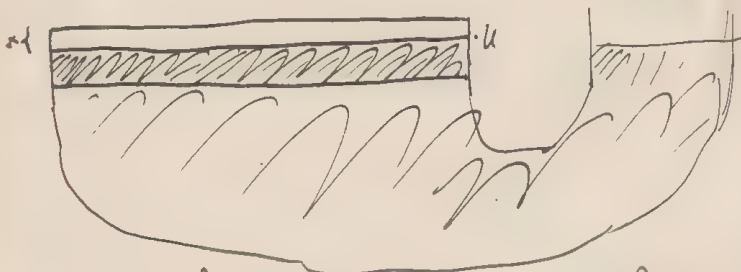
$$\frac{\partial u}{\partial t} = \frac{\partial u}{\partial x} \frac{dx}{dt} \quad x = x_0 = a = a_0$$

$$\frac{dx}{dt} = u = \frac{x_0}{a_0} \frac{da}{dt} \quad u = x \frac{1}{a} \frac{da}{dt}$$

$$\frac{\partial u}{\partial x} = \frac{1}{a} \frac{da}{dt} = c$$

$$\frac{\partial u}{\partial y} = 0$$

$$\Phi = 0!$$



$$u = U \frac{x}{a}$$

$$\frac{\partial u}{\partial x} = \frac{U}{x}$$

$$p_{\text{eff}} = -p + 2\mu \frac{\partial u}{\partial x} - \frac{2}{3} \mu \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = -p + \frac{4}{3} \mu \frac{\partial u}{\partial x} = -p + \frac{4}{3} \mu \frac{U}{x}$$

$$M \frac{d^2 u}{dt^2} = -2Q \times 1g \cdot a - p_0 + p - \frac{4}{3} \mu \frac{dx}{dt}$$

$$p = p_0 \frac{a}{x}$$

$$M \frac{dx}{dt} = -p_0 - 2\phi_{sg} \cdot x + \frac{p_0 a}{x} - \frac{4}{3} \frac{p_0}{x} \frac{dx}{dt}$$

$$\frac{dx}{dt} = 2 \quad \frac{dx}{dt} = \frac{dz}{dt} = \frac{dz}{dx} \cdot 2$$

$$M 2 \frac{dz}{dx} + \frac{4}{3} \mu \frac{z}{x} = \frac{p_0 a}{x} + 2\phi_{sg} \cdot x + p_0 = 0$$

$$\frac{D}{Dt} \left[\frac{c}{A} \theta + \frac{1}{2} (u^2 + v^2 + w^2) + U \right] = \left[\frac{\partial}{\partial x} (u \cdot p_{xx}) + \frac{\partial}{\partial y} (v \cdot p_{yy}) + \frac{\partial}{\partial z} (w \cdot p_{zz}) \right. \\ \left. + \frac{\partial}{\partial y} (u \cdot p_{xy}) + \frac{\partial}{\partial x} (v \cdot p_{yx}) + \dots \right] \frac{dx}{dt}$$

$$\frac{D}{Dt} \theta = \rho u \frac{\partial u}{\partial x} + \rho v \frac{\partial v}{\partial y} + \dots + \rho u \frac{\partial p_{xx}}{\partial x} + \rho v \frac{\partial p_{yy}}{\partial y} + \dots + \rho u \frac{\partial p_{xy}}{\partial y} + \rho v \frac{\partial p_{yx}}{\partial x} + \dots \\ = u \left(\rho \frac{\partial u}{\partial x} - \rho \chi \right) + v \left(\rho \frac{\partial v}{\partial y} - \rho \chi \right) + \dots - \rho \operatorname{div} + \Phi$$

$$\frac{D}{Dt} \theta = 2u \frac{\partial \theta}{\partial x}$$

$$2u \frac{\partial u}{\partial x} + 2u \frac{\partial u}{\partial x} + 2v u \frac{\partial u}{\partial y} + 2v u \frac{\partial u}{\partial z} \\ = 2u \left[\frac{\partial u}{\partial x} + u \frac{\partial}{\partial x} \right]$$

$$\rho \frac{D\theta}{Dt} = -\rho \operatorname{div} + \Phi$$

$$\rho u = \frac{\partial \rho}{\partial x} \quad \rho v = \frac{\partial \rho}{\partial y} \quad \rho \omega = \frac{\partial \rho}{\partial z}$$

$$u = f(x, t)$$

$$v = 0$$

$$\text{div} = \frac{\partial u}{\partial x}$$

$$v = \varphi(x, t)$$

$$\rho \left[\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} \right] = - \frac{\partial p}{\partial x} + \frac{4\mu}{3} \frac{\partial^2 u}{\partial x^2}$$

$$\rho \left[\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} \right] = \mu \frac{\partial^2 v}{\partial x^2}$$

$$\frac{\partial p}{\partial x} + u \frac{\partial p}{\partial x} + (k\mu) \rho \frac{\partial u}{\partial x} = \Phi$$

$$= \frac{4\mu}{3} \left(\frac{\partial u}{\partial x} \right)^2 + \mu \left(\frac{\partial v}{\partial x} \right)^2 + k\Delta^2$$

$$\frac{\partial v}{\partial t} = \frac{\mu}{\rho_0} \frac{\partial^2 v}{\partial x^2}$$

$$\frac{\partial u}{\partial t} + (k\mu) \rho_0 \frac{\partial u}{\partial x} = \mu \left(\frac{\partial v}{\partial x} \right)^2 \quad \left| \quad \frac{\partial}{\partial x} \right. \quad \left. \frac{\partial}{\partial t} \right\} \quad \rho_0 \frac{\partial^2 u}{\partial x^2} - k \rho_0 \frac{\partial^2 u}{\partial x^2} = \mu \frac{\partial}{\partial x} \left(\frac{\partial v}{\partial x} \right)^2 + \mu \frac{\partial^3 \theta}{\partial x^3}$$

$$\frac{\partial u}{\partial t} = - \frac{1}{\rho_0} \frac{\partial p}{\partial x} \quad \left| \quad \frac{\partial}{\partial t} \right. \quad \left. \frac{\partial}{\partial x} \right\} \quad \frac{\partial^2 u}{\partial t^2} = a^2 \frac{\partial^2 u}{\partial x^2} + \frac{\mu}{\rho_0} \frac{\partial}{\partial x} \left(\frac{\partial v}{\partial x} \right)^2 + k \frac{\partial^3 \theta}{\partial x^3}$$

$$v = A e^{-\alpha x} \cos(\beta x + \gamma t)$$

$$\frac{\partial v}{\partial x} = A e^{-\alpha x} [-\alpha \cos + \beta \sin]$$

$$\left(\frac{\partial v}{\partial x} \right)^2 = A^2 e^{-2\alpha x} [\alpha^2 \cos^2 + \beta^2 \sin^2 - 2\alpha\beta \cos \sin]$$

$$v = A e^{-x\sqrt{\frac{\rho_0}{2\mu}}} \cos(2\alpha n t - x\sqrt{\frac{\rho_0}{2\mu}})$$

$$\left(\frac{\partial v}{\partial x} \right)^2 = A^2 e^{-2\alpha x} \cdot \underbrace{[1 - 2 \cos \sin]}_{[1 - \sin 2(\gamma t - \rho x)]}$$

$$x = \frac{\sqrt{\frac{\rho_0}{2\mu}}}{\gamma}$$

$$2\alpha n \sqrt{\frac{\rho_0}{2\mu}}$$

$$y = 2\alpha n$$

$$-\sin = \left(\frac{\mu}{\rho_0} \right) [\alpha^2 \cos^2 - \beta^2 \sin^2] \cos 2\alpha \rho \sin$$

$$\alpha = \beta$$

$$1 = 2 \sqrt{\frac{\mu}{\rho_0}} \alpha^2$$

$$\alpha = \sqrt{\frac{\rho_0}{2\mu}}$$

$$u = \frac{1}{2\alpha n} \left(\frac{\partial v}{\partial x} \right)^2$$

$$\rho \frac{\partial v}{\partial t} + \frac{\partial \rho}{\partial x} v = \mu \frac{\partial^2 v}{\partial x^2}$$

$$\frac{\partial \rho}{\partial t} = \left(\mu \left(\frac{\partial v}{\partial x} \right)^2 + \kappa \frac{\partial^2 \rho}{\partial x^2} \right)$$

$$\frac{\partial \rho}{\partial t} + \frac{\partial \rho}{\partial x} v = 0 \quad \rho = \text{const} = \frac{1}{R\theta}$$

$$\frac{\partial \rho}{\partial t} + \rho \frac{\partial v}{\partial x} = 0$$

$$R\rho \frac{\partial \theta}{\partial t} = \mu \left(\frac{\partial v}{\partial x} \right)^2 + \kappa \frac{\partial^2 \theta}{\partial x^2}$$

$$\rho \frac{\partial v}{\partial t} = \mu \frac{\partial^2 v}{\partial x^2}$$

$$\frac{\partial v}{\partial t} + v \frac{\partial v}{\partial x} + \kappa_f \frac{\partial v}{\partial x} = \left[\frac{\gamma \mu}{3} \left(\frac{\partial v}{\partial x} \right)^2 + \kappa \frac{\partial^2 v}{\partial x^2} \right] (k-1)$$

$$u = f(t) x = x f$$

$$\mu x x = \mu \Rightarrow \frac{4}{3} \mu \frac{\partial u}{\partial x} = a$$

$$f = a + \frac{4}{3} \mu \frac{\partial u}{\partial x} \mu$$

$$\frac{\gamma \mu}{3} \frac{\partial f}{\partial t} + k f \left[a + \frac{\gamma}{3} \mu f \right] = \frac{\gamma \mu}{3} f^2 (k-1)$$

$$\frac{\gamma \mu}{3} \frac{\partial f}{\partial t} + a k f + \frac{\gamma \mu}{3} f^2 = 0$$

$$\frac{\partial f}{\partial t} + \frac{3 a k}{\gamma \mu} \frac{1}{f} + 1 = 0$$

$$-\frac{\partial}{\partial t} \left(\frac{1}{f} \right) + \frac{3 a k}{\gamma \mu} \left(\frac{1}{f} \right) + 1 = 0$$

$$-A \alpha e^{\alpha t} + \frac{3 a k}{\gamma \mu} [A e^{\alpha t} + B] + 1 = 0$$

$$\frac{1}{f} = A e^{\alpha t} + B$$

$$\alpha = + \frac{3 a k}{\gamma \mu}$$

$$B = - \frac{\gamma \mu}{3 a k}$$

$$u = \frac{x}{A e^{\frac{3 a k}{\gamma \mu} t} - \frac{\gamma \mu}{3 a k}}$$

$$\frac{1}{A - \frac{\gamma \mu}{3 a k}} = \frac{1}{(a - \mu_0) \frac{3}{\gamma \mu}}$$

$$A = \frac{\gamma \mu}{3 a k} + \frac{\gamma \mu}{3 a k} (\mu_0 - a)$$

$$\rho \left(u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right) = - \frac{\partial p}{\partial x}$$

$$\rho \left(u \frac{\partial v}{\partial x} + \dots \right) = - \frac{\partial p}{\partial y}$$

$$\rho \left(u \frac{\partial w}{\partial x} + \dots \right) = - \frac{\partial p}{\partial z}$$

$$\rho_0 = \left(\frac{p_0}{k} \right)^{\frac{1}{\gamma}}$$

$$\frac{1}{\rho} \frac{\partial \rho}{\partial x} = \frac{1}{k} \frac{1}{p} \frac{\partial p}{\partial x}$$

$$r_1^2 = k^2$$

$$r_2^2 = \sqrt{a^2 - c^2}$$

$$r_1^2 \cdot r_2^2 = c^2$$

$$\frac{\partial \rho u}{\partial x} + \dots = 0$$

$$r = \sqrt{a - cx} = \sqrt{r_1^2 - \frac{a}{2} (r_1^2 - r_2^2)}$$

$$u = \frac{(y^2 - y^2) c}{4\mu \sqrt{a - cx}}$$

$$\frac{\partial u}{\partial y} = \frac{(2y) c}{4\mu \sqrt{a - cx}}$$

$$\frac{\partial u}{\partial x} = + \frac{(y^2 - y^2) c^2}{8\mu \sqrt{a - cx}^3}$$

$$\frac{\partial u}{\partial y^2} = \frac{-2c}{4\mu \sqrt{a - cx}}$$

$$\frac{\partial u}{\partial x^2} \sim \frac{c^2 y^2}{(a - cx)^3} \sim \frac{y^2}{x^3}$$

$$\frac{\partial^2 u}{\partial x^2} = \frac{3(y^2 - y^2) c^3}{16\mu \sqrt{a - cx}^5}$$

$$\frac{\partial^2 u}{\partial x \partial y} = \frac{(2y) c^2}{8\mu \sqrt{a - cx}^3}$$

$$\frac{\partial p}{\partial x} = \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) + \frac{1}{3} \frac{\partial^2 u}{\partial x^2}$$

$$\frac{\partial p}{\partial y} = \frac{1}{3} \frac{\partial^2 u}{\partial x \partial y}$$

$$0 = \mu \frac{\partial}{\partial y} \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$$

$$\frac{\partial u}{\partial x^2} + \frac{\partial u}{\partial y^2} = f(x) = f(x)$$

$$\frac{\partial}{\partial x} (\mu u) = 0$$

$$\mu u = f(y) = \varphi(y)$$

$$\Delta^2 p = \mu \frac{\partial}{\partial x} \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) + \frac{1}{3} \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$$

$$= \frac{4\mu}{3} \frac{\partial}{\partial x} \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) = \frac{4\mu}{3} \frac{\partial f}{\partial x}$$

$$\mu = \frac{4}{3} \frac{\partial u}{\partial x} + \varphi(x, y) \quad \parallel \quad \frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} = 0$$

$$\frac{\partial \mu}{\partial y} = \frac{4}{3} \frac{\partial^2 u}{\partial x \partial y} + \frac{\partial \varphi}{\partial y}$$

$$\frac{\partial \varphi}{\partial y} = -\mu \frac{\partial^2 u}{\partial x \partial y} = -3 \frac{\partial \mu}{\partial y}$$

$$\varphi(x, y) = \chi(x) - 3\mu$$

$$\mu = \frac{\mu}{3} \frac{\partial u}{\partial x} + \frac{1}{4} \chi(x)$$

$$\Delta^2 u = \frac{2}{3} \frac{d\chi}{dx} \parallel \mu u = \varphi(y)$$

$$\mu = \frac{\mu}{3} \frac{\partial^2 u}{\partial x^2} + \frac{1}{4} \frac{d\chi}{dx} = \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{1}{3} \right) + \frac{1}{4} \frac{d\chi}{dx}$$

$$\Delta^2 \mu = \frac{4}{3} \frac{2}{3} \frac{\partial^2 \mu}{\partial x^2} = \frac{8}{9} \frac{d^2 \chi}{dx^2} = \frac{1}{12} \frac{d^2 \chi}{dx^2}$$

$$2 = \frac{1}{4} \quad \frac{d\chi}{dx} = -\frac{1}{4} \frac{d\chi}{dx}$$

$$\mu u = \frac{\mu}{3} \frac{\partial u}{\partial x} + \frac{1}{4} \mu \chi(x) = \varphi(y)$$

$$= \frac{\mu}{6} \frac{\partial^2 u}{\partial x^2} + \frac{1}{4} \mu \chi(x)$$

$$2 \frac{d\chi}{dx} + 2\chi = a$$

$$-\frac{1}{4} \frac{d\chi}{dx} + \frac{1}{4} \chi = a$$

$$\frac{\mu}{3} \left(\frac{\partial u}{\partial x} \right)^2 + \frac{\mu}{3} \frac{\partial^2 u}{\partial x^2} + \frac{1}{4} \frac{\partial^2 u}{\partial x^2} \chi + \frac{\mu}{4} \frac{\partial \chi}{\partial x} = 0$$

$$\frac{dy}{dx} + ay^2 - \chi y^2 = 0$$

$$\mu \frac{\partial u}{\partial x} + \mu \frac{\partial \varphi}{\partial x} = 0$$

$$\frac{\varphi(y)}{\mu} = \frac{\mu}{3} \frac{\partial u}{\partial x} + \frac{1}{4} \chi(x)$$

$$\frac{\mu}{3} \frac{\partial \mu}{\partial y} - \frac{\mu}{4} \chi(x) = \varphi(y)$$

$$\frac{\mu}{3} \left(\frac{\partial u}{\partial x} \right)^2$$

$$\frac{\mu}{3} \mu \frac{\partial u}{\partial x} + \frac{1}{4} \mu \chi(x) = \varphi(y)$$

$$\frac{1}{4} \frac{d\chi}{dx} = -\frac{\mu}{3} \frac{\partial^2 u}{\partial x^2} - \frac{\varphi(y)}{\mu} \frac{\partial u}{\partial x} = \mu \left[\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right]$$

$$\frac{\partial^2 u}{\partial y^2} = -\frac{4}{3} \frac{\partial^2 u}{\partial x^2} - \frac{\varphi(y)}{\mu \mu} \frac{\partial u}{\partial x} = -\frac{2}{\partial x} \left[\frac{4}{3} \frac{\partial u}{\partial x} \mu - \frac{\varphi(y)}{\mu \mu} \right]$$

$$\frac{\partial u}{\partial x} = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right) = \frac{du}{dx} \quad \left\| \quad \frac{\partial u}{\partial z} = 0 \right.$$

~~for $\frac{\partial u}{\partial z} = 0$~~

$$\frac{\partial}{\partial z} \left(r \frac{\partial u}{\partial r} \right) = r \frac{du}{dx}$$

$$r \frac{\partial u}{\partial z} = \frac{r^2}{2} \frac{du}{dx} + \varphi(x)$$

$$\frac{\partial u}{\partial z} = \frac{r}{2} \frac{du}{dx} + \frac{1}{2} \varphi(x)$$

$$u = \frac{r^2}{4} \frac{du}{dx} + \varphi(x) \log(r) + \psi(x)$$

$$u = \frac{r^2 - \delta^2}{4} \frac{du}{dx}$$

$$\frac{r}{R \left\{ \theta_0 - \frac{(\delta^2 - r^2)^2}{128 \mu k} \left[\frac{r^2 - p^2}{l} \right]^2 \frac{1}{r^2} \right\}} \frac{r^2 - \delta^2}{4} \frac{du}{dx} = f_c(r)$$

$$\frac{(r^2 - \delta^2) r^2 d(p^2)}{8R \left[\theta_0 - \frac{(\delta^2 - r^2)^2}{128 \mu k} \left[\frac{r^2 - p^2}{l} \right]^2 \right]} = f_c(r) \cdot dx$$

$$\int \frac{z dz}{a z - b} = \frac{1}{a} \int \left\{ dz + \frac{b dz}{a z - b} \right\} = \frac{1}{a} \left[z + \frac{b}{a} \log(a z - b) \right]$$

$$= \frac{1}{a} \left[p^2 + \frac{b}{a} \log(a p^2 - b) \right]$$

$$\frac{1}{a} \left[p^2 + \frac{b}{a} \log(a p^2 - b) \right] = \frac{\partial R}{\partial (r^2 - \delta^2)} f_c(r) \cdot x + \text{const}$$

$$\frac{1}{a} \left[p^2 + \frac{b}{a} \log(a p^2 - b) \right] = \text{const}$$

$$\frac{1}{a} \left[p^2 + \frac{b}{a} \log(a p^2 - b) \right] = \frac{\partial R}{\partial (r^2 - \delta^2)} f_c(r) \cdot l + \text{const}$$

$$\frac{\partial R}{\partial (r^2 - \delta^2)} f_c(r) = \frac{1}{a} \left[p^2 - p_i^2 + \frac{b}{a} \log \left(\frac{a p_i^2 - b}{a p^2 - b} \right) \right] \frac{\partial R}{\partial R l}$$

Suppose: $\frac{\partial v_s}{\partial z} \propto \delta$

$$\frac{\partial v_s}{\partial \theta} + v_s \frac{d\theta}{ds} = 0$$

$$\log v_s = - \int \frac{d\theta}{\sin \theta} d\theta$$

$$= - \log \sin \theta$$

$$v_s \sin \theta = f_s(r)$$

$$V = -cx \left(1 + \frac{a^2}{2r^2}\right)$$

$$= -cr \cos \theta \left(1 + \frac{a^2}{2r^2}\right)$$

$$\frac{\partial V}{\partial r} = -c \cos \theta \left(1 + \frac{a^2}{2r^2}\right) + \frac{3c \cos \theta}{2r^3}$$

$$\Delta^2 = \frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} + \frac{\cos \theta}{r^2 \sin \theta} \frac{\partial}{\partial \theta}$$

$$\lambda \frac{\partial}{\partial r} (V + \Phi) = 0$$

$$\Delta^2 V = \frac{\partial^2 V}{\partial r^2} + \frac{2}{r} \frac{\partial V}{\partial r} + \frac{1}{r^2} \frac{\partial^2 V}{\partial \theta^2} + \frac{\cos \theta}{r^2 \sin \theta} \frac{\partial V}{\partial \theta} = v_n \frac{\partial^2 V}{\partial r^2} + v_s \frac{\partial^2 V}{\partial \theta^2} + \left[v_n \frac{\partial V}{\partial r} + v_s \frac{\partial V}{\partial \theta} \right]$$

$$\Delta^2 V = \frac{1}{r} \frac{\partial V}{\partial r} \quad \frac{\partial V}{\partial \theta} = \frac{1}{r} \frac{\partial V}{\partial \theta}$$

$$\begin{cases} \frac{\partial^2 V}{\partial r^2} = v_n \frac{\partial^2 V}{\partial r^2} + v_s \frac{\partial^2 V}{\partial \theta^2} \\ \frac{\partial V}{\partial r} = \frac{1}{r} \frac{\partial V}{\partial r} + \left[\frac{\partial V}{\partial \theta} \right] \\ \frac{\partial V}{\partial \theta} = \frac{1}{r} \frac{\partial V}{\partial \theta} + \left[\frac{\partial V}{\partial r} \right] \end{cases} \quad \left\{ \begin{array}{l} \frac{\partial}{\partial r} \\ \frac{\partial}{\partial \theta} \end{array} \right\} = \frac{\partial V}{\partial r} \frac{\partial V}{\partial \theta} + \frac{\partial}{\partial r} \left(\frac{\partial^2 V}{\partial r^2} + \frac{2}{r} \frac{\partial V}{\partial r} \right)$$

$$v_n \frac{\partial^2 V}{\partial r^2} = - \frac{1}{r} \frac{\partial V}{\partial r} = - \frac{1}{4r} \frac{\partial^2 V}{\partial r^2} \frac{\partial V}{\partial \theta}$$

$$\frac{\partial v_s}{\partial r} = \frac{1}{4r} \frac{\partial^2 V}{\partial r^2} \frac{\partial V}{\partial \theta} + \dots$$

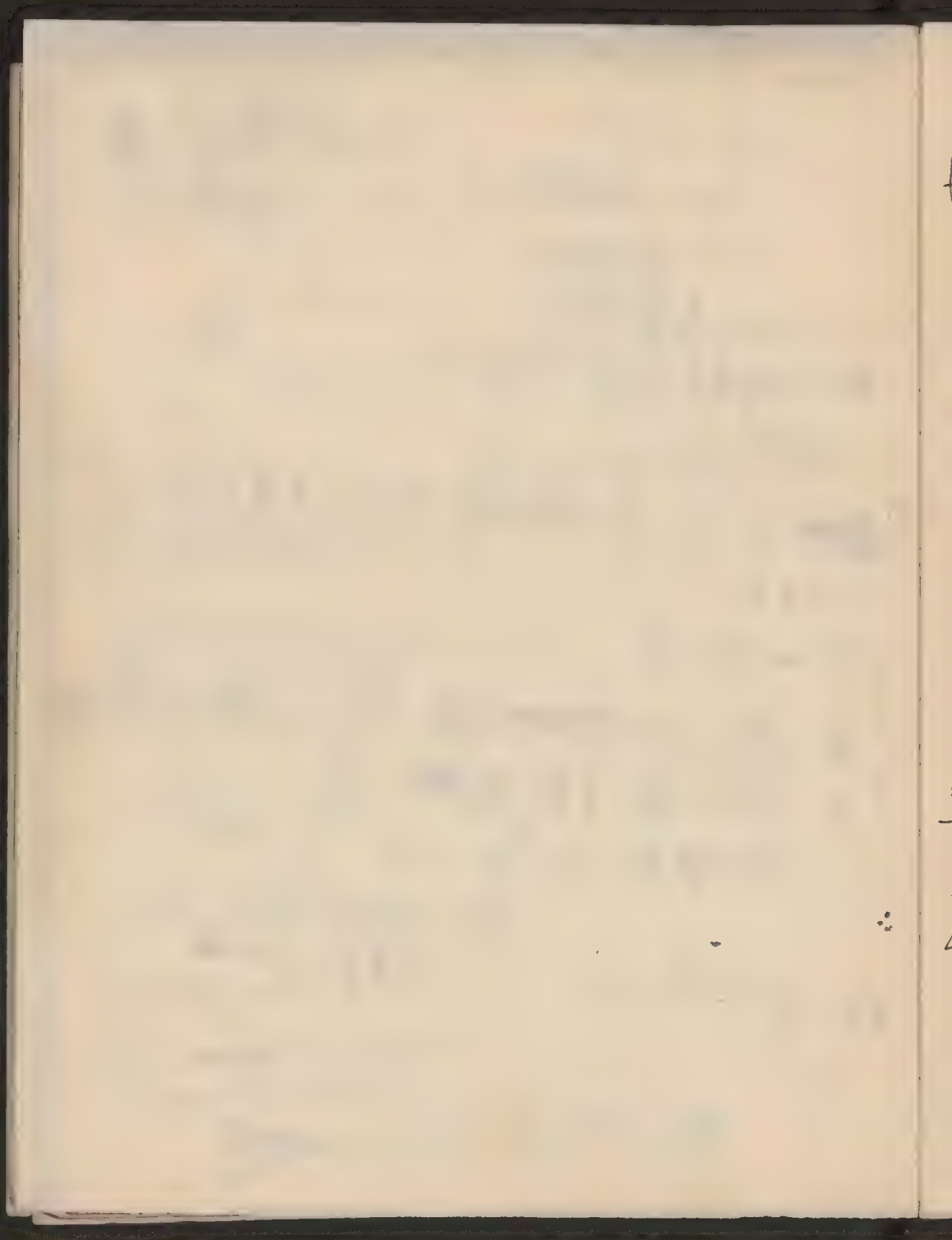
$$v_s = \frac{1}{4r} \frac{\partial^2 V}{\partial r^2} \frac{\partial V}{\partial \theta} + \dots = \frac{f_s(r)}{\sin \theta}$$

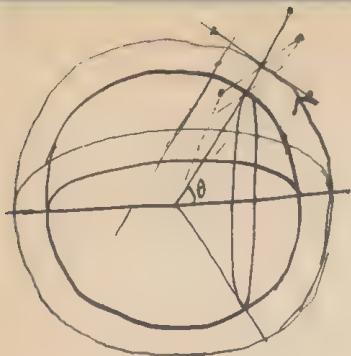
$$\frac{\partial v_n}{\partial r} + \frac{\partial v_s}{\partial \theta} + \frac{v_s}{r} \frac{d\theta}{ds} = 0$$

$$v_n +$$

$$\frac{\partial V}{\partial r} = \frac{f_s(r)}{\sin \theta} + \dots$$

$$V = f_s(r) \int \frac{d\theta}{\sin \theta} + \dots$$





$v_n \quad v_s$

$$\cos \theta \cos \theta_1 - \sin \theta \sin \theta_1 = \cos(\theta + \theta_1)$$

$$v_f = v_n \cos \theta + v_s \sin \theta$$

$$v_f = v_n [\cos \theta_1 \cos \theta + \sin \theta_1 \sin \theta \cos \varphi] + v_s [\sin \theta_1 \cos \theta + \cos \theta_1 \sin \theta \cos \varphi]$$

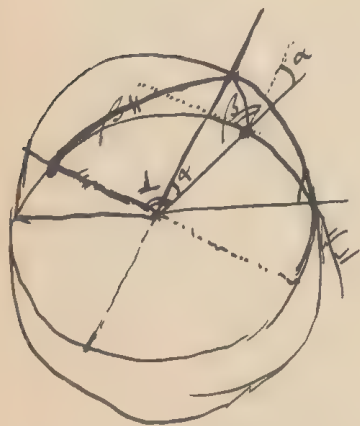
$$v_f = v_n \cos \alpha + v_s \cos \beta$$

$$\cos \alpha = \cos \theta \cos \theta_1 + \sin \theta \sin \theta_1 \cos \varphi$$

$$\cos \beta = \sin \theta \cos \theta_1 + \cos \theta \sin \theta_1 \cos \varphi$$

$$= \cos \theta \cos \theta_1 - \sin \theta \sin \theta_1 \cos \varphi - \cos \theta_1$$

$$\cos \beta = -\sin \theta \cos \theta_1 + \sin \theta_1 \cos \theta \cos \varphi$$



$$v_f = v_n (\cos \theta \cos \theta_1 + \sin \theta \sin \theta_1 \cos \varphi) + v_s (-\sin \theta \cos \theta_1 + \sin \theta_1 \cos \theta \cos \varphi)$$

$$v_f = \cos \theta_1 (v_n \cos \theta - v_s \sin \theta) + \sin \theta_1 (v_n \sin \theta + v_s \cos \theta) \cos \varphi$$

$$\Delta^2 = \frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} + \frac{1}{r^2 \sin \theta} \frac{\partial^2}{\partial \varphi^2} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} + \frac{\cos \theta}{r^2 \sin \theta} \frac{\partial}{\partial \theta}$$

$$\Delta^2 v_f = \cos \theta_1 \left[\frac{\partial^2 v_n}{\partial r^2} \cos \theta - \frac{\partial^2 v_s}{\partial r^2} \sin \theta \right] + \sin \theta_1 \left[\frac{\partial^2 v_n}{\partial r^2} \sin \theta + \frac{\partial^2 v_s}{\partial r^2} \cos \theta \right] \cos \varphi +$$

$$+ \frac{2}{r} \cos \theta_1 \left[\frac{\partial v_n}{\partial r} \cos \theta - \frac{\partial v_s}{\partial r} \sin \theta \right] + \frac{2}{r} \sin \theta_1 \left[\frac{\partial v_n}{\partial r} \sin \theta + \frac{\partial v_s}{\partial r} \cos \theta \right] \cos \varphi +$$

$$- \frac{1}{r^2 \sin \theta} \sin \theta_1 [v_n \sin \theta + v_s \cos \theta] \cos \varphi +$$

$$+ \frac{1}{r^2 \sin \theta} \cos \theta_1 [v_n \cos \theta - v_s \sin \theta] \cos \varphi$$



$$v_n = -\cos\theta \left[1 - \frac{a^3}{r^3} \right]$$

$$v_s = +\frac{3}{2} \sin\theta$$

$$\frac{\partial v_n}{\partial \theta} = -\sin\theta \frac{3a^3}{r^3}$$

$$\frac{\partial v_n}{\partial r} = +\sin\theta \left[1 - \frac{a^3}{r^3} \right]$$

$$\frac{\partial v_s}{\partial \theta} = \frac{3}{2} \cos\theta$$

$$\frac{\partial^2 v_n}{\partial \theta^2} = +\cos\theta \frac{12a^3}{r^3}$$

$$\frac{\partial^2 v_n}{\partial r^2} = +\sin\theta \left[1 - \frac{a^3}{r^3} \right]$$

$$\Delta^2 v_\xi = +12 \frac{\cos\theta}{a^2} - \frac{6 \cos\theta}{a^2} - \frac{3 \cos\theta}{a^2} - \frac{3}{a^2} \cos\theta = 0$$

Wojół ~~nie~~ ^{na} ~~pr~~ ^{pr} ~~mi~~ ^{mi} ~~nie~~ ^{nie} (gdzie $v=0$):

$$\Delta^2 v_\xi = \frac{\partial^2 v_n}{\partial r^2} + \frac{2}{a} \frac{\partial v_n}{\partial r}$$

$$\Delta^2 v_\xi = \frac{\partial^2 v_s}{\partial r^2} + \frac{2}{a} \frac{\partial v_s}{\partial r}$$

$$v_s = \sin\theta \left[\frac{r}{a} + \frac{a^2}{2r^2} \right]$$

$$\frac{\partial v_s}{\partial r} = \sin\theta \left[\frac{1}{a} - \frac{a^2}{r^3} \right] \Big|_{r=0} \quad \left| \quad \frac{\partial v_s}{\partial \theta} = \cos\theta \left[\quad \right] \right|$$

$$\frac{\partial^2 v_s}{\partial r^2} = \sin\theta \left[\frac{3a^2}{r^4} \right] \quad \left| \quad \frac{\partial^2 v_s}{\partial \theta^2} = -\sin\theta \left[\quad \right] \right|$$

$$\Delta^2 v_\xi = \frac{3}{a^2} \sin\theta - \frac{3}{2a^2} \frac{\sin\theta}{\sin^2\theta} - \frac{\sin\theta}{a^2} \frac{3}{2} + \frac{1}{a^2} \frac{3}{2} \frac{\cos\theta}{\sin\theta}$$

$$= \frac{\sin\theta}{a^2} \left[\frac{3}{2} - \frac{3}{2 \sin^2} + \frac{3}{2} \frac{\cos^2}{\sin^2} \right] = \frac{3}{2} \frac{\sin\theta}{a^2 \sin} \left[1 - 1 \right] = 0$$

$$\cos\theta_1 \left[\frac{\partial v_n}{\partial \theta} \cos\theta - \frac{\partial v_s}{\partial \theta} \sin\theta \right] + \sin\theta_1 \left[\frac{\partial v_n}{\partial \theta} \sin\theta + \frac{\partial v_s}{\partial \theta} \cos\theta \right. \\ \left. - v_n \sin\theta - v_s \cos\theta \right] \cos\varphi$$

$$\frac{\cos\theta_1}{a^2 \sin\theta_1} \left[\frac{\partial v_n}{\partial \theta} (\cos^2\theta_1 + \sin^2\theta_1 \cos\varphi) - \frac{\partial v_s}{\partial \theta} (1 - \cos\varphi) \sin\theta_1 \cos\theta_1 \right. \\ \left. - v_n \cos\theta_1 \cos\theta_1 (1 - \cos\varphi) + v_s (\cos^2\theta_1 + \sin^2\theta_1 \cos\varphi) \right]$$

$$\cos\theta_1 \left[\frac{\partial^2 v_n}{\partial \theta^2} \cos\theta - \frac{\partial^2 v_s}{\partial \theta^2} \sin\theta \right. \\ \left. - 2 \frac{\partial v_n}{\partial \theta} \sin\theta - 2 \frac{\partial v_s}{\partial \theta} \cos\theta \right. \\ \left. - v_n \cos\theta + v_s \sin\theta \right] + \sin\theta_1 \cos\varphi \left[\frac{\partial^2 v_n}{\partial \theta^2} \sin\theta + \frac{\partial^2 v_s}{\partial \theta^2} \cos\theta \right. \\ \left. + 2 \frac{\partial v_n}{\partial \theta} \cos\theta - 2 \frac{\partial v_s}{\partial \theta} \sin\theta \right. \\ \left. - v_n \sin\theta - v_s \cos\theta \right]$$

$$\frac{1}{a^2} \left\{ \frac{\partial^2 v_n}{\partial \theta^2} (\cos^2\theta_1 + \sin^2\theta_1 \cos\varphi) - \frac{\partial^2 v_s}{\partial \theta^2} (1 - \cos\varphi) \sin\theta_1 \cos\theta_1 - 2 \frac{\partial v_n}{\partial \theta} \sin\theta_1 \cos\theta_1 (1 - \cos\varphi) \right. \\ \left. - 2 \frac{\partial v_s}{\partial \theta} (\cos\theta_1 + \sin\theta_1 \cos\varphi) - v_n (\cos\theta_1 + \sin\theta_1 \cos\varphi) + v_s \sin\theta_1 \cos\theta_1 (1 - \cos\varphi) \right\}$$

$\varphi=0 \parallel \cos\varphi=1$

$$\cos\theta_1 + \sin\theta_1 \cos\varphi = 1$$

$$\Delta^2 v_z = \frac{\partial^2 v_n}{\partial r^2} + \frac{2}{a} \frac{\partial v_n}{\partial r} - \frac{v_n}{a^2} - \frac{v_s}{a^2} \cot\theta_1 + \frac{1}{a^2} \left(\frac{\partial^2 v_n}{\partial \theta^2} - 2 \frac{\partial v_n}{\partial \theta} - v_n \right) \\ + \frac{1}{a^2} \cot\theta_1 \left[\frac{\partial v_n}{\partial \theta} - v_s \right]$$

$$\Delta^2 v_z = \frac{\partial^2 v_n}{\partial r^2} + \frac{2}{a} \frac{\partial v_n}{\partial r} - \frac{2v_n}{a^2} + \frac{1}{a^2} \frac{\partial^2 v_n}{\partial \theta^2} + \frac{1}{a^2} \cot\theta_1 \frac{\partial v_n}{\partial \theta} - \frac{2v_s}{a^2} \cot\theta_1 - \frac{2}{a^2} \frac{\partial v_s}{\partial \theta}$$

$$\text{Final } v_n=0 \quad \frac{\partial v_n}{\partial r} \odot \delta \quad \frac{\partial^2 v_n}{\partial r^2} \odot 1 \quad = \frac{\partial^2 v_n}{\partial r^2} + \left(\frac{2}{a} + \frac{2v_n}{a^2} \right) \frac{\partial v_n}{\partial r} + \frac{2v_n}{a^2} + \frac{1}{a^2} \frac{\partial^2 v_n}{\partial \theta^2} + \frac{1}{a^2} \cot\theta \frac{\partial v_n}{\partial \theta}$$

$$\Delta^2 v_z = \frac{\partial^2 v_n}{\partial r^2} - \frac{2v_s}{a^2} \cot\theta_1 - \frac{2}{a} \frac{\partial v_s}{\partial \theta}$$

$$\Delta^2 v_f = \frac{\partial^2 v_f}{\partial r^2} + \frac{2}{a} \frac{\partial v_f}{\partial r} + 1$$

$$= \frac{1}{a^2 \sin^2 \theta_1} [v_n \cos \theta_1 \sin \theta_1 + v_s \sin^2 \theta_1]$$

$$+ \frac{\cos \theta_1}{a^2 \sin^2 \theta_1} \left\{ \frac{\partial v_n}{\partial \theta} [-\sin \theta_1 \cos \theta + \cos \theta_1 \sin \theta \cos \varphi] + \frac{\partial v_s}{\partial \theta} [\sin \theta_1 \sin \theta + \cos \theta_1 \cos \theta \cos \varphi] \right. \\ \left. + v_n [\sin \theta_1 \sin \theta + \cos \theta_1 \cos \theta \cos \varphi] + v_s [\sin \theta_1 \cos \theta - \cos \theta_1 \sin \theta \cos \varphi] \right\}$$

$$+ \frac{1}{a^2} \left\{ \frac{\partial^2 v_n}{\partial \theta^2} + 2 \frac{\partial v_n}{\partial \theta} [\sin^2 \theta_1 + \cos^2 \theta_1 \cos \varphi] + \frac{\partial^2 v_s}{\partial \theta^2} + 2 \frac{\partial v_s}{\partial \theta} [\sin^2 \theta_1 + \cos^2 \theta_1 \cos \varphi] \right\}$$

$$= \frac{\partial^2 v_s}{\partial r^2} + \frac{2}{a} \frac{\partial v_s}{\partial r} - \frac{v_n}{a^2} \frac{d\theta_1}{dr} + \frac{v_s}{a^2} \frac{d\theta_1}{dr} + \frac{v_n}{a^2} \frac{d\theta_1}{dr} + \frac{\partial v_s}{\partial \theta} \frac{d\theta_1}{a^2}$$

$$+ \frac{1}{a^2} \frac{\partial^2 v_n}{\partial \theta^2} + \frac{2}{a^2} \frac{\partial v_n}{\partial \theta} - \frac{v_s}{a^2}$$

$$1 + \frac{d\theta_1}{dr} = 1 + \frac{v_n}{r} = \frac{1}{a^2}$$

$$= \frac{\partial^2 v_s}{\partial r^2} + \frac{2}{a} \frac{\partial v_s}{\partial r} - \frac{v_n}{a^2 \sin^2 \theta_1} + \frac{1}{a^2} \frac{\partial^2 v_n}{\partial \theta^2} + \frac{1}{a^2} \frac{\partial v_n}{\partial \theta} \frac{d\theta_1}{dr} + \frac{2}{a^2} \frac{\partial v_s}{\partial \theta}$$

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$$\Delta^2 v_f = \frac{\partial^2 v_f}{\partial r^2} + \frac{2}{a} \frac{\partial v_f}{\partial r} + 1 = 0$$

$$\sin \theta \frac{\partial}{\partial r} (v_n \sin \theta) + v_n \frac{\partial}{\partial \theta} (\sin \theta) = 0$$

$$2 \frac{v_n}{r} + \frac{v_n}{r} + \frac{\partial v_n}{\partial \theta} + v_n \frac{d\theta}{dr} = 0$$

$$\frac{d\theta}{dr} = -\frac{v_n}{\sin^2 \theta} - 1$$

$$\Delta^2 v_f = \frac{\partial^2 v_f}{\partial r^2} + \frac{2}{a} \frac{\partial v_f}{\partial r} + 1 = 0$$

$$\Delta^2 v_f = \frac{\partial^2 v_s}{\partial r^2} + \frac{2}{a} \frac{\partial v_s}{\partial r} - \frac{v_n}{a^2} \frac{d\theta_1}{dr}$$

$$\frac{\partial \psi}{\partial x} = \mu \nabla u + \frac{p_1}{h_1} \frac{x}{2}$$

$$\frac{\partial \psi}{\partial y} = \mu \nabla v + \frac{p_2}{h_2} \frac{y}{2}$$

$$\psi = \mu \nabla w + \frac{p_3}{h_3} \frac{z}{2}$$

$$\frac{\partial \psi}{\partial x} = \mu \nabla u + \frac{p_1}{h_1} \frac{x}{2}$$

$$\rho \left(\frac{\partial u}{\partial x} + \dots \right) + u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} = 0$$

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$$\left(u \frac{\partial}{\partial x} + \dots \right) - \frac{k}{h_1} \rho \left(u \frac{\partial \theta}{\partial x} + \dots \right) + \mu \phi + k \Delta \theta = 0$$

$$\frac{1}{a} \left[\rho^2 + \frac{b}{a} \log(a\rho^2 - b) \right] = \frac{1}{a} \left[\rho_1^2 - \rho_2^2 + \frac{b}{a} \log \left(\frac{a\rho_1^2 - b}{a\rho_2^2 - b} \right) \right] \frac{x}{l} + \frac{1}{a} \left[\rho_1^2 + \frac{b}{a} \log(a\rho_1^2 - b) \right]$$

$$\rho^2 - \rho_1^2 + \frac{b}{a} \log \frac{a\rho^2 - b}{a\rho_1^2 - b} = \left[\rho_1^2 - \rho_2^2 + \frac{b}{a} \log \left(\frac{a\rho_1^2 - b}{a\rho_2^2 - b} \right) \right] \frac{x}{l}$$

$$2\pi \int \rho u r dr = \frac{2\pi}{2} \int \rho^2 r dr \quad \frac{2\pi}{2} \int \frac{r^2 - \delta^2}{4} \rho \frac{d\rho}{dr} r dr$$

$$= 2\pi \int r dr \left[\theta_0 - \frac{(\delta^2 - r^2)^2}{16\mu h} \left(\frac{\rho_1^2 - \rho_2^2}{l} \right) \frac{1}{\rho^2} \right] \frac{(r^2 - \delta^2)}{2R} + \frac{1}{\theta_0} \left[\rho_1^2 \rho_2^2 + \frac{b}{a} \log \left(\frac{a\rho_1^2 - b}{a\rho_2^2 - b} \right) \right]$$

$$\log(a\rho^2 - b) = \log a\rho^2 + \log \left(1 - \frac{b}{a\rho^2} \right) = \log(a\rho^2) - \frac{b}{a\rho^2}$$

$$u^2 = \frac{y^2 \delta^2 y^2 c^2}{16\mu^2 (a - cx)^2}$$

$$\frac{(y^2 \delta^2 y^2 c^2)}{16\mu^2 (a - cx)^2} \frac{1}{Ru}$$

$$\frac{1}{\rho} \frac{\partial u}{\partial x} = \frac{R\theta}{h} \frac{\partial u}{\partial x}$$

$$= \frac{R\theta (r^2 - \delta^2) c^2}{16\mu \sqrt{\dots}}$$

$$\frac{R\theta c^2 (r^2 - \delta^2)}{16\mu (a - cx)^2} = \frac{(y^2 \delta^2 y^2 c^2)}{4\mu (a - cx)}$$

$$\frac{\partial (u^2)}{\partial x} = \frac{(r^2 - \delta^2)^2 c^3}{16\mu^2 (a - cx)^2} \parallel r dr$$

$$\int \frac{\partial u}{\partial x} u r dr = \frac{r^2 - \delta^2 c^3}{(a - cx)^2}$$

~~...~~

$$\int \rho u r dr = \frac{k}{h-1} \frac{\delta \theta}{\theta} \frac{c(r^2 - \delta^2) r dr}{\rho}$$

